HAWAII-CALIFORNIA TRAINING AND TESTING DRAFT ENVIRONMENTAL IMPACT STATEMENT/ OVERSEAS ENVIRONMENTAL IMPACT STATEMENT

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Volume 2



Hawaii-California Training and Testing

Draft Environmental Impact Statement/ Overseas Environmental Impact Statement



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Appendix A Activity Descriptions

Environmental Impact Statement/

Overseas Environmental Impact Statement

Hawaii-California Training and Testing Activities

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APPENDIX A Activity Descriptions

A.1 Training Activities

The proposed training activities would be conducted by the U.S. Navy (Navy), U.S. Marine Corps (USMC), U.S. Coast Guard (USCG), U.S. Army (Army), and U.S. Air Force (USAF). The Navy as the lead agency, jointly with the USCG, Army, and USAF, are action proponents for the training activities described in this appendix. The training activities are organized generally into eight primary mission areas and a miscellaneous category (Other Training) that includes those activities that do not fall within a primary mission area, but are an essential part of military training.

Descriptions of training and testing activities are included in Data Sheets, beginning on p. A-3. Location information provided on the Data Sheets indicate where activities would occur within the broad HCTT Study Area. Specific locations which are typically scheduled for the activity are included within parentheticals and are not intended to restrict activity to only those locations.

The tempo of activities, i.e., the number of events per year, are found in Chapter 2, Tables 2-11 through 2-19.

In addition, because the military conducts a number of activities within larger training exercises, descriptions of those larger exercises are also included here. It is important to note that these larger exercises are comprised entirely of individual activities described in the primary mission areas. These exercises frequently include multiple services (Navy, USMC, USCG, Army, USAF) and could include foreign participants from time to time. Foreign participation is episodic to location and time (by year). Data collected to make assumptions about events has factored a certain number of participants which could include foreign participants.

New technologies and tactics require forces to be distributed over increasingly larger areas to conduct realistic training and testing.

A.1.1 Major Anti-Submarine Warfare (ASW) Training Exercises

A major training exercise is comprised of multiple "unit level" activities conducted by several units operating together while commanded and controlled by a single commander. These ASW exercises typically employ an exercise scenario developed to train and evaluate the larger integrated force in naval tactical tasks. In a major training exercise, most of the operations and activities being directed and coordinated by the strike group commander are identical in nature to the operations conducted during individual, crew, and smaller-unit training events. In a major training exercise, however, these disparate training tasks are conducted in concert, rather than by an individual smaller unit. Table A-1 describes the differences between major training exercises and smaller integrated/coordinated anti-submarine warfare exercises based on scale, duration, and sonar hours.

	Exercise Group	Description	Scale	Duration	Location	Exercise Examples	Modeled Hull-mounted Sonar per Exercise
ing Exercises	Large Integrated ASW	Larger-scale, longer duration integrated ASW exercises	Greater than 6 surface ASW units (up to 30 with the largest exercises), 2 or more submarines, multiple ASW aircraft	Generally >10 days	CA HI	Strike Group COMPTUEX, RIMPAC	>500 hours
Major Traini	Medium Integrated ASW	Medium-scale, medium duration integrated ASW exercises	Approximately 3– 8 surface ASW units, at least 1 submarine, multiple ASW aircraft	Generally 4–10 days	CA HI	Task Force/ Sustainment Exercise, Multi-Warfare Exercise	100–500 hours
Integrated/Coordinated Training	Small Integrated ASW	Small-scale, short duration integrated ASW exercises	Approximately 3–6 surface ASW units, 2 dedicated submarines, 2–6 ASW aircraft	Generally <5 days	CA HI	SWATT, NUWTAC	50–100 hours
	Medium Coordinated ASW	Medium-scale, medium duration, coordinated ASW exercises	Approximately 2– 4 surface ASW units, possibly a submarine, 2–5 ASW aircraft	Generally 3–10 days	CA HI	SCC, Fleet Battle Problem, TACDEVEX	<100 hours
	Small Coordinated ASW	Small-scale, short duration, coordinated ASW exercises	Approximately 2–4 surface ASW units, possibly a submarine, 1–2 ASW aircraft	Generally 2–4 days	CA HI	ARG/MEU COMPTUEX, ID CERTEX	<50 hours

Table A-1: Major Anti-Submarine Warfare Training Exercises and Integrated/Coordinated Anti-Submarine Warfare Training

Notes: ASW = Anti-Submarine Warfare, CA = California Study Area, HI = Hawaii Study Area, SOCAL = Southern California Range Complex, PMSR = Point Mugu Sea Range, HRC = Hawaii Range Complex, RIMPAC = Rim of the Pacific, COMPTUEX = Composite Training Unit Exercise, SWATT = Surface Warfare Advanced Tactical Training, NUWTAC = Naval Undersea Warfare Training Assessment Course, SCC = Submarine Command Course, ARG/MEU CERTEX = Amphibious Ready Group/Marine Expeditionary Unit Certification Exercise, TACDEVEX = Tactical Development Exercise, ID CERTEX/ASW = Independent Deployer Certification Exercise/Tailored Anti-submarine Warfare Training, ">" = greater than, "<" = less than

Major ASW training exercises are listed below.

A.1.1.1 Composite Training Unit Exercise (Strike Group)

Major Training Exercise – Large Integrated Anti-Submarine Warfare				
Composite Training	g Unit Exercise (Strike Group)			
Short Description	Aircraft carrier and carrier air wing integrate with surface and submarine units in a challenging multi-threat operational environment that certifies them ready to deploy.			
Long Description	The Composite Training Unit Exercise is an integration phase, at-sea, major training exercise, designed to forge the aircraft carrier strike group into a cohesive fighting team before deployment. The Composite Training Unit Exercise normally consists of a four- week schedule of event-driven scenarios. An exercise typically consists of seven surface ships, multiple fixed-wing and rotary-wing aircraft, up to two submarines, and various unmanned vehicles. The exercise integrates the aircraft carrier and carrier air wing with surface and submarine units to achieve certification prior to deployment. Coast Guard and Air Force assets may participate in this activity.			
Typical Components	Platforms: Aircraft Carrier, Fleet Support Vessel, Fixed Wing – Patrol Aircraft, Fixed-Wing – Strike Aircraft, Rotary-Wing Aircraft, Submarine, Surface Combatant, Unmanned Surface Vehicle, Unmanned Underwater Vehicle, Unmanned Aerial Vehicle – Fixed Wing			
	Targets: Sub-surface Targets – Maneuvering, Surface Targets - Maneuvering			
	Systems being Trained/Tested: Countermeasures, Sonar Systems - Dipping, Sonar Systems - Hull Mounted, Sonar Systems - Towed, Sonobuovs			
	Munitions: See notes in parameters for analysis			
Active Sonar	LFH, MF1, MF1C, MFM, MFH, Broadband (MF to HF)			
In-Water Explosives	See notes in parameters for analysis			
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity-based Mitigation): Active acoustic sources Manned surface vessels Towed in-water devices Unmanned vehicles			
Parameters for Analysis	Only the anti-submarine warfare activities were analyzed as a Composite Training Unit Exercise. Other warfare area training conducted during the Composite Training Unit Exercise is analyzed elsewhere as unit-level training (e.g., gunnery exercise, missile exercise, etc.).			
	Phase IV Requirement 2025-2032			
Location (typical	NOCAL			
specific location	PMSR			
wnere applicable)	SOCAL			
	Hawaii Range Complex			

Major Training Exercise - Large Integrated Anti-Submarine Warfare			
Rim of the Pacific Exercise			
Short Description	A biennial multinational training exercise in which navies from Pacific Rim nations and other allies assemble in Pearl Harbor, Hawaii, to conduct training throughout the Hawaiian Islands in a number of warfare areas. Components of a Rim of the Pacific exercise may be conducted in the California Study Area.		
Long Description	Rim of the Pacific is the world's largest multinational maritime exercise, typically lasting four to five weeks. Hosted by Commander, Pacific Fleet, the exercise is scheduled in the summer on even years. Rim of the Pacific includes participation by multiple nations (in 2024 included 30 nations, 40 surface ships, 4 submarines, 14 national land forces, approximately 171 aircraft, and more than 25,000 personnel). The exercise typically consists of three major phases. Phase I, the Harbor Phase, will consist of operational planning meetings, safety briefings, and sporting events. This phase is designed to make final preparations for the at-sea phases of the exercises, as well as build on professional and personal relationships between the participating countries. Phase II, the Force Integration Training (FIT) Phase, is driven by a structured schedule of events. This portion may include live-fire gunnery and missile exercises, maritime interdiction and vessel boarding, surface warfare, undersea warfare, naval maneuvers, air defense exercises, as well as explosive ordnance disposal, diving and salvage operations, mine clearance operations, and an amphibious landing. This phase exercises the ability of each nation to conduct robust command and control operations with multinational players and enhances each unit's operational capabilities. Phase III, the Tactical Phase of the exercise, is scenario-driven. The intense training during this phase allows participating nations to further strengthen their maritime skills and capabilities and improve their ability to communicate and operate in simulated hostile scenarios. This phase concludes with the ships' return to Pearl Harbor, where participating nations will reconvene to discuss the exercise and overall accomplishments. Multiple ships and aircraft search for, locate, and track submarines under an integrated command structure. Marine mammal systems may be used during this exercise. Coast Guard cutters and aircraft may participate in this activity.		
Typical Components	Platforms: Aircraft Carrier, Amphibious Warfare Vessel, Fixed Wing - Other, Fixed Wing – Patrol Aircraft, Fixed Wing - Strike Aircraft, Fleet Support Vessel, Patrol Combatant, Rotary-Wing Aircraft, Submarine, Surface Combatant, Unmanned Surface Vehicle, Unmanned Underwater Vehicle, Unmanned Aerial Vehicle – Fixed Wing		
	Targets: Sub-surface Targets - Maneuvering		
	Systems being Trained/Tested: Countermeasures, Sonar Systems - Dipping, Sonar Systems - Hull Mounted, Sonar Systems - Mine Warfare, Sonar Systems - Towed, Sonobuoys		
	Munitions: Torpedoes – Exercise, see notes in parameters for analysis		
Active Sonar	MF1, MF1C, MFM, MFH, HFH, Broadband (MF to HF)		
In-Water Explosives	See notes in parameters for analysis		
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigations):		

	Active acoustic sources Manned surface vessels Towed in-water devices Unmanned vehicles
Parameters for Analysis	Only the anti-submarine warfare activities were analyzed as a Rim of the Pacific Exercise. Other warfare area training conducted during the Rim of the Pacific Exercise is analyzed elsewhere as unit-level training (e.g., gunnery exercise, missile exercise, etc.). All acoustic sources which may be used during training and testing activities by U.S. and foreign forces have been accounted for in the modeling and analysis presented in this major training exercise.
	Phase IV Requirement 2025-2032
Location (typical specific location where applicable)	PMSR SOCAL Hawaii Range Complex
	Hawaii Range Complex

A.1.1.3 Task Force/Sustainment Exercise

Major Training Exercise - Medium Integrated Anti-Submarine Warfare	
Task Force/Sustai	nment Exercise
Short Description	Aircraft carrier and carrier air wing integrates with surface and submarine units in a challenging multi-threat operational environment to maintain ability to deploy.
Long Description	Sustainment Exercises are similar in scope to Composite Training Unit Exercises but shorter in duration and therefore fewer active sonar hours. Sustainment Exercises are conducted to ensure that a Carrier Strike Group maintains an acceptable level of readiness after returning from deployment in order to maintain a surge capability.
Typical Components	Platforms: Aircraft Carrier, Fleet Support Vessel, Fixed Wing – Patrol Aircraft, Fixed Wing – Strike Aircraft, Rotary-Wing Aircraft, Submarine, Surface Combatant, Unmanned Surface Vehicle, Unmanned Underwater Vehicle, Unmanned Aerial Vehicle – Fixed Wing
	Targets: Sub-surface Targets - Maneuvering Systems being Trained/Tested: Countermeasures, Sonar Systems - Dipping, Sonar Systems - Hull Mounted, Sonar Systems - Towed, Sonobuoys
	Munitions: See notes in parameters for analysis
Active Sonar	LFH, MF1, MF1C, MFM, MFH, Broadband (MF to HF)
In-Water Explosives	See notes in parameters for analysis
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity-based Mitigations): Active acoustic sources Manned surface vessels Towed in-water devices Unmanned vehicles
Parameters for Analysis	Only the anti-submarine warfare activities were analyzed as a Task Force/Sustainment Exercise. Other warfare area training conducted during the Task Force/Sustainment Exercise is analyzed elsewhere as unit-level training (e.g., gunnery exercise, missile exercise, etc.).
	Phase IV Requirement 2025-2032
Location (typical	NOCAL
specific location	PMSR
where applicable)	SOCAL
	Hawaii Range Complex

A.1.2 Integrated/Coordinated Training Anti-Submarine Warfare

Integrated or coordinated anti-submarine warfare training exercises are similar to major training exercises in that they are comprised of several basic, unit-level exercises, with training conducted by an individual unit, but are generally on a smaller scale, are of shorter duration, and use fewer hours of active sonar than a major training exercise.

A.1.2.1 Independent Deployer Certification Exercise/Tailored Surface Warfare Training

Integrated/Coordinated Anti-Submarine Warfare Training	
Independent Deplo	over Certification Exercise/Tailored Surface Warfare Training
Short Description	Multiple ships, aircraft, and submarines conduct integrated multi-warfare training with a surface warfare emphasis. Serves as a ready-to-deploy certification for individual surface ships tasked with surface warfare missions.
Long Description	This event stresses planning, coordination, and communications during multiple warfare training scenarios. Two or more ships and two to six helicopters searching for, locating, and attacking one submarine. Typically, one ship and helicopter are actively prosecuting while the other ship and helicopter are repositioning. Simultaneously, the submarine may practice simulated attacks against the ships. Example exercises include: Naval Undersea Warfare Training Assessment Course and Surface Warfare Advanced Tactical Training. Multiple acoustic sources may be active at one time.
Typical Components	 Platforms: Fixed Wing - Strike Aircraft, Rotary-Wing Aircraft, Submarine, Surface Combatant, Unmanned Aerial Vehicle - Fixed Wing, Unmanned Aerial Vehicle - Rotary Wing, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: Surface Targets Systems being Trained/Tested: None Munitions: See notes in parameters for analysis
Active Sonar	See notes in parameters for analysis
In-Water Explosives	See notes in parameters for analysis
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigations): Active acoustic sources Manned surface vessels Unmanned Vehicles
Parameters for Analysis	All anti-submarine acoustic sources which may be used during Independent Deployer Certification Exercise/Tailored Surface Warfare Training have been accounted for in the modeling and analysis of anti-submarine unit-level training events presented in this EIS/OEIS. Additionally, other warfare area training conducted during the Deployer Certification Exercise/Tailored Surface Warfare Training is analyzed elsewhere as unit- level training (e.g., gunnery exercise, missile exercise, etc.).

Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	NOCAL
	PMSR
	SOCAL

A.1.2.2 Medium Coordinated Anti-Submarine Warfare

Integrated/Coordin	nated Anti-Submarine Warfare Training
Medium Coordinat	ed Anti-Submarine Warfare
Short Description	Typically, a 3–10-day exercise with multiple ships, ASW aircraft, and submarines integrating the use of their sensors, including sonobuoys, to search, detect, and track threat submarines.
Long Description	Medium coordinated ASW exercises are tailored events designed to train submarines and surface combatants and develop warfighting tactics, techniques and procedures, and may include torpedo firing. These exercises generally consist of a coordinated training scenario that typically involves two to four surface ships, embarked helicopters, two to three submarines, unmanned vehicles, and maritime patrol aircraft. These exercises may be stand-alone ASW events, such as a Tactical Development Exercise (TACDEVEX) or a Fleet Battle Problem event, generally lasting 3-10 days, or they may be included as part of the "mini-war" phase of the Submarine Commanders Course (SCC), during which torpedoes may be fired.
Typical Components	 Platforms: Fixed Wing – Patrol Aircraft, Rotary-Wing Aircraft, Submarine, Surface Combatant, Unmanned Surface Vehicle, Unmanned Underwater Vehicle, Unmanned Aerial Vehicle - Fixed Wing Targets: Sub-surface Targets - Maneuvering, Surface Targets - Maneuvering Systems being Trained/Tested: Countermeasures, Sonar Systems - Dipping, Sonar Systems - Hull Mounted, Sonar Systems - Towed, Sonobuoys Munitions: Torpedoes – Exercise, see notes in parameters for analysis
Active Sonar	MF1, MF1C, MFM, MFH, HFH, Broadband (LF to HF), Broadband (MF to HF)
In-Water Explosives	See notes in parameters for analysis
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigations): Active acoustic sources Manned surface vessels Towed in-water devices Unmanned Vehicles
Parameters for Analysis	 While preference will be to train against an actual submarine or MK 30 recoverable target, assume only MK 39 expendable targets will be used. One MK 39 Expendable Mobile Anti-Submarine Warfare Training Target may be used in place of an actual submarine target. Only the anti-submarine warfare activities were analyzed as a medium coordinated ASW exercise. All other warfare area training conducted during the larger exercise was analyzed as unit-level training (e.g., bombing, gunnery, missile exercise, etc.).

Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	NOCAL
	PMSR
	SOCAL
	Hawaii Range Complex

A.1.2.3 Small Coordinated Anti-Submarine Warfare

Integrated/Coordir	nated Anti-Submarine Warfare Training
Small Coordinated	Anti-Submarine Warfare Exercise
Short Description	Typically, a 2 to 5-day exercise with multiple ships, aircraft and submarines integrating the use of their sensors, including sonobuoys, to search, detect, and track threat submarines.
Long Description	This is an Anti-Submarine Warfare (ASW) exercise conducted in the HCTT Study Area by forward deployed Navy Strike Groups to sustain and assess their ASW proficiency. The exercise is designed to assess the Strike Groups' ability to conduct ASW in the most realistic environment, against the level of threat expected, in order to effect changes to both training and capabilities (e.g., equipment, tactics, and changes to size and composition) of U.S. Navy Strike Groups. The Strike Group receives significant training value in ASW and other warfare areas, as training is inherent in all at-sea exercises. Additional unit-level activities, such as MISSILEX may be conducted during these events.
Typical Components	Platforms: Aircraft Carrier, Fixed Wing – Patrol Aircraft, Rotary-Wing Aircraft, Submarine, Surface Combatant, Unmanned Surface Vehicle, Unmanned Underwater Vehicle, Unmanned Aerial Vehicle - Fixed Wing
	Targets: Sub-surface Targets - Maneuvering
	Systems being Trained/Tested: Countermeasures, Sonar Systems - Dipping, Sonar Systems - Hull Mounted, Sonar Systems - Towed, Sonobuoys
	Munitions: See notes in parameters for analysis
Active Sonar	LFH, MF1, MF1C, MFM, MFH, Broadband (MF to HF)
In-Water Explosives	See notes in parameters for analysis
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Towed in-water devices Unmanned Vehicles
Parameters for Analysis	Only the anti-submarine warfare activities were analyzed as a Small Coordinated Anti- Submarine Warfare Exercise. All other warfare area training conducted during the exercise was analyzed as unit-level training (e.g., bombing exercises, gunnery exercises, missile exercises, etc.).
	Phase IV Requirement 2025-2032
Location (typical	NOCAL
specific location	PMSR
where applicable)	SOCAL
	Hawaii Range Complex

A.1.3 Integrated/Coordinated Training – Other

Integrated or coordinated training – other exercises are similar to major training exercises in that they are comprised of several basic, unit-level exercises, with training conducted by an individual unit, but are generally on a smaller scale, are of shorter duration, or use fewer hours of active sonar than a major training exercise.

A.1.3.1 Composite Training Unit Exercise (Amphibious Ready Group/Marine Expeditionary Unit)

Integrated/Coo	Integrated/Coordinated Training – Other	
Composite Train	ning Unit Exercise (Amphibious Ready Group/Marine Expeditionary Unit)	
Short Description	The amphibious ready group and the Marine expeditionary unit integrate with surface and submarine units in a challenging multi-threat operational environment that certifies them ready to deploy.	
Long Description	The Composite Training Unit Exercise is an integration phase, at-sea, major training exercise, designed to forge the amphibious ready group and the Marine expeditionary unit into a cohesive fighting team before deployment. The Composite Training Unit Exercise normally consists of a four-week schedule of event-driven scenarios. An exercise typically consists of surface ships, multiple fixed-wing and rotary-wing aircraft, up to two submarines, and various unmanned vehicles. The exercise integrates the amphibious ready group and the Marine expeditionary unit to achieve certification prior to deployment. Coast Guard and Air Force assets may participate in this activity.	
Typical Components	 Platforms: Amphibious Warfare Vessel, Fixed Wing – Patrol Aircraft, Rotary-Wing Aircraft, Submarine, Surface Combatant, Unmanned Aerial Vehicle - Rotary Wing, Unmanned Surface Vehicle, Unmanned Underwater Vehicle, Unmanned Aerial Vehicle – Fixed Wing Targets: Sub-surface Targets – Maneuvering, Surface Targets - Maneuvering Systems being Trained/Tested: Countermeasures, Sonar Systems - Dipping, Sonar Systems - Hull Mounted, Sonar Systems - Towed, Sonobuoys Munitions: See notes in parameters for analysis 	
Active Sonar	LFH, MF1, MFM, MFH, Broadband (MF to HF)	
In-Water Explosives	See notes in parameters for analysis	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity-based Mitigation): Active acoustic sources Manned surface vessels Towed in-water devices Unmanned vehicles	
Parameters for Analysis	Only the anti-submarine warfare activities were analyzed as a Composite Training Unit Exercise. Other warfare area training conducted during the Composite Training Unit Exercise is analyzed elsewhere as unit-level training (e.g., gunnery exercise, missile exercise, etc.).	

Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	NOCAL
	PMSR
	SOCAL (Del Mar Boat Basin, Camp Pendleton Amphibious Assault Area, Camp Pendleton Amphibious Vehicle Training Area)
	Amphibious Corridors 1-4
	Hawaii Range Complex

A.1.3.2 Innovation and Demonstration Exercise

Integrated/Coordin	Integrated/Coordinated Training - Other	
Innovation and De	monstration Exercise	
Short Description	These exercises are conducted to demonstrate or test new capabilities, tactics, techniques, and procedures, and generate standardized, actionable data for evaluation.	
Long Description	Innovation and Demonstration Exercises give the Navy and Marine Corps the opportunity to test potential initiatives that address capability gaps and provide inventive solutions in an operational environment. These exercises are conducted to demonstrate or evaluate new capabilities, tactics, techniques and procedures, and generate standardized, actionable data for evaluation. Innovation and Demonstration exercises could include Carrier Strike Groups (CSGs), Expeditionary Strike Groups (ESGs), and joint or coalition forces, and involve Air Warfare, Amphibious Warfare, Anti-Submarine Warfare, Electronic Warfare, Expeditionary Warfare, Mine Warfare, Seabed Warfare, Surface Warfare, and C4I (Command, Control, Communications, Computer, and Intelligence). Unmanned systems may be used. Specific exercises included in this category include certain Fleet Battle Problem, Tactical Development Exercises, Large At-Sea Field Experiment, Project Convergence, and Unmanned Systems Integrated Battle Problem.	
Typical Components	 Platforms: Extra Large Unmanned Underwater Vehicle, Fixed Wing – Patrol Aircraft, Fixed Wing - Strike Aircraft, Rotary-Wing Aircraft, Submarine, Surface Combatant, Unmanned Aerial Vehicle - Fixed Wing, Unmanned Aerial Vehicle - Rotary Wing, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: Air Targets - Drone, Mine Targets, Sub-surface Targets - Maneuvering, Surface Targets - Maneuvering Systems being Trained/Tested: Countermeasures, Signal, Underwater sound Devices, Sonar Systems - Dipping, Sonar Systems - Hull Mounted, Sonar Systems - Towed, Sonobuoys Munitions: Projectile - Large Caliber, Projectile - Medium Caliber, Projectile - Small Caliber, Surface-to-Air Missiles, Aerial Loitering Munitions, Torpedoes - Exercise 	
Active Sonar	LFH, MF1, MF1C, MFM, MFH, HFH, Broadband (LF to HF), Broadband (MF to HF)	
In-Water Explosives	E5	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Active acoustic sources Explosive gunnery Non-explosive gunnery Towed in-water devices Unmanned vehicles Weapon firing noise	
Parameters for Analysis	None	

Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	NOCAL
	PMSR
	SOCAL (Del Mar Boat Basin)
	Amphibious Corridors 1-4
	Hawaii Range Complex
	Transit Corridor

A.1.3.3 Integrated Air Missile Defense Exercise

Integrated/Coordinated Training - Other	
Integrated Air Miss	sile Defense Exercise
Short Description	Missiles are launched from a ship against airborne targets, including Ballistic Missiles, simulating an airborne threat to ships.
Long Description	The purpose of Integrated Air Missile Defense (IAMD) Exercises is to deepen relationships and enhance interoperability between United States and allies. Missiles are launched from a ship against a dynamic test target. Platforms could include F/A-18, ships (allied navies), aerial targets (BQM, Aegis Readiness Assessment Vehicle (ARAV)), unmanned aerial systems (e.g., MQ-9) RF. Ship on-board systems track and engage the target in the open ocean. Fixed-wing aircraft could simultaneously make runs against Advanced Radar Detection Laboratory.
	Another scenario for this type of activity is the Pacific Dragon IAMD Exercise, in which the allied forces involved typically include the Japan Maritime Self Defense Force (JMSDF), Republic of Korea Navy (ROKN), Royal Australian Navy (RAN), and Royal Canadian Navy (RCN). Test target missiles are launched from the Kauai Test Facility at Pacific Missile Range Facility (PMRF) over the open ocean portion of the Hawaii Study Area.
Typical Components	Platforms: Fixed-Wing – Strike Aircraft, Surface Combatant, Unmanned Aerial Vehicles – Fixed-Wing
	Targets: Air Targets - Drone, Air Targets - Other
	Systems being Trained/Tested: None
	Munitions: Surface-to-Air Missiles
Active Sonar	Νο
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	Includes explosive bins at medium altitudes. Establishment of and impacts from land based firing points covered in separate NEPA.
	Phase IV Requirement 2025-2032
Location	Hawaii Range Complex
	Temporary Operating Area

A.1.3.4 Large Scale Amphibious Exercise

Integrated/Coordinated Training - Other	
Large Scale Amphil	pious Exercise
Short Description	The Large Scale Amphibious Exercise utilizes all elements of the Marine Air Ground Task Force (Amphibious) to secure the battlespace (air, land, and sea), maneuver to and seize the objective, and conduct self-sustaining operations ashore with logistic support of the Expeditionary Strike Group. This exercise could include activities in multiple warfare areas in support of at-sea operations such as in the littorals or during straits transits.
Long Description	The Large Scale Amphibious Exercise utilizes all elements of the Marine Air Ground Task Force (Amphibious) to secure the battlespace (air, land, and sea), maneuver to and seize the objective, and conduct self-sustaining operations ashore with logistic support of the Expeditionary Strike Group. This exercise could include activities in multiple warfare areas in support of at-sea operations such as in the littorals or during straits transits. Amphibious ships, Marine aircraft, and ground units are all integrated to complete the objective. Large Scale Amphibious Exercises could include named events such as ARG- MEU Exercise, Amphibious Squadron MEU Integrated Training (PMINT), Dawn Blitz, Steel Knight, Winter Fury, or Summer Fury. Shore activities could include establishment and use of an Expeditionary Advanced Base (EAB). At-sea activities could include integration of Marine Corps MCM capabilities with MIW, combating mines in surf zone/landing craft zone, amphibious operations (logistics across the shore), and long-range, inland air assaults. Some training scenarios include small boat raids; visit, board, search, and seizure training; helicopter and mechanized amphibious raids; and non-combatant evacuation operations. Unmanned systems and lasers could be employed. This exercise could last up to 1 week and involve the use of various weapons, weapon systems, and ordnance. These exercises typically employ widely distributed elements over an extended area for training to replicate real-world missions and assignment areas.
Typical Components	 Platforms: Amphibious Vehicles, Amphibious Warfare Vessel, Fixed Wing - Strike Aircraft, Rotary-Wing Aircraft, Small Boat, Surface Combatant, Tiltrotor Aircraft, Unmanned Surface Vehicle, Unmanned Underwater Vehicle, Unmanned Aerial Vehicle - Fixed Wing Targets: Air Targets - Drone, Mine Targets, Sub-surface Targets - Maneuvering, Surface Targets - Maneuvering Systems being Trained/Tested: None Munitions: See notes in parameters for analysis
Active Sonar	No
In-Water Explosives	See notes in parameters for analysis
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Unmanned vehicles
Parameters for Analysis	Potential acoustic and explosive use during this activity are accounted for under appropriate individual unit-level activities.

Location	Phase IV Requirement 2025-2032
	NOCAL
	PMSR
	SOCAL (Del Mar Boat Basin)
	Amphibious Corridors 1–4
	Hawaii Range Complex

A.1.3.5 Multi-Warfare Exercise

Integrated/Coordinated Training - Other		
Multi-Warfare Exercise		
Short Description	Multi-Warfare Exercises are integrated events that include training in multiple warfare areas.	
Long Description	Multi-Warfare Exercises are integrated events that include training in multiple warfare areas. Some events may involve only Navy surface ships firing missiles and guns in Air Warfare and Surface Warfare scenarios. Other events, such as the Large Scale Exercise could involve ships, aircraft, submarines, amphibious forces, and joint and coalition participants engaged in all warfare areas. These exercises could include air-to-surface missiles, air-to-air missiles, surface-to-air missiles and guns, surface-to-air lasers, surface-to-surface missiles and guns, torpedoes, shore-based gunnery and missiles such as HIMARS and Aerial Loitering Munitions, and ASW sonar.	
Typical Components	Platforms: Aircraft Carrier, Amphibious Warfare Vessel, Fixed Wing – Patrol Aircraft, Fixed Wing - Strike Aircraft, Rotary-Wing Aircraft, Submarine, Surface Combatant, Unmanned Surface Vehicles	
	Targets: Air Targets - Drone, Sub-surface Targets - Maneuvering	
	Systems being Trained/Tested: Countermeasures, Sonar Systems - Dipping, Sonar Systems - Hull Mounted, Sonar Systems - Towed, Sonobuoys	
	Munitions: Torpedoes - Exercise, See notes in parameters for analysis	
Active Sonar	LFH, MF1, MF1C, MFM, MFH, HFH, Broadband (LF to HF), Broadband (MF to HF)	
In-Water Explosives	See notes in parameters for analysis	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Towed in-water devices Unmanned vehicles	
Parameters for Analysis	All other warfare area training conducted during Multi-Warfare Exercise were analyzed as unit-level training (gunnery, missile exercise, etc.). All military expended materials, munitions, explosives and sonar use is included in individual unit-level events. Additional activities utilizing sources not listed in the Sonar and Other Transducer Bins section above may occur during this exercise. All acoustic sources which may be used during training and testing activities have been accounted for in the modeling and analysis presented in this EIS/OEIS.	
	Phase IV Requirement 2025-2032	
	NOCAL	
Location	PMSR	
	SOCAL	
	Hawaii Range Complex	

A.1.4 Air Warfare Training

The mission of air warfare is to destroy or reduce enemy air and missile threats (including unmanned airborne threats) and serves two purposes: to protect U.S. forces from attacks from the air and to gain air superiority. Air warfare provides U.S. forces with adequate attack warnings, while denying hostile forces the ability to gather intelligence about U.S. forces.

Aircraft conduct air warfare through radar search, detection, identification, and engagement of airborne threats. Surface ships conduct air warfare through an array of modern anti-aircraft weapon systems such as aircraft detecting radar, naval guns linked to radar-directed fire-control systems, surface-to-air missile systems, and radar-controlled guns for close-in point defense.

A.1.4.1 Air Combat Maneuvers

Air Warfare	
Air Combat Maneuvers	
Short Description	Fixed-wing aircrews aggressively maneuver against threat aircraft to gain tactical advantage.
Long Description	Basic flight maneuvers in which fixed-wing aircrew engage in offensive and defensive maneuvering against each other. No ordnance is expended during this training, however countermeasures such as chaff and flares may be used. These maneuvers typically involve two aircraft; however, based upon the training requirement, air combat maneuvers may involve over a dozen aircraft.
Typical Components	Platforms: Fixed Wing - Strike Aircraft
	Targets: None
	Systems being Trained/Tested: None
Antina Canan	
Active Sonar	NO
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	None
Parameters for Analysis	No munitions fired. Flare and chaff may be used. All flare and chaff accounted for in flare exercise and chaff exercise events.
	Phase IV Requirement 2025-2032
	NOCAL
Location	PMSR
	SOCAL
	Hawaii Range Complex

A.1.4.2 Air Defense Exercise

Air Warfare	
Air Defense Exercise	
Short Description	Aircrew and ship crews conduct defensive measures against threat aircraft or simulated missiles.
Long Description	Fixed-wing aircrew and ship personnel perform measures designed to defend against attacking threat aircraft or missiles or reduce the effectiveness of such attack. This exercise involves full detection through engagement sequence. Aircraft operate at varying altitudes and speeds. This exercise includes air intercept control exercises where aircraft controllers on ships, in fixed-wing aircraft, or at land based locations, use search radars to track and direct friendly aircraft to intercept the threat aircraft. This exercise also includes detect to engage exercises, where personnel on ships use search radars to detect, classify, and track enemy aircraft or missiles up to the point of engagement. No ordnance is fired during this exercise, however countermeasures, such as chaff and flares, may be used.
Typical Components	 Platforms: Aircraft Carrier, Fixed Wing – Adversary Aircraft, Fixed Wing - Command and Control Aircraft, Fixed Wing - Strike Aircraft, Surface Combatant Targets: None Systems being Trained/Tested: Chaff, Flare, Radar Munitions: None
Active Sonar	Νο
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	No munitions are fired.
	Phase IV Requirement 2025-2032
Location	SOCAL NOCAL PMSR Hawaii Range Complex

A.1.4.3 Gunnery Exercise Air-to-Air – Medium Caliber

Air Warfare	
Gunnery Exercise Air-to-Air – Medium Caliber	
Short Description	Fixed-wing aircrews fire medium-caliber guns at air targets.
Long Description	Navy, Marine Corps, and Air Force fixed-wing aircrews maneuver aircraft in a gunnery pattern to achieve a weapons firing solution with integrated medium-caliber guns. Typically involves two to eight fixed-wing aircraft and a target banner towed by a contract aircraft (e.g., Lear jet). The target banner is recovered after the exercise.
Typical Components	Platforms: Fixed Wing - Strike Aircraft Targets: Air Targets - Other Systems being Trained/Tested: None Munitions: Projectile - Medium Caliber
Active Sonar	Νο
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	None
Parameters for Analysis	This activity is conducted at an altitude of 15,000 feet and above, during the daytime, and approximately 40 nautical miles from shore. A towed air target is a banner target and will be recovered. Only non-explosive munitions used.
	Phase IV Requirement 2025-2032
	NOCAL
Location	PMSR
	SOCAL
	Hawaii Range Complex

A.1.4.4 Gunnery Exercise Air-to-Air – Small Caliber

Air Warfare		
Gunnery Exercise Air-to-Air Small Caliber		
Short Description	Rotary-wing aircrews fire small-caliber guns at air targets.	
Long Description	Helicopter aircrews maneuver aircraft to engage a small airborne threat with crew served weapons. Typically involves one helicopter and an airborne UAV or drone target.	
Typical Components	Platforms: Rotary-Wing Aircraft Targets: Air Targets - Drone Systems being Trained/Tested: None Munitions: Projectile - Small Caliber	
Active Sonar	Νο	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	None	
Parameters for Analysis	Typically involves two or more rotary-wing aircraft and aerial drones. The drone is not recovered after the exercise.	
Location	Phase IV Requirement 2025-2032	
	NOCAL	
	PMSR	
	SOCAL	
	Hawaii Range Complex	

A.1.4.5 Gunnery Exercise Surface-to-Air – Large Caliber

Air Warfare		
Gunnery Exercise Surface-to-Air Large Caliber		
Short Description	Surface ship crews fire large-caliber guns at air targets.	
Long Description	Navy and Coast Guard surface ship crews defend against threat aircraft or missiles with large-caliber guns to disable or destroy the threat. An exercise involves one ship and a simulated threat aircraft or missile that is detected by the ship's radar. Large-caliber guns fire non-explosive projectiles at the threat before it reaches the ship. The target is towed by a contract air services jet or is an expendable unmanned aerial vehicle.	
Typical Components	Platforms: Surface Combatant Targets: Air Targets - Other Systems being Trained/Tested: None Munitions: Projectile - Large Caliber	
Active Sonar	No	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Weapon firing noise	
Parameters for Analysis	The towed target is a fiberglass finned target that is towed approximately 3 nautical miles behind the towing aircraft. All projectiles are assumed to be non-explosive.	
Location	Phase IV Requirement 2025-2032	
	NOCAL	
	PMSR	
	SOCAL	
	Hawaii Range Complex	
A.1.4.6 Gunnery Exercise Surface-to-Air – Medium Caliber

Air Warfare	
Gunnery Exercise S	urface-to-Air Medium Caliber
Short Description	Surface ship crews fire medium-caliber guns at air targets.
Long Description	Navy and Coast Guard surface ship crews defend against threat aircraft or missiles with medium-caliber guns to disable or destroy the threat. An exercise involves one ship and a simulated threat aircraft or anti-ship missile that is detected by the ship's radar. Medium- caliber guns fire non-explosive projectiles to disable or destroy the threat before it reaches the ship. The target is towed by a contract air services jet or is an expendable unmanned aerial vehicle.
Typical Components	Platforms: Surface Combatant
	Targets: Air Targets - Other
	Systems being Trained/Tested: None
	Munitions: Projectile - Medium Caliber
Active Sonar	Νο
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	The target is a fiberglass finned target that is towed approximately 3 nautical miles behind the towing aircraft.
	Phase IV Requirement 2025-2032
	NOCAL
Location	PMSR
	SOCAL
	Hawaii Range Complex

A.1.4.7 High-Energy Laser Exercise Surface-to-Air

Air Warfare	
High-Energy Laser I	Exercise Surface-to-Air
Short Description	Surface ship crews disable or destroy air targets with high-energy laser systems.
Long Description	Ship crews employ high-power energy laser systems that are used to create critical failures in airborne targets. System directs a directed energy beam that can penetrate thin layers of metal at short distances that can render air targets inoperative. Laser systems can also be used in a low power setting as non-lethal deterrent during maritime security operations (force protection). The low power capability would not be used against manned platforms during training.
Typical Components	Platforms: Surface Combatant
	Targets: Air Targets - Drone
	Systems being Trained/Tested: High-Energy Laser Systems
	Munitions: None
Active Sonar	Νο
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	None
	Phase IV Requirement 20252032
Location (typical	NOCAL
specific location where applicable)	PMSR
	SOCAL
	Hawaii Range Complex

A.1.4.8 Medium Range Interceptor Capability

Air Warfare	
Medium Range Inte	erceptor Capability
Short Description	Ground personnel defend against threat missiles and aircraft with vehicle-launched ground-to-air missile systems.
Long Description	Ground personnel defend against threat missiles and aircraft with vehicle-launched ground-to-air missile systems. The event involves an aerial target simulating a threat aircraft, anti-ship missile, or land attack missile, which is detected by the air defense systems radar or other sensors. Vehicle-launched ground-to-air missiles are fired to disable or destroy the threat. Missiles are either explosive warheads or non-explosive practice munitions. The target typically is a remote controlled drone.
Typical Components	Platforms: Wheeled or tracked vehicle Targets: Air Targets - Drone Systems being Trained/Tested: None Munitions: Land-Based Surface-to-Air Missiles
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	None
Parameters for Analysis	Includes explosive bins at medium altitudes. Establishment of and impacts from land based firing points covered in separate NEPA.
	Phase IV Requirement 2025-2032
Location	SOCAL
	Hawaii Range Complex (PMRF [land area])

A.1.4.9 Missile Exercise Air-to-Air

Air Warfare	
Missile Exercise Air	-to-Air
Short Description	Fixed-wing aircrews fire air-to-air missiles at air targets.
Long Description	An exercise involves two or more fixed-wing aircraft and a target. Missiles are either explosive warheads or non-explosive practice munitions. The target is an unmanned aerial target drone, a tactical air-launched decoy, or a parachute suspended illumination flare. Target drones deploy parachutes and are recovered by small boat or rotary-wing aircraft; tactical air-launched decoys and illumination flares are expended and not recovered. These exercises typically occur at high altitudes.
Typical Components	Platforms: Fixed Wing - Strike Aircraft
	Targets: Air Targets - Decoy, Air Targets - Flare
	Systems being Trained/Tested: None
	Munitions: Air-to-Air Missiles
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	None
Parameters for Analysis	Assumes that all missiles are explosive, although non-explosive practice munitions may be used. All missiles explode at high altitude. All propellant and explosives are consumed. Assume 1.5 flares per Missile Exercise event.
	Phase IV Requirement 2025-2032
Location	PMSR
Location	SOCAL
	Hawaii Range Complex

A.1.4.10 Missile Exercise – Man-Portable Air Defense System

Air Warfare	Air Warfare	
Missile Exercise - N	Ian-Portable Air Defense System	
Short Description	Personnel employ a shoulder fired surface-to-air missile at air targets.	
Long Description	Personnel employ the Man-Portable Air Defense Systems, a shoulder fired surface to air missile, against threat missiles or aircraft. An exercise involves personnel firing the Man- Portable Air Defense System at remote piloted or other aerial targets. Activity is conducted by combat forces firing from shore or shipboard at targets over the water. Small boats are used to ensure range safety.	
Typical Components	Platforms: Amphibious Vehicles Targets: Air Targets - Drone Systems being Trained/Tested: None Munitions: Land-Based Surface-to-Air Missiles	
Active Sonar	Νο	
In-Water Explosives	Νο	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels	
Parameters for Analysis	Includes explosive bins at medium altitudes. For analysis, all missiles are assumed to be explosive, although non-explosive practice munitions may be used. All propellant and explosives are consumed. Establishment of, and impacts from land based firing points covered in separate NEPA.	
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032	
	Hawaii Range Complex (PMRF[land area])	
	SOCAL (SCI)	

A.1.4.11 Missile Exercise Surface-to-Air

Air Warfare	
Missile Exercise Su	rface-to-Air
Short Description	Surface ship crews defend against threat missiles and aircraft with missiles.
Long Description	Surface ship crews defend against threat missiles and aircraft with ship-launched surface- to-air missiles. The exercise involves an aerial target that simulates a threat aircraft, anti- ship missile, or land attack missile, which is detected by the ship's radar. Ship-launched surface-to-air missiles are fired to disable or destroy the threat. The target typically is either a sub-sonic remote-controlled drone or a supersonic target. Target drones deploy parachutes and are recovered by small boat or rotary-wing aircraft; when used, tactical air-launched decoys are not recovered. Supersonic targets are not recovered.
Typical Components	Platforms: Surface Combatant
	Targets: Air Targets - Drone
	Systems being Trained/Tested: None
	Munitions: Surface-to-Air Missiles
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	Assumes that all surface-to-air missiles are high-explosive. Missile explodes well above surface at medium and high altitudes. All explosive and propellant are consumed.
	Phase IV Requirement 2025-2032
Location (typical	PMSR
where applicable)	SOCAL
	Hawaii Range Complex

A.1.5 Amphibious Warfare Training

The mission of amphibious warfare is to project military power from the sea to the shore (i.e., attack a threat on land by a military force embarked on ships) through the use of naval firepower and expeditionary landing forces. Amphibious warfare operations include small unit reconnaissance or raid missions to large-scale amphibious exercises involving multiple ships and aircraft combined into a strike group.

Amphibious warfare training ranges from individual, crew, and small unit events to large task force exercises. Individual and crew training include amphibious vehicles and naval gunfire support training. Such training includes shore assaults, boat raids, airfield or port seizures, and reconnaissance. Large scale amphibious exercises involve ship-to-shore maneuver, naval fire support, such as shore bombardment, and air strike and attacks on targets that are in close proximity to friendly forces.

A.1.5.1 Amphibious Assault

Amphibious Warfare	
Amphibious Assaul	t
Short Description	Large unit forces move ashore from amphibious ships at sea for the immediate execution of inland objectives.
Long Description	Large unit forces move ashore from amphibious ships at sea for the immediate execution of inland objectives. Amphibious assault is conducted for the purposes of prosecuting further combat operations, obtaining a site for an Expeditionary Advanced Base, or denying the enemy use of an area.
	Unit-level training exercises involve one or more amphibious ships, and their associated watercraft and aircraft, to move personnel and equipment from ship to shore without the command and control and supporting elements involved in a full scale exercise. The goal is to practice loading, unloading, and movement and to develop the timing required for a full-scale exercise.
Typical Components	Platforms: Amphibious Warfare Vessel, Fixed Wing - Strike Aircraft, Fleet Support Vessel, Rotary-Wing Aircraft, Tiltrotor Aircraft
	Targets: None
	Systems being Trained/Tested: None
	Munitions: None
Active Sonar	No
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	Typical event: 1–3 amphibious ships (e.g., LHA or LHD, LPD, LSD); 2-8 landing craft (landing craft, air cushioned; landing craft, utility); 4–14 amphibious assault vehicles; up to 22 aircraft (e.g., HMH-53, H-46/MV-22, AH-1, UH-1, AV-8); a Marine Expeditionary Unit (2,200 Marines).
	Phase IV Requirement 2025-2032
	NOCAL
	PMSR
Location (typical location where applicable)	SOCAL (Camp Pendleton Amphibious Assault Area [CPAAA], Del Mar Boat Basin, Camp Pendleton Amphibious Vehicle Training Area, San Clemente Island, Pyramid Cove, Horse Beach Cove, West Cove, Wilson Cove)
	Amphibious Corridors 1-4
	Hawaii Range Complex (Marine Corps Training Area Bellows, Kaneohe Bay, Marine Corps Base Hawaii, PMRF [land area])

A.1.5.2 Amphibious Operations in a Contested Environment

Amphibious Warfare	
Amphibious Opera	tions in a Contested Environment
Short Description	Navy and Marine Corps forces conduct operations in coastal and offshore waterways against air, surface, and subsurface threats.
Long Description	USMC forces establish Expeditionary Advanced Bases on land and protect against air, surface, and subsurface attacks. Systems employed include but are not limited to Marine Air Defense Integrated System (MADIS), Navy Marine Expeditionary Ship Interdiction System (NMESIS), Long Range Unmanned Surface Vehicle (LRUSV) employing unmanned aerial systems, high-energy laser systems, 155 mm Howitzer artillery, and High Mobility Artillery Rocket Systems.
Typical Components	Platforms: Amphibious Warfare Vessel, Fixed Range, Rotary-Wing Aircraft, Tiltrotor Aircraft
	Targets: Air Targets - Drone, Surface Targets - Maneuvering
	Systems being Trained/Tested: None
	Munitions: Projectile - Medium Caliber, Land-Based Surface-to-Air Missiles, Land-Based Surface-to-Surface Missiles
Active Sonar	No
In-Water Explosives	See notes in parameters for analysis.
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Explosive missiles and rockets
Parameters for Analysis	In-water explosives used during this activity are addressed in other Unit-Level activities such as Shore-to-Surface Artillery Exercise and Shore-to-Surface Missile Exercise. Includes explosive bins at medium and high altitudes. Impacts on land from firing points is covered in separate NEPA.
	Phase IV Requirement 2025-2032
Location (typical	SOCAL (CPAAA, San Clemente Island, SHOBA, Camp Pendleton Amphibious Vehicle Training Area, Del Mar Boat Basin)
specific location	PMSR
where applicable)	Amphibious Corridor 1-4
	Hawaii Range Complex (Marine Corps Training Area Bellows, Kaneohe Bay, Marine Corps Base Hawaii, PMRF [land area])

A.1.5.3 Amphibious Raid

Amphibious Warfare	
Amphibious Raid	
Short Description	Small unit forces move from amphibious ships at sea for a specific short-term
	mission. These are quick operations with as few personnel as possible.
Long Description	Small unit forces swiftly move from amphibious vessels at sea into hostile territory for a specific mission, including a planned withdrawal. Raids are conducted to inflict loss or damage, secure information, create a diversion, confuse the enemy, or capture or evacuate individuals or material. Amphibious raid forces are kept as small as possible to maximize stealth and speed of the operation. An event may employ assault amphibian vehicle units, small boats, small unit live- fire and non-live-fire operations. Surveillance or reconnaissance unmanned surface and aerial vehicles may be used during this event.
Typical Components	Platforms: Amphibious Warfare Vessel, Small Boat, Unmanned Aerial Vehicle – Rotary Wing, Unmanned Surface Vehicles Targets: Land Targets
	Systems being Trained/Tested: None
	Munitions: None
Active Sonar	No
In-Water Explosives	No
Mitigation Involving	Mitigation is required for the following stressors as described in Section 5.6
Visual Observations for	(Activity-based Mitigation):
Marine Species	Unmanned vehicles
Parameters for Analysis	Weapons firing during this event is discussed in appropriate activity descriptions (e.g., surface-to-surface and air-to-surface small-caliber gunnery exercises).
	Phase IV Requirement 2025-2032
	SSTC
Location (typical specific	PMSR
location where applicable)	SOCAL (CPAAA, SHOBA, West Cove)
	Amphibious Corridors 1-4
	Hawaii Range Complex (Marine Corps Training Area Bellows, Kaneohe Bay, Marine Corps Base Hawaii, PMRF [land area])

A.1.5.4 Amphibious Vehicle Maneuvers

Amphibious Warfa	Amphibious Warfare	
Amphibious Vehicle	Amphibious Vehicle Maneuvers	
Short Description	Crews practice the employment of amphibious craft, amphibious vehicles, and small boats.	
Long Description	Navy and Marine Corps personnel train to learn handling characteristics of a variety of amphibious craft, to include the Landing Craft Air Cushion (LCAC), the Landing Craft Utility (LCU), the Amphibious Combat Vehicle (ACV), the Amphibious Assault Recovery Vehicle (AAV-R), and the Lighter Amphibious Resupply Cargo (LARC) vehicle. Small boats include the use of the Landing Craft Personnel Light (LCPL), the Improved Navy Lighterage System (INLS), the Rigid Hull Inflatable Boats (RHIBs), and the Combat Rubber Raiding Craft (CRRCs). Training includes the use of amphibious craft to and from the shore as well as driving amphibious vehicles into and out of the water from ship or shore and launching and recovering small boats into the water for operations between ship and shore.	
Typical Components	Platforms: Amphibious Vehicles, Amphibious Vessels, Small Boats Targets: None Systems being Trained/Tested: None Munitions: None	
Active Sonar	No	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels	
Parameters for Analysis	None	
	Phase IV Requirement 2025-2032	
	PMSR	
Location (typical specific location where applicable)	SOCAL (CPAAA, Del Mar Boat Basin, San Clemente Island, SHOBA)	
	Amphibious Corridors 1-4	
	Hawaii Range Complex (Marine Corps Training Area Bellows, Marine Corps Base Hawaii, Kaneohe Bay, PMRF [land area])	

A.1.5.5 Expeditionary Fires Exercise/Supporting Arms Coordination Exercise

Amphibious Warfare	
Expeditionary Fires	Exercise/Supporting Arms Coordination Exercise
Short Description	Military units provide integrated and effective close air support, Naval Surface Fire Support fire, and Marine Corps artillery fire in support of amphibious operations.
Long Description	Military units provide integrated and effective close air support, Naval Surface Fire Support, and Marine Corps artillery fire in support of amphibious operations. The mission of the exercises is to achieve effective integration of Naval gunfire, close air support, and Marine Corps artillery fire support.
Typical Components	Platforms: Amphibious Warfare Vessels, Fixed Wing - Strike Aircraft, Rotary-Wing Aircraft, Surface Combatant
	Systems being Trained/Tested: None
	Munitions: None
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	Impacts from land based firing points and targets are not analyzed in this EIS/OEIS. Only the at-sea components of this activity (naval gunfire from surface ships) are analyzed in this document.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL (SHOBA)

A.1.5.6 Naval Surface Fire Support Exercise – At Sea

Amphibious Warfare	
Naval Surface Fire	Support Exercise – At Sea
Short Description	Surface ship crews fire large caliber guns at a passive acoustic hydrophone scoring system.
Long Description	Surface ship crews use large caliber guns to support forces ashore; however, the land target is simulated at sea. Rounds are scored by passive acoustic buoys located at or near the target area. The portable scoring system is composed of buoys set in a predesigned pattern at specific intervals, which are retrieved after the exercise. A scoring system provides a realistic presentation, such as a land mass with topography, to the vessels combat system. This virtual land target area overlays the hydrophone array. The vessel fires its munitions into the target area and the acoustic noise resulting from the impact of the round landing in the water is detected by the hydrophones. The scoring system triangulates the exact point of impact of the round, allowing the exercise to be conducted as if the vessel were firing at an actual land target. Surface ship crews use large caliber main battery guns to support forces ashore.
Typical Components	Platforms: Surface Combatant Targets: None Systems being Trained/Tested: None Munitions: Projectile - Large Caliber
Active Sonar	No
In-Water Explosives	E5
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Explosive gunnery Weapons firing noise Non-explosive gunnery
Parameters for Analysis	Events occur greater than 12 nautical miles from shore. Non-explosive practice munitions may be used when acoustic sensors can detect projectile splash. High explosives may be used during all other events. Assume all explosive projectiles detonate on impact with water surface.
Location (turnical	Phase IV Requirement 2025-2032
specific location where applicable)	Hawaii Range Complex (BARSTUR, BSURE)

A.1.5.7 Naval Surface Fire Support Exercise – Land-Based Target

Amphibious Warfare	
Naval Surface Fire	Support Exercise – Land-Based Target
Short Description	Surface ship crews fire large-caliber guns at land-based targets in support of forces ashore.
Long Description	Surface ship crews use large-caliber guns to support forces ashore.
	One or more ships position themselves from three to six NM from the target area and a land-based spotter relays type and exact location of the target. After observing the fall of the shot, the spotter relays any adjustments needed to reach the target. Once the projectiles are on target, the spotter requests a sufficient number to effectively destroy the target.
	This exercise occurs on land ranges where explosive and non-explosive practice munitions are authorized and is often supported by target shapes such as tanks, trucks, trains, or aircraft on the ground.
Typical Components	Platforms: Surface Combatant
	Targets: Land Targets
	Systems being Trained/Tested: None
	Munitions: Projectile - Large Caliber
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Weapons firing noise
Parameters for Analysis	Impacts on land-based targets is covered in separate NEPA.
Location (typical	Phase IV Requirement 2025-2032
specific location where applicable)	SOCAL (SHOBA)

A.1.5.8 Non-Combat Amphibious Operation

Amphibious Warfare	
Non-Combat Amp	nibious Operations
Short Description	Amphibious vehicles move personnel and equipment from ships to shore and back.
Long Description	Navy and Marine Corps forces train to move personnel and equipment from ship-to-shore and from shore-to-ship to facilitate non-combat military operations. These training events include Non-Combatant Evacuation Operation, Humanitarian Assistance Operations, and Disaster Relief Operations. Noncombatants are evacuated when their lives are endangered by war, civil unrest, or natural disaster. Helicopters, landing crafts, amphibious ships, and other forces could be expected to participate in this operation during day or night.
Typical Components	Platforms: Amphibious Warfare Vessel, Rotary-Wing Aircraft, Tiltrotor Aircraft
	Targets: None
	Systems being Trained/Tested: None
	Munitions: None
Active Sonar	Νο
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
	SOCAL (CPAAA, San Clemente Island, SHOBA)
Location (typical specific location where applicable)	PMSR
	Amphibious Corridors 1-4
	Hawaii Range Complex (Marine Corps Training Area Bellows, Marine Corps Base Hawaii, PMRF [land area])

A.1.5.9 Shore-to-Surface Artillery Exercise

Expeditionary Warfare	
Shore-to-Surface A	rtillery Exercise
Short Description	Army and Marine Corps crews engaging surface targets at sea with their main battery cannons (typically 105mm and 155mm) and mortars (typically 120mm).
Long Description	This exercise involves Army or Marine Corps artillery gun crews engaging surface targets at sea with their main battery cannons (typically 105mm and 155mm) and mortars (typically 120mm). Targets are typically stationary such as killer tomatoes. Some targets are expended during the exercise and are not recovered. This exercise may involve a single-firing artillery battery, or be undertaken in the context of a coordinated larger exercise involving multiple batteries. During all exercises, either high-explosive or non- explosive projectiles may be used. High-explosive projectiles can either be fused for detonation on impact (with water surface or targets), or for proximity to the target (in air detonation).
Typical Components	Platforms: Amphibious Vehicles Targets: Surface Targets - Floating Systems being Trained/Tested: None Munitions: Projectile - Large Caliber
Active Sonar	No
In-Water Explosives	E6
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Explosive gunnery
Parameters for Analysis	In water impacts are similar to those analyzed under Gunnery Exercise Surface-to-Surface Ship Large-Caliber. Shore based firing point impacts are addressed in other NEPA documentation. All projectiles will impact beyond 3 NM from shore.
Location (tunical	Phase IV Requirement 2025-2032
specific location where applicable)	SOCAL (SCI)
	Hawaii Range Complex (PMRF Training Area)

A.1.5.10 Shore-to-Surface Missile Exercise

Expeditionary Warfare	
Missile Exercise Sh	ore-to-Surface
Short Description	Army and Marine Corps units launch missiles from shore at surface maritime targets.
Long Description	Army and Marine Corps units launch missiles from shore at surface maritime targets with the goal of destroying or disabling enemy ships or boats. Weapon systems include the HIMARS and NMESIS.
Typical Components	Platforms: Vehicle Launch Platform Targets: Surface Targets - Maneuvering Systems being Trained/Tested: None Munitions: Air-to-Surface Missiles, Rockets
Active Sonar	No
In-Water Explosives	E9
Mitigation Involving Visual Observations for Marine Species	None
Parameters for Analysis	In-water impacts are similar to those analyzed under Missile Exercise Surface-to-Surface. Shore based firing point impacts are addressed in other NEPA documentation.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	PMSR
	SOCAL
	Hawaii Range Complex (PMRF Training Area)

A.1.6 Anti-Submarine Warfare Training

Anti-submarine warfare involves helicopter and maritime patrol aircraft, ships, and submarines. These units operate alone or in combination to locate, track, and neutralize submarines. Controlling the undersea battlespace is a unique naval capability and a vital aspect of sea control. Undersea battlespace dominance requires proficiency in anti-submarine warfare. Every deploying strike group and individual surface combatant must possess this capability.

Various types of active and passive sonar are used by the Navy to determine water depth, and identify, track, and target submarines. Passive sonar "listens" for sound waves by using underwater microphones, called hydrophones, which receive, amplify, and process underwater sounds. No sound is introduced into the water when using passive sonar. Passive sonar can indicate the presence, character, and movement of submarines. However, passive sonar provides only a bearing (direction) to a sound-emitting source; it does not provide an accurate range (distance) to the source. Active sonar is needed to locate objects because active sonar provides both bearing and range to the detected contact (such as an enemy submarine).

The Navy's anti-submarine warfare training plan, including the use of active sonar in at-sea training scenarios, includes multiple levels of training. Individual-level anti-submarine warfare training addresses basic skills such as detection and classification of contacts, distinguishing discrete acoustic signatures including those of ships, submarines, and marine life, and identifying the characteristics, functions, and effects of controlled jamming and evasion devices.

More advanced, integrated anti-submarine warfare training exercises involving active sonar are conducted in coordinated, at-sea operations during training events involving submarines, ships, aircraft, and helicopters. This training integrates the full anti-submarine warfare continuum from detecting and tracking a submarine to attacking a target using either exercise torpedoes or simulated weapons. Training events include detection and tracking exercises against "enemy" submarine contacts; torpedo employment exercises against the target; and exercising command and control tasks in a multi-dimensional battlespace.

A.1.6.1 Torpedo Exercise – Helicopter

Anti-Submarine Wa	Anti-Submarine Warfare	
Anti-Submarine Wa	Anti-Submarine Warfare Torpedo Exercise – Helicopter	
Short Description	Helicopter crews search for, track, and detect submarines. Recoverable air launched torpedoes are employed against submarine targets.	
Long Description	Helicopters using sonobuoys and dipping sonar search for, detect, classify, localize, and track a simulated threat submarine with the goal of determining a firing solution that could be used to launch a torpedo and destroy the submarine. Sonobuoys (both passive and active) are typically employed by a helicopter operating at low altitude. Dipping sonar (both passive and active) is employed after the search area has been narrowed based on the sonobuoy search. The anti-submarine warfare target used for this exercise may be expendable or non-expendable mobile targets, or a live submarine. This exercise may involve a single aircraft or occur during a coordinated larger exercise involving multiple aircraft and ships, including a major range event. Unmanned aerial systems, such as the MQ-8 Fire Scout, may also be used. The exercise torpedo is recovered by a special recovery helicopter or small craft. The preferred range for this exercise is an instrumented underwater range, but it may be conducted in other parts of the Study Area depending on training requirements and available assets.	
Typical Components	 Platforms: Rotary-Wing Aircraft, Unmanned Surface Vehicle, Unmanned Aerial Vehicle – Rotary-Wing, Unmanned Underwater Vehicle Targets: Sub-surface Targets - Maneuvering Systems being Trained/Tested: Sonar Systems - Dipping, Sonobuoys Munitions: Torpedoes - Exercise 	
Active Sonar	MFM, MFH, HFH	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels	
Parameters for Analysis	None	
	Phase IV Requirement 2025-2032	
Location (typical	SOCAL (SOAR, Tanner Bank SWTR, San Clemente Island SWTR)	
specific location where applicable)	PMSR	
	Hawaii Range Complex (BARSTUR, BSURE)	

A.1.6.2 Torpedo Exercise – Maritime Patrol Aircraft

Anti-Submarine Warfare	
Anti-Submarine W	arfare Torpedo Exercise – Maritime Patrol Aircraft
Short Description	Maritime patrol aircraft crews search for, track, and detect submarines. Recoverable air launched torpedoes are employed against submarine targets.
Long Description	Fixed-wing maritime patrol aircraft employ sonobuoys to search for, detect, classify, localize, and track a simulated threat submarine with the goal of determining a firing solution that could be used to launch a torpedo and destroy the submarine.
	Both sonobuoys and torpedoes (using the High Altitude Anti-Submarine Warfare Weapon Capability kit) may be delivered at high altitudes to remain clear of high threat areas. Sonobuoys are deployed in specific patterns based on the expected threat submarine and specific water conditions. Depending on these two factors, these patterns will cover many different size areas. For certain sonobuoys, tactical parameters of use may be classified. The anti-submarine warfare target used for this exercise may be expendable or non- expendable mobile targets, or a live submarine. This exercise may involve a single aircraft, or be undertaken in the context of a coordinated larger exercise involving multiple aircraft and vessels, including a major range event. The exercise torpedo is recovered by helicopter or small boat. The preferred range for this exercise is an instrumented underwater range, but it may be conducted in other parts of the Study Area depending on training requirements and available assets.
Typical Components	Platforms: Fixed Wing – Patrol Aircraft, Unmanned Surface Vehicle, Unmanned
	Targets: Sub-surface Targets - Maneuvering
	Systems being Trained/Tested: Sonobuoys
	Munitions: Torpedoes - Exercise
Active Sonar	MFM, HFH
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation):
	Active acoustic sources Manned surface vessels
Parameters for Analysis	Submarine may provide service as the target. If target is air-dropped, one parachute per target. Torpedoes are recovered.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL (SOAR, Tanner Bank SWTR, San Clemente Island SWTR)
	PMSR
	Hawaii Range Complex (BARSTUR, BSURE)

A.1.6.3 Torpedo Exercise – Ship

Anti-Submarine Wa	Anti-Submarine Warfare	
Anti-Submarine Wa	arfare Torpedo Exercise – Ship	
Short Description	Surface ship crews search for, track, and detect submarines. Exercise torpedoes are used during this exercise.	
Long Description	Surface ships search for, detect, and track threat submarines to determine a firing position to launch a torpedo and attack the submarine. A surface ship operates at slow speeds while employing hull-mounted or towed array sonar. Passive or active sonar is employed depending on the type of threat submarine, the tactical situation, and environmental conditions. The anti-submarine warfare target used for this exercise is a MK-39 Expendable Mobile Anti-Submarine Warfare Training Target, MK-30 Target, or live submarine. This exercise may involve a single ship, or be undertaken in the context of a coordinated larger exercise involving multiple aircraft, ships, and submarines, including a major range event.	
Typical Components	 Platforms: Surface Combatant, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: Sub-surface Targets - Maneuvering Systems being Trained/Tested: Countermeasures, Sonar Systems - Hull Mounted Munitions: Torpedoes - Exercise 	
Active Sonar	MF1, MF1C, HFH, Broadband (MF to HF)	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Towed in-water devices	
Parameters for Analysis	Submarines may provide service as the target. Torpedoes are recovered.	
	Phase IV Requirement 2025-2032	
Location (typical specific location where applicable)	SOCAL (SOAR, Tanner Banks SWTR, San Clemente Island SWTR)	
	PMSR	
	Hawaii Range Complex (BARSTUR, BSURE)	

A.1.6.4 Torpedo Exercise – Submarine

Anti-Submarine Wa	Anti-Submarine Warfare	
Anti-Submarine Wa	Anti-Submarine Warfare Torpedo Exercise – Submarine	
Short Description	Submarine crews search for, track, and detect submarines. Exercise torpedoes are used during this exercise.	
Long Description	Submarine crews search for, detect and track a threat submarine to develop firing position to launch a torpedo. A single submerged submarine operates at slow speeds and various depths while using its hull mounted or towed array sonar to track a threat submarine. Passive sonar is used almost exclusively. Non-explosive exercise torpedoes can be fired, and active sonar can be used during this training exercise.	
	This exercise may involve a single submarine, or be undertaken in the context of a coordinated larger exercise involving multiple aircraft, ships, and submarines, including a major range event. The exercise torpedo is recovered by helicopter or small craft. The preferred range for this exercise is an instrumented underwater range, but it may be conducted in other range complexes depending on training requirements and available assets.	
Typical Components	Platforms: Submarine, Unmanned Surface Vehicle, Unmanned Underwater Vehicle	
	Targets: Sub-surface Targets - Maneuvering	
	Systems being Trained/Tested: Countermeasures, Sonar Systems - Hull Mounted	
	Munitions: Torpedoes - Exercise	
Active Sonar	MFH, HFH, Broadband (LF to HF)	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Towed in-water devices	
Parameters for Analysis	Specific modeling areas for this activity include: BARSTUR, SOAR. Torpedoes are recovered. Guidance wire has a low breaking strength and breaks easily. Weights and flex tubing sink rapidly.	
	Phase IV Requirement 2025-2032	
Location (typical specific location where applicable)	SOCAL (SOAR, Tanner Banks SWTR, San Clemente Island SWTR)	
	PMSR	
	Hawaii Range Complex (BARSTUR, BSURE)	

A.1.6.5 Tracking Exercise – Helicopter

Anti-Submarine Warfare	
Anti-Submarine Wa	arfare Tracking Exercise – Helicopter
Short Description	Helicopter crews search for, track, and detect submarines.
Long Description	Helicopters using sonobuoys and dipping sonar search for, detect, classify, localize, and track a simulated threat submarine with the goal of determining a firing solution that could be used to launch a torpedo and destroy the submarine.
	The anti-submarine warfare target used for this exercise may be a MK-39 Expendable Mobile Anti-submarine Warfare Training Target, a MK-30 target, or a live submarine. This exercise may involve a single aircraft, or occur during a coordinated larger exercise involving multiple aircraft and ships, including a major range event. Unmanned aerial systems, such as the MQ-8 Fire Scout, may also be used. The preferred range for this exercise is an instrumented range, but it may be conducted in other range complexes depending on training requirements and available assets.
Typical Components	Platforms: Rotary-Wing Aircraft, Unmanned Aerial Vehicle – Rotary-Wing, Unmanned Surface Vehicle, Unmanned Underwater Vehicle
	Targets: Sub-surface Targets - Maneuvering
	Systems being Trained/Tested: Sonar Systems - Dipping, Sonobuoys
	Munitions: None
Active Sonar	MFM, MFH
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels
Parameters for Analysis	Submarines may provide service as the target.
	Phase IV Requirement 2025-2032
Location (typical	NOCAL
specific location	PMSR
where applicable)	SOCAL (SOAR, Tanner Banks SWTR, San Clemente Island SWTR)
	Hawaii Range Complex (BARSTUR, BSURE)

A.1.6.6 Tracking Exercise –Unmanned Surface Vessel

Anti-Submarine Warfare	
Anti-Submarine Wa	arfare Tracking Exercise – Unmanned Surface Vessel
Short Description	USVs search for, detect, and track a sub-surface target simulating a threat submarine with the goal of determining a firing solution that could be used to launch a torpedo.
Long Description	USVs search for, detect, and track a sub-surface target simulating a threat submarine with the goal of determining a firing solution that could be used to launch a torpedo.
	A USV operates at slow speeds while employing sonobuoys, hull-mounted sonar, or towed array sonar. Passive or active sonar is employed depending on the type of threat submarine, the tactical situation, and environmental conditions. The target for this scenario is either a MK39 EMATT, MK30 recoverable target, or live sub.
	This exercise may involve a single USV or be undertaken in the context of a coordinated larger exercise involving multiple aircraft, ships, and submarines, including a major range event.
Typical Components	Platforms: Fleet Support, Unmanned Surface Vehicle, Unmanned Underwater Vehicle
	Targets: Sub-surface Targets - Maneuvering
	Systems being Trained/Tested: Sonobuoys
	Munitions: Projectile – Medium Caliber
Active Sonar	MFM
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
Location (typical	NOCAL
specific location	PMSR
where applicable)	SOCAL (SOAR, Tanner Bank SWTR, San Clemente Island SWTR)
	Hawaii Range Complex (BARSTUR, BSURE)

A.1.6.7 Tracking Exercise – Maritime Patrol Aircraft

Anti-Submarine Wa	arfare
Anti-Submarine Wa	arfare Tracking Exercise – Maritime Patrol Aircraft
Short Description	Maritime patrol aircraft crews search for, track, and detect submarines.
Long Description	Fixed-wing maritime patrol aircraft employ sonobuoys to search for, detect, classify, localize, and track a simulated threat submarine with the goal of determining a firing solution that could be used to launch a torpedo and destroy the submarine.
	Sonobuoys may be released at higher altitudes. Sonobuoys are deployed in specific patterns based on the expected threat submarine and specific water conditions. The anti-submarine warfare target used for this exercise may be a MK-39 Expendable Mobile Anti-Submarine Warfare Training Target, a MK-30 target, or a live submarine. This exercise may involve a single aircraft, or be undertaken in the context of a coordinated larger exercise involving multiple aircraft and vessels, including a major range event.
Typical Components	Platforms: Fixed Wing – Patrol Aircraft, Unmanned Surface Vehicle, Unmanned Underwater Vehicle
	Targets: Sub-surface Targets - Maneuvering
	Systems being Trained/Tested: Sonobuoys
	Munitions: None
Active Sonar	LFM, LFH, MFM
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels
Parameters for Analysis	Submarine may provide service as the target. If target is air-dropped, one parachute per target.
	Phase IV Requirement 2025-2032
Location (typical	NOCAL
specific location	PMSR
where applicable)	SOCAL (SOAR, Tanner Bank SWTR, San Clemente Island SWTR)
	Hawaii Range Complex (BARSTUR, BSURE)

A.1.6.8 Tracking Exercise – Ship

Anti-Submarine Wa	Anti-Submarine Warfare	
Anti-Submarine Wa	Anti-Submarine Warfare Tracking Exercise – Ship	
Short Description	Surface ship crews search for, track, and detect submarines.	
Long Description	Surface ships search for, detect, and track threat submarines to determine a firing position to launch a torpedo and attack the submarine. A surface ship operates at slow speeds while employing sonobuoys, hull-mounted sonars, or towed array sonar. Passive or active sonar is employed depending on the type of threat submarine, the tactical situation, and environmental conditions. The target for this exercise is either a MK-39 Expendable Mobile Anti-Submarine Warfare Training Target, MK-30 Recoverable Training Target, or live submarine. This exercise may involve a single ship, or be undertaken in the context of a coordinated larger exercise involving multiple aircraft, ships, and submarines, including a major range event.	
Typical Components	Platforms: Surface Combatant, Unmanned Surface Vehicle, Unmanned Underwater Vehicle	
	Targets: Sub-surface Targets - Maneuvering	
	Systems being Trained/Tested: Countermeasures, Sonar Systems - Hull Mounted, Sonar Systems - Towed	
	Munitions: None	
Active Sonar	MF1, MF1C, MFH, Broadband (MF to HF)	
In-Water Explosives	Νο	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels	
	Towed in-water devices	
Parameters for Analysis	A Submarine may provide service as the target.	
	Phase IV Requirement 2025-2032	
Location (typical	NOCAL	
specific location where applicable)	PMSR	
	SOCAL (SOAR, Tanner Bank SWTR, San Clemente Island SWTR)	
	Hawaii Range Complex (BARSTUR, BSURE)	

A.1.6.9 Tracking Exercise – Submarine

Anti-Submarine Warfare	
Anti-Submarine Wa	arfare Tracking Exercise – Submarine
Short Description	Submarine crews search for, track, and detect submarines.
Long Description	Submarine crews search for, detect, and track a threat submarine to develop firing position to launch a torpedo.
	A single submerged submarine operates at slow speeds and various depths while using its hull mounted sonar to track a threat submarine. Passive sonar is used almost exclusively. The target for this exercise is either an MK 39 expendable mobile anti-submarine warfare training target, MK 30 recoverable training target, or live submarine.
	This exercise may involve a single submarine, or be undertaken in the context of a coordinated larger exercise involving multiple aircraft, ships, and submarines, including a major range event.
Typical Components	Platforms: Submarine, Unmanned Surface Vehicle, Unmanned Underwater Vehicle
	Targets: Sub-surface Targets - Maneuvering
	Systems being Trained/Tested: Sonar Systems - Hull Mounted
	Munitions: None
Active Sonar	MFH, HFH
In-Water Explosives	Νο
Mitigation Involving Visual Observations	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation):
for Marine Species	Active acoustic sources Manned surface vessels
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
Location (typical specific location where applicable)	NOCAL
	PMSR
	SOCAL (SOAR, Tanner Bank SWTR, San Clemente Island SWTR)
	Hawaii Range Complex (BARSTUR, BSURE)
	Transit Corridor

A.1.6.10 Training and End-to-End Mission Capability Verification – Torpedo

Anti-Submarine Warfare	
Training and End-to-End Mission Capability Verification – Torpedo	
Short Description	Air, surface, or submarine crews employ explosive torpedoes against virtual targets.
Long Description	Non-explosive and explosive torpedoes (carrying a warhead) would be launched at a suspended target by a submarine and fixed- or rotary-wing aircraft or surface combatants. Torpedoes would detonate on an artificial target below the water's surface. Event duration is 1-2 days during daylight hours. Only one heavyweight torpedo test could occur in 1 day; two heavyweight torpedo tests could occur on consecutive days. Two lightweight torpedo tests could occur in a single day.
Typical Components	Platforms: Submarine, Unmanned Surface Vehicle, Unmanned Underwater Vehicle
	Targets: Sub-surface Targets - Stationary
	Systems being Trained/Tested: Signal, Underwater sound Devices, Sonar Systems - Hull Mounted
	Munitions: Torpedoes - Exercise, Torpedoes - HE
Active Sonar	MFH, HFM, HFH
In-Water Explosives	E11
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Explosive torpedoes
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL (SOAR, Tanner Bank SWTR, San Clemente Island SWTR)
	Hawaii Range Complex (BARSTUR, BSURE)

A.1.7 Electronic Warfare

The mission of electronic warfare is to degrade the enemy's ability to use electronic systems, such as communication systems and radar, and to confuse or deny them the ability to defend their forces and assets. Electronic warfare is also used to detect enemy threats and counter their attempts to degrade the electronic capabilities of the Navy.

Typical electronic warfare activities include threat avoidance training, signals analysis for intelligence purposes, and use of airborne and surface electronic jamming devices (that block or interfere with other devices) to defeat tracking, navigation, and communications systems.

A.1.7.1 Counter Targeting Chaff Exercise – Aircraft

Electronic Warfare	Electronic Warfare	
Counter Targeting	Chaff Exercise – Aircraft	
Short Description	Fixed-winged aircraft and helicopter aircrews deploy chaff to disrupt threat targeting and missile guidance radars.	
Long Description	Fixed-winged aircraft and helicopter aircrews deploy chaff to disrupt threat targeting and missile guidance radars.	
	Fixed-winged aircraft and helicopter aircrews detect electronic targeting signals from threat radars or missiles, dispense chaff, and immediately maneuver to defeat the threat. The chaff cloud deceives the inbound missile, and the aircraft clears away from the threat.	
	Chaff is a radar reflector material made of thin, narrow, metallic strips cut in various lengths to elicit frequency responses, which deceive enemy radars. Chaff is employed to create a target that will lure enemy radar and weapons system away from the actual friendly platform.	
Typical Components	Platforms: Fixed Wing - Strike Aircraft, Rotary-Wing Aircraft	
	Targets: None	
	Systems being Trained/Tested: None	
	Munitions: None	
Active Sonar	Νο	
In-Water Explosives	Νο	
Mitigation Involving Visual Observations for Marine Species	None	
Parameters for Analysis	Chaff is usually expended while conducting other training activities, such as air combat maneuvering.	

Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	NOCAL
	PMSR
	SOCAL
	Hawaii Range Complex

A.1.7.2 Counter Targeting Chaff Exercise – Ship

Electronic Warfare	
Counter Targeting	Chaff Exercise – Ship
Short Description	Surface ship crews deploy chaff to disrupt threat targeting and missile guidance radars.
Long Description	Navy surface ship and Coast Guard cutter crews deploy chaff to disrupt threat targeting and missile guidance radars to defend against an attack.
	Surface ship crews detect electronic targeting signals from threat radars or missiles, dispense chaff, and immediately maneuver to defeat the threat. The chaff cloud deceives the inbound missile, and the vessel clears away from the threat. The typical exercise duration is approximately 1.5 hours.
	Chaff is a radar reflector material made of thin, narrow, metallic strips cut in various lengths to elicit frequency responses, which deceive enemy radars. Chaff is employed create a target that will lure enemy radar and weapons system away from the actual friendly platform.
	Ships may also train with advanced countermeasure systems, such as the MK 53 Decoy Launching System (Nulka).
Typical Components	Platforms: Surface Combatant
	Targets: None
	Systems being Trained/Tested: Chaff Launchers
	Munitions: MK 53 Nulka
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	Stressors to human resources were not analyzed for this activity since it occurs greater than 12 nautical miles from shore.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	NOCAL
	PMSR
	SOCAL
	Hawaii Range Complex

A.1.7.3 Counter Targeting Flare Exercise

Electronic Warfare	
Counter Targeting	Flare Exercise
Short Description	Fixed-winged aircraft and helicopter aircrews deploy flares to disrupt threat infrared missile guidance systems.
Long Description	Navy, Marine Corps, and Coast Guard fixed-winged aircraft and helicopter aircrews deploy flares to disrupt threat infrared missile guidance systems.
	Aircraft detect electronic targeting signals from threat radars or missiles or a threat missile plume when launched and dispense flares and immediately maneuver to defeat the threat. This exercise trains aircraft personnel in the use of defensive flares designed to confuse infrared sensors or infrared homing missiles, thereby causing the sensor or missile to lock onto the flares instead of the real aircraft. Typically, an aircraft will expend five flares in an exercise while operating above 3,000 ft. Flare exercises are often conducted with chaff exercises, rather than as a stand-alone exercise.
Typical Components	Platforms: Fixed Wing – Patrol Aircraft, Fixed Wing - Strike Aircraft, Rotary-Wing Aircraft
	Targets: None
	Systems being Trained/Tested: None
	Munitions: None
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	None
Parameters for Analysis	Approximately five flares per aircraft while operating above 3,000 ft.
	Phase IV Requirement 2025-2032
Location (typical	NOCAL
applicable location where applicable)	PMSR
	SOCAL
	Hawaii Range Complex

A.1.7.4 Electronic Warfare Operations

Electronic Warfare		
Electronic Warfare	Electronic Warfare Operations	
Short Description	Aircraft and surface ship crews control portions of the electromagnetic spectrum used by enemy systems to degrade or deny the enemy's ability to take defensive actions.	
Long Description	Aircraft and surface ship crews control the electromagnetic spectrum used by enemy systems to degrade or deny the enemy's ability to take defensive actions. Electronic Warfare Operations can be active or passive, offensive or defensive. Fixed-wing aircraft employ active jamming and deception against enemy search radars to mask the friendly inbound strike aircraft mission. Surface ships detect and evaluate enemy electronic signals from enemy aircraft or missile radars, evaluate courses of action concerning the use of passive or active countermeasures, then use ship maneuvers and either chaff, flares, active electronic countermeasures, or a combination of them to defeat the threat.	
Typical Components	Platforms: Rotary-Wing Aircraft, Fixed Wing – Electronic Warfare Aircraft, Submarine, Surface Combatant Targets: None Systems being Trained/Tested: None Munitions: None	
Active Sonar	No	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels	
Parameters for Analysis	All chaff and flares involved in this event are covered under chaff exercise and flare exercises, respectively.	
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032	
	NOCAL	
	PMSR	
	SOCAL	
	Hawaii Range Complex	

A.1.8 Expeditionary Warfare

The mission of expeditionary warfare is to provide security and surveillance in the littoral (at the shoreline), riparian (along a river), or coastal environments. Expeditionary warfare is wide ranging and includes defense of harbors, operation of remotely operated vehicles, defense against swimmers, and boarding/seizure operations.

Expeditionary warfare training activities include underwater construction team training, dive and salvage operations, and insertion/extraction via air, surface, and subsurface platforms.

A.1.8.1 Dive and Salvage Operations

Expeditionary Warfare	
Dive and Salvage O	perations
Short Description	Navy divers perform dive operations and salvage training.
Long Description	Navy divers will conduct a variety of salvage training to include refloating grounded vessels, underwater repairs to ships, facilities, underwater survey operations, and other underwater training as required.
Typical Components	Platforms: Support Craft Targets: None Systems being Trained/Tested: None Munitions: None
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	The practice salvage platform can be sunk and then refloated and removed.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL
	Port Hueneme Harbor
	Hawaii Range Complex (Naval Defense Sea Area, Puuloa Underwater Range, Kaneohe Bay)

A.1.8.2 Gunnery Exercise Ship-to-Shore

Expeditionary Warfare	
Gunnery Exercise S	hip-to-Shore
Short Description	Small boat crews fire small- and medium-caliber guns at land-based targets.
Long Description	Personnel conduct training in open ocean and littoral operations, including in the vicinity of SCI. Training events include firing of crew-served machine guns and hand held weapons into land impact areas of SHOBA. The boats used by these units include small unit river craft, combat rubber raiding craft, rigid hull inflatable boats, patrol craft, and many other versions of these types of boats.
Typical Components	Platforms: Small Boat Targets: None Systems being Trained/Tested: None Munitions: Projectile - Small Caliber, Projectile - Medium Caliber
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	Impacts on land-based targets is covered in separate NEPA.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL (SHOBA)

A.1.8.3 Obstacle Loading

Expeditionary Warfare	
Obstacle Loading	
Short Description	Military personnel use explosive charges to destroy barriers or obstacles to amphibious vehicle access to beach areas.
Long Description	Navy personnel train to construct, place, and safely detonate multiple charges laid in a pattern for underwater obstacle clearance. Explosive Ordnance Disposal and other expeditionary personnel locate barriers or obstacles designed to block amphibious vehicle access to beach areas, then use explosive charges to destroy them. Obstacle Clearance and Mat Weave may use between 350-500 lb. charges. Time delay fuses may be used for these events.
Typical Components	Platforms: Small Boat Targets: Metal Plates, Sub-surface Targets – Stationary, Bottom-Placed Targets Systems being Trained/Tested: None Munitions: Demolition Devices
Active Sonar	No
In-Water Explosives	E2, E6, E10
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Explosive underwater demolition multiple charge – mat weave and obstacle loading
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL (TAR2, TAR3)
	Hawaii Range Complex (Barbers Point Underwater Range, Ewa Training Minefield, Puuloa Underwater Range, Lima Landing Pearl Peninsula [Victor One])
A.1.8.4 Personnel Insertion/Extraction – Air

Expeditionary Warfare		
Personnel Insertion	Personnel Insertion/Extraction – Air	
Short Description	Personnel are inserted into and extracted from an objective area by fixed-wing aircraft or helicopters.	
Long Description	Personnel are inserted into a water objective via fixed-wing aircraft using parachutes or by helicopters via ropes or jumping into the water. They will conduct an infiltration to an objective (harbor, beach, moored vessel, etc.) and conduct a variety of tasks. The insertion/extraction activities are confined to in-water training. Upon completion of training objectives, personnel are extracted by helicopters or small boats. Small scale explosive charges may be utilized.	
Typical Components	Platforms: Fixed Wing - Cargo and Transport Aircraft, Rotary-Wing Aircraft, Small Boat Targets: None Systems being Trained/Tested: None Munitions: Small scale munitions	
Active Sonar	Νο	
In-Water Explosives	E1	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels	
Parameters for Analysis		
	Phase IV Requirement 2025-2032	
	SOCAL	
Location (typical specific location where applicable)	SSTC (Boat Lanes – North and South)	
	Hawaii Range Complex	

A.1.8.5 Personnel Insertion/Extraction – Surface and Subsurface

Expeditionary Warfare	
Personnel Insertion	n/Extraction – Surface and Subsurface
Short Description	Personnel are inserted into and extracted from an objective area by small boats or subsurface platforms.
Long Description	Utilizing both surface and subsurface platforms, personnel are inserted in the water. They will conduct an infiltration to an objective (harbor, beach, moored vessel, etc.) and conduct a variety of tasks. Underwater platforms and small, manned submersibles are used to simulate deploying from and recovering to a submarine. The insertion/extraction activities are confined to in-water training.
Typical Components	Platforms: Small Boat
	Targets: Air Targets - Drone, Surface Targets - Maneuvering
	Systems being Trained/Tested: None
	Munitions: Small-scale munitions
Active Sonar	Νο
In-Water Explosives	E1
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	Events are typically conducted in waters near land.
	Phase IV Requirement 2025-2032
Location (typical specific location where applicable)	SSTC (Boat Lanes – North and South)
	SOCAL
	Hawaii Range Complex

A.1.8.6 Personnel Insertion/Extraction – Swimmer/Diver

Expeditionary Warfare	
Personnel Insertion	n/Extraction – Swimmer/Diver
Short Description	Divers and swimmer infiltrate harbors, beaches, or moored vessels and conduct a variety of tasks.
Long Description	Divers and swimmer infiltrate harbors, beaches, or moored vessels and conduct a variety of tasks. Activity may include Navy personnel learning advanced self-contained underwater breathing apparatus (SCUBA) diving to include tactics, techniques, and procedures and emergency procedures. Small boats are used for safety.
Typical Components	Platforms: Small Boat Targets: Surface Targets - Maneuvering Systems being Trained/Tested: None Munitions: Grenades
Active Sonar	Νο
In-Water Explosives	E1
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SSTC (Boat Lanes – North and South)
	SOCAL (Del Mar Boat Basin)
	Hawaii Range Complex

A.1.8.7 Port Damage Repair

Other Training Activities	
Port Damage Repai	ir
Short Description	Navy Expeditionary forces train to repair critical port facilities.
Long Description	Navy Expeditionary Forces support Fleet mission through expedient repair of critical port facilities. Training includes diving operations, pile driving and removal, salvage operations, and repairs to piers, quay walls, and other waterfront infrastructure. Training events normally last up to 30 days.
Typical Components	Platforms: Structure Targets: None Systems being Trained/Tested: None Munitions: None
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Pile driving and pile removal
Parameters for Analysis	Port Damage Repair training activities could occur up to 12 times per year. Each training event is comprised of up to seven separate modules, each which could occur up to three iterations during a single event (for a maximum of 21 modules). Training events would last a total of 30 days, of which pile driving is only anticipated to occur for a maximum of 14 days. Per training event, piles of various shapes, sizes and materials would be installed using impact or vibratory methods. Crews could work 24 hours a day for each event. All piles or sheets would be removed after the training event using vibratory or dead pull methods. During pile driving events, the Action Proponent performs soft starts during impact installation of each pile to ensure proper operation of the diesel impact hammer. During a soft start, the Action Proponent performs an initial set of strikes from the impact hammer at reduced energy before it can be operated at full power and speed. The energy reduction of an individual hammer cannot be quantified because it varies by individual driver.
Location (typical	Phase IV Requirement 2025-2032
specific location where applicable)	Port Hueneme Harbor

A.1.8.8 Small Boat Attack

Expeditionary Warfare	
Small Boat Attack	
Short Description	Afloat units defend against small boat or personal water craft attack.
Long Description	For this activity, one or two small boats or personal watercraft conduct attack activities on units afloat, training ship crews how to respond to small boat attack in harbors, restricted channels, and nearshore areas using non-lethal means or armament appropriate to the threat and location.
Typical Components	Platforms: All Navy Ships and Boats, Small Boat, Unmanned Surface Vehicle Targets: Surface Targets - Maneuvering Systems being Trained/Tested: None Munitions: Projectile - Small Caliber
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Non-explosive gunnery
Parameters for Analysis	Non-explosive practice munitions only
	Phase IV Requirement 2025-2032
Location (typical	NOCAL
specific location where applicable)	PMSR
	SOCAL
	Hawaii Range Complex

A.1.8.9 Underwater Construction Team Training

Expeditionary War	Expeditionary Warfare	
Underwater Constr	uction Team Training	
Short Description	Navy and Coast Guard divers conduct underwater repair and construction.	
Long Description	Navy and Coast Guard divers will perform cutting, welding, assembly, and installation of deep-water structures, mooring systems, underwater instrumentation, and other systems as needed.	
Typical Components	Platforms: Small Boat, Unmanned Bottom Crawler Targets: None Systems being Trained/Tested: None Munitions: None	
Active Sonar	No	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels	
Parameters for Analysis	None	
	Phase IV Requirement 2025-2032	
Location (typical specific location where applicable)	Port Hueneme Harbor	
	Naval Base San Diego	
	Hawaii Range Complex (Naval Defense Sea Area, Puuloa Underwater Range, Kaneohe Bay, Pearl Harbor)	

A.1.9 Mine Warfare

The mission of mine warfare is to detect, classify, and avoid or neutralize (disable) mines to protect Navy ships and submarines and to maintain free access to ports and shipping lanes. Mine warfare also includes offensive mine laying to gain control of or deny the enemy access to sea space. Naval mines can be laid by ships, submarines, or aircraft.

Mine warfare neutralization training includes exercises in which ships, aircraft, submarines, underwater vehicles, unmanned vehicles, or marine mammal detection systems search for mine shapes. Personnel train to destroy or disable mines by attaching underwater explosives to or near the mine or using remotely operated vehicles to destroy the mine.

A.1.9.1 Airborne Mine Countermeasure – Mine Detection

Mine Warfare	
Airborne Mine Cou	ntermeasure - Mine Detection
Short Description	Helicopter aircrews detect mines using laser mine detection systems.
Long Description	Helicopter aircrews use airborne devices to detect, locate, and classify potential mines. Airborne devices utilize laser systems to locate mines located below the surface.
	Devices used include the Airborne Laser Mine Detection System (ALMDS), developed to detect and classify floating and near-surface, moored mines.
Typical Components	Platforms: Rotary-Wing Aircraft, Unmanned Surface Vehicle, Unmanned Underwater Vehicle
	Targets: Mine Targets
	Systems being Trained/Tested: Laser Detection Systems
	Munitions: None
Active Sonar	No
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	None
Parameters for Analysis	Airborne laser systems used to detect mine shapes. Laser systems are similar to commercial Light Detection And Ranging systems. The in-air low energy laser stressor was used in analysis of potential impacts on human resources. Mine shapes may be deployed via ship and will be recovered.
	Phase IV Requirement 2025-2032
Location (typical	SOCAL (, Tanner/Cortes Training Minefield, Pyramid Cove Mine Training Range,)
specific location where applicable)	SSTC (Airborne Mine Countermeasure [AMCM] Training Range, Imperial Beach Mine Training Range)
	Hawaii Range Complex (Barbers Point Underwater Range, Barbers Point Harbor to Lighthouse, , , Waiapuaa Bay PMRF Training Area)

A.1.9.2 Airborne Mine Laying

Mine Warfare	
Airborne Mine Layi	ng
Short Description	Fixed-wing aircraft drop non-explosive mine shapes.
Long Description	Fixed-winged aircraft lay offensive or defensive mines for a tactical advantage for friendly forces. Fixed-winged aircraft lay a precise minefield pattern for specific tactical situations. Training shapes are non-explosive.
Typical Components	Platforms: Fixed Wing - Other, Fixed Wing - Strike Aircraft, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: None
	Systems being Trained/Tested: Mine Warfare Devices Munitions: Mines
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Non-explosive aerial-deployed mines and bombs
Parameters for Analysis	Mine laying is similar to a non-explosive bombing exercise. These events primarily occur during major training exercises. Mine laying will typically take place in waters less than 100 feet in depth. Assume 12 mine shapes are used per event.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL
	Hawaii Range Complex

A.1.9.3 Amphibious Breaching Operations

Mine Warfare	
Amphibious Breach	ning Operations
Short Description	Amphibious forces use explosive clearing systems to clear simulated mines on beaches, shallow water, and surf zones for potential landing of personnel and vehicles.
Long Description	Trains amphibious forces to create lanes in simulated enemy obstacle systems to allow maneuver forces freedom of movement. Includes use of explosive clearing systems to breach simulated minefields on beaches, shallow water, and surf zones for potential landing of personnel and vehicles. Systems include, but are not limited to, Mine Line Clearing Charges (MICLIC) and similar. Anticipated tempo similar to Amphibious Assault- Battalion Landing activity.
Typical Components	 Platforms: Amphibious Warfare Vessel, Small Boat, Unmanned Bottom Crawler, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: Sub-surface Targets - Stationary Systems being Trained/Tested: None Munitions: Demolition Devices
Active Sonar	No
In-Water Explosives	E4, E5, E6
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Explosive mine countermeasure and neutralization (no divers)
Parameters for Analysis	MICLIC and other breaching activities conducted at Pyramid Cove and Horse Beach Cove may rely on multiple charges during an event.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL (CPAAA, Pyramid Cove, Horse Beach Cove, SHOBA, TAR 2, TAR 3) SSTC (Boat Lanes – North and South)
	Hawaii Range Complex (Barbers Point Underwater Range, Ewa Training Minefield, Puuloa Underwater Range, Lima Landing, Pearl Peninsula [Victor One])

A.1.9.4 Civilian Port Defense – Homeland Security Anti-Terrorism/Force Protection Exercise

Mine Warfare	
Civilian Port Defense – Homeland Security Anti-Terrorism/Force Protection Exercises	
Short Description	Maritime security personnel train to protect civilian ports and harbors against enemy efforts to interfere with access to those ports.
Long Description	Naval forces provide mine warfare capabilities to support Department of Homeland Security sponsored exercises. The three pillars of mine warfare, airborne (helicopter), surface (surface ships and unmanned surface vehicles), and undersea (divers, marine mammals, and unmanned vehicles) mine countermeasures will be brought to bear in order to ensure strategic U.S. ports remain free of mine threats. Various mine warfare sensors, which utilize active acoustics, will be employed in the detection, classification, and neutralization of mines. Along with traditional mine warfare techniques, such as helicopter towed mine countermeasures, new technologies (unmanned vehicles) will be utilized. Marine mammal systems may be used during this exercise. Exercise locations and scenarios will vary according to Department of Homeland Security strategic goals and evolving world events. Coast Guard cutters, small boats, and aircraft may participate in this activity.
Typical Components	Platforms: Rotary-Wing Aircraft, Small Boat, Surface Combatant, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: Mine Targets Systems being Trained/Tested: Acoustic Communications, Electromagnetic Systems, Sonar Systems - Mine Warfare, Unmanned Vehicle Systems Munitions: Mine Warfare Devices
Active Sonar	MEH, HEM, HEH
In-Water Explosives	F4
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Towed in-water devices Unmanned vehicles Explosive mine neutralization (with divers) Explosive mine countermeasure and neutralization (no divers)
Parameters for Analysis	Non-permanent bottom or in-volume mine shapes will be placed and then recovered at the completion of the training. They will be recovered using normal assets, with diver involvement. In addition to mine shapes detection using lasers, mine neutralization or mine countermeasures may be employed. Explosives may be used if required for scheduled mine neutralization events and will be limited to areas authorized for underwater detonations.

Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	Port Hueneme Harbor, Los Angeles, Long Beach
	San Diego Harbor (Naval Base San Diego, Naval Base Coronado, Naval Base Point Loma)
	Seal Beach
	Hawaii Range Complex (Naval Defense Sea Area, Kaneohe Bay, Honolulu Harbor, Pearl Harbor)

A.1.9.5 Mine Countermeasure Exercise – Ship Sonar

Mine Warfare	
Mine Countermeas	ures – Ship Sonar
Short Description	Ship crews detect and avoid mines while navigating restricted areas or channels using remotely operated active sonar systems.
Long Description	Ship crews use unmanned surface vehicles and remotely operated vehicles to tow mine detection (hunting) equipment to detect and avoid mines while navigating restricted areas or channels. These active sonar systems will operate from a shallow zone to deep water. Exercises could be embedded within major training exercises.
Typical Components	Platforms: Surface Combatant, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: None
	Systems being Trained/Tested: Sonar Systems - Hull Mounted, Sonar Systems - Mine Warfare
	Munitions: None
Active Sonar	MF1K, HFH
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Unmanned vehicles Towed in-water devices
Parameters for Analysis	Assume system will be operated in areas free of obstructions, and will be towed well above the seafloor. Towed system will be operated in a manner to avoid entanglement and damage. Events will take place in water depths 40 ft. and greater. Existing placed mine shapes to be used. There is the potential for temporary placement of mine shapes.
	Phase IV Requirement 2025-2032
Location (typical	SOCAL (Tanner/Cortes Training Minefield, Pyramid Cove Mine Training Range, AMCM Training Range)
specific location where applicable)	SSTC (Imperial Beach Mine Training Range)
	Hawaii Range Complex (Naval Defense Sea Area, Barbers Point Underwater Range, Ewa Training Minefield, Puuloa Underwater Range, Kingfisher, Kalohi Channel, Pailolo Channel, Maui Basin, Alalakeiki Channel)

A.1.9.6 Mine Countermeasures – Mine Neutralization – Remotely Operated Vehicle Operations

Mine Warfare	
Mine Countermeas	sures – Mine Neutralization – Remotely Operated Vehicle Operations
Short Description	Ship, small boat, and helicopter crews locate and disable mines using remotely operated underwater vehicles.
Long Description	Ship, small boat, and helicopter crews utilize remotely operated vehicles to neutralize potential mines. Remotely operated vehicles will use sonar and optical systems to locate and target mine shapes. Explosive mine neutralizers may be used during live fire events.
Typical Components	Platforms: Rotary-Wing Aircraft, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: Mine Targets
	Systems being Trained/Tested: Sonar Systems - Mine Warfare
Active Sonar	HFM
In-Water Explosives	E4
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Explosive mine countermeasure and neutralization (no divers) Unmanned vehicles
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
Location (typical specific location where applicable)	SOCAL (ARPA Training Minefield, Ocean Beach Mine Training Area, Tanner/Cortes Training Minefield, Pyramid Cove Mine Training Range, Mine Training Range – 1 and 2)
	SSTC (Boat Lanes – North and South, AMCM Training Range, Imperial Beach Mine Training Range, Echo)
	Hawaii Range Complex (Kalohi Channel, Pailolo Channel, Maui Basin, Alalakeiki Channel, Kahoolawe Sub Training Minefield, Barbers Point Underwater Range, Barbers Point Harbor to Lighthouse, Marine Corps Training Area Bellows, Ewa Training Minefield, Naval Defense Sea Area, Puuloa Underwater Range, Kaneohe Bay, Kingfisher, Waiapuaa Bay, PMRF Training Area)

A.1.9.7 Mine Neutralization Explosive Ordnance Disposal

Mine Warfare		
Mine Neutralizatio	Mine Neutralization Explosive Ordnance Disposal	
Short Description	Personnel disable threat mines using explosive charges.	
Long Description	Navy divers, typically explosive ordnance disposal personnel, disable threat mines with explosive charges to create a safe channel for friendly vessels to transit or placing or detonating limpet mines on steel structures. Time-delay fuses may be used for these exercises. These operations are normally conducted during daylight hours for safety reasons. Personnel detect, identify, evaluate, and neutralize mines in the water with an explosive	
	device and may involve detonation of one or more explosive charges up to 20 pounds NEW.	
	Personnel may also identify and place limpet charges on a steel structure in the water and detonate an explosive charge of up to 2.2 pounds NEW.	
Typical Components	Platforms: Small Boat, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: Mine Targets Systems being Trained/Tested: None Munitions: Demolition Devices	
Active Sonar	No	
In-Water Explosives	E6	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Explosive mine neutralization (with divers)	
Parameters for Analysis	Time delayed fuses may be used (up to 10 minutes) for charges up to 20 lb. net explosive weight in some locations. Charge placed anywhere in water column, including bottom. Some mine shapes will be recovered.	
	Phase IV Requirement 2025-2032	
Location (typical specific location where applicable)	SOCAL (ARPA Training Minefield, Ocean Beach Mine Training Area, Pyramid Cove Mine Training Range, TAR 2, TAR 3)	
	SSTC (Boat Lanes – North and South, Echo, AMCM Training Range, Imperial Beach Mine Training Range)	
	Hawaii Range Complex (Barbers Point Underwater Range, Ewa Training Minefield, Puuloa Underwater Range, Lima Landing, Pearl Peninsula [Victor One])	

A.1.9.8 Submarine Mine Avoidance Exercise

Mine Warfare	
Submarine Mine A	voidance Exercise
Short Description	Submarine crews practice detecting mines in a designated area.
Long Description	Submarine crews use active sonar to detect and avoid mines or other underwater hazardous objects, while navigating restricted areas or channels, such as while entering or leaving port. This event trains submarine crews to detect and avoid mines. Training utilizes simulated minefields constructed of moored or bottom mines, or instrumented mines that can record effectiveness of mine detection efforts. In a typical training exercise, submarine crews will use high-frequency sonar to locate and avoid the mine shapes. Each mine avoidance exercise involves one submarine operating the high-frequency sonar for 6 hours to navigate through the training minefield.
Typical Components	 Platforms: Submarine, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: Mine Targets Systems being Trained/Tested: Sonar Systems - Hull Mounted, Sonobuoys, Unmanned Vehicle Systems Munitions: None
Active Sonar	HFH, VHFH, Broadband (MF to HF)
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Unmanned vehicles
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
Location (typical	PMSR
specific location where applicable)	SOCAL (ARPA Training Minefield, Ocean Beach Mine Training Area, Tanner/Cortes Training Minefield, Pyramid Cove Mine Training Range)
	Hawaii Range Complex (Kalohi Channel, Pailolo Channel, Maui Basin, Alalakeiki Channel, Kahoolawe Sub Training Minefield)

A.1.9.9 Submarine Mobile Mine and Mine Laying Exercise

Mine Warfare	
Submarine Mobile	Mine and Mine Laying Exercise
Short Description	Submarine crews practice deploying submarine launched mines.
Long Description	The submarine launched mine exercise submarine involves a submarine deploying mines. During this event, passive sonar is used almost exclusively, active sonar use is restricted because it would reveal the submarines presence. This exercise typically involves only a single submarine. Mine laying exercises may have a range support craft or a support helicopter to recover mines.
Typical Components	 Platforms: Extra Large Unmanned Underwater Vehicle, Submarine, Unmanned Surface Vehicle Targets: None Systems being Trained/Tested: Acoustic Communications, Unmanned Vehicle Systems Munitions: Mines (Non-Explosive)
Active Sonar	MFM, HFL, HFM, VHFL
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Unmanned vehicles
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
Location (typical	PMSR
specific location where applicable)	SOCAL (Tanner/Cortes Training Minefield, Pyramid Cove Mine Training Range, Mine Training Range – 1 and 2)
	Hawaii Range Complex (Kalohi Channel, Pailolo Channel, Maui Basin, Alalakeiki Channel, Kahoolawe Sub Training Minefield)

A.1.9.10 Surface Ship Object Detection

Mine Warfare	
Surface Ship Objec	t Detection
Short Description	Cruiser and Destroyer crews detect and avoid mines while navigating restricted areas or channels using hull-mounted active sonar.
Long Description	Cruiser and Destroyer crews use the ship's hull-mounted sonar to detect and avoid mines or other underwater hazardous objects while navigating restricted areas or channels. These systems will operate from a shallow zone greater than 40 ft. to deep water. Exercises could be embedded within major training exercises.
Typical Components	Platforms: Surface Combatant Targets: None Systems being Trained/Tested: Sonar Systems - Hull Mounted Munitions: None
Active Sonar	MF1K
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels
Parameters for Analysis	Events will take place in water depths 40 ft. and greater. Existing placed mine shapes to be used. There is the potential for temporary placement of mine shapes.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL (Tanner/Cortes Training Minefield, Pyramid Cove Mine Training Range)
	SSTC (Imperial Beach Mine Training Range)
	Hawaii Range Complex (Naval Defense Sea Area, Pearl Harbor)

A.1.9.11 Training and End-to-End Mission Capability Verification – Mobile Mine and Mine Laying Exercise

Mine Warfare	Mine Warfare	
Training and End-to-End Mission Capability Verification – Mobile Mine and Mine Laying Exercise		
Short Description	Submarine crew launches mobile mine(s) to a planned location.	
Long Description	Submarine crew launches mobile mine(s) to a planned location. The mine(s) are subsequently recovered by an external source. Active sonar is used periodically. This exercise typically would involve only a single submarine, UUV, or surface craft.	
Typical Components	Platforms: Submarine, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: None Systems being Trained/Tested: None Munitions: None	
Active Sonar	Νο	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels	
Parameters for Analysis	None	
	Phase IV Requirement 2025-2032	
Location (typical	PMSR	
specific location where applicable)	SOCAL (Tanner/Cortes Training Minefield, Pyramid Cove Mine Training Range, Mine Training Range – 1 and 2)	
	Hawaii Range Complex (Kalohi Channel, Pailolo Channel, Maui Basin, Alalakeiki Channel, Kahoolawe Sub Training Minefield)	

A.1.9.12 Underwater Demolition Qualification and Certification

Mine Warfare		
Underwater Demo	Underwater Demolition Qualification and Certification	
Short Description	Navy divers conduct various levels of training and certification in placing underwater demolition charges.	
Long Description	Demolition requalification and training provides teams with experience in underwater detonations by conducting detonations on metal plates near the shoreline. At water depths less than 100 ft, single or sequential charges (less than 25 lb.) are placed on, or near the seafloor.	
Typical Components	Platforms: Small Boat, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: Metal Plates Systems being Trained/Tested: None Munitions: Demolition Devices	
Active Sonar	No	
In-Water Explosives	E5, E6	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Explosive mine neutralization (with divers)	
Parameters for Analysis	Only small charges are used within the Bayside area of SSTC.	
	Phase IV Requirement 2025-2032	
Location (typical specific location where applicable)	SOCAL (ARPA Training Minefield, Ocean Beach Mine Training Area, Pyramid Cove Mine Training Range, TAR 2, TAR 3)	
	SSTC (Boat Lanes – North and South, AMCM Training Range, Imperial Beach Mine Training Range)	
	Hawaii Range Complex (Barbers Point Underwater Range, Ewa Training Minefield, Puuloa Underwater Range, Lima Landing, Pearl Peninsula [Victor One])	

A.1.9.13 Underwater Demolition Multiple Charge – Large Area Clearance

Mine Warfare	Mine Warfare	
Underwater Demo	litions Multiple Charge – Large Area Clearance	
Short Description	Military personnel use explosive charges to destroy barriers or obstacles to amphibious vehicle access to beach areas.	
Long Description	Navy personnel train to construct, place, and safely detonate multiple charges laid in a pattern for underwater obstacle clearance. Navy divers locate barriers or obstacles designed to block amphibious vehicle access to beach areas, then use explosive charges to destroy them. Pattern charges (mat weaves) may use as much as 650 pounds of high explosive. Time delay fuses are used for these events.	
Typical Components	Platforms: Small Boat, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: None Systems being Trained/Tested: None Munitions: Demolition Devices	
Active Sonar	No	
In-Water Explosives	E13	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Explosive underwater demolition multiple charge – mat weave and obstacle loading	
Parameters for Analysis	None	
Location (typical	Phase IV Requirement 2025-2032	
specific location where applicable)	SOCAL (SCI)	

A.1.9.14 Underwater Mine Countermeasure Raise, Tow, Beach, and Exploitation

Mine Warfare	
Underwater Mine	Countermeasure Raise, Tow, and Beach, and Exploitation
Short Description	Personnel locate mines, perform mine neutralization, raise and tow mines to the beach, and conduct exploitation operations for intelligence gathering.
Long Description	Navy divers, typically explosive ordnance disposal personnel, locate mines using unmanned underwater vehicle, marine mammals, or other diver search techniques. Mines are then neutralized, or prevented from working as they are intended. A lift balloon is attached to the line and slowly tows the shape to the beach. The final step, exploitation, is intelligence gathering, identifying the mine and how it works, and then disassembling it or disposing of it.
Typical Components	Platforms: Rotary-Wing Aircraft, Small Boat, Unmanned Surface Vehicle, Unmanned Underwater Vehicle
	Targets: Mine Targets
	Systems being Trained/Tested: None
	Munitions: None
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Unmanned vehicles
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
Location (typical	SSTC (Boat Lanes – North and South)
specific location where applicable)	SOCAL (ARPA Training Minefield, SCI)
	Hawaii Range Complex (Barbers Point Underwater Range, Marine Corps Training Area Bellows, Ewa Training Minefield, Naval Defense Sea Area, Puuloa Underwater Range, Kaneohe Bay, PMRF Training Area, Waiapuaa Bay and Beach)

A.1.10 Surface Warfare Training

Surface warfare is a type of naval warfare in which aircraft, surface ships, and submarines employ weapons and sensors in operations directed against enemy surface ships or small boats. Aircraft-to-surface Surface warfare is conducted by long-range attacks using air-launched cruise missiles, precision guided munitions, or aircraft guns. Surface warfare also is conducted by warships employing torpedoes, naval guns, and surface-to-surface missiles. Submarines attack surface ships using torpedoes or submarine-launched, anti-ship cruise missiles. Training in surface warfare includes surface-to-surface gunnery and missile exercises, air-to-surface gunnery and missile exercises, air-to-surface gunnery and missile exercises, and submarine missile or torpedo launch events. Gunnery and missile training generally involves expenditure of ordnance against a towed target. A sinking exercise is a specialized training event that provides an opportunity for ship, submarine, and aircraft crews to use multiple weapons systems to deliver high-explosive ordnance on a deactivated vessel, which is deliberately sunk.

Surface warfare also encompasses maritime security, that is, the interception of a suspect surface ship by a Navy ship for the purpose of boarding-party inspection or the seizure of the suspect ship. Training in these tasks is conducted in visit, board, search and seizure exercises.

A.1.10.1 Bombing Exercise Air-to-Surface

Surface Warfare	
Bombing Exercise A	Air-to- Surface
Short Description	Fixed-wing aircrews and UASs deliver bombs against surface targets.
Long Description	 Fixed-wing aircraft conduct bombing exercises against stationary floating targets (e.g., MK-58 smoke buoy), towed targets, or maneuvering targets. An aircraft clears the area, deploys a smoke buoy, and then delivers high-explosive or non-explosive practice bombs on the target. Exercises for strike fighters typically involve a flight of two aircraft delivering unguided or guided munitions that may be either high-explosive or non-explosive. The following munitions may be employed by strike fighter aircraft in the course of bombing exercise: Unguided munitions including non-explosive subscale bombs (MK-76 and BDU-45) and explosive and non-explosive general purpose bombs (MK-80 series). Precision-guided munitions include laser-guided bombs (explosive, non-explosive), laser-guided training projectiles (non-explosive), Joint Direct Attack Munitions (explosive, non-explosive).
Typical Components	Platforms: Fixed Wing - Strike Aircraft
	Targets: Surface Targets - Floating, Surface Targets - Maneuvering
	Systems being Trained/Tested: None
	Munitions: Bombs
Active Sonar	No
In-Water Explosives	E9, E10, E12
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Non-explosive aerial-deployed mines and bombs Explosive bombs
Parameters for Analysis	Approximately 90 percent of non-explosive bombs are the sub-scale bombs such as the MK-76 and BDU-48. Approximately 155 explosive bombs used per year throughout HCTT Study Area. Approximately half of the explosive bombs (80) would be 500-lb. bombs, 60 would be 1,000-lb. bombs, and 15 would be 2,000-lb. bombs. Live bombs will not be used in NOCAL.
Location (typical specific location	Phase IV Requirement 2025-2032
	NOCAL
	PMSR
where applicable)	SOCAL
	Hawaii Range Complex

A.1.10.2 Gunnery Exercise Air-to-Surface – Medium Caliber

Surface Warfare	
Gunnery Exercise A	ir-to-Surface Medium Caliber
Short Description	Fixed-wing and helicopter aircrews fire medium-caliber guns at surface targets.
Long Description	Navy, Marine Corps, and Coast Guard fixed-wing and helicopter aircrews engage surface targets with medium-caliber guns. Targets simulate enemy ships, boats, and floating/near- surface mines. Fighter aircraft descend on a target firing high-explosive or non-explosive practice munitions medium-caliber projectiles. Helicopters will fly a racetrack pattern around an at-sea target. Aircrew will engage the target with medium-caliber weapons. Targets range from a smoke float, or an empty steel drum, to high speed remote controlled boats and jet-skis.
Typical Components	Platforms: Fixed Wing - Strike Aircraft, Rotary-Wing Aircraft Targets: Surface Targets - Floating, Surface Targets - Maneuvering Systems being Trained/Tested: None Munitions: Projectile - Medium Caliber
Active Sonar	Νο
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Non-explosive gunnery Unmanned vehicles
Parameters for Analysis	Most medium-caliber air-to-surface gunnery exercises will be with non-explosive projectiles. High-explosive projectiles will supplement when non-explosive projectiles are not available. Fixed-wing casings remain with aircraft, and helicopter shell casings are expended into the water. Two fixed-wing aircraft (400 projectiles each) or one helicopter (400 projectiles) per activity. One target used per event: expendable smoke float (50 percent), stationary target (45 percent), or remote-controlled target (5 percent). High-explosive projectiles used during this activity would be de minimis.
	Phase IV Requirement 2025-2032
Location (typical	NOCAL
specific location	PMSR
where applicable)	SOCAL
	Hawaii Range Complex

A.1.10.3 Gunnery Exercise Air-to-Surface – Small Caliber

Surface Warfare	
Gunnery Exercise A	ir-to-Surface Small Caliber
Short Description	Helicopter and tiltrotor aircrews, use small-caliber guns to engage surface targets.
Long Description	Helicopters and tiltrotor aircraft, fly a racetrack pattern around an at-sea target. Targets simulate enemy ships, boats, and floating/near-surface mines. Each gunner will engage the target with small-caliber weapons. Targets range from a smoke float, an empty steel drum, to high speed remote controlled boats and jet-skis.
Typical Components	Platforms: Rotary-Wing Aircraft, Tiltrotor Aircraft
	Targets: Surface Targets - Floating, Surface Targets - Maneuvering
	Systems being Trained/Tested: None
	Munitions: Projectile - Small Caliber
Active Sonar	Νο
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Non-explosive gunnery
Parameters for Analysis	Most events will occur proximate to naval stations where MH-60 helicopters are home based and target services are available.
	Phase IV Requirement 2025-2032
Location (typical	NOCAL
specific location where applicable)	PMSR
	SOCAL
	Hawaii Range Complex

A.1.10.4 Gunnery Exercise Surface-to-Surface Boat – Medium Caliber

Surface Warfare	
Gunnery Exercise Surface-to-Surface Boat Medium Caliber	
Short Description	Small boat crews fire medium-caliber guns at surface targets.
Long Description	 Army, Navy, and Coast Guard small boat crews fire medium-caliber guns at surface targets. Boat crews may use high or low speeds to approach and engage targets simulating other boats, floating mines, or nearshore land targets with medium-caliber (up to and including 40 mm) weapons. A commonly used target is an empty steel drum. A number of different types of boats are used depending on the unit using the boat and their mission. The boats used by these units include small unit river craft, combat rubber raiding craft, rigid-hull inflatable boats, patrol craft, and many other versions of these types of boats.
Typical Components	Platforms: Small Boat Targets: Surface Targets - Floating, Surface Targets - Maneuvering Systems being Trained/Tested: None Munitions: Grenades, Projectile - Medium Caliber
Active Sonar	No
In-Water Explosives	E1
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Explosive gunnery Non-explosive gunnery Towed in-water devices
Parameters for Analysis	Assume all events include the use of some explosive projectiles. Most events will involve boat crews training with MK 203 40 mm grenade launcher. Most events will occur proximate to naval stations. One target used per event, typically a stationary target such as a 50-liter steel drum. The boats used in this activity have inboard or outboard diesel or gasoline engines with either propeller or water jet propulsion.
	Phase IV Requirement 2025-2032
Location (typical	NOCAL
specific location	PMSR
where applicable)	SOCAL
	Hawaii Range Complex

A.1.10.5 Gunnery Exercise Surface-to-Surface Boat – Small Caliber

Surface Warfare		
Gunnery Exercise S	Gunnery Exercise Surface-to-Surface Boat Small Caliber	
Short Description	Small boat crews fire small-caliber guns at surface targets.	
Long Description	Army, Navy, and Coast Guard small boat crews fire small-caliber guns at surface targets. Boat crews may use high or low speeds to approach and engage targets simulating other boats, swimmers, floating mines, or nearshore land targets with small-caliber (up to and including 0.50 caliber) weapons. A commonly used target is an empty steel drum.	
Typical Components	Platforms: Small Boat	
	Targets: Surface Targets - Floating, Surface Targets - Maneuvering	
	Systems being Trained/Tested: None	
	Munitions: Projectile - Small Caliber	
Active Sonar	No	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Non-explosive gunnery Towed in-water devices	
Parameters for Analysis	The majority of events will occur proximate to naval stations. Events will occur relatively nearshore due to short range of boats and safety concerns. Events mostly occur within 3 nautical miles of the shoreline, but can occur further from shore.	
	Phase IV Requirement 2025-2032	
	NOCAL	
Location (typical	PMSR	
where applicable)	SOCAL	
	SSTC (Boat Lanes – North and South)	
	Hawaii Range Complex	

A.1.10.6 Gunnery Exercise Surface-to-Surface Ship – Large Caliber

Surface Warfare	Surface Warfare	
Gunnery Exercise S	Surface-to-Surface Ship Large Caliber	
Short Description	Surface ship crews fire large-caliber guns at surface targets.	
Long Description	Navy and Coast Guard gun crews engage surface targets at sea with their main battery large-caliber (typically 57 mm, 76 mm, and 5-inch) guns. Targets include the QST-35 seaborne powered target, high speed maneuverable surface target, or a specially configured remote controlled watercraft. Some targets are expended during the exercise and are not recovered.	
	The exercise proceeds with the target boat approaching from about 10-NM distance. The target is tracked by radar and when within a predetermined range, it is engaged first with large-caliber "warning shots." As threats get closer all weapons may be used to disable the threat.	
	This exercise may involve a single firing ship, or be undertaken in the context of a coordinated larger exercise involving multiple ships, including a major training exercise.	
	Large-caliber guns will also be fired during weapon certification events and in conjunction with weapon maintenance.	
	During all exercises, either high-explosive or non-explosive projectiles may be used. High- explosive projectiles can either be fused for detonation on impact (with water surface or targets), or for proximity to the target (in air detonation).	
Typical Components	Platforms: Surface Combatant, Cutter	
	Targets: Surface Targets - Floating, Surface Targets - Maneuvering	
	Systems being Trained/Tested: None	
	Munitions: Projectile - Large Caliber	
Active Sonar	Νο	
In-Water Explosives	E3, E5	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Explosive gunnery Non-explosive gunnery Towed in-water devices Weapon firing noise	
Parameters for Analysis	Activity always occurs beyond 3 nautical miles of the shoreline. For analytical purposes assume all high explosive projectiles are fused to detonate upon impact with water surface or target. After impacting the water, the high explosive projectiles are expected to detonate within three feet of the surface.	

Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	NOCAL
	PMSR
	SOCAL
	Hawaii Range Complex
	Transit Corridor

A.1.10.7 Gunnery Exercise Surface-to-Surface Ship – Medium Caliber

Surface Warfare	
Gunnery Exercise Surface-to-Surface Ship Medium Caliber	
Short Description	Surface ship crews fire medium-caliber guns at surface targets.
Long Description	Navy and Coast Guard crews fire medium-caliber guns at surface targets.
	Ships use medium-caliber weapons to practice defensive marksmanship, typically against a stationary floating target (a 10 ft. diameter red balloon [Killer Tomato]) and high-speed mobile targets. Some targets are expended during the exercise and are not recovered.
	Shipboard protection systems (Close-In Weapon System) utilizing medium-caliber projectiles would train against high speed mobile targets.
Typical Components	Platforms: Surface Combatant, Cutter
	Targets: Surface Targets - Floating, Surface Targets - Maneuvering
	Systems being Trained/Tested: None
	Munitions: Projectile - Medium Caliber
Active Sonar	Νο
In-Water Explosives	E1
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Non-explosive gunnery Explosive gunnery Towed in-water devices
Parameters for Analysis	One target used per event. Approximately 50 percent of targets are "Killer Tomatoes". Approximately 35 percent are high-speed maneuvering targets, which are recovered. Approximately 15 percent of targets are other stationary targets such as a steel drum.
	Phase IV Requirement 2025-2032
	SOCAL
Location (typical specific location where applicable)	PMSR
	NOCAL
	Hawaii Range Complex
	Transit Corridor

A.1.10.8 Gunnery Exercise Surface-to-Surface Ship – Small Caliber

Surface Warfare	
Gunnery Exercise Surface-to-Surface Ship Small Caliber	
Short Description	Surface ship crews fire small-caliber guns at surface targets.
Long Description	Navy and Coast Guard ship crews fire small-caliber guns at surface targets.
	Ships use small-caliber weapons to practice defensive marksmanship, typically against stationary floating targets. The target may be a 10 ft. diameter red balloon (Killer Tomato, see Figure A.2 4), a 50 gallon steel drum, or other available target, such as a cardboard box. Some targets are expended during the exercise and are not recovered.
	Ship crew qualifications conducted at sea employ stationary targets on deck. Small-caliber projectiles fired during these exercises will be expended in the water.
	Shipboard protection systems utilizing small-caliber projectiles will train against high speed mobile targets.
Typical Components	Platforms: Surface Combatant, Cutter
	Targets: Surface Targets - Floating
	Systems being Trained/Tested: None
	Munitions: Projectile - Small Caliber
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Non-explosive gunnery Towed in-water devices
Parameters for Analysis	Small-caliber gun projectiles per event: 1,000 to 3,000 non-explosive practice munitions.
	Phase IV Requirement 2025-2032
	SOCAL
Location (typical	PMSR
where applicable)	NOCAL
	Hawaii Range Complex
	Transit Corridor

A.1.10.9 Laser Targeting – Aircraft

Surface Warfare	
Laser Targeting – A	ircraft
Short Description	Fixed-wing and helicopter aircrews illuminate enemy targets with lasers.
Long Description	Fixed-winged and helicopter aircrew illuminate enemy targets with lasers for engagement by aircraft with laser guided bombs or missiles. This exercise may be conducted alone or in conjunction with other exercises utilizing precision guided munitions, such as surface missiles and guided rockets. Exercises where weapons are fired are addressed in the appropriate activity (e.g., air-to-surface missile exercise). Lower powered lasers may also be used as non-lethal deterrents during maritime security operations (force protection).
Typical Components	Platforms: Fixed Wing - Strike Aircraft, Rotary-Wing Aircraft
	Targets: Surface Targets - Towed
	Systems being Trained/Tested: Aircraft Laser Illuminator
	Munitions: None
Active Sonar	Νο
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Towed in-water devices
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
Location (typical	NOCAL
specific location where applicable)	PMSR
	SOCAL
	Hawaii Range Complex

A.1.10.10 High-Energy Laser Exercise Surface-to-Surface

Surface Warfare	
High-Energy Laser I	Exercise Surface-to-Surface
Short Description	Surface ship crews disable or destroy surface targets with high-energy laser systems.
Long Description	Ship crews employ high-power energy laser systems that are used to create critical failures in surface targets. System directs a directed energy beam that can penetrate thin layers of metal at short distances that can render surface targets inoperative. Laser systems can also be used in a low power setting as non-lethal deterrent during maritime security operations (force protection). The low power capability would not be used against manned platforms during training.
Typical Components	Platforms: Surface Combatant
	Targets: Surface Targets - Maneuvering
	Systems being Trained/Tested: High-Energy Laser Systems
	Munitions: None
Active Sonar	Νο
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Towed in-water devices
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
Location (typical	NOCAL
specific location where applicable)	PMSR
	SOCAL
	Hawaii Range Complex

A.1.10.11 Maritime Security Operations

Surface Warfare	
Maritime Security	Operations
Short Description	Helicopter, surface ship, and small boat crews conduct a suite of maritime security operations at sea, to include visit, board, search and seizure; maritime interdiction operations; force protection; and anti-piracy operations.
Long Description	Navy and Coast Guard helicopter and surface ship crews conduct a suite of maritime security operations (e.g., visit, board, search and seizure, maritime interdiction operations, force protection, and anti-piracy operations). These activities involve training of boarding parties delivered by helicopters and surface ships to surface vessels for the purpose of simulating vessel search and seizure operations. Various training scenarios are employed and may include small arms with non-explosive blanks and surveillance or reconnaissance unmanned surface and aerial vehicles. The entire exercise may last two to three hours.
	suspect vessels, potentially under hostile conditions.
	Maritime Interdiction Operations: Ships and aircraft train in pursuing, intercepting, and ultimately detaining suspect vessels.
	Maritime Infrastructure Protection and Harbor Defense: Naval personnel train to defend oil platforms, similar at sea structures, harbors, piers, and other infrastructure.
	Warning Shot/Disabling Fire: Naval personnel train in the use of weapons to force fleeing or threatening small boats (typically operating at high speeds) to come to a stop.
	Ship Force Protection: Ship crews train in tracking multiple approaching, circling small craft, assessing threat potential, and communicating amongst crewmates and other vessels to ensure ships are protected against attack.
	Anti-Piracy Training: Naval personnel train in deterring and interrupting piracy activity. Training includes large vessels (pirate "mother ships"), and multiple small, maneuverable, and fast craft.
Typical Components	Platforms: Amphibious Warfare Vessel, Rotary-Wing Aircraft, Small Boat, Surface Combatant, Cutter
	Targets: Surface Targets - Maneuvering
	Systems being Trained/Tested: None
	Munitions: None
Active Sonar	Νο
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels

	Non-explosive gunnery Unmanned vehicles
Parameters for Analysis	Maritime Security Operations is a broad term used to describe activities intended train naval forces in the skills necessary to protect naval vessels from small boat attack, counter piracy and drug operations (maritime interdiction operations and visit, board, search, and seizure), and protect key infrastructure (e.g., oil platforms). Maritime security operations need to remain broad as naval forces need to be able to tailor training events to respond to emergent threats. Maritime Security Operations events typically do not involve live fire of weapons. All maritime security operations events involve vessel movement, sometimes at high rates of speed (naval vessels maneuvering to overtake suspect vessel or small boats (targets) closing in and maneuvering around naval vessels), and some events involve helicopters and boarding parties. Maritime security operations training events are conducted proximate to homeports (e.g., San Diego, California and Honolulu, Hawaii) including during times of transit in and out of port, as well as during major training exercises.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	NOCAL
	PMSR
	SOCAL
	Hawaii Range Complex

A.1.10.12 Missile Exercise Air-to-Surface

Surface Warfare	
Missile Exercise Air	-to-Surface
Short Description	Fixed-wing and helicopter aircrews and UASs fire air-to-surface missiles at surface targets.
Long Description	Fighter, maritime patrol aircraft, and helicopter aircrews fire precision-guided missiles against surface targets. Aircraft involved may be unmanned.
	Fixed-wing aircraft (fighters or maritime patrol aircraft) approach an at-sea surface target from high altitude, and launch high-explosive precision guided missiles.
	Helicopters designate at-sea surface targets with a laser or optics for a precision guided high-explosive or non-explosive practice munitions missile. Helicopter launched missiles typically pass through the target's "sail," and, if explosive, detonate at or just below, the water's surface.
Typical Components	Platforms: Fixed Wing – Patrol Aircraft, Fixed Wing - Strike Aircraft, Rotary-Wing Aircraft, Unmanned Aircraft
	Targets: Surface Targets - Floating, Surface Targets - Towed
	Systems being Trained/Tested: None
	Munitions: Air-to-Surface Missiles
Active Sonar	No
In-Water Explosives	E6, E7, E8, E9
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Explosive missiles and rockets Non-explosive missiles and rocket Towed in-water devices
Parameters for Analysis	Assume one missile and one target per event. While missiles could explode above the water's surface after contacting targets, analysis assumes all warheads explode at or just below the water's surface.
	Phase IV Requirement 2025-2032
Location (typical	SOCAL
where applicable)	PMSR
	Hawaii Range Complex
A.1.10.13 Missile Exercise Air-to-Surface Rocket

Surface Warfare	
Missile Exercise Ai	r-to-Surface Rocket
Short Description	Helicopter aircrews fire both precision-guided and unguided rockets at surface targets.
Long Description	Helicopters designate an at-sea surface target with a laser or optics for precision-guided high explosive or non-explosive practice munitions rockets.
Typical Components	Platforms: Rotary-Wing Aircraft Targets: Surface Targets - Floating, Surface Targets - Maneuvering Systems being Trained/Tested: None Munitions: Rockets
Active Sonar	No
In-Water Explosives	E3
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Explosive missiles and rockets Non-explosive missiles and rockets
Parameters for Analysis	Assume all explosive rockets detonate in water. Rockets may be used in conjunction with force protection events.
	Phase IV Requirement 2025-2032
Location (typical specific location where applicable)	SOCAL PMSR
	Hawaii Range Complex

A.1.10.14 Missile Exercise Surface-to-Surface

Surface Warfare		
Missile Exercise Su	Missile Exercise Surface-to-Surface	
Short Description	Surface ship crews defend against surface threats (ships or small boats) and engage them with missiles.	
Long Description	Surface ships launch missiles at surface maritime targets with the goal of destroying or disabling enemy ships or boats. After detecting and confirming a surface threat, the ship will fire a precision guided surface missile.	
	Events with destroyers and cruisers will involve long range (over the horizon) Harpoon (or similar) surface missiles. Events with littoral combat certify ship's crew to defend against "close-in" surface threats and will use shorter range surface missiles such as Griffin or Hellfire.	
	These exercises are live fire, meaning that a missile is fired down range. Surface missiles could be equipped with either high-explosive or non-explosive warheads.	
Typical Components	Platforms: Surface Combatant	
	Targets: Surface Targets - Maneuvering	
	Systems being Trained/Tested: None	
	Munitions: Surface-to-Surface Missiles	
Active Sonar	No	
In-Water Explosives	E9	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels	
Parameters for Analysis	Assume one missile and one target used per event. While missile could explode above water's surface after contacting target, analysis assumes all warheads explode at or just below surface.	
	Phase IV Requirement 2025-2032	
Location (typical specific location where applicable)	SOCAL	
	PMSR	
	Hawaii Range Complex	

A.1.10.15 Sinking Exercise

Surface Warfare	
Sinking Exercise	
Short Description	Aircraft, ship, and submarine crews deliberately sink a seaborne target, usually a decommissioned ship made environmentally safe for sinking according to U.S. Environmental Protection Agency standards, with a variety of ordnance.
Long Description	Ship personnel and aircrew deliver high-explosive ordnance on a seaborne target (large deactivated vessel), which is deliberately sunk using multiple weapon systems. A sinking exercise is typically conducted by aircraft, surface vessels, and submarines to train in live ordnance delivery on a full size ship target. The target is typically a decommissioned ship made environmentally safe for sinking according to U.S. Environmental Protection Agency standards. The location is greater than 50 nautical miles from shore and in water depths greater than 6,000 feet (ft.). Ship, aircraft, and submarine crews attack with coordinated tactics and deliver a variety of inert and high-explosive ordnance. Coast Guard cutters and aircraft may participate in this activity. Typically, the exercise lasts for 4 to 8 hours and possibly over 1 to 2 days, however it is unpredictable and ultimately ends when the target ship sinks.
Typical Components	 Platforms: Fixed Wing – Strike Aircraft, Submarine, Surface Combatant Targets: Surface Target - Stationary Systems being Trained/Tested: None Munitions: Air-to-Surface Missiles, Bombs, Projectile - Large Caliber, Projectile - Medium Caliber, Torpedoes - HE
Active Sonar	HFH
In-Water Explosives	E5, E8, E9, E11, E12
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Unmanned vehicles SINKEX
Parameters for Analysis	 The participants and assets typically include: 1 full-size target ship hulk 1-5 CG, DDG, or LCS ships 1-10 F/A-18, or maritime patrol aircraft 1 or 2 MH-60 helicopters 1 E-2 aircraft for Command and Control 1 submarine 1-3 range clearance aircraft 1-2 Harpoon surface-to-surface or air-to-surface missiles 2-4 Maverick or Hellfire air-to-surface missiles 2-12 MK-80 series general purpose bombs 200 large-caliber projectiles 1-2 MK-48 heavyweight submarine-launched torpedo

	 2,000-10,000 projectiles .50-caliber and 7.62 millimeter Assume 2 guidance wires expended per event Acoustic effects modeling assumed only a percentage of munitions missed target and exploded in water. Precision guided munitions are assumed to impact target well above waterline and are not modeled (or reported) as in water explosions.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL
	Hawaii Range Complex

A.1.10.16 Surface Warfare Torpedo Exercise – Submarine

Surface Warfare	
Surface Warfare Torpedo Exercise – Submarine	
Short Description	Submarine crews search for, detect, and track a surface ship simulating a threat surface ship with the goal of determining a firing solution that could be used to launch a torpedo with the intent to simulate destroying the targets.
Long Description	Submarine crews search for, detect and track a surface ship(s) simulating threat surface ship(s) with the goal of determining a firing solution that could be used to launch a torpedoes with the intent to simulate destroying the targets. A single submerged submarine operates at various speeds and depths while using its hull mounted and towed array passive and active sonars and potentially UAVs to track the threat target. Passive sonar is used extensively with active sonar used less frequently. Submarine launched exercise torpedoes are fired at the target surface ship(s) and surface ship targets and/or threat supporting fixed and/or rotary wind aircraft may fire light weight torpedoes at the submarine. All exercise participants may employ countermeasures and decoys. This exercise may involve a single submarine, or be undertaken in the context of a coordinated larger exercise involving multiple aircraft, ships, and submarines, including a major range event. The exercise torpedoes are recovered by helicopter or small craft. The preferred range for this exercise is an instrumented underwater range, but it may be conducted off an instrumented range.
Typical Components	Platforms: Submarine, Unmanned Aircraft
	Targets: Surface Targets - Maneuvering
	Systems being Trained/Tested: None
	wunitions: Torpedoes - Exercise
Active Sonar	HFH
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Towed in-water devices
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	PMSR
	SOCAL (SOAR, Tanner Bank SWTR, San Clemente Island SWTR)
	Hawaii Range Complex (BARSTUR, BSURE)

A.1.10.17 Training and End-to-End Mission Capability Verification – Submarine Missile Maritime

Surface Warfare	
Training and End-to	o-End Mission Capability Verification – Submarine Missile Maritime
Short Description	Submarine crews launch missile(s) which may have an explosive warhead at a maritime target simulating an adversary surface ship with the goal of destroying or disabling adversary surface ship.
Long Description	Submarines launch missiles at surface maritime targets with the goal of destroying or disabling enemy ships or boats. After detecting and confirming a surface threat, the submarine will fire a precision guided surface missile.
Typical Components	Platforms: Submarine
	Targets: Surface Targets - Maneuvering
	Systems being Trained/Tested: None
	Munitions: Subsurface-to-Surface Missiles
Active Sonar	No
In-Water Explosives	E9, E10
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL
	Hawaii Range Complex (BARSTUR, BSURE)

A.1.11 Other Training Activities

Other training activities includes training that falls outside the Primary Mission Areas.

A.1.11.1 Aerial Firefighting

Other Training Act	Other Training Activities	
Aerial Firefighting		
Short Description	Helicopter aircrews conduct proficiency training in the use of airborne firefighting water baskets, dropping seawater on terrestrial targets on SCI or the Hawaii Range Complex.	
Long Description	Helicopters connect to water baskets that are suspended beneath the aircraft. The helicopter and water basket fly to a point over the ocean, descend, and fill the basket with seawater. The helicopter then flies to a predesignated target where the aircrew releases the water. The aircrew gains proficiency in both filling the water basket and in hitting the desired target with the water.	
Typical Components	Platforms: Rotary-Wing Aircraft Targets: None Systems being Trained/Tested: None Munitions: None	
Active Sonar	Νο	
In-Water Explosives	Νο	
Mitigation Involving Visual Observations for Marine Species	None	
Parameters for Analysis	None	
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032	
	SOCAL (San Clemente Island)	
	Hawaii Range Complex	

A.1.11.2 At-Sea Vessel Refueling Training

Other Training Activities	
At-sea Vessel Refu	eling Training
Short Description	Crews would practice transferring fuel onto small vessels.
Long Description	Navy and USMC personnel would practice boat handling skills to maneuver the small vessels alongside a larger vessel. Fuel lines would connect to a fuel bladder or a tank on the larger vessel to a refueling point on a smaller vessel. Fuel would then be transferred through the fuel lines to the small vessel.
Typical Components	Platforms: Small Boat Targets: None Systems being Trained/Tested: None Munitions: None
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL
	Hawaii Range Complex

A.1.11.3 Combat Swimmer/Diver Training and Certification

Other Training Activities	
Combat Swimmer/	Diver Training and Certification
Short Description	Navy and Marine Corps personnel conduct combat swimming conditioning swims and surf passage to execute a variety of tasks in the open water and littoral waterways.
Long Description	Navy and Marine Corps personnel conduct combat swimming conditioning swims and surf passage to execute a variety of tasks in the open water and littoral waterways. Personnel will conduct dive training in open and closed circuit self-contained underwater breathing apparatus (SCUBA). Divers practice underwater navigation in harbors, along beaches, or moored vessels and conduct a variety of tasks. Activity may include personnel learning advanced SCUBA diving, to include tactics, techniques, and procedures and emergency procedures. Small boats and jet skis are used for safety.
Typical Components	Platforms: Small Boat
	Targets: None
	Systems being Trained/Tested: None
	Munitions: None
Active Sonar	Νο
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
Location (typical specific location where applicable)	SSTC (Boat Lanes – North and South, Echo)
	SOCAL (Del Mar Boat Basin, Camp Pendleton Amphibious Assault Area, Camp Pendleton Amphibious Vehicle Training Area)
	Hawaii Range Complex

A.1.11.4 Kilo Dip

Other Training Acti	Other Training Activities	
Kilo Dip		
Short Description	Functional check of the dipping sonar prior to conducting a full test or training event on the dipping sonar.	
Long Description	A kilo dip is the operational term used to describe a functional check of a helicopter deployed dipping sonar system. During a functional check, a single MH-60 helicopter would transit to an area designated for dipping sonar testing (i.e., a dip point usually close to shore) and would deploy the sonar transducer assembly via a reel mechanism to a predetermined depth or series of depths while the helicopter hovers over the dip point. After the check is completed, the sonar transducer assembly would be reeled in, and in some instances the helicopter would transit to a second dip point before the procedure is repeated. A kilo dip is the precursor to more comprehensive testing or training.	
Typical Components	Platforms: Rotary-Wing Aircraft	
	Targets: None	
	Systems being Trained/Tested: Dipping Sonar	
	Munitions: None	
Active Sonar	Νο	
In-Water Explosives	Νο	
Mitigation Involving Visual Observations for Marine Species	None	
Parameters for Analysis	None	
	Phase IV Requirement 2025-2032	
	NOCAL	
Location (typical	PMSR	
where applicable)	SSTC (AMCM Training Range, Imperial Beach Mine Training Range)	
	SOCAL	
	Hawaii Range Complex (BARSTUR, BSURE)	

A.1.11.5 Multi-Domain Unmanned Systems

Other Training Activities	
Multi-Domain Unm	nanned Systems
Short Description	Multi-domain (surface, subsurface, and airborne) unmanned systems are launched from land, ships, and boats, in support of intelligence, surveillance, and reconnaissance operations, when necessary, employ weapon systems or electronic warfare systems to support intelligence or warfare objectives.
Long Description	Multi-domain unmanned systems (UxS) are launched from land, ships and boats, utilizing various sensors attached to the system to support intelligence, surveillance, and reconnaissance (ISR) operations and when necessary, employ weapon systems or electronic warfare systems to support intelligence or warfare objectives. UxS include unmanned aerial vehicles (UAV), unmanned surface vessels (USV) and unmanned underwater vehicles (UUV).
Typical Components	Platforms: Unmanned Aircraft System, Small Boat, Unmanned Aerial Vehicle - Rotary Wing, Unmanned Surface Vehicle, Unmanned Underwater Vehicle
	Targets: Sub-surface Targets - Stationary, Surface Targets - Floating
	Systems being Trained/Tested: Unmanned Vehicle Systems
	Munitions: Demolition Devices
Active Sonar	VHFH, Broadband (MF to HF)
In-Water Explosives	E5, E7
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Unmanned vehicles Active acoustic sources Explosive missiles and rockets
Parameters for Analysis	In California, this activity to be conducted within San Diego harbor, as well as in coastal waters and beaches around San Diego and San Clemente Island, using air, surface, and subsurface transit corridors. Unmanned systems maneuvering and intelligence and effects training would occur around San Clemente Island with access to dry and underwater demolition ranges.
	Phase IV Requirement 2025-2032
Location (typical specific location where applicable)	SOCAL
	Hawaii Range Complex

A.1.11.6 Precision Anchoring

Other Training Acti	Other Training Activities	
Precision Anchorin	g	
Short Description	Releasing of anchors in designated locations.	
Long Description	Navy and Coast Guard ship crews choose the best available anchoring sites. The ship uses all means available to determine its position when anchor is dropped to demonstrate calculating and plotting the anchor's position within 100 yards of center of planned anchorage.	
Typical Components	Platforms: All Navy and USCG Ships and Boats	
	Targets: None	
	Systems being Trained/Tested: None	
	Munitions: None	
Active Sonar	No	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels	
Parameters for Analysis	None	
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032	
	SSTC (SSTC Anchorages)	
	Hawaii Range Complex (Naval Defense Sea Area)	

A.1.11.7 Search and Rescue

Other Training Acti	Other Training Activities	
Search and Rescue		
Short Description	Navy and Coast Guard helicopter, ship, and submarine crews practice the skills required to recover personnel lost at sea.	
Long Description	Navy and Coast Guard helicopter, ship, and submarine crews practice the skills required to recover personnel lost at sea. Helicopters locate survivors and deploy rescue swimmer and rescue basket. Survivors are winched up to the hovering helicopter. Surface ships would conduct man overboard drills and deploy a dummy figure in the water. Ship crews would launch a small boat, direct the recovery of the dummy, and recover the small boat. Submarine crews would maneuver submarine to effect recovery of personnel.	
Typical Components	Platforms: Aircraft Carrier, Amphibious Warfare Vessels, Fleet Support Craft, Patrol Combatant, Surface Combatant, Cutter Rotary-Wing Aircraft, Submarine Targets: None Systems being Trained/Tested: None Munitions: None	
Active Sonar	No	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels	
Parameters for Analysis	None	
	Phase IV Requirement 2025-2032	
Location (typical	NOCAL	
specific location where applicable)	PMSR	
	SOCAL	
	Hawaii Range Complex	

A.1.11.8 Ship-to-Shore Fuel Transfer Training

Other Training Acti	Other Training Activities	
Ship-to-Shore Fuel	Transfer Training	
Short Description	This activity trains personnel in the transfer of petroleum (though only sea water is used during training) from ship to shore.	
Long Description	Offshore petroleum discharge system training consists of five training subcomponents including the beach termination unit, operation utility boat technicians, boat coxswain, dive boat operation technician, and single anchor leg moor training. This activity trains personnel in the transfer of petroleum (though only sea water is used during training) from ship to shore. From approximately one mile offshore, technicians and underwater construction team divers roll out conduit from a ship offshore, deploy the single anchor leg mooring which sinks to and settles on the ocean floor, and use anchors at various points along the conduit to secure it to the seafloor. The conduit terminates at the shore location of the termination unit manifold. The current training at Silver Strand Training Complex consists of rolling out a four mile fluid-transfer conduit from the beach out to approximately one mile offshore, but like the current system, would still be rolled out to approximately one mile offshore, but like the current system.	
Typical Components	Platforms: Fleet Support	
	Targets: None	
	Systems being Trained/Tested: Offshore petroleum discharge system	
	Munitions: None	
Active Sonar	Νο	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels	
Parameters for Analysis		
	Phase IV Requirement 2025-2032	
Location (typical	SOCAL (San Clemente Island, CPAAA)	
specific location where applicable)	SSTC (Boat Lanes – North and South)	
	Hawaii Range Complex (Waiapuaa Bay and Beach)	

A.1.11.9 Submarine Navigation Exercise

Other Training Activities	
Submarine Navigat	ion
Short Description	Submarine crews operate sonar for navigation and detection while transiting into and out of port during reduced visibility.
Long Description	Submarine crews train to operate sonar for navigation. The ability to navigate using sonar is critical for detection while transiting into and out of port during periods of reduced visibility. During this activity the submarine will be surfaced.
Typical Components	Platforms: Submarine Targets: None Systems being Trained/Tested: Sonar Systems - Hull Mounted Munitions: None
Active Sonar	MFH, HFH
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL
	Hawaii Range Complex (Naval Defense Sea Area, Pearl Harbor)

A.1.11.10 Submarine Sonar Maintenance and Systems Checks

Other Training Activities	
Submarine Sonar N	Naintenance and Systems Checks
Short Description	Maintenance of submarine sonar and other system checks are conducted pierside or at sea.
Long Description	A submarine performs periodic maintenance on the AN/BQQ-10 sonar systems while in port or at sea. Submarines conduct maintenance to their sonar systems in shallow water near their homeport, however, sonar maintenance could occur anywhere as the system's performance may warrant.
Typical Components	Platforms: Submarine Targets: None Systems being Trained/Tested: Sonar Systems - Hull Mounted, Sonar Systems - Other Munitions: None
Active Sonar	MFH
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels
Parameters for Analysis	
	Phase IV Requirement 2025-2032
	PMSR
Location (typical specific location where applicable)	SOCAL
	Hawaii Range Complex (Pearl Harbor)
	Transit Corridor

A.1.11.11 Submarine Under Ice Training and Certification

Other Training Acti	vities
Submarine Under I	ce Training and Certification
Short Description	Submarine crews operate sonar while transiting under ice. Ice conditions are simulated during training and certification events.
Long Description	Submarine crews train to operate under ice. Ice conditions are simulated during training and certification exercises. A single exercise is comprised of 30 hours of training, spread out over 5 days in 6-hour training sessions.
Typical Components	Platforms: Submarine Targets: None Systems being Trained/Tested: Sonar Systems - Hull Mounted Munitions: None
Active Sonar	HFH
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL
	Hawaii Range Complex

A.1.11.12 Submarine and UUV Subsea and Seabed Warfare Exercise

Other Training Acti	vities
Submarine and UU	V Subsea and Seabed Warfare Exercise
Short Description	Submarine crews and shore-based operators train to launch or recover and operate all classes of UUVs in the subsea and seabed environment in order to defend deep ocean and seabed infrastructure or take offensive action against a simulated adversary's subsea and seabed infrastructure.
Long Description	Submarine crews and shore-based operators train to launch and/or recover and operate all classes of UUVs in the subsea and seabed environment in order to defend deep ocean and seabed infrastructure or take offensive action against a simulated adversary's subsea and seabed infrastructure. The UUV using on board sensors locates the targets and potentially employs non-kinetic effectors against the targets and/or deploys acoustic and non-acoustic sensors. ROV may be employed.
	XL, L, M and some SUUVs will be recovered during or post exercise. Some deployable non- kinetic effectors and acoustic and non-acoustic sensors may be recovered post exercise.
Typical Components	Platforms: Submarine, Unmanned Underwater Vehicle Targets: Seabed Targets Systems being Trained/Tested: Unmanned Vehicle Systems Munitions: Demolition Devices, Projectile - Medium Caliber
Active Sonar	VHFH
In-Water Explosives	E3
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Explosive gunnery
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
Location (typical	NOCAL
specific location where applicable)	PMSR
	SOCAL
	Hawaii Range Complex

A.1.11.13 Surface Ship Sonar Maintenance and Systems Checks

Other Training Acti	Other Training Activities	
Surface Ship Sonar	Maintenance and Systems Checks	
Short Description	Maintenance of surface ship sonar and other system checks are conducted pierside or at sea.	
Long Description	This scenario consists of surface ships performing periodic maintenance to sonar and other ship systems while in port or at sea. This maintenance takes up to 4 hours. Surface ships operate active sonar systems for maintenance while in shallow water near their homeport, however, sonar maintenance could occur anywhere as the system's performance may warrant.	
Typical Components	Platforms: Surface Combatant Targets: None Systems being Trained/Tested: Sonar Systems - Hull Mounted Munitions: None	
Active Sonar	MF1K, MF1, MFH, HFH	
In-Water Explosives	Νο	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels	
Parameters for Analysis		
	Phase IV Requirement 2025-2032	
	SOCAL	
Location (typical specific location	Naval Base San Diego	
where applicable)	Hawaii Range Complex (Pearl Harbor)	
	Transit Corridor	

A.1.11.14 Training and End-to-End Mission Capability Verification – Subsea and Seabed Warfare Kinetic Effectors

Other Training Acti	vities
Training and End-to Effectors	o-End Mission Capability Verification – Subsea and Seabed Warfare Kinetic
Short Description	Submarine crews or shore-based operators employ UUV with munitions or non-munition systems on the sea floor or in the water column.
Long Description	Submarine crews and shore-based operators train to launch and/or recover and operate all classes of UUVs in the subsea and seabed environment in order to take offensive action against a simulated adversary's subsea and seabed infrastructure. Submarine crews or shore-based operators employ UUVs kinetic effectors on the sea floor or in the water column. The kinetic effector is subsequently detonated. ROVs may be employed.
Typical Components	Platforms: Unmanned Underwater Vehicle, Remotely Operated Vehicles Targets: Seabed Targets Systems being Trained/Tested: None Munitions: Projectile - Large Caliber
Active Sonar	Νο
In-Water Explosives	E3
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Explosive gunnery Unmanned vehicles
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
Location (typical	NOCAL
specific location where applicable)	PMSR
	SOCAL
	Hawaii Range Complex

A.1.11.15 Training and End-to-End Mission Capability Verification – UAV

Other Training Activities	
Training and End-to	p-End Mission Capability Verification – UAV
Short Description	Submarine crews or shore-based personnel controlling a UUV launch a capsule containing a UAV. The canister is deployed underwater and ascends to a programmed depth. The canister subsequently launches a UAV, and the canister sinks.
Long Description	Submarine crews or shore-based personnel controlling a UUV launch a negatively buoyant capsule containing a UAV. The canister is deployed underwater and subsequently launches a UAV and the canister sinks. Radio frequency communications are used to control and communicate with the UAV. The UAV's explosive charge would be remotely actuated or on impact with the target. During an exercise the submarine or UUV launches 2 to 4 UAVs.
Typical Components	Platforms: Submarine, Unmanned Aircraft System, Unmanned Underwater Vehicle
	Targets: Surface Targets - Floating
	Systems being Trained/Tested: None
	Munitions: Projectile – Large Caliber
Active Sonar	No
In-Water Explosives	E3
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Explosive missiles and rockets Unmanned vehicles
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
Location (typical	NOCAL
specific location where applicable)	PMSR
	SOCAL
	Hawaii Range Complex

A.1.11.16 Underwater Survey

Other Training Acti	vities
Underwater Survey	/
Short Description	Navy divers train in survey of underwater conditions and features in preparation for insertion, extraction, or intelligence, surveillance, and reconnaissance activities.
Long Description	A survey of underwater terrain conditions nearshore and a report of findings to provide precise analysis for amphibious landings. Personnel perform methodical reconnoitering of beaches and surf conditions during the day and night to find and clear underwater obstacles and determine the feasibility of landing an amphibious force on a particular beach.
Typical Components	Platforms: Small Boat
	Targets: None
	Systems being Trained/Tested: None
	Munitions: None
Active Sonar	Νο
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
	SSTC (Boat Lanes – North and South)
Location (typical specific location	SOCAL (TAR 2, Del Mar Boat Basin)
where applicable)	Amphibious Corridors 1-4
	Hawaii Range Complex (Marine Corps Training Area Bellows, Waiapuaa Bay and Beach)

A.1.11.17 Unmanned Aerial System Training

Other Training Acti	vities
Unmanned Aerial S	System Training
Short Description	Surface ships and submarines launch unmanned aerial systems to conduct intelligence, surveillance, and reconnaissance (ISR) missions.
Long Description	Navy, Marine Corps, and Coast Guard forces deploy unmanned aerial vehicles (UAVs) from surface ships, submarines, and ashore locations to conduct ISR. These UAVs are typically recovered, with flight times lasting from 1-8 hours. Personnel use radio frequency communications to control and communicate with the unmanned aerial system during its flight. For submarine launched UAVs, a negatively buoyant capsule is deployed underwater and descends to a programmed depth. The capsule then drops a weight, inflates a flotation collar, rises to the surface, and launches an unmanned aerial system. Submarine launched UAVs are not typically recovered.
Typical Components	 Platforms: Amphibious Warfare Vessel, Cutter, Submarine, Surface Combatant, Unmanned Aerial Vehicle - Fixed Wing Targets: None Systems being Trained/Tested: Unmanned Systems Munitions: None
Active Sonar	Νο
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	
	Phase IV Requirement 2025-2032
	SOCAL
Location (typical	PMSR
where applicable)	NOCAL
	Hawaii Range Complex
	Transit Corridor

A.1.11.18 Unmanned Underwater Vehicle Training – Certification and Development Exercises

Other Training Acti	Other Training Activities	
Unmanned Underv	vater Vehicle Training – Certification and Development Exercises	
Short Description	Unmanned underwater vehicle certification involves training with unmanned platforms to ensure submarine crew proficiency. Tactical development involves training with various payloads, for multiple purposes to ensure that the systems can be employed effectively in an operational environment.	
Long Description	Unmanned underwater vehicle certification and tactical development involves the training with unmanned platforms on which various payloads are attached and used for different purposes. Unmanned underwater vehicles may be deployed by surface ships and Coast Guard cutters, small boats, submarines, aircraft, and target support vessels. Payload certification and development training assesses various systems that can be incorporated onto unmanned platforms for mine warfare, bottom mapping, and other missions. Training can range from basic remote control and autonomous navigation tests to deployment and activation of onboard systems which may include hydrodynamic instruments, launchers, and recovery capabilities. These vehicles are capable of expanding the communication and surveillance capabilities of submarines, and terrestrial commands.	
Typical Components	 Platforms: Small Boat, Cutter, Submarine, Rotary-Wing Aircraft, Fixed-Wing Aircraft, Unmanned Underwater Vehicle Targets: Mine Targets, Sub-surface Targets - Stationary Systems being Trained/Tested: Acoustic Communications, Sonar Systems - Other, Unmanned Vehicle Systems Munitions: None 	
Active Sonar	HFM, VHFH, Broadband (MF to HF)	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Unmanned vehicles	
Parameters for Analysis	None	
	Phase IV Requirement 2025-2032	
	NOCAL	
Location (typical	SSTC (Boat Lanes – North and South)	
where applicable)	SOCAL (San Clemente Island)	
	PMSR	
	Hawaii Range Complex	

A.1.11.19 Waterborne Training

Other Training Acti	Other Training Activities	
Waterborne Traini	ng	
Short Description	Small boat crews conduct a variety of training, including boat launch and recovery, operation of crew-served unmanned vehicles, mooring to buoys, anchoring, and maneuvering. Small boats include rigid hull inflatable boats, and riverine patrol, assault, and command boats up to approximately 50 feet in length.	
Long Description	Waterborne Training includes qualification and certification as safety observer, safety swimmer, coxswain, and crewman utilizing a variety of Navy and Coast Guard small crafts. These craft include, but are not limited, to rigid hull inflatables, aluminum chambered boats, patrol boats, stand-up paddleboards, kayaks, and jet skis. Small boat crews train to launch and recover, moor to buoys, anchor, and operate a variety of missions in shallow waters.	
Typical Components	Platforms: Small Boat	
	Targets: None	
	Systems being Trained/Tested: None	
	Munitions: None	
Active Sonar	No	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels	
Parameters for Analysis	None	
	Phase IV Requirement 2025-2032	
	SOCAL	
Location (typical	NOCAL	
where applicable)	PMSR	
	SSTC (Boat Lanes – North and South)	
	Hawaii Range Complex (Pearl Harbor)	

A.2 Testing Activities

A.2.1 Naval Air Systems Command Testing Activities

Naval Air Systems Command activities will generally fall under fleet primary mission areas, such as the testing of airborne mine warfare and anti-submarine warfare weapons and systems. Naval Air Systems Command activities include, but are not limited to, the testing of new aircraft platforms, weapons, and systems that will ultimately be integrated into fleet training activities. In addition to testing new platforms, weapons, and systems, Naval Air Systems Command also conducts lot acceptance testing of sonobuoys and follow-on testing and evaluation of updated systems in support of fleet operational units. In general, the potential environmental effects from most Naval Air Systems Command testing events are similar to the associated fleet training events.

While many of these systems tested by Naval Air Systems Command will ultimately be used by the fleet, testing activities involving the same or similar systems may be conducted in different locations and manners than when conducted by the fleet. Because of these differences, the results of the analysis for testing activities may differ from the results for training activities.

A.2.1.1 Air Warfare

Testing of air warfare systems is required to ensure the equipment is fully functional under the conditions in which it will be used. Tests may be conducted on radar and other early-warning detection and tracking systems, new guns or gun projectiles, and missiles. Testing of these systems may be conducted on new ships and aircraft, and on existing ships and aircraft following maintenance, repair, or modification. For some systems, tests are conducted periodically to assess operability. Additionally, tests may be conducted in support of scientific research to assess new and emerging technologies.

Air Warfare	
Large Force Test Event	
Short Description	U.S. Navy led Large Force Test Event focused on Interoperability Testing and Tactics of Near-Future capabilities in a Maritime environment across the DoD's Air, Sea, and Space domains.
Long Description	U.S. Navy led Large Force Test Event focused on Interoperability Testing and Tactics of Near-Future capabilities in a Maritime environment across the DoD's Air, Sea, and Space domains. Large Force Test Events provide cross service participants with fleet- aligned mission scenarios, robust Blue Air tactics, and Red Air presentations that allow for data driven assessment at the engineering, tactical and operational level.
Typical Components	Platforms: Fixed Wing – Patrol Aircraft, Support Craft Targets: Surface Targets Systems being Trained/Tested: Electronic Warfare Systems Munitions: None
Active Sonar	Νο
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	None
Parameters for Analysis	None
Location (typical specific	Phase IV Requirement 2025-2032
location where applicable)	California Study Area

A.2.1.1.1 Large Force Test Event

A.2.1.1.2 Air Combat Maneuvers Test

Air Warfare	
Air Combat Maneu	vers Test
Short Description	Aircrews engage in flight maneuvers designed to gain a tactical advantage during combat. Fixed-wing aircrews aggressively maneuver against threat aircraft to gain tactical advantage.
Long Description	Air combat maneuver is the general term used to describe an air-to-air test event involving two or more aircraft, each engaged in continuous proactive and reactive changes in aircraft attitude, altitude, and airspeed.
Typical Components	 Platforms: Fixed Wing – Other Aircraft, Fixed Wing – Strike Aircraft Targets: Air Targets - Decoy, Air Targets - Drone Systems being Trained/Tested: None Munitions: Projectile - Medium Caliber
Active Sonar	Νο
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	None
Parameters for Analysis	Includes explosive bins at medium altitudes. Chaff and flare expenditures are captured under Chaff Test and Flare Test, respectively.
	Phase IV Requirement 2025-2032
Location (typical specific areas where applicable)	California Study Area
	Hawaii Study Area

A.2.1.1.3 Air Platform Vehicle Test

Air Warfare		
Air Platform Vehicl	Air Platform Vehicle Test	
Short Description	Testing performed to quantify the flying qualities, handling, airworthiness, stability, controllability, and integrity of an air platform or vehicle. No explosive weapons are released during an air platform/vehicle test.	
Long Description	The air platform/vehicle test describes the testing performed to quantify the flying qualities, handling, airworthiness, stability, controllability, and integrity of an air platform/vehicle. Integration of non-weapons system including aerial refueling tests are also conducted as part of an air platform/vehicle test. Test results are compared against design and performance specifications for compliance. The test results are also used to define stability and controllability characteristics and limitations and to improve and update existing analytical and predictive models. A wide variety of fixed-wing and rotary-wing aircraft, including unmanned aerial systems could undergo air platform/vehicle testing. No weapons are released during an Air Platform/Vehicle Test. Aircraft may employ laser detection for targeting systems and trailing antenna. Events may involve two or more fighter jet aircraft and a towed target tractor by a contracted aircraft (e.g., Learjet for laser targeting tests).	
Typical Components	Platforms: Fixed Wing - Command and Control Aircraft	
	Targets: None	
	Systems being Trained/Tested: Aircraft Platform/Vehicle	
	Munitions: None	
Active Sonar	Νο	
In-Water Explosives	Νο	
Mitigation Involving Visual Observations for Marine Species	None	
Parameters for Analysis	None	
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032	
	California Study Area	
	Hawaii Study Area	

A.2.1.1.4 Air Platform Weapons Integration Test

Air Warfare		
Air Platform Weap	Air Platform Weapons Integration Test	
Short Description	Testing performed to quantify the compatibility of weapons with the aircraft from which they would be launched or released. Non-explosive weapons or shapes are used.	
Long Description	The air platform weapons integration test describes the testing performed to quantify the compatibility of weapons with the aircraft from which they would be released. Tests evaluate the compatibility of the weapon and its carriage, suspension, and launch equipment with the performance and handling characteristics of the designated aircraft. Additional tests assess the ability of the weapon to separate or launch safely from the aircraft at combat velocities, including at supersonic speeds. Test results are compared against design specifications for compliance. The test results are also used to define performance characteristics and to improve and update existing analytical and predictive models.	
Typical Components	Platforms: Fixed Wing – Other Aircraft, Fixed Wing – Strike Aircraft Targets: Air Targets - Drone, Surface Targets - Maneuvering Systems being Trained/Tested: Air Platform/Vehicle, Air Weapons Systems Munitions: Air-to-Air Missiles, Air-to-Surface Missiles, Bombs	
Active Sonar	No	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Non-explosive aerial-deployed mines and bombs Non-explosive missiles and rockets	
Parameters for Analysis	None	
Location (typical	Phase IV Requirement 2025-2032	
specific location where applicable)	California Study Area	
	Hawaii Study Area	

A.2.1.1.5 Air-to-Air Missile Test

Air Warfare	
Air-to-Air Missile T	est
Short Description	Test is performed to evaluate the effectiveness of air-launched missiles against designated airborne targets. Fixed-wing aircraft will be used.
Long Description	These tests are a type of air-to-air weapons system test in which air-to-air missiles (non- explosive or in-air explosive) are fired from fixed-wing aircraft against unmanned aerial drones.
Typical Components	 Platforms: Fixed Wing – Strike Aircraft Targets: Air Targets – Drone, Surface Targets - Maneuvering Systems being Trained/Tested: Missile Delivery Systems Munitions: Air-to-Air Missiles
Active Sonar	No
In-Water Explosives	E7
Mitigation Involving Visual Observations for Marine Species	None
Parameters for Analysis	Includes explosive bins at medium altitudes. This activity may occur anywhere within the California Study Area, but is also known to occur within PMSR.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	California Study Area (PMSR)

A.2.1.1.6 Surface-to-Air Gunnery Test – Large Caliber

Air Warfare	
Surface-to-Air Gun	nery Test – Large Caliber
Short Description	Surface ship crews fire large-caliber guns at air targets.
Long Description	Surface ship crews defend against threat aircraft or missiles with large-caliber guns to disable or destroy the threat. An exercise involves one ship and a simulated threat aircraft or missile that is detected by the ship's radar. Large-caliber guns fire projectiles at the threat before it reaches the ship. The target is towed by a contract air services jet.
Typical Components	Platforms: Surface Combatant Targets: Air Targets - Decoy, Air Targets - Drone Systems being Trained/Tested: Weapons Systems Munitions: Projectile - Large Caliber
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	Includes explosive bins at medium altitudes. This activity may occur anywhere within the California Study Area, but is also known to occur within PMSR.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	California Study Area (PMSR)

A.2.1.1.7 Surface-to-Air Gunnery Test – Medium Caliber

Air Warfare	
Surface-to-Air Gun	nery Test - Medium Caliber
Short Description	Surface ship crews fire medium-caliber guns at air targets.
Long Description	Surface ship crews defend against threat aircraft or missiles with medium-caliber guns to disable or destroy the threat. An exercise involves one ship and a simulated threat aircraft or anti-ship missile that is detected by the ship's radar. Medium-caliber guns fire projectiles to disable or destroy the threat before it reaches the ship. The target is towed by a contract air services jet.
Typical Components	Platforms: Surface Combatant
	Targets: Air Targets - Decoy, Air Targets - Drone
	Systems being Trained/Tested: Weapons Systems
	Munitions: Projectile - Medium Caliber
Active Sonar	Νο
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	Includes explosive bins at medium altitudes. This activity may occur anywhere within the California Study Area, but is also known to occur within PMSR.
Location (typical	Phase IV Requirement 2025-2032
specific location where applicable)	California Study Area (PMSR)

A.2.1.1.8 Intelligence, Surveillance, and Reconnaissance Test

Air Warfare	
Intelligence, Survei	illance, and Reconnaissance Test
Short Description	Aircrews use all available sensors to collect data on threat vessels.
Long Description	An air warfare intelligence, surveillance, and reconnaissance (ISR) test involves evaluating communications capabilities of aircraft, including unmanned aerial systems that can carry cameras, sensors, communications equipment, or other payloads. New systems are tested at sea to ensure proper communications between aircraft and ships. ISR aircraft systems act as eyes in the sky, relaying raw imagery back to military personnel on the ground or to ships at-sea. The data is processed, analyzed, and shared with U.S. Navy or other U.S. military aircraft or vessels. New ISR technology systems provide combat identification (friend or foe) and are used for aircraft and ship-based communications.
Typical Components	 Platforms: Fixed Wing - Command and Control Aircraft, Unmanned Aerial Vehicle - Fixed Wing Aircraft Targets: Air Targets - Drone Systems being Trained/Tested: Communication Systems, Unmanned Vehicle Systems Munitions: None
Active Sonar	Νο
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	None
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	California Study Area
	Hawaii Study Area

A.2.1.1.9 Surface-to-Air Missile Test

Air Warfare	
Surface-to-Air Miss	ile Test
Short Description	Surface ship crews defend against threat missiles and aircraft with missiles.
Long Description	Surface ship crews defend against threat missiles and aircraft with ship-launched surface- to-air missiles. The exercise involves an aerial target that simulates a threat aircraft, anti- ship missile, or land attack missile, which is detected by the ship's radar. Ship-launched surface-to-air missiles are fired to disable or destroy the threat. The target typically is either a sub-sonic remote-controlled drone or a supersonic target. Target drones deploy parachutes and are recovered by small boat or rotary-wing aircraft. Supersonic targets are not recovered.
Typical Components	Platforms: Surface Combatant Targets: Air Targets - Drone, Surface Targets - Maneuvering Systems being Trained/Tested: Weapons Systems Munitions: Surface-to-Air Missiles
Active Sonar	No
In-Water Explosives	E8
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Explosive missiles and rockets Non-explosive missiles and rockets
Parameters for Analysis	Includes explosive bins at high, medium altitudes. This activity may occur anywhere within the California Study Area, but is also known to occur within PMSR.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	California Study Area (PMSR)

A.2.1.1.10 Surface-to-Air High-Energy Laser Test

Air Warfare	
Surface-to-Air High	-Energy Laser Test
Short Description	High-energy laser tests would evaluate the specifications, integration, and performance of an aircraft mounted, approximately 25-kilowatt high-energy laser. The laser is intended to be used as a weapon to disable small surface vessels.
Long Description	During a Surface-to-Air High-Energy Laser Test, aircrew evaluate the specifications, integration, and performance of an aircraft mounted, approximately 25 kilowatt high- energy laser that is intended to be used as a weapon against stationary and mobile, unmanned surface targets. The high-energy laser would be employed from a rotary-wing aircraft and is designed to disable the surface vessel, rendering it immobile. The high- energy laser would have a range of up to six kilometers.
Tunical Components	
Typical components	Platforms: Fixed Structure, Surface Combatant
	Targets: Air Targets - Drone, Surface Targets - Floating, Surface Targets - Maneuvering
	Systems being Trained/Tested: High-Energy Laser System
	Munitions: None
Active Sonar	No
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	This activity may occur anywhere within the California Study Area, but is also known to occur within PMSR.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	California Study Area (PMSR)
A.2.1.1.11 Surface-to-Air High-Power Microwave Test

Air Warfare	Air Warfare	
Surface-to-Air High	-Power Microwave Test	
Short Description	During a High-Power Microwave Test, energy is directed from a ship or land-based system to engage air targets.	
Long Description	Pulsed-wave high-power microwave systems convert electrical or chemical energy into radiated energy and deliver high-power, short bursts of radiofrequency energy to neutralize a target. High-power microwave systems operate within a wide range of frequencies, from 1 megahertz to 100 gigahertz, and transmit energy to a target to degrade or destroy electrical components in the target. During a Surface-to-Air High-Power Microwave Test energy is directed from a ship or land-based system to engage air targets. Initial land-based tests in the maritime environment will yield decisive experience before installation of high-power microwave systems on a ships.	
Typical Components	Platforms: Surface Combatant Targets: Air Targets - Drone Systems being Trained/Tested: High-Power Microwave System Munitions: None	
Active Sonar	No	
In-Water Explosives	Νο	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels	
Parameters for Analysis	This activity may occur anywhere within the California Study Area, but is also known to occur within PMSR.	
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032	
	California Study Area (PMSR)	

A.2.1.2 Anti-Submarine Warfare

Testing of anti-submarine warfare systems is conducted to develop new technologies and assess weapon performance and operability with new systems and platforms, such as unmanned systems. Testing uses ships, submarines, and aircraft to demonstrate capabilities of torpedoes, missiles, countermeasure systems, and underwater surveillance and communications systems. Tests may be conducted as part of a large-scale fleet training event involving submarines, ships, fixed-wing aircraft, and helicopters. These integrated training events offer opportunities to conduct research and acquisition activities and to train aircrew in the use of new or newly enhanced systems during a large-scale, complex exercise.

A.2.1.2.1 Anti-Submarine Warfare Torpedo Test (Aircraft)

Anti-Submarine Wa	arfare
Anti-Submarine Wa	arfare Torpedo Test (Aircraft)
Short Description	Test evaluates anti-submarine warfare systems onboard rotary-wing and fixed-wing aircraft and the ability to search for, detect, classify, localize, track, and attack a submarine or similar target.
Long Description	An anti-submarine warfare torpedo test evaluates anti-submarine warfare systems onboard rotary-wing and fixed-wing aircraft and the ability to search for, detect, classify, localize, track, and attack a submarine or similar target. Both sonobuoys and torpedoes (using the High Altitude Anti-Submarine Warfare Weapon Capability kit) may be delivered at high altitudes to remain clear of high threat areas. The focus of the anti-submarine warfare torpedo test is the operation of non-explosive torpedoes, but other anti- submarine warfare systems are often used during the test. Targets simulate a submarine threat and are deployed at varying depths and speeds. If available, tests may be conducted using an actual submarine as the target. This activity can be conducted in shallow or deep waters and aircraft can originate from a land base or from a surface ship. The torpedo test culminates with the release of an exercise torpedo against the target and is intended to evaluate the targeting, release, and tracking process of deploying torpedoes from aircraft. All exercise torpedoes used in testing are either running (EXTORP) or non-running (REXTORP) and are non-explosive. Eighty-five percent of torpedoes are recovered. A parachute assembly used for aircraft-launched torpedoes is jettisoned and sinks. Ballast (typically lead weights) may be released from the torpedoes to allow for recovery, leaving the ballast to sink to the bottom.
Typical Components	Platforms: Rotary-Wing Aircraft, Fixed Wing – Patrol Aircraft
	Targets: Sub-surface Targets - Maneuvering
	Systems being Trained/Tested: Sonar Systems - Dipping, Sonobuoys
	Munitions: Torpedoes - Exercise
Active Sonar	MFM, MFH, HFH
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources
Parameters for Analysis	Assume one torpedo accessory package (parachute, ballast) per torpedo. Assume one target per torpedo.
Location (typical	Phase IV Requirement 2025-2032
specific location where applicable)	California Study Area
	Hawaii Study Area

A.2.1.2.2 Anti-Submarine Warfare Tracking Test – Rotary-Wing

Anti-Submarine Warfare		
Anti-Submarine Wa	Anti-Submarine Warfare Tracking Test -Rotary-Wing	
Short Description	The test evaluates the sensors and systems used to detect and track submarines and to ensure that rotary-wing aircraft systems used to deploy the tracking systems perform to specifications.	
Long Description	An Anti-Submarine Warfare Tracking Test — Rotary-Wing evaluates the sensors and systems used to detect and track submarines and to ensure that platform systems used to deploy the tracking systems perform to specifications. Targets may also be employed during an anti-submarine warfare tracking test event. If available, tests may be conducted using an actual submarine as the target. This activity would be conducted in shallow or deep waters and could initiate from a land base or from a surface ship. Rotary-Wing Anti-Submarine Warfare tests are intended to evaluate the sensors and systems used to detect and track submarines and to ensure that platform systems used to detect as perform to specifications. Some anti-submarine rotary-wing tracking tests could be conducted as part of an anti-submarine tracking coordinated event with fleet training activities.	
Typical Components	Platforms: Rotary-Wing Aircraft Targets: Sub-surface Targets - Maneuvering Systems being Trained/Tested: Sonar Systems - Dipping, Sonobuoys Munitions: None	
Active Sonar	MFM, MFH	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels	
Parameters for Analysis		
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032	
	California Study Area	
	Hawaii Study Area	

Anti-Submarine Wa	Anti-Submarine Warfare	
Anti-Submarine Warfare Tracking Test - Fixed-Wing		
Short Description	The test evaluates the sensors and systems used by fixed-wing aircraft to detect and track submarines and to ensure that aircraft systems used to deploy the tracking systems perform to specifications and meet operational requirements.	
Long Description	An anti-submarine warfare tracking test—Fixed-Wing evaluates the sensors and systems used to detect and track submarines and to ensure that platform systems used to deploy the tracking systems perform to specifications and meet operational requirements. Targets may also be employed during an anti-submarine warfare scenario. If available, tests may be conducted using an actual submarine deploy the tracking systems perform to specifications and meet operational requirements. Targets may also be employed during an anti-submarine warfare scenario. If available, tests may be conducted using an actual submarine as the target. This activity would be conducted in deep (typically beyond 100 feet) waters. Some anti-submarine warfare fixed-wing aircraft tracking tests could be conducted as part of a coordinated event with fleet training activities.	
Typical Components	Platforms: Fixed Wing – Patrol Aircraft	
	Targets: Sub-surface Targets - Maneuvering	
	Systems being Trained/Tested: Sonobuoys	
	Munitions: None	
Active Sonar	LFM, LFH, MFM, HFM	
In-Water Explosives	Νο	
Mitigation Involving Visual Observations	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation):	
for Marine Species	Active acoustic sources	
Parameters for Analysis	None	
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032	
	California Study Area	
	Hawaii Study Area	

A.2.1.2.3 Anti-Submarine Warfare Tracking Test – Fixed-Wing

A.2.1.2.4 Kilo Dip Test

Anti-Submarine Warfare	
Kilo Dip Test	
Short Description	Functional check of a rotary-wing aircraft deployed dipping sonar system prior to conducting a testing or training event using the dipping sonar system.
Long Description	A kilo dip is the operational term used to describe a functional check of a rotary-wing aircraft deployed dipping sonar system. During a functional check, a single rotary-wing aircraft would deploy the sonar transducer assembly via a reel mechanism to a predetermined depth or series of depths while the rotary-wing aircraft hovers over the dip point. Once at the desired depth, the sonar transducer would be activated and would briefly transmit a pulsed, acoustic signal (i.e., ping) to check that all systems are functioning properly. After the check is completed, the sonar transducer assembly would be reeled in, and in some instances the rotary-wing aircraft would transit to a second dip point before the procedure is repeated. A kilo dip is a precursor to more comprehensive testing.
Typical Components	Platforms: Rotary-Wing Aircraft Targets: None Systems being Trained/Tested: Sonar Systems - Dipping Munitions: None
Active Sonar	MFH
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	California Study Area
	Hawaii Study Area

A.2.1.2.5 Sonobuoy Lot Acceptance Test

Anti-Submarine Warfare	
Sonobuoy Lot Acce	ptance Test
Short Description	Sonobuoys are deployed from surface vessels and aircraft to verify the integrity and performance of a lot or group of sonobuoys in advance of delivery to the fleet for operational use.
Long Description	Sonobuoys are deployed from surface vessels and aircraft to verify the integrity and performance of a lot or group of sonobuoys in advance of delivery to the fleet for operational use. Lot acceptance testing would occur for multiple types of sonobuoys which may include non-impulsive or explosive.
Typical Components	Platforms: Support Vessels, Fixed Wing – Other Aircraft
	Targets: None
	Systems being Trained/Tested: Sonobuoys
	Munitions: None
Active Sonar	LFM, LFH, MFM, HFM
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels
Parameters for Analysis	Assume one parachute per sonobuoy
Location (typical	Phase IV Requirement 2025-2032
specific location where applicable)	California Study Area
	Hawaii Study Area

A.2.1.3 Electronic Warfare

Testing of electronic warfare systems is conducted to improve the capabilities of systems and ensure compatibility with new systems. Testing involves the use of aircraft, surface ships, and submarine crews to evaluate the effectiveness of electronic systems. Similar to training activities, typical electronic warfare testing activities include the use of airborne and surface electronic jamming devices (including testing chaff and flares) to defeat tracking and communications systems. Chaff tests evaluate newly developed or enhanced chaff, chaff dispensing equipment, or modified aircraft systems' use against chaff deployment. Flare tests evaluate deployment performance and crew competency with newly developed or enhanced flares, flare dispensing equipment, or modified aircraft systems' use against flare deployment.

A.2.1.3.1 Chaff Test

Electronic Warfare	
Chaff Test	
Short Description	Chaff tests evaluate newly developed or enhanced chaff, chaff dispensing equipment, or modified aircraft systems against chaff deployment. Tests may also train pilots and aircrews in the use of new chaff dispensing equipment. Chaff tests are often conducted with flare tests and air combat maneuver events, as well as other test events, and are not typically conducted as standalone tests.
Long Description	Chaff tests are conducted to evaluate newly developed or enhanced chaff dispensing equipment, to ensure other newly developed or modified aircraft systems are compatible with chaff deployment, and to train pilots and aircrew in the use of new chaff dispensing equipment. Fixed-wing, rotary-wing, and tiltrotor aircraft deploy chaff to disrupt threat targeting and missile guidance radars and to defend against an attack (Electronic Protect deployment). Chaff tests are often conducted with flare tests or air combat maneuver events, as well as other tests, rather than as a standalone test. Weapons are not typically fired during chaff tests. Chaff is employed for a number of different tactical reasons, but the end goal is to create a target that will distract enemy radar and weapon systems away from the friendly platform. Chaff may also be employed offensively (Electronic Attack deployment), such as before a major strike to "hide" inbound striking aircraft. Different chaff types are used by a variety of different Navy aircraft; however, all chaff consists of a radar reflector material made of thin, narrow, metallic strips cut in various lengths, and is intended to elicit frequency responses which deceive enemy radars. Defensive chaff tests are the most common type of chaff test. In most cases, the chaff test is conducted to evaluate systems on the aircraft deploying the chaff, but it is also critical to view the effect of the chaff from the "enemy" perspective so that radar system operators may practice corrective procedures to overcome the chaff jamming effect. Chaff tests are often designed to gain experience and data from both perspectives. Chaff is typically deployed from an aircraft as the aircraft makes evasive maneuvers to defeat a simulated threat missile or threat aircraft. The chaff deploys in a cloud of the highly reflective filaments and deceives the guidance system of an inbound missile, allowing the aircraft to escape the threat.
Typical Components	 Platforms: Fixed Wing - Electronic Warfare Aircraft, Rotary-Wing Aircraft, Tiltrotor Aircraft Targets: None Systems being Trained/Tested: Chaff systems Munitions: None
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	None
Parameters for Analysis	Chaff emissions during testing primarily occur 3 NM or more from shore and are only released when wind conditions will carry the emissions away from shore.

Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	California Study Area
	Hawaii Study Area

A.2.1.3.2 Electronic Systems Test

Electronic Warfare	
Electronic Systems	Test
Short Description	Test that evaluates the effectiveness of electronic systems to control, deny, or monitor critical portions of the electromagnetic spectrum. In general, electronic warfare testing will assess the performance of three types of electronic warfare systems: electronic attack, electronic protect, and electronic support.
Long Description	Electronic systems evaluations are performed to determine the effectiveness of designated electronic warfare systems to control, deny, or monitor critical portions of the electromagnetic spectrum. In general, electronic warfare testing will assess the performance of three types of electronic warfare systems; specifically, electronic attack, electronic protect, and electronic support. Aircraft electronic attack systems are designed to confuse the enemy or deny the enemy the use of its electronically-targeted weapons systems. The suppression of enemy air defenses and active jamming against hostile aircraft and surface combatant radars are examples of the application of electronic attack. Aircraft electronic protect systems are designed to intercept, identify, categorize, and defeat threat weapons systems that are already targeting that or other friendly aircraft. Aircraft electronic support systems employ passive tactics to intercept, exploit, locate (target), collect, collate, and decipher information from the radio frequency spectrum for the purpose of determining the intentions of the radiating source. Test results are compared against design specifications to evaluate the performance of the actually electronic warfare system. The test results are also used to define performance characteristics and to improve and update existing analytical and predictive models.
Typical Components	Platforms: Fixed Wing - Command and Control Aircraft
	Targets: Air Targets - Drone
	Systems being Trained/Tested: Electronic systems Munitions: None
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	None
Parameters for Analysis	All chaff and flare expenditure is captured under Chaff Test and Flare Test, respectively
	Phase IV Requirement 2025-2032
Location (typical	California Study Area
where applicable)	Hawaii Study Area

A.2.1.3.3 Flare Test

Electronic Warfare	
Flare Test	
Short Description	Flare tests evaluate newly developed or enhanced flares, flare dispensing equipment, or modified aircraft systems against flare deployment. Tests may also train pilots and aircrew in the use of newly developed or modified flare deployment systems. Flare tests are often conducted with chaff tests and air combat maneuver events, as well as other test events, and are not typically conducted as standalone tests.
Long Description	Flare tests are conducted to evaluate new flares, newly developed or modified flare deployment systems, to ensure that other newly enhanced aircraft systems are compatible with flare deployment, and to train pilots and aircrew in the use of newly developed or modified flare deployment systems. Flare tests are often conducted with chaff tests and air combat maneuver events, as well as other test events, and are not typically conducted as stand-alone tests. During a flare test, flares (and in some cases chaff) are deployed, but no weapons are typically fired. Flare dispensers may also be jettisoned during a flare test intended to assess the safe release of the dispenser in the event of an emergency. Rotary-wing and tiltrotor aircraft deploy flares as a defensive tactic (electronic protect deployment) to disrupt the infrared missile guidance systems used by heat-seeking missiles, thereby causing the missile to lock onto the flare instead of onto the aircraft and enabling the aircraft to avoid the threat. In a typical scenario, an aircraft may detect the electronic targeting signals emitted from threat radars or missiles, or aircrew may visually identify a threat missile plume when a missile is launched. At a strategically appropriate time, the pilot dispenses flares and immediately maneuvers the aircraft to distract and defeat the threat. During a typical flare test, an aircraft will dispense flares 3,000 ft. above mean sea level and flares are completely consumed while in the air. Aircraft flares use a magnesium extruded flare grain.
Typical Components	 Platforms: Fixed Wing - Electronic Warfare Aircraft, Rotary-Wing Aircraft, Tiltrotor Aircraft Targets: None Systems being Trained/Tested: Flare systems Munitions: None
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	None
Parameters for Analysis	Flare use from all other events are captured under this activity.
Location (typical	Phase IV Requirement 2025-2032
specific location where applicable)	California Study Area
	Hawaii Study Area

A.2.1.4 Mine Warfare

Testing and development of mine warfare systems is conducted to improve sonar, laser, and magnetic detectors intended to hunt, locate, and record the positions of mines for avoidance or subsequent neutralization. Mine warfare testing and development falls into two primary categories: mine detection and classification, and mine countermeasure and neutralization. Mine detection and classification testing involves the use of air, surface, and subsurface vessels and uses sonar, including towed and side-scan sonar, and unmanned vehicles to locate and identify objects underwater. Mine detection and classification systems are sometimes used in conjunction with a mine neutralization system. Mine countermeasure and neutralization testing includes the use of air, surface, and subsurface units to evaluate the effectiveness of tracking devices and countermeasure and neutralization systems to neutralize mine threats. Most neutralization tests use mine shapes, or non-explosive practice mines, to evaluate a new or enhanced capability. For example, during a mine neutralization test, a previously located mine is destroyed or rendered nonfunctional using a helicopter or manned/unmanned surface vehicle based system that may involve the deployment of a towed neutralization system.

A small percentage of mine warfare tests require the use of high-explosive mines to evaluate and confirm the ability of the system to neutralize a high-explosive mine under operational conditions. The majority of mine warfare systems are deployed by ships, helicopters, and unmanned vehicles. Tests may also be conducted in support of scientific research to support these new technologies.

A.2.1.4.1 Airborne Dipping Sonar Minehunting Test

Mine Warfare	
Airborne Dipping S	onar Minehunting Test
Short Description	A mine-hunting dipping sonar system that is deployed from a rotary-wing aircraft and uses high frequency sonar for the detection and classification of bottom and moored mines.
Long Description	Tests of a mine-hunting dipping sonar system to evaluate the search capabilities of this rotary-wing aircraft-deployed, mine hunting, detection, and classification system. The sonar identifies mine-like objects.
Typical Components	Platforms: Rotary-Wing Aircraft Targets: Mine Targets Systems being Trained/Tested: Sonar Systems - Mine Warfare Munitions: None
Active Sonar	HFH
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	California Study Area
	Hawaii Study Area

A.2.1.4.2 Airborne Laser Mine Detection System Test

Mine Warfare		
Airborne Laser Mir	Airborne Laser Mine Detection System Test	
Short Description	An airborne mine hunting test of a laser-based mine detection system, that is operated from a rotary-wing aircraft and evaluates the system's ability to detect, classify, and fix the location of floating and near-surface, moored mines. The system uses a low-energy laser to locate mines.	
Long Description	During an airborne mine detection system test, a rotary-wing aircraft evaluates the search capabilities of the AN/AES-1 Airborne Laser Mine Detection System. The Airborne Laser Mine Detection System is a mine hunting system designed to detect, classify, and localize floating and near-surface, moored sea mines using a laser system. The Airborne Laser Mine Detection System will be integrated into the rotary-wing aircraft to provide a rapid wide-area reconnaissance and assessment of mine threats in littoral zones, confined straits, choke points, and amphibious objective areas for Carrier and Expeditionary Strike Groups. The Airborne Laser Mine Detection System uses pulsed laser light to image the entire near-surface volume potentially containing mines. Airborne Laser Mine Detection System is capable of day or night operations without stopping to deploy or recover equipment and without towing any equipment in the water. With untethered operations, it can attain high area search rates. Airborne Laser Mine Detection System also provides accurate target geo-location to support follow on neutralization of the detected mines.	
Typical components	Platforms: Rotary-Wing Aircraft	
	Systems being Trained/Tested: Airborne Laser Mine Detection System	
	Munitions: None	
Active Sonar	No	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	None	
Parameters for Analysis	Mine shapes are on an established mine warfare training range	
Location (typical	Phase IV Requirement 2025-2032	
specific location	California Study Area	
where applicable)	Hawaii Study Area	

A.2.1.4.3 Airborne Mine Neutralization System Test

Mine Warfare	
Airborne Mine Neu	utralization System Test
Short Description	A test of the airborne mine neutralization system evaluates the system's ability to detect and destroy mines from an airborne mine countermeasures capable rotary-wing aircraft. The airborne mine neutralization system uses up to four unmanned underwater vehicles equipped with high-frequency sonar, video cameras, and explosive and non-explosive neutralizers.
Long Description	Mine neutralization tests evaluate aircraft and aircraft systems intended to neutralize or otherwise destroy mines through the use of explosives or other munitions. For most neutralization tests, mine shapes or non-explosive mines are used to evaluate new or enhanced mine neutralization systems. The airborne mine neutralization system uses up to four unmanned underwater vehicles equipped with high-frequency sonar and video cameras to relocate previously detected submerged mines. The unmanned underwater vehicles are also equipped with explosives to neutralize the mines after they are located. Data from unmanned underwater vehicles are relayed to the operator in the rotary-wing aircraft through a fiber optic cable enabling the operator to position the neutralizing charge onto the most vulnerable area of the mine. The explosive charge is then detonated to neutralize the mine. For most tests, recoverable non-explosive neutralizers are used. A mine shape, rather than an explosive mine, serves as the target and a range support vessel recovers the non-explosive neutralizer and the mine shape following the test. Testing scenarios include a non-explosive neutralizer against an inert mine shape, or an explosive neutralizer against an explosive mine.
Typical Components	Platforms: Rotary-Wing Aircraft
	Targets: Mine Targets
	Systems being Trained/Tested: None
	Munitions: Mine Warfare Devices
Active Sonar	No
In-Water Explosives	E4
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Explosive mine countermeasure and neutralization (no divers)
Parameters for Analysis	No explosive mines (E11) would be used under the preferred alternative. Explosive mines are proposed and analyzed under the non-preferred alternative.
	Phase IV Requirement 2025-2032
Location (typical	California Study Area
where applicable)	Hawaii Study Area

A.2.1.4.4 Airborne Minehunting Test – Sonobuoy

Mine Warfare	
Airborne Minehun	ting Test – Sonobuoy
Short Description	A mine-hunting system made up of sonobuoys is deployed from a rotary-wing aircraft. A field of sonobuoys, using high-frequency sonar, is used for detection and classification of bottom and moored mines.
Long Description	Tests of mine-hunting sonobuoys to evaluate the search capabilities of this rotary-wing aircraft-deployed, mine hunting, detection, and classification system. The sonar identifies mine-like objects.
Typical Components	Platforms: Rotary-Wing Aircraft Targets: Mine Targets Systems being Trained/Tested: Sonobuoys Munitions: None
Active Sonar	MFM
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	None
Parameters for Analysis	None
Location (tunical	Phase IV Requirement 2025-2032
specific location where applicable)	California Study Area
	Hawaii Study Area

A.2.1.4.5 Mine Laying Test

Mine Warfare	
Mine Laying Test	
Short Description	Fixed-wing aircraft evaluate the performance of mine laying equipment and software systems to lay mines. A mine test may also train aircrew in laying mines using a new or enhanced mine deployment system.
Long Description	During a mine laying test, fixed-wing aircraft evaluate the performance of aircraft mine laying equipment or associated software systems to lay mines using non-explosive mine shapes. A mine test may also train aircrew in the technique of laying mines and in using a new or enhanced mine deployment system. Aircrew typically drop a series of about four non-explosive mine shapes, making multiple passes in the same flight pattern and dropping one or more shapes each time. The non-explosive mine shapes are expendable and are typically not recovered after the test.
Typical Components	Platforms: Fixed Wing – Patrol Aircraft Targets: None Systems being Trained/Tested: Mine laying systems Munitions: Bombs
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Non-explosive aerial-deployed mines and bombs
Parameters for Analysis	When a test event occurs and aircrew receive training, the event will be analyzed as a testing event.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	California Study Area
	Hawaii Study Area

A.2.1.5 Surface Warfare

Testing of weapons used in surface warfare is conducted to develop new technologies and to assess weapon performance and operability with new systems and platforms, such as unmanned systems. Tests include various air-to-surface guns and missiles, surface-to-surface guns and missiles, and bombing tests. Testing events may be integrated into training activities to test aircraft or aircraft systems in the delivery of munitions on a surface target. In most cases the tested systems are used in the same manner in which they are used for fleet training activities.

Training may occur in conjunction with weapons testing to provide Fleet operators unique opportunities to train with combat weapon systems and personnel in scripted warfare environments. For example, Fleet training could occur while testing a weapon system, in which Sailors would experience (be trained in) the use of the system being tested.

A.2.1.5.1 Air-to-Surface Bombing Test

Surface Warfare	
Air-to-Surface Bom	ibing Test
Short Description	Fixed-wing aircraft test the delivery of bombs against surface maritime targets with the goal of evaluating the bomb, the bomb carry and delivery system, and any associated systems that may have been newly developed or enhanced.
Long Description	Fixed-wing aircraft test the delivery of bombs against surface maritime targets with the goal of evaluating the bomb, the bomb carry and delivery system, and any associated systems that may have been newly developed or enhanced. Both explosive and non-explosive bombs will be released during this type of test; however, the vast majority of releases will be non-explosive bombs and typically include non-explosive general purpose bombs and guided bomb units of various sizes. Surface targets may also be used.
Typical Components	Platforms: Fixed Wing – Strike Aircraft
	Targets: Land Targets, Surface Targets - Maneuvering
	Systems being Trained/Tested: Bomb delivery system
	Munitions: Bombs
Active Sonar	No
In-Water Explosives	E7, E9
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Non-explosive aerial-deployed mines and bombs Explosive bombs
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
Location (typical specific location	California Study Area
where applicable)	Hawaii Study Area

A.2.1.5.2 Air-to-Surface Gunnery Test

Surface Warfare	
Air-to-Surface Gun	nery Test
Short Description	Fixed-wing and rotary-wing aircrews evaluate new or enhanced aircraft guns against surface maritime targets to test that the gun, gun ammunition, or associated systems meet required specifications or to train aircrew in the operation of a new or enhanced weapons system.
Long Description	Fixed-wing and rotary-wing aircrews evaluate new or enhanced aircraft guns against surface maritime targets to test that the gun, gun ammunition, or associated systems meet required specifications or to train aircrew in the operation of a new or enhanced weapons system. Non-explosive practice munitions are typically used during this type of test; however, a small number of high explosive projectiles may be used during final testing. Rounds that may be used include 7.62 millimeter (mm), 20 mm, and 30 mm.
Typical Components	 Platforms: Fixed Wing – Strike Aircraft, Rotary-Wing Aircraft Targets: Surface Targets - Floating, Surface Targets - Maneuvering Systems being Trained/Tested: Gunnery systems Munitions: Projectile - Medium Caliber, Projectile - Small Caliber
Active Sonar	Νο
In-Water Explosives	E1
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Explosive gunnery Non-explosive gunnery
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
Location (typical specific location	California Study Area
where applicable)	Hawaii Study Area

A.2.1.5.3 Air-to-Surface High-Energy Laser Test

Surface Warfare	
Air-to-Surface High	-Energy Laser Test
Short Description	High-energy laser tests would evaluate the specifications, integration, and performance of an aircraft mounted, approximately 25 kilowatt high-energy laser. The laser is intended to be used as a weapon to disable small surface vessels.
Long Description	During a high energy laser test, aircrew evaluate the specifications, integration, and performance of an aircraft mounted, approximately 25 kilowatt high energy laser that is intended to be used as a weapon against stationary and mobile, unmanned surface targets. The high energy laser would be employed from a rotary-wing aircraft and is designed to disable the surface vessel, rendering it immobile. The high energy laser would have a range of up to six kilometers. Unmanned surface targets would be used during the high energy laser test.
Typical Components	Platforms: Rotary-Wing Aircraft Targets: Surface Targets - Floating, Surface Targets - Maneuvering Systems being Trained/Tested: High Energy Laser System Munitions: None
Active Sonar	Νο
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	None
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	California Study Area
	Hawaii Study Area

A.2.1.5.4 Air-to-Surface High-Power Microwave Test

Surface Warfare	Surface Warfare	
Air-to-Surface High	-Power Microwave Test	
Short Description	A High-Power Microwave Test is where energy is directed from a ship or land-based system to engage a surface target, or energy is directed from a system mounted on an aircraft platform onto a surface target.	
Long Description	Pulsed-wave high-power microwave systems convert electrical or chemical energy into radiated energy and deliver high-power, short bursts of radiofrequency energy to neutralize a target. High-power microwave systems operate within a wide range of frequencies, from 1 megahertz to 100 gigahertz, and transmit energy to a target to degrade or destroy electrical components in the target. High-power microwave systems can be based on ships and aircraft and directed to engage land and surface targets. Initial land-based tests in a maritime environment will yield decisive experience before installation of high-power microwave weapons on a ships or aircraft.	
Typical Components	Platforms: Rotary-Wing Aircraft Targets: Surface Targets - Floating, Surface Targets - Maneuvering Systems being Trained/Tested: High-Power Microwave System Munitions: None	
Active Sonar	Νο	
In-Water Explosives	Νο	
Mitigation Involving Visual Observations for Marine Species	None	
Parameters for Analysis	This activity may occur anywhere within the California Study Area, but is also known to occur within PMSR.	
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032	
	California Study Area (PMSR)	

A.2.1.5.5 Air-to-Surface Laser Targeting Test

Surface Warfare	Surface Warfare	
Air-to-Surface Lase	r Targeting Test	
Short Description	Aircrews illuminate enemy targets with lasers.	
Long Description	During a laser targeting test, aircrew use laser targeting devices integrated into aircraft or weapons systems to evaluate targeting accuracy and precision and to train aircrew in the use of newly developed or enhanced laser targeting devices designed to illuminate designated targets for engagement with laser-guided weapons. No explosive munitions are released during a laser targeting test.	
Typical Components	Platforms: Unmanned Aerial Vehicle - Fixed Wing Aircraft Targets: Surface Targets - Floating Systems being Trained/Tested: Targeting Lasers Munitions: Bombs	
Active Sonar	No	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Non-explosive aerial-deployed mines and bombs	
Parameters for Analysis	None	
Location (typical	Phase IV Requirement 2025-2032	
specific location where applicable)	California Study Area	
	Hawaii Study Area	

A.2.1.5.6 Air-to-Surface Missile Test

Surface Warfare	
Air-to-Surface Miss	sile Test
Short Description	Test may involve both fixed-wing and rotary-wing aircraft launching missiles at surface maritime targets to evaluate the weapons system or as part of another systems integration test.
Long Description	An air-to-surface missile test may involve both fixed-wing and rotary-wing aircraft launching missiles at surface maritime targets to evaluate the weapons system or as part of another systems integration test. Air-to-surface missile tests can include high explosive, non-explosive, or non-firing (captive air training missile) weapons. Laser targeting systems may also be used. Both stationary and mobile targets would be utilized during testing.
Typical Components	 Platforms: Fixed Wing – Strike Aircraft, Rotary-Wing Aircraft, Tiltrotor Aircraft Targets: Air Targets - Decoy, Air Targets - Drone, Surface Targets - Floating, Surface Targets - Maneuvering Systems being Trained/Tested: Missile Delivery Systems Munitions: Air-to-Surface Missiles
Active Sonar	Νο
In-Water Explosives	E6, E7, E8, E9
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Non-explosive aerial-deployed mines and bombs Manned surface vessels Explosive missiles and rockets Non-explosive missiles and rockets
Parameters for Analysis	
	Phase IV Requirement 2025-2032
Location (typical specific location where applicable)	California Study Area Hawaii Study Area
Analysis Location (typical specific location where applicable)	Phase IV Requirement 2025-2032 California Study Area Hawaii Study Area

A.2.1.5.7 Long-Range Weapons Delivery System/Hypersonic Vehicle Test

Surface Warfare	
Long-Range Weapo	ons Delivery Systems (OTH)/Hypersonic Vehicle Test
Short Description	The objective of the Hypersonic Vehicle Program is to develop and demonstrate key technologies to enable an air- or land-launched tactical range hypersonic vehicle for rapid response capabilities.
Long Description	Precision long range standoff weapons are missiles or bombs that may be launched from a distance sufficient to allow attacking personnel to evade defensive fire from the target area. Typically, they are used against land- and sea-based targets in an offensive operation. These weapon systems provide the ability to engage the target while standing off outside the range at which the defenders are likely to engage the attacker. Typical standoff weapons include cruise missiles, glide bombs, and ballistic missiles. The objective of the Hypersonic Vehicle Program is to develop and demonstrate key technologies to enable an air- or land-launched tactical range hypersonic vehicle for rapid response capabilities. Data collected during these events are utilized to predict the performance of future, mature vehicle delivery systems. F-15, B-52, or similar aircraft serve as the primary platform for hypersonic vehicle launches. Flights are typically conducted at altitudes of up to 80,000 feet and can travel 450–2,000 miles, at hypersonic speeds (over Mach 5). The flight vehicle is released and air-launched where its solid rocket motor booster will ignite. The spent booster or boosters and protective shroud then separate from the vehicle which will continue to travel towards a pre-determined impact site in the open ocean.
	Systems being Trained/Tested: Weapons Systems
Activo Sonar	
In-Water Explosives	E9
Mitigation Involving Visual Observations for Marine Species	None
Parameters for Analysis	Testing at PMSR would occur within the extended special use airspace.
Location (typical	Phase IV Requirement 2025-2032
specific location where applicable)	California Study Area

A.2.1.5.8 Rocket Test

Surface Warfare	
Rocket Test	
Short Description	Rocket tests are conducted to evaluate the integration, accuracy, performance, and safe separation of guided and unguided rockets fired from a hovering or forward flying rotary-wing aircraft or tilt rotor aircraft.
Long Description	Rocket tests are conducted to evaluate the integration, accuracy, performance, and safe separation of laser-guided and unguided rockets fired from a hovering or forward flying rotary-wing aircraft. Rocket tests would involve the release of primarily live motor/non-explosive warhead rockets. Some explosive warhead rockets would be tested, and during a jettison test, rockets with a non- explosive motor and non-explosive warhead would be jettisoned along with the rocket launcher. Rocket tests are also conducted to train aircrew on the use of new or enhanced weapons systems. Non-explosive warhead rocket types also include flechette rockets. Some rocket tests may be conducted in conjunction with upgrades to or integration of the Forward Looking Infrared targeting system.
Typical Components	 Platforms: Rotary-Wing Aircraft, Surface Combatant, Tiltrotor Aircraft, Vehicle Launch Platform Targets: Surface Targets - Floating, Surface Targets - Maneuvering Systems being Trained/Tested: Rocket Delivery Systems Munitions: Air-to-Air Missiles, Rockets
Active Sonar	No
In-Water Explosives	E3, E9
Mitigation Involving Visual Observation s for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity-based Mitigation): Manned surface vessels Explosive missiles and rockets Non-explosive missiles and rockets
Parameters for Analysis	
Location	Phase IV Requirement 2025-2032
(typical specific location where applicable)	California Study Area Hawaii Study Area

A.2.1.5.9 Subsurface-to-Surface Missile Test

Surface Warfare	Surface Warfare	
Subsurface-to-Surf	ace Missile Test	
Short Description	Submarines launch missiles at surface maritime targets with the goal of destroying or disabling enemy ships or boats.	
Long Description	Submarines launch missiles at surface maritime targets with the goal of destroying or disabling enemy ships or boats. After detecting and confirming a surface threat, the submarine will fire a precision guided surface missile.	
Typical Components	Platforms: Submarine Targets: Surface Targets Systems being Trained/Tested: Weapons Systems Munitions: Subsurface-to-Surface Missiles, Surface-to-Surface Missiles	
Active Sonar	No	
In-Water Explosives	E10	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels	
Parameters for Analysis	This activity may occur anywhere within the California Study Area, but is also known to occur within PMSR.	
Location (typical	Phase IV Requirement 2025-2032	
specific location where applicable)	California Study Area (PMSR)	

A.2.1.5.10 Surface-to-Surface Gunnery Test – Large Caliber

Surface Warfare	
Surface-to-Surface Gunnery Test - Large Caliber	
Short Description	Surface ship crews fire large-caliber guns at surface targets.
Long Description	This exercise involves ships gun crews engaging surface targets at sea with their main battery large-caliber (typically 57 mm and 5-inch) guns. Targets include the QST-35 seaborne powered target, high speed maneuverable surface target, or a specially configured remote controlled watercraft. Some targets are expended during the exercise and are not recovered. The exercise proceeds with the target boat approaching from about 10-NM distance. The target is tracked by radar and when within a predetermined range, it is engaged first with large-caliber warning shots. As threats get closer all weapons may be used to disable the threat. This exercise may involve a single firing ship, or be undertaken in the context of a coordinated larger exercise involving multiple ships, including a major training exercise. Large-caliber guns will also be fired during weapon certification events and in conjunction with weapon maintenance. During all exercises, either high-explosive or non-explosive projectiles may be used. High- explosive projectiles can either be fused for detonation on impact (with water surface or targets), or for proximity to the target (in air detonation).
Typical Components	Platforms: Surface Combatant
	Systems heing Trained/Tested: Weapons Systems
	Munitions: Projectile - Large Caliber
Active Sonar	No
In-Water Explosives	E3, E5
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Explosive gunnery Non-explosive gunnery Weapons firing noise
Parameters for Analysis	This activity may occur anywhere within the California Study Area, but is also known to occur within PMSR.
Location (typical	Phase IV Requirement 2025-2032
where applicable)	California Study Area (PMSR)

A.2.1.5.11 Surface-to-Surface Gunnery Test – Medium Caliber

Surface Warfare	
Surface-to-Surface Gunnery Test – Medium Caliber	
Short Description	Surface ship crews fire medium-caliber guns at surface targets.
Long Description	Surface ship crews fire medium-caliber guns at surface targets. Ships use medium-caliber weapons to practice defensive marksmanship, typically against a stationary floating target (a 10 ft. diameter red balloon (Killer Tomato)) and high-speed mobile targets. Some targets are expended during the exercise and are not recovered. Shipboard protection systems (Close-In Weapon System) utilizing medium-caliber projectiles would train against high speed mobile targets.
Typical Components	 Platforms: Fleet Support Vessel, Support Craft, Surface Combatant Targets: Air Targets - Drone, Surface Targets - Floating, Surface Targets - Maneuvering Systems being Trained/Tested: Weapons Systems Munitions: Projectile - Medium Caliber
Active Sonar	Νο
In-Water Explosives	E1, E3
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Explosive gunnery Non-explosive gunnery
Parameters for Analysis	This activity may occur anywhere within the California Study Area, but is also known to occur within PMSR.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	California Study Area (PMSR)

A.2.1.5.12 Surface-to-Surface Gunnery Test – Small Caliber

Surface Warfare	
Surface-to-Surface Gunnery Test – Small Caliber	
Short Description	Surface ship crews fire small-caliber guns at surface targets.
Long Description	Surface ship crews fire small-caliber guns at surface targets. Ships use small-caliber weapons to practice defensive marksmanship, typically against a stationary floating target (a 10 ft. diameter red balloon (Killer Tomato)) and high-speed mobile targets. Some targets are expended during the exercise and are not recovered.
Typical Components	Platforms: Support Craft, Surface Combatant Targets: Surface Targets - Maneuvering Systems being Trained/Tested: Weapons Systems Munitions: Projectile - Small Caliber
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Non-explosive gunnery
Parameters for Analysis	This activity may occur anywhere within the California Study Area, but is also known to occur within PMSR.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	California Study Area (PMSR)

A.2.1.5.13 Surface-to-Surface High-Energy Laser Test

Surface Warfare	
Surface-to-Surface	High-Energy Laser Test
Short Description	High-energy laser weapons tests would evaluate the specifications, integration, and performance of a ship-mounted, approximately 25 kilowatt high-energy laser. The laser is intended to be used as a weapon to disable small surface vessels.
Long Description	During a high energy laser weapons test, ship crews evaluate the specifications, integration, and performance of a ship-mounted, approximately 25 kilowatt high energy laser that is intended to be used as a weapon against stationary and mobile, unmanned surface targets. The high energy laser would be employed from a ship and is designed to disable the surface vessel, rendering it immobile. The high energy laser would have a range of up to six kilometers. Unmanned surface targets would be used during the high energy laser test.
Typical Components	Platforms: Rotary-Wing Aircraft, Surface Combatant Targets: Air Targets - Drone, Surface Targets - Floating, Surface Targets - Maneuvering Systems being Trained/Tested: High-Energy Laser System Munitions: None
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	This activity may occur anywhere within the California Study Area, but is also known to occur within PMSR.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	California Study Area (PMSR)

A.2.1.5.14 Surface-to-Surface High-Power Microwave Test

Surface Warfare	Surface Warfare	
Surface-to-Surface High-Power Microwave Test		
Short Description	A High-Power Microwave Test where energy is directed from a ship or land-based system to engage a surface target, or energy is directed from a system mounted on an aircraft platform onto a surface target.	
Long Description	Pulsed-wave high-power microwave systems convert electrical or chemical energy into radiated energy and deliver high-power, short bursts of radiofrequency energy to neutralize a target. High-power microwave systems operate within a wide range of frequencies, from 1 megahertz to 100 gigahertz, and transmit energy to a target to degrade or destroy electrical components in the target. High power microwave systems can be based on ships and aircraft and directed to engage land and surface targets. Initial land-based tests in a maritime environment will yield decisive experience before installation of high-power microwave weapons on a ships or aircraft.	
Typical Components	Platforms: Surface Combatant Targets: Surface Targets - Floating, Surface Targets - Maneuvering Systems being Trained/Tested: High-Power Microwave Systems Munitions: None	
Active Sonar	No	
In-Water Explosives	Νο	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels	
Parameters for Analysis	This activity may occur anywhere within the California Study Area, but is also known to occur within PMSR.	
Location (typical	Phase IV Requirement 2025-2032	
specific location where applicable)	California Study Area (PMSR)	

A.2.1.5.15 Surface-to-Surface Missile Test

Surface Warfare	
Surface-to-Surface Missile Test	
Short Description	Surface ship crews defend against surface threats (ships or small boats) and engage them with missiles.
Long Description	Surface ships launch missiles at surface maritime targets with the goal of destroying or disabling enemy ships or boats. After detecting and confirming a surface threat, the ship will fire a precision guided surface missile. Events with littoral combat and patrol combatant ships would be to certify ship's crew to defend against close-in (less than 10 miles) surface threats. These exercises are live fire, meaning that a missile is fired down range. Surface missiles could be equipped with either high-explosive or non-explosive warheads.
Typical Components	Platforms: Surface Combatant, Vehicle Launch Platform Targets: Land Targets, Surface Targets - Floating, Surface Targets - Maneuvering Systems being Trained/Tested: None Munitions: Surface-to-Surface Missiles
Active Sonar	No
In-Water Explosives	E9, E10
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Explosive missiles and rockets Non-explosive missiles and rockets
Parameters for Analysis	This activity may occur anywhere within the California Study Area, but is also known to occur within PMSR.
Location (typical	Phase IV Requirement 2025-2032
specific location where applicable)	California Study Area (PMSR)

A.2.1.6 Other Testing Activities

A.2.1.6.1 Acoustic and Oceanographic Research

Other Testing Activities	
Acoustic and Oceanographic Research	
Short Description	Active transmissions within the band 10 hertz (Hz)-100 kilohertz (kHz) from sources deployed from ships and aircraft.
Long Description	Active acoustic transmissions within the band 10 Hz-100 kHz used for engineering tests of acoustic sources, validation of ocean acoustic models, characterization of acoustic interactions with the ocean bottom and ocean surface.
Typical Components	Platforms: Fixed Wing – Patrol Aircraft, Small Boat
	Targets: Surface Targets - Maneuvering
	Systems being Trained/Tested: Acoustic Transmission Systems
	Munitions: None
Active Sonar	Νο
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	California Study Area
	Hawaii Study Area

A.2.1.6.2 Air Platform Shipboard Integration Test

Other Testing Activities	
Air Platform Shipboard Integration Test	
Short Description	Aircraft are tested to determine operability from shipboard platforms, performance of shipboard physical operations, and to verify and evaluate communications and tactical data links.
Long Description	The air platform shipboard integration test is performed to evaluate the compatibility of an aircraft to operate from designated shipboard platforms, perform shipboard physical operations, and to verify and evaluate communications and tactical data links. This test function also includes an assessment of carrier-shipboard suitability, such as hazards of electromagnetic radiation to ordnance, hazard of electromagnetic radiation to personnel, and high energy radio frequency.
Typical Components	 Platforms: Fixed Wing - Command and Control Aircraft, Rotary-Wing Aircraft, Surface Combatant, Tiltrotor Aircraft, Unmanned Aerial Vehicle - Fixed Wing, Unmanned Aerial Vehicle - Rotary Wing Targets: None Systems being Trained/Tested: Communications Systems Munitions: None
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	California Study Area
	Hawaii Study Area
A.2.1.6.3 Undersea Range System Test

Other Testing Activities		
Undersea Range S	Undersea Range System Test	
Short Description	Following installation of a Navy underwater warfare training and testing range, tests of the nodes (components of the range) will be conducted to include node surveys and testing of node transmission functionality.	
Long Description	The bottom-mounted bi-directional nodes are surveyed post-installation utilizing a range pinger and tested to establish system parameters and baseline hearing ranges. Each acoustic projector is activated at full power while listening is occurring on adjacent hydrophones. The nodes may also be activated during periodic operational and maintenance checks and following significant weather events to confirm that nodes are located correctly and functioning properly prior to ongoing training or testing.	
Typical Components	Platforms: Range , Small Boat, Support Craft, Unmanned Underwater Vehicle Targets: None Systems being Trained/Tested: Acoustic Communications, Sonar Systems - Other Munitions: None	
Active Sonar	MFM	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels	
Parameters for Analysis	None	
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032	
	California Study Area	
	Hawaii Study Area	

A.2.2 Naval Facilities Engineering and Expeditionary Warfare Center

EXWC provides research, development, testing, and evaluation and in-service engineering and lifecycle management for the shore, oceans, and expeditionary domains. EXWC's proposed activities include ocean energy and cable systems research; undersea range system testing; and underwater search, deployment, and recovery.

A.2.2.1 Other Testing

A.2.2.1.1 Ocean Energy and Cable Systems Research

Other Testing Activ	Other Testing Activities	
Ocean Energy and	Cable Systems Research	
Short Description	Testing of ocean and marine energy harvesting/producing systems, energy storage and distribution, subsea power systems and associated infrastructure, and temporary subsea cable network deployment and interoperability.	
Long Description	Testing of marine energy harvesting/producing systems, energy storage systems, and infrastructure that supports distribution of power to naval research applications and systems in littoral and deep-sea locations. This may include diverse payloads and other packages associated with ocean energy. Activities also include temporary subsea cable network deployments. Standard oceanographic research sensing (acoustic Doppler current profiler, fathometer like systems) also to be employed. Routine maintenance of systems under test may occur to ensure they are located correctly and functioning properly, especially for long duration tests and if there has been a significant weather event. Maintenance may involve repairing or replacing equipment such as batteries and cables.	
Typical Components	 Platforms: Structure, Support Craft, Unmanned Bottom Crawler, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: None Systems being Trained/Tested: Wave Energy Converters, Marine Energy Converters, Power Storage and Distribution Systems, Fiber Optic Cables Munitions: None 	
Active Sonar	No	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Unmanned vehicles	
Parameters for Analysis	None	
Location (typical	Phase IV Requirement 2025-2032	
specific location	SOCAL	
where applicable)	Hawaii Range Complex (Navy Wave Energy Test Site)	

PMSR

A.2.2.1.2 Undersea Range System Testing

Other Testing Activities		
Undersea Range Sy	Undersea Range System Testing	
Short Description	This activity supports advanced ocean technology development for fixed ocean and seafloor systems, including deployment of free-fall penetrometers and gravity deployed anchors used to determine seafloor characteristics and seafloor interaction testing of anchors, small foundations and packages. Advanced ocean technology development for fixed and seafloor systems.	
Long Description	This activity supports advanced ocean technology development for fixed ocean and seafloor systems, including deployment of free-fall penetrometers and gravity deployed anchors used to determine seafloor characteristics and seafloor interaction testing of anchors, small foundations and packages. Also includes surveying of the seafloor to determine geophysical characteristics prior to testing.	
Typical Components	Platforms: All Navy Ships and Boats, Unmanned Underwater Vehicle Targets: None Systems being Trained/Tested: <i>De minimis</i> sources, Unmanned Vehicle Systems Munitions: None	
Active Sonar	No	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels	
Parameters for Analysis	None	
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032	
	PMSR	
	SOCAL	

A.2.2.2 Unmanned Systems

A.2.2.2.1 Underwater Search, Deployment, and Recovery

Unmanned Systems		
Underwater Search	Underwater Search, Deployment, and Recovery	
Short Description	Tests various systems associated with Remotely Operated Vehicles and Unmanned Underwater Vehicles to include seafloor sampling, surveying, seafloor excavating, and subsea cable deployment.	
Long Description	Subsurface activities include a variety of underwater vehicles, robotic or autonomous systems, and items placed on the seafloor. Diving activities and special operations training also occur to iteratively test engineering solutions for hardening and mitigating seafloor infrastructure vulnerabilities. Other subsurface activities involve manned and unmanned underwater vehicles. All subsurface vehicles are retrieved after use, while most objects (e.g., non-explosive mines) remain for a period of time to be used as testing fixtures. Personnel install, remove for maintenance, or move seabed infrastructure to include cables of varying diameters and lengths and equipment tethered to the bottom that is floating in the water column. Repositioning may be conducted on a routine basis to ensure equipment is functioning properly and seafloor conditions are consistent.	
Typical Components	 Platforms: All Navy Ships and Boats, Unmanned Underwater Vehicle Targets: None Systems being Trained/Tested: Acoustic Communications, Sonar Systems - Hull Mounted, Sonar Systems - Other, Unmanned Vehicle Systems Munitions: None 	
Active Sonar	No	
In-Water Explosives	Νο	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Unmanned vehicles Manned surface vessels	
Parameters for Analysis	None	
Lesstion (tunical	Phase IV Requirement 2025-2032	
specific location	PMSR	
where applicable)	SOCAL	

A.2.3 Naval Sea Systems Command Testing Activities

A.2.3.1 Anti-Submarine Warfare

Testing of anti-submarine warfare systems is conducted to develop new technologies and assess weapon performance and operability with new systems and platforms, such as unmanned systems. Testing uses ships, submarines, and aircraft to demonstrate capabilities of torpedoes, missiles, countermeasure systems, and underwater surveillance and communications systems. Tests may be conducted as part of a large-scale fleet training event involving submarines, ships, fixed-wing aircraft, and helicopters. These integrated training events offer opportunities to conduct research and acquisition activities and to train aircrew in the use of new or newly enhanced systems during a large-scale, complex exercise.

A.2.3.1.1 Anti-Submarine Warfare Mission Package Testing

Anti-Submarine Warfare		
Anti-Submarine Wa	Anti-Submarine Warfare Mission Package Testing	
Short Description	Ships and their supporting platforms (rotary-wing aircraft and unmanned aerial systems) detect, localize, and prosecute submarines.	
Long Description	Ships conduct detect-to-engage operations against modern diesel-electric and nuclear submarines using airborne and surface assets (both manned and unmanned). Active and passive acoustic systems are used to detect and track submarine targets, culminating in the deployment of lightweight torpedoes to engage the threat.	
Typical Components	Platforms: Rotary-Wing Aircraft, Surface Combatant	
	Targets: Sub-surface Targets - Maneuvering	
	Systems being Trained/Tested: Sonar Systems - Dipping, Sonar Systems - Hull Mounted, Sonar Systems - Towed, Sonobuoys	
	Munitions: Torpedoes - Exercise	
Active Sonar	LFM, LFH, MF1, MFM, MFH, HFH	
In-Water Explosives	Νο	
Mitigation Involving Visual Observations	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation):	
for Marine Species	Active acoustic sources	
	Manned surface vessels	
	Towed in-water devices	
Parameters for Analysis	None	
Location (typical location where applicable)	Phase IV Requirement 2025-2032	
	SOCAL	
	Hawaii Range Complex	

A.2.3.1.2 At-Sea Sonar Testing

Anti-Submarine Warfare		
At-Sea Sonar Testing		
Short Description	At-sea testing to ensure systems are fully functional in an open ocean environment.	
Long Description	At-sea sonar testing is required to calibrate or document the functionality of sonar and torpedo systems while the ship or submarine is in an open ocean environment. At-sea sonar testing is conducted to verify the ship meets design acoustic specifications, define the underwater characteristics of the ship, determine effects of systems and equipment on ships acoustic characteristics, and provide technical background necessary to initiate development of design improvements to reduce noise. Tests also consist of electronic support measurement, photonics, and sonar sensor accuracy testing. In some instances, a submarine's passive detection capability is tested when a second submarine utilizes its active sonar or is equipped with a noise augmentation system in order to replicate acoustic or electromagnetic signatures of other vessel types or classes.	
Typical Components	Platforms: Fleet Support, Range, Submarine, Support Craft, Surface Combatant	
	Targets: Sub-surface Targets - Maneuvering, Surface Targets - Maneuvering	
	Systems being Trained/Tested: Acoustic Communications, Countermeasures, Sonar Systems - Hull Mounted, Sonar Systems - Other, Sonar Systems - Towed, Sonobuoys, Underwater Range Systems	
	Munitions: Torpedoes - Exercise	
Active Sonar	LFM, LFH, MF1K, MF1, MF1C, MFL, MFM, MFH, HFL, HFM, HFH, Broadband (LF to MF), Broadband (LF to HF), Broadband (MF to HF)	
In-Water Explosives	Νο	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Towed in-water devices	
Parameters for Analysis	Active sonar is intermittent throughout the duration of this event.	
	Phase IV Requirement 2025-2032	
Location	SOCAL (SOAR)	
	Hawaii Range Complex (PMRF Training Area)	

A.2.3.1.3 Pierside Sonar Testing

Anti-Submarine Warfare		
Pierside Sonar Test	Pierside Sonar Testing	
Short Description	Pierside testing to ensure systems are fully functional in a controlled pierside environment prior to at-sea test activities.	
Long Description	Ships and submarines would activate mid- and high-frequency tactical sonars, underwater communications systems, and navigational devices to ensure they are fully functional prior to at-sea test events. Testing may also include the firing of inert torpedo shapes. Event duration varies; with average durations of three weeks with active sonar used intermittently over two days during the total event duration. This also includes pierside sonar testing during surface combatant sea trials.	
Typical Components	 Platforms: Submarine, Surface Combatant Targets: None Systems being Trained/Tested: Acoustic Communications, Countermeasures, Sonar Systems - Hull Mounted, Sonar Systems - Other Munitions: None 	
Active Sonar	MFM, MFH, HFM, HFH, Broadband (MF to HF)	
In-Water Explosives	Νο	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources	
Parameters for Analysis	Event duration is three weeks with active sonar used intermittently.	
	Phase IV Requirement 2025-2032	
Location (typical specific location where applicable)	Port Hueneme	
	Naval Base San Diego	
	Hawaii Range Complex (Pearl Harbor)	

A.2.3.1.4 Surface Ship Sonar Testing/Maintenance

Anti-Submarine Warfare	
Surface Ship Sonar	Testing/Maintenance
Short Description	Pierside and at-sea testing of ship systems occurs periodically following major maintenance periods and for routine maintenance.
Long Description	Following major and routine maintenance periods, pierside and at-sea testing and maintenance is required. Multiple systems with active and passive acoustic sources such as tactical sonar, navigation systems, fathometers, underwater communications systems, underwater distress beacons, range finders, and other similar systems will be tested.
Typical Components	Platforms: Surface Combatant Targets: None Systems being Trained/Tested: Acoustic Communications, Countermeasures, Sonar Systems - Hull Mounted, Sonar Systems - Other Munitions: None
Active Sonar	LFL, MF1K, MF1, MFM, Broadband (MF to HF)
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels
Parameters for Analysis	Sonar will not be continuously active for the duration of the test.
	Phase IV Requirement 2025-2032
Location (typical	SOCAL
specific location where applicable)	Naval Base San Diego
	Hawaii Range Complex (Pearl Harbor)

A.2.3.1.5 Torpedo (Explosive) Testing

Anti-Submarine Warfare		
Torpedo (Explosive	Torpedo (Explosive) Testing	
Short Description	Air, surface, or submarine crews employ explosive and non-explosive torpedoes against virtual targets.	
Long Description	Non-explosive and explosive torpedoes (carrying a warhead) will be launched at a suspended target by a submarine and fixed- or rotary-wing aircraft or surface combatants.	
Typical Components	Platforms: Fixed Wing – Other Aircraft, Fixed Wing – Patrol Aircraft, Rotary-Wing Aircraft, Submarine, Support Craft, Surface Combatant	
	Targets: Mine Targets, Sub-surface Targets - Stationary, Surface Targets - Floating	
	Systems being Trained/Tested: Countermeasures, Signal, Underwater sound Devices, Sonar Systems - Dipping, Sonar Systems - Hull Mounted, Sonobuoys	
	Munitions: Torpedoes - Exercise, Torpedoes - HE	
Active Sonar	MF1, MFM, MFH, HFH, Broadband (MF to HF)	
In-Water Explosives	E8, E11	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Explosive torpedoes	
Parameters for Analysis	Only one heavyweight torpedo test could occur in 1 day; two heavyweight torpedo tests could occur on consecutive days. Two lightweight torpedo tests could occur in a single day. All non-explosive torpedoes are recovered.	
	Phase IV Requirement 2025-2032	
Location (typical specific location where applicable)	PMSR	
	SOCAL	
	Hawaii Range Complex	

A.2.3.1.6 Torpedo (Non-Explosive) Testing

Anti-Submarine W	Anti-Submarine Warfare	
Torpedo (Non-Explosive) Testing		
Short Description	Air, surface, or submarine crews employ non-explosive torpedoes against targets, submarines, or surface vessels.	
Long Description	Aerial, surface, and subsurface assets fire exercise torpedoes against surface or subsurface targets or at no target and programmed with a particular run geometry. Torpedo testing evaluates the performance and the effectiveness of hardware and software upgrades of heavyweight or lightweight torpedoes. It also includes testing of experimental torpedoes. Not all torpedo tests involve acoustics. Exercise torpedoes are recovered, typically from surface ships and helicopters that are specifically crewed and outfitted for torpedo recovery. Event duration is dependent on number of torpedoes fired.	
Typical Components	 Platforms: Contracted Aircraft, Fixed Wing - Command and Control Aircraft, Fixed Wing – Other Aircraft, Fixed Wing – Patrol Aircraft, Moored Platform, Rotary-Wing Aircraft, Submarine, Support Craft, Surface Combatant Targets: Mine Targets, Sub-surface Targets - Maneuvering, Sub-surface Targets - Stationary, Surface Targets - Floating, Surface Targets - Maneuvering Systems being Trained/Tested: Acoustic Communications, Countermeasures, Signal, Underwater sound Devices, Sonar Systems - Dipping, Sonar Systems - Hull Mounted, Sonobuoys, Underwater Range Systems Munitions: Torpedoes - Exercise 	
Active Sonar	MF1, MFL, MFM, MFH, HFM, HFH, VHFH, Broadband (LF to HF), Broadband (MF to HF)	
In-Water Explosives	Νο	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels	
Parameters for Analysis	All torpedoes are recovered. Events can last up to two weeks and use up to 40 torpedoes. Typically, no more than eight torpedoes are fired per day during daylight hours.	
	Phase IV Requirement 2025-2032	
	PMSR	
Location (typical specific location where applicable)	SOCAL (San Clemente Island)	
	Hawaii Range Complex (BARSTUR, Maui Basin, PMRF Training Area)	

A.2.3.2 Electronic Warfare

Testing of electronic warfare systems is conducted to improve the capabilities of systems and ensure compatibility with new systems. Testing involves the use of aircraft, surface ships, and submarine crews to evaluate the effectiveness of electronic systems. Similar to training activities, typical electronic warfare testing activities include the use of airborne and surface electronic jamming devices (including testing chaff and flares) to defeat tracking and communications systems. Chaff tests evaluate newly developed or enhanced chaff, chaff dispensing equipment, or modified aircraft systems' use against chaff deployment.

A.2.3.2.1	Radar and	Other Systems	Testing
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Electronic Warfare		
Radar and Other Sy	Radar and Other Systems Testing	
Short Description	Test may include use of military or commercial radar, communication systems (or simulators), or high energy lasers. Testing may occur aboard a ship against drones, small boats, rockets, missiles, or other targets	
Long Description	At-sea and docked testing may use military or commercial radar, communication systems (or simulators), or high-energy lasers. No subsurface transmission will occur during this testing. Testing of various air and surface targets may include unmanned aerial systems, small boats (floating cardboard tri-walls, towed, anchored, or self-propelled vessels).	
Typical Components	 Platforms: Aircraft Carrier, Amphibious Warfare Vessel, Fixed Wing – Adversary Aircraft, Fixed Wing – Patrol Aircraft, Fixed Wing – Strike Aircraft, Fleet Support, Patrol Combatant, Rotary-Wing Aircraft, Structure, Submarine, Support Craft, Surface Combatant, Unmanned Aerial Vehicle - Fixed Wing Aircraft, Unmanned Bottom Crawler Targets: Air Targets - Drone, Air Targets - Other, Mine Targets, Sub-surface Targets - 	
	Maneuvering, Sub-surface Targets - Stationary, Surface Targets - Floating, Surface Targets - Maneuvering Systems being Trained/Tested: Sonar Systems – Other, High-Energy Laser System	
	Munitions: Projectile - Large Caliber	
Active Sonar	Νο	
In-Water Explosives	Νο	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation):	
	Manned surface vessels Non-explosive gunnery Non-explosive missiles and rockets Towed in-water devices Unmanned vehicles Weapon firing noise	
Parameters for Analysis	HE lasers will not be tested pierside.	

Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	PMSR
	SOCAL
	Hawaii Range Complex (PMRF Training Area)

A.2.3.3 Mine Warfare

Testing and development of mine warfare systems is conducted to improve sonar, laser, and magnetic detectors intended to hunt, locate, and record the positions of mines for avoidance or subsequent neutralization. Mine warfare testing and development falls into two primary categories: mine detection and classification, and mine countermeasure and neutralization. Mine detection and classification testing involves the use of air, surface, and subsurface vessels and uses sonar, including towed and side-scan sonar, and unmanned vehicles to locate and identify objects underwater. Mine detection and classification systems are sometimes used in conjunction with a mine neutralization system. Mine countermeasure and neutralization testing includes the use of air, surface, and subsurface units to evaluate the effectiveness of tracking devices and countermeasure and neutralization systems to neutralize mine threats. Most neutralization tests use mine shapes, or non-explosive practice mines, to evaluate a new or enhanced capability. For example, during a mine neutralization test, a previously located mine is destroyed or rendered nonfunctional using a helicopter or manned/unmanned surface vehicle based system that may involve the deployment of a towed neutralization system.

A small percentage of mine warfare tests require the use of high-explosive mines to evaluate and confirm the ability of the system to neutralize a high-explosive mine under operational conditions. The majority of mine warfare systems are deployed by ships, helicopters, and unmanned vehicles. Tests may also be conducted in support of scientific research to support these new technologies.

A.2.3.3.1 Mine Countermeasure and Neutralization Testing

Mine Warfare		
Mine Countermeas	Mine Countermeasure and Neutralization Testing	
Short Description	Air, surface, and subsurface vessels neutralize threat mines and mine-like objects.	
Long Description	Mine countermeasure-neutralization and mine system testing is required to ensure systems can effectively neutralize threat (live or inert) mines that will otherwise restrict passage through an area and to ensure U.S. Navy mines remain effective against enemy ships. These systems may be deployed with a variety of ships, aircraft, submarines, or unmanned autonomous vehicles. Mines are neutralized by cutting mooring cables of buoyant mines, producing acoustic energy that triggers acoustic-influence mines, employing radar or laser fields, producing electrical energy to replicate the magnetic signatures of surface ships in order to detonate threat mines, detonation of mines using remotely-operated vehicles, and using explosive charges to destroy threat mines.	
Typical Components	 Platforms: Rotary-Wing Aircraft, Support Craft, Submarine, Unmanned Underwater Vehicle Targets: Mine Targets Systems being Trained/Tested: None Munitions: Mine Warfare Devices 	
Active Sonar	Νο	
In-Water Explosives	E4	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Non-explosive aerial deployed mines and bombs Manned surface vessels Explosive mine countermeasure and neutralization (no divers) Unmanned vehicle	
Parameters for Analysis	None	
Location (typical	Phase IV Requirement 2025-2032	
specific location where applicable)	SOCAL	

A.2.3.3.2 Mine Countermeasure Mission Package Testing

Mine Warfare	
Mine Countermeas	sure Mission Package Testing
Short Description	Vessels and associated aircraft conduct mine countermeasure operations.
Long Description	Ships conduct mine detection using unmanned submersible and aerial vehicles, magnetic and acoustic sensor systems deployed by vessel or support helicopters, and high-energy laser systems. Mines are then neutralized using magnetic, acoustic, explosive, and supercavitating systems.
Typical Components	Platforms: Fixed Wing – Other Aircraft, Rotary-Wing Aircraft, Surface Combatant, Unmanned Aerial Vehicle - Rotary Wing Aircraft, Unmanned Underwater Vehicle Targets: Mine Targets
	Systems being Trained/Tested: Electromagnetic Systems, Sonar Systems – Other, Unmanned Vehicle Systems
	Munitions: Bombs, Mine Warfare Devices
Active Sonar	MFH, HFM
In-Water Explosives	E4
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Aerial deployed mines and non-explosive bombs Explosive mine countermeasure and neutralization (no divers) Unmanned vehicles
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
	PMSR
Location (typical	SOCAL (CPAAA, Tanner/Cortes Training Minefield)
specific location where applicable)	SSTC (Imperial Beach Minefield)
,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	Hawaii Range Complex (Kahoolawe Sub Training Minefield, PMRF Training Area)

A.2.3.3.3 Mine Detection and Classification Testing

Mine Warfare	
Mine Detection and Classification Testing	
Short Description	Air, surface, and subsurface vessels and systems detect and classify mines and mine-like objects. Vessels also assess their potential susceptibility to mines and mine-like objects.
Long Description	Mine detection and classification systems require testing to evaluate the capability of generating underwater magnetic and acoustic signature fields as well as sonar systems that can detect, and classify a wide range of threat mines at tactically different water depths. Surface craft may deploy an underwater sensor system that uses ship signature to develop a susceptibility profile against mine-like objects. In order to develop better and safer methods of minesweeping, the Navy is currently testing new systems to detect locate, identify, and avoid mines including a laser airborne mine detection system that uses laser illumination coupled with sensitive electro-optic receivers to find mines in the upper part of the water column. These systems allow for identification of threat materials in an undersea environment without opening or touching the objects. This type of equipment has traditionally been designed for operation from a manned helicopter; however, the Navy is developing the capability to operate from unmanned aerial systems. The Navy is also developing new threat detection electromagnetic (X-ray) systems that allow for identification of threat materials in an undersea environment without placing targets on the seabed or water column and employing the use of detection systems deployed from a Remotely Operated Vehicle to inspect the objects.
Typical Components	Platforms: Fleet Support Vessel, Moored Platform, Range, Submarine, Support Craft, Unmanned Underwater Vehicle
	Targets: Mine Targets
	Systems being Trained/Tested: Sonar Systems - Hull Mounted Munitions: None
Active Sonar	HFH
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Non-explosive aerial-deployed mines and bombs Unmanned vehicles
Parameters for Analysis	Some mine shapes could be deployed for a specific event, and then retrieved afterwards. However, some mine shapes are left in place so that multiple events could use the same shapes without needing to redeploy. The in-air low energy laser stressor was used in analysis of potential impacts on human resources.

Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	PMSR
	SOCAL
	SSTC (Imperial Beach Minefield, Tanner/Cortes Training Minefield)
	Hawaii Range Complex (Kahoolawe Sub Training Minefield)

A.2.3.4 Surface Warfare

Testing of weapons used in surface warfare is conducted to develop new technologies and to assess weapon performance and operability with new systems and platforms, such as unmanned systems. Tests include various surface-to-surface guns and missiles. Testing events may be integrated into training activities. In most cases the tested systems are used in the same manner in which they are used for fleet training activities.

A.2.3.4.1 Gun Testing – Large Caliber

Surface Warfare		
Gun Testing – Large	Gun Testing – Large Caliber	
Short Description	Surface crews test large-caliber guns to defend against surface targets.	
Long Description	Surface combatants conduct surface warfare by detecting, tracking, and prosecuting small-boat threats. Gun testing may also include the surface warfare mission package for the Littoral Combat Ship, which provides a layered strike-defensive capability by use of its embarked support aircraft, medium range surface-to-surface missiles, and 57 millimeter gun weapon system.	
Typical Components	 Platforms: Fleet Support Vessel, Rotary-Wing Aircraft, Surface Combatant Targets: Air Targets - Drone, Air Targets - Other, Surface Targets - Floating, Surface Targets - Maneuvering Systems being Trained/Tested: None Munitions: Projectile - Large Caliber, Projectile – Medium Caliber, Projectile – Small Caliber, Torpedoes – Exercise 	
Active Sonar	HFH	
In-Water Explosives	E3, E5	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Explosive gunnery Non-explosive gunnery Towed in-water devices Weapon firing noise	
Parameters for Analysis	None	
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032	
	PMSR	
	SOCAL	

A.2.3.4.2 Gun Testing – Medium Caliber

Surface Warfare	
Gun Testing – Med	ium Caliber
Short Description	Surface crews test medium-caliber guns to defend against surface targets.
Long Description	Surface combatants conduct surface warfare by detecting, tracking, and prosecuting small-boat threats. Gun testing may also include the surface warfare mission package on the Littoral Combat Ship, which provides a layered strike-defensive capability by use of its embarked support aircraft, medium range surface-to-surface missiles, and 30 mm gun weapon system.
Typical Components	Platforms: Contracted Aircraft, Fleet Support, Surface Combatant
	Targets: Air Targets - Other, Surface Targets - Maneuvering, Surface Targets - Towed
	Systems being Trained/Tested: None
	Munitions: Projectile - Large Caliber, Projectile - Medium Caliber
Active Sonar	Νο
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
	Explosive gunnery
	Non-explosive gunnery
	Towed in-water devices
Parameters for Analysis	This activity includes in-air explosive gunnery at low altitudes.
Location (typical	Phase IV Requirement 2025-2032
specific location where applicable)	SOCAL

A.2.3.4.3 Gun Testing – Small Caliber

Surface Warfare	
Gun Testing – Smal	ll Caliber
Short Description	Surface crews test small-caliber guns to defend against surface targets.
Long Description	Small-caliber guns are fired from surface vessels. This testing also includes anti- terrorism/force protection. During this event, surface craft surface targets will make threat profile approaches to the ship. Ship will demonstrate small-caliber gun testing with non-explosive projectiles against the threat target. Small-caliber gun testing includes other class ship sea trials and surface warfare mission package testing.
Typical Components	Platforms: Fleet Support Vessel Targets: None
	Systems being Trained/Tested: None
	Munitions: Projectile - Small Caliber
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Non-explosive gunnery Towed in-water devices
Parameters for Analysis	400–2,000 projectiles per event. Ships may not be conducting tests consistently for the entire duration.
Location (typical	Phase IV Requirement 2025-2032
specific location where applicable)	SOCAL

A.2.3.4.4 Missile and Rocket Testing

Surface Warfare	
Missile and Rocket	Testing
Short Description	Missile and rocket testing includes various missiles or rockets fired from submarines and surface combatants. Testing of the launching system and ship defense is performed.
Long Description	Missile and rocket testing includes various missiles or rockets (standard missiles, Water Piercing Missile Launch) fired from submarines and surface combatants. Testing may occur during surface combatant sea trials and surface warfare mission package testing. This activity includes both air warfare and surface warfare events.
Typical Components	Platforms: Fleet Support Vessel, Submarine, Surface Combatant Targets: Air Targets - Drone, Land Targets, Surface Targets - Maneuvering Systems being Trained/Tested: None Munitions: Subsurface-to-Surface Missiles, Surface-to-Air Missiles
Active Sonar	No
In-Water Explosives	E6, E7, E8, E10
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	Includes explosive bins at low and medium altitudes. Targets used during non-explosive tests will be recovered. Explosive missiles will detonate either in the air or at the water's surface. Ships will not be conducting test constantly for the entire duration.
	Phase IV Requirement 2025-2032
Location (typical	PMSR
specific location where applicable)	SOCAL
	Hawaii Range Complex (PMRF Training Area)

A.2.3.5 Unmanned Systems

A.2.3.5.1 Underwater Search, Deployment, and Recovery

Unmanned System	Unmanned Systems	
Underwater Search	n, Deployment, and Recovery	
Short Description	Various underwater, bottom crawling, robotic, vehicles are utilized in underwater search, recovery, installation, and scanning activities.	
Long Description	Subsurface activities include a variety of underwater vehicles, robotic or autonomous systems, and items placed on the seafloor. This activity will include demonstration and testing of new technologies using low power magnetic resonance for point-to-point diver communications. Diving activities and special operations training also occur. Other subsurface activities involve manned and unmanned underwater vehicles. All subsurface vehicles are retrieved after use, while most objects (e.g., non-explosive mines) remain for a period of time to be used as testing fixtures. The Navy is developing new technologies using low power magnetic resonance for point-to-point divers in the water testing the effectiveness of communication.	
Typical Components	 Platforms: All Navy Ships and Boats, Rotary-Wing Aircraft, Small Boat, Unmanned Aerial Vehicle - Fixed Wing, Unmanned Aerial Vehicle - Rotary Wing, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: Surface Targets - Floating Systems being Trained/Tested: None Munitions: None 	
Active Sonar	No	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Unmanned vehicles Manned surface vessels	
Parameters for Analysis	None	
	Phase IV Requirement 2025-2032	
	Port Hueneme Harbor	
Location (typical	Naval Base San Diego	
where applicable)	PMSR	
	SOCAL	
	SSTC (Imperial Beach Minefield)	

A.2.3.5.2 Unmanned Surface Vehicle System Testing

Unmanned Systems	
Unmanned Surface	e Vehicle System Testing
Short Description	Unmanned surface vehicles are primarily autonomous systems designed to augment current and future platforms to help deter maritime threats. They employ a variety of sensors designed to extend the reach of manned ships.
Long Description	Unmanned surface vehicles (USV) can include remotely operated craft (semisubmersible, plane hull, semi-plane hull, etc.) and test vehicles. During testing, they can operate autonomously, semi-autonomously, or non-autonomously. Non-autonomous or remotely controlled vehicles may be tethered like remotely operated vehicles (ROVs) or remotely controlled via radio link. USVs may have multiple test objectives or payloads (such as cameras and sonar) onboard so that numerous tests can be executed during a single testing activity. USVs may be used in conjunction with unmanned underwater vehicles and unmanned aerial systems to meet test objectives. USV launch and retrieval methods are highly variable because of the differences in vehicle type and size. USV test vehicle launch methods include lowering onto the water from a support craft or pier, deploying from another craft, or launching from a boat ramp. The vehicle will propel itself through the water to complete the test objectives, which could include deployment or recovery of a payload, sonar or other sensor use, or completion of a propulsion test. Occurs year-round, daytime only.
Typical Components	 Platforms: Support Craft, Unmanned Surface Vehicle, Unmanned Underwater Vehicles Targets: Sub-surface Targets - Stationary Systems being Trained/Tested: Oceanographic - Other, Unmanned Vehicle Systems Munitions: None
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Unmanned vehicles
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
Location (typical	PMSR
where applicable)	SOCAL
	Port Hueneme Harbor

A.2.3.5.3 Unmanned Underwater Vehicle Testing

Unmanned System	Unmanned Systems	
Unmanned Underv	vater Vehicle Testing	
Short Description	Testing involves the production or upgrade of unmanned underwater vehicles. This may include testing of mission capabilities (e.g., mine detection), evaluating the basic functions of individual platforms, or conducting complex events with multiple vehicles.	
Long Description	Unmanned underwater vehicle testing ranges from single-vehicle tests to evaluate hydrodynamic parameters, to full mission, multiple vehicle functionality assessments. Most unmanned underwater vehicle operations include a launch, transit, mission profile execution, and recovery operations. Unmanned underwater vehicles include modular, multi-mission platforms and their payloads, and anti-submarine warfare targets. Nets could be used during some extra-large UUV testing activities to test subsurface obstacle avoidance. These tests would occur only during daylight hours. All nets and other obstacle avoidance "targets" would be recovered at the end of each exercise. Placement of submerged nets and other obstacles would avoid sensitive habitats and high-traffic areas.	
Typical Components	 Platforms: Extra Large Unmanned Underwater Vehicle, Support Craft, Unmanned Underwater Vehicle Targets: Mine Targets, Sub-surface Targets - Stationary Systems being Trained/Tested: Acoustic Communications, Sonar Systems - Other, Unmanned Vehicle Systems Munitions: None 	
Active Sonar	MFM, HFL, HFM, VHFL, VHFH, Broadband (MF to HF)	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Unmanned vehicles Towed in-water devices	
Parameters for Analysis	Some mine shapes could be deployed for a specific event, and then retrieved afterwards. However, some mine shapes are left in place so that multiple events could use the same shapes without needing to redeploy. Multiple vehicles may operate simultaneously in one or multiple areas.	
Location (typical	Phase IV Requirement 2025-2032	
	Port Hueneme Harbor	
where applicable)	SOCAL	
	Hawaii Range Complex (Pearl Harbor)	

A.2.3.6 Vessel Evaluation

A.2.3.6.1 Air Defense Testing

Vessel Evaluation		
Air Defense Testing	Air Defense Testing	
Short Description	Tests the ship's capability to detect, identify, track, and successfully engage live and simulated targets. Gun systems are tested using explosive and non-explosive projectiles.	
Long Description	Air Defense tests are conducted in clear and varied electronic attack environments, using a mix of missile firings to verify the ship's capability to detect, identify, track, and successfully engage live and simulated targets. The tests include testing the radar's track load in the presence of debris, long range engagement processing, low-elevation detection and tracking, track load in the presence of electronic attack and chaff, and missile performance. Tests currently include firing of the 5 inch .62-caliber gun, and will potentially include a 155 millimeter gun.	
Typical Components	 Platforms: Amphibious Warfare Vessel, Contracted Aircraft, Fixed Wing – Adversary Aircraft, Fixed Wing - Electronic Warfare Aircraft, Fixed Wing – Strike Aircraft, Fleet Support Vessel, Surface Combatant Targets: Air Targets - Drone, Air Targets - Other Systems being Trained/Tested: None Munitions: Projectile - Large Caliber, Projectile - Medium Caliber, Rockets, Surface-to-Air Missiles 	
Active Sonar	No	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Weapon firing noise	
Parameters for Analysis	Includes in-air explosive bins at low and medium altitudes.	
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032	
	PMSR	
	SOCAL	
	Hawaii Range Complex (PMRF Training Area))	

A.2.3.6.2 In-Port Maintenance Testing

Vessel Evaluation	
In-Port Maintenan	ce Testing
Short Description	Each combat system is tested to ensure they are functioning in a technically acceptable manner and are operationally ready to support at-sea Combat System Ship Qualification Trial events.
Long Description	Each combat system is tested to ensure they are functioning in a technically acceptable manner and are operationally ready to support at-sea Combat System Ship Qualification Trial events. The ship's test plans and procedures, Maintenance Repair/Requirements Cards, and computerized planned maintenance system are used in establishing testing standards for each system and pieces of equipment. Ship's crew, under supervision of subject matter experts, complete all actions and receive remedial training where required. Trouble Observation Reports are written on noted discrepancies.
Typical Components	Platforms: All Navy Ships and Boats, Surface Combatant Targets: None Systems being Trained/Tested: Sonar Systems - Hull Mounted Munitions: None
Active Sonar	MF1
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	Port Hueneme Harbor
	Naval Base San Diego
	Hawaii Range Complex (Pearl Harbor)

A.2.3.6.3 Propulsion Testing

Vessel Evaluation	
Propulsion Testing	
Short Description	Ship is run at high speeds in various formations and at various depths.
Long Description	Propulsion testing is one part of the total sea trial activity. During this activity, the ship is tested for maneuverability, including full power and endurance runs.
Typical Components	Platforms: Amphibious Warfare Vessel, Fleet Support Vessel Targets: Surface Targets - Floating Systems being Trained/Tested: Propulsion Systems Munitions: None
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	Ships will not be conducting test constantly for the entire duration. Ships may not be traveling in a straight line. Ships will operate across the full spectrum of capable speeds. During surface combatant sea trials full-power runs are conducted for a total of 4 hours, and endurance runs are conducted for a total of 2 hours.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL
	Hawaii Range Complex

A.2.3.6.4 Signature Analysis Operations

Vessel Evaluation	
Signature Analysis	Operations
Short Description	Surface ship and submarine testing of electromagnetic, acoustic, optical, and radar signature measurements.
Long Description	Signature analysis activities include electromagnetic, acoustic, optical, and radar signature measurements, recording, and post-run analyses of data of Navy surface and subsurface vessels. These activities include electromagnetic signature measurement, calibration, and detection of submarines, acoustic and magnetic signature detection of unmanned underwater vehicles and surface ships, radar, and optical detection of surface ships. Testing includes intelligence, surveillance, reconnaissance missions.
Typical Components	Platforms: Amphibious Warfare Vessel, Moored Platform, Submarine, Support Craft Targets: None Systems being Trained/Tested: Acoustic Communications Munitions: None
Active Sonar	MFM, HFM
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	Naval Base San Diego
	Hawaii Range Complex

A.2.3.6.5 Small Ship Shock Trial

Vessel Evaluation	
Small Ship Shock Ti	rial
Short Description	Underwater detonations are used to test new ships or major upgrades.
Long Description	Each new class (or major upgrade) of surface ships constructed for the Navy may undergo an at-sea shock trial. A shock trial is a series of underwater detonations that sends a shock wave through the ship's hull to simulate near misses during combat. A series of up to four underwater detonations per event will be conducted at various distances from the ship (charges are set closer to the ship as the trial progressives).
Typical Components	 Platforms: Fixed Wing – Other Aircraft, Support Craft, Surface Combatant, Rotary Wing Aircraft Targets: None Systems being Trained/Tested: None Munitions: Explosives
Active Sonar	No
In-Water Explosives	E16
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Ship shock trials
Parameters for Analysis	One event may occur during the 7-year period, which will involve up to three 10,000-lb. charges with at least six full days between detonations. Testing will occur in waters deeper than 650 feet. Stressors to human resources were not analyzed for this activity since it occurs greater than 12 nautical miles (NM) from shore.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL

A.2.3.6.6 Submarine Sea Trials – Weapons System Testing

Vessel Evaluation	
Submarine Sea Tria	als – Weapons System Testing
Short Description	Submarine weapons and sonar systems are tested at-sea to meet the integrated combat system certification requirements.
Long Description	Submarine weapons and sonar systems are tested at-sea to meet the integrated combat system certification requirements. This test involves subjecting the integrated combat system through rigorous testing which consists of passive and active sonar activities, launching 'water slugs' and exercise torpedoes.
Typical Components	Platforms: Moored Platform, Submarine, Support Craft
	Targets: Sub-surface Targets - Maneuvering
	Systems being Trained/Tested: Acoustic Communications, Sonar Systems - Hull Mounted, Sonar Systems - Other, Underwater Range Systems
	Munitions: Torpedoes - Exercise
Active Sonar	MFL, MFH, HFM, HFH, Broadband (LF to HF)
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL
	Hawaii Range Complex

A.2.3.6.7 Surface Warfare Testing

Vessel Evaluation	
Surface Warfare Te	esting
Short Description	Tests the capabilities of shipboard sensors to detect, track, and engage surface targets. Testing may include ships defending against surface targets using explosive and non- explosive projectiles, gun system structural test firing and demonstration of the response to Call for Fire against land based targets (simulated by sea-based locations).
Long Description	Surface warfare events are gun weapons system tests conducted in a clear environment to demonstrate the capability of shipboard and remote (helicopter) sensors to detect and track surface or land based (simulated by sea based locations) targets and engage targets with simulated and live gun and missile firings. Testing can also include structural test firing.
Typical Components	Platforms: Amphibious Warfare Vessel, Fixed Wing – Adversary Aircraft, Fixed Wing – Electronic Warfare Aircraft, Fixed Wing – Other Aircraft, Fixed Wing – Patrol Aircraft, Fixed Wing – Strike Aircraft, Rotary-Wing Aircraft, Submarine, Support Craft, Surface Combatant Targets: Air Targets - Drone, Air Targets - Other, Sub-surface Targets - Maneuvering, Surface Targets - Floating, Surface Targets - Maneuvering, Surface Targets - Towed Systems being Trained/Tested: Sonobuoys
	Caliber, Rockets, Surface-to-Air Missiles, Surface-to-Surface Missiles, Torpedoes - Exercise
Active Sonar	MFM, HFH
In-Water Explosives	E3, E5, E6, E7, E8, E9
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Explosive gunnery Explosive missiles and rockets Non-explosive gunnery Non-explosive missiles and rockets Towed in-water devices Weapon firing noise
Parameters for Analysis	Specific modeling areas for this activity include SOAR. Includes explosive bins at high altitudes. Ships will not be conducting tests constantly for the entire duration.
	Phase IV Requirement 2025-2032
Location (typical	PMSR
where applicable)	SOCAL
	Hawaii Range Complex (PMRF Training Area)

A.2.3.6.8 Undersea Warfare Testing

Vessel Evaluation	
Undersea Warfare	Testing
Short Description	Ships demonstrate capability of countermeasure systems and underwater surveillance, weapons engagement, and communications systems. This tests ship's ability to detect, track, and engage undersea targets.
Long Description	Undersea warfare events may be comprised of tracking and firing events or tests of hull- mounted sonar system capabilities to detect and avoid torpedo type targets. Tracking and firing events ensure the operability of the undersea warfare suite and its interface with the rotary-wing helicopter. Tests include demonstrating the ability of the ship to search, detect, and track a target and conduct attacks with exercise torpedoes. Detection and avoidance events may use surface craft and underwater platforms to test the capability of mid- and high frequency acoustic sources. Subsurface moving targets, rocket and air- dropped weapons, sonobuoys, towed arrays, and sub-surface torpedo-like devices may be used.
Typical Components	 Platforms: Fleet Support Vessel, Rotary-Wing Aircraft, Submarine, Support Craft, Surface Combatant, Unmanned Surface Vehicle Targets: Sub-surface Targets - Maneuvering Systems being Trained/Tested: Sonar Systems - Dipping, Sonar Systems - Hull Mounted, Sonar Systems – Mine Warfare, Sonobuoys Munitions: Air-to-Surface Missiles, Torpedoes - Exercise
Active Sonar	MF1, MFM, MFH, HFH
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Non-explosive missiles and rockets Towed in-water devices
Parameters for Analysis	Five targets per event. All sonobuoys have a parachute unless otherwise noted. Ships will not be conducting test constantly during the entire duration.
	Phase IV Requirement 2025-2032
Location (typical specific location where applicable)	SOCAL Hawaii Range Complex (PMRF Training Area)

A.2.3.6.9 Vessel Signature Evaluation

Vessel Evaluation	
Vessel Signature Evaluation	
Short Description	Surface ship, submarine, and auxiliary system signature assessments. This may include electronic, radar, acoustic, infrared and magnetic signatures.
Long Description	Radar cross signature testing of surface ships and submarines is accomplished on new ships and periodically throughout a ship's life cycle to measure how detectable the ship is to radar. For example, Assessment Identification of Mine Susceptibility assessments are passive electromagnetic and acoustic measurements performed on mine countermeasure ships and on the Littoral Combat Ship mine countermeasure modules (i.e., auxiliary systems) to determine their mine susceptibility using seafloor deployed magnetometers and hydrophones, and a ship-board global positioning sensor tracking system. Signature testing of all surface ships and submarines verifies that each vessel's signature is within specifications, and may include the use of helicopter-deployed instrumentation, ship-mounted safety and navigation systems, fathometers, tracking devices, radar systems, and underwater communications equipment. Also included in this activity is the Shipboard Electronic Systems Evaluation Facility which conducts measurements of antenna radiation patterns, Federal Aviation Administration identification of Friend or Foe systems, and Tactical Air Navigation Systems.
Typical Components	Platforms: Amphibious Warfare Vessel, Surface Combatant Targets: None Systems being Trained/Tested: None Munitions: None
Active Sonar	No
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032 PMSR SOCAL (San Clemente Island)

A.2.3.7 Other Testing

A.2.3.7.1 Acoustic and Oceanographic Research

Other Testing Activities		
Acoustic and Ocea	Acoustic and Oceanographic Research	
Short Description	Research using active transmissions from sources deployed from ships, aircraft, and unmanned underwater vehicles. Research sources can be used as proxies for current and future Navy systems.	
Long Description	Active acoustic transmissions used for engineering tests of acoustic sources, validation of ocean acoustic models, tests of signal processing algorithms, characterization of acoustic interactions with the ocean bottom, fish, and ocean surface. Standard oceanographic research testing (acoustic Doppler current profiler, fathometer-like systems) also to be employed.	
Typical Components	Platforms: Moored Platform, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: None	
	Systems being Trained/Tested: Acoustic Communications, Sonar Systems – Other, Sonar Systems – Towed, Unmanned Vehicle Systems	
	Munitions: None	
Active Sonar	LFM, MFM, MFH, HFM, Broadband (LF to HF), Broadband (MF to HF)	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Unmanned vehicles	
Parameters for Analysis	None	
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032	
	PMSR	
	SOCAL	
	Hawaii Range Complex (PMRF Training Area)	

A.2.3.7.2 Countermeasure Testing

Other Testing Activities		
Countermeasure To	Countermeasure Testing	
Short Description	Countermeasure testing involves the testing of systems that will detect, localize, and track incoming weapons, including marine vessel targets. Testing includes surface ship torpedo defense systems and marine vessel stopping payloads.	
Long Description	Countermeasure testing involves the testing of systems that will detect, localize, and track incoming weapons, including marine vessel targets. At-sea testing of the Surface Ship Torpedo Defense systems includes towed acoustic systems, torpedo warning systems, and countermeasure anti-torpedo subsystems. Some countermeasure scenarios would employ non-explosive torpedoes against targets released by secondary platforms (helicopter or submarine). While surface vessels are in transit, countermeasure systems may be used to identify false alert rates. Testing of the maritime vessel stopping payloads will deliver the appropriate measure(s) to affect a target vessel's propulsion and associated control surfaces to significantly slow and potentially stop the advance of the vessel.	
Typical Components	 Platforms: Aircraft Carrier, Rotary-Wing Aircraft, Surface Combatant Targets: Air Targets - Other, Sub-surface Targets - Maneuvering, Surface Targets - Floating Systems being Trained/Tested: Countermeasures Munitions: Rockets, Torpedoes - Exercise 	
Active Sonar	MFM, MFH, HFH, VHFH, Broadband (LF to HF), Broadband (MF to HF)	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Unmanned vehicles	
Parameters for Analysis	Not all events will include the use of acoustics.	
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032	
	SOCAL	
	Hawaii Range Complex (Kalohi Channel, Pailolo Channel, Maui Basin, Alalakeiki Channel, PMRF Training Area)	
A.2.3.7.3 Insertion/Extraction

Other Testing Activities	
Insertion/Extractio	n
Short Description	Testing of submersibles capable of inserting and extracting personnel and payloads into denied areas from strategic distances.
Long Description	Testing of submersibles capable of inserting and extracting personnel and payloads into denied areas from strategic distances. Testing could include the use of forces deployed from submerged submarines while at sea.
Typical Components	Platforms: Fleet Support Vessel, Submarine Targets: None Systems being Trained/Tested: Acoustic Communications, Sonobuoys Munitions: None
Active Sonar	LFH, HFM, Broadband (LF to MF)
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels
Parameters for Analysis	Test will not occur constantly throughout duration. For biological resource analysis, vessel noise and vessel strike are only analyzed for the periods while the submarines are surfaced, typically brief in nature. Mitigation measures related to vessel movement are only considered during the period of surfacing as well. For human resource stressor analysis, physical disturbance and strike and physical interactions are only analyzed for the periods while the submarine are surfaced, typically brief in nature.
Location (typical	Phase IV Requirement 2025-2032
specific location where applicable)	SOCAL
	Hawaii Range Complex

A.2.3.7.4 Non-Acoustic Component Testing

Other Testing Activities	
Non-Acoustic Com	ponent Testing
Short Description	Testing of towed or floating buoys for communications through radio-frequencies or two- way optical communications between an aircraft and underwater system(s).
Long Description	Testing associated with radio frequency communications could occur from towed antennas from surface vessels, from single-transmit buoys released from submarines, or tethered buoys from submarines for two-way communication. Optical communications tests may include communication between helicopter or fixed wing aircraft and manned or unmanned underwater systems, and may also include ground truth sensors mounted on surface craft.
Typical Components	 Platforms: All Navy Ships and Boats, Amphibious Warfare Vessel, Fleet Support Vessel, Rotary-Wing Aircraft, Small Boat, Support Craft Targets: None Systems being Trained/Tested: None Munitions: None
Active Sonar	No
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels Towed in-water devices
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL

A.2.3.7.5 Semi-Stationary Equipment Testing

Other Testing Activities	
Semi-Stationary Equ	ipment Testing
Short Description	Semi-stationary equipment (e.g., hydrophones) is deployed to determine functionality.
Long Description	Semi-stationary equipment testing is performed from a fixed site, suspended over the side of a boat, moored to the bottom, suspended in the water column, or on the surface. Examples of semi-stationary equipment include moored hydrophones (i.e., devices to listen to underwater sound), line arrays (i.e., multiple hydrophones) deployed on the ocean bottom, acoustic countermeasures, a moored oceanographic sensor that moves vertically through the water column, and sonobuoys (i.e., expendable sonar systems). Some units produce sound in the water (e.g., acoustic countermeasures), while others only listen (e.g., passive sonobuoys, vector sensors that measure particle motion). Some tests could require deployment in an area that provides opportunistic data collection (e.g., placing a hydrophone near a shipping lane to collect shipping noise data), or with specific geographic or oceanographic requirements.
Typical Components	Platforms: Moored Platform, Structure Targets: None Systems being Trained/Tested: Distributed Systems Munitions: Demolition Devices
Active Sonar	HFH
In-Water Explosives	E4
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity-based Mitigation): Active acoustic sources Manned surface vessels Explosive mine countermeasure and neutralization (no divers)
Parameters for Analysis	None
Location (typical	Phase IV Requirement 2025-2032
specific location where	Naval Base San Diego
applicable)	Hawaii Range Complex (Pearl Harbor)

A.2.3.7.6 Simulant Testing

Other Testing Activities	
Simulant Testing	
Short Description	The capability of surface ship and aircraft defense systems to detect and protect against chemical and biological attacks are tested.
Long Description	The capabilities of surface ship defense systems to detect and protect in the event of chemical and biological attacks are tested. Testing involves the deployment of harmless compounds (i.e., simulants) as substitutes for chemical and biological warfare agents. Because chemical and biological warfare agents remain a security threat, the Department of Defense uses relatively harmless compounds (simulants) as substitutes for chemical and biological warfare agents to test equipment intended to detect their presence. Chemical and biological agent detectors monitor for the presence of chemical and biological warfare agents. The simulants trigger a response by sensors in the detection equipment without irritating or injuring personnel involved in testing detectors.
Typical Components	Platforms: Fixed Wing – Other Aircraft, Surface Combatant Targets: None Systems being Trained/Tested: None Munitions: None
Active Sonar	No
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vessels
Parameters for Analysis	Examples of Chemical Simulants: glacial acetic acid, triethyl phosphate Examples of Biological Simulants: spore-forming bacteria, non-spore-forming bacteria, the protein ovalbumin, MS2 bacteriophages, and the fungus <i>Aspergillus niger</i>
Location (typical	Phase IV Requirement 2025-2032
specific location where applicable)	SOCAL

A.2.4 Naval Information Warfare Systems Command

A.2.4.1 Acoustic and Oceanographic Science and Technology

A.2.4.1.1 Acoustic, Oceanographic, and Energy Research

Acoustic and Ocea	nographic Science and Technology
Acoustic, Oceanographic, and Energy Research	
Short Description	Research and testing utilizing the marine environment for acoustics, oceanographic research, novel techniques for energy generation, and research in support of marine mammal sciences.
Long Description	Testing includes activities utilizing the marine environment for research, development, test, and evaluation of activity-related systems. Tests may involve radar, environmental sensors, magnetic sensors, passive and active acoustic sensors, optical sensors, and lasers. Instrumentation would be temporarily placed in the water column, seafloor, and recovered upon completion of testing. Surface operations would utilize a variety of vessels including unmanned surface and subsurface vehicles, and temporary moorings and buoys for deployment, operation, and testing. Energy research would include the development and testing of energy harvesting and storage technologies, maritime charging stations, remote communications, and associated infrastructure. This testing would also include bioacoustics research in support of marine mammal science.
Typical Components	 Platforms: Moored Platform, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: None Systems being Trained/Tested: Acoustic Communications, Sonar Systems - Other, Sonar Systems - Towed, Unmanned Vehicle Systems, Laser, Radar, Energy Harvesting and Charging Munitions: None
Active Sonar	LFM, MFM, MFH, HFM, Broadband (LF to HF), Broadband (MF to HF)
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Unmanned vehicles
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
Location (tynical	PMSR
specific location	SOCAL
where applicable)	SOCAL Nearshore (San Diego Bay)
	Hawaii Range Complex (Pearl Harbor)

A.2.4.2 Other Testing Activities

A.2.4.2.1 Communications

Other Testing Activities	
Communications	
Short Description	Testing communications and networks.
Long Description	 Communications testing may include following activities: Develop and test real-time command-and-control communication networks that function above, on, and under the ocean. Testing underwater network systems that may include fiber-optic cables, laser communications, and acoustic modem networks. Testing would include the temporary placement of fiber-optic cable, communication nodes, and other instrumentation on the seafloor. Underwater fiber-optic nodes (or endpoints) may also be connected via cable to temporary surface communications buoys. Testing would include air to water communications, such as radio frequency and laser.
Typical Components	 Platforms: Aerostat, Fixed Wing Aircraft, Moored Platform, Remotely Operated Underwater Vehicle, Support Craft, Unmanned Aerial Vehicle, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: None Systems being Trained/Tested: Acoustic Communications, Sonar Systems - Other Munitions: None
Active Sonar	Broadband (LF to MF)
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Unmanned vehicles
Parameters for Analysis	None
	Phase IV Requirement 2025-2032
Location	SOCAL Hawaii Range Complex

A.2.4.2.2 Intelligence, Surveillance, Reconnaissance

Other Testing Activ	vities
Intelligence, Surve	illance, Reconnaissance
Short Description	Testing ISR technologies may include mine detection and classification; detection and classification of targets of interest; devices under test on submarine cables; systems to detect mine shapes on ship hulls and pier structures; sensors for swimmer interdiction and other threats; and instrumentation that can detect explosive, radioactive, and other signatures.
Long Description	 Intelligence, Surveillance, and Reconnaissance systems testing may include the following activities: Testing undersea technologies that improve the Navy's capability to conduct effective anti-submarine warfare operations in littoral waters. Such tests would measure undersea surveillance performance using electromagnetic or passive acoustic sensors and active transducers. Acoustic modems/communications transducers would be used to send messages. Systems may also employ towed devices, remotely operated vehicles, or unmanned underwater vehicles. Acoustic releases would be used for the recovery of seafloor-mounted or water columnsuspended hardware. Semi-stationary equipment testing is performed from a fixed site, suspended over the side of a boat, moored to the bottom, suspended in the water column, or on the surface. Semi-stationary equipment may include moored hydrophones (i.e., devices to listen to underwater sound), line arrays (i.e., multiple hydrophones) deployed on the ocean bottom, acoustic countermeasures, a moored oceanographic sensor that moves vertically through the water column, and transducers. Mine detection and classification testing to evaluate the capability of generating underwater magnetic and acoustic signature fields, andsonar systems that can detect and classify a wide range of threat mines at various water depths. Devices at test on submarine cables Testing of sensors for swimmer interdiction and other threats. Testing of instrumentation that can detect explosive and radioactive signatures of concern.
Typical Components	 Platforms: Moored Platform, Small Boat, Support Craft, Remotely Operated Vehicle, Unmanned Aerial Vehicle - Fixed Wing Aircraft, Unmanned Aerial Vehicle - Rotary Wing Aircraft, Unmanned Bottom Crawler, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: Mine Targets Systems being Trained/Tested: Acoustic Communications, Air Gun, Sonar Systems - Other, Sonar Systems - Towed, Unmanned Vehicle Systems Munitions: Demolition Devices
Active Sonar	LFH, MFL, MFM, MFH, HFL, HFM, VHFH, Broadband (LF), Broadband (LF to HF), Broadband (MF to HF)
In-Water Explosives	No

Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Unmanned vehicles
Parameters for Analysis	Multiple areas modeled in SOCAL for this activity along with HRC.
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	PMSR
	SOCAL (CPAAA, San Clemente Island)
	Naval Base San Diego
	SSTC (Boat Lanes – North and South)
	Hawaii Range Complex (Pearl Harbor)

A.2.4.2.3 Vehicle Testing

Other Testing Activities		
Vehicle Testing	Vehicle Testing	
Short Description	Testing of surface and subsurface vehicles and sensor systems, which may involve Unmanned Underwater Vehicles, gliders, and Unmanned Surface Vehicles.	
Long Description	 The vehicle testing and sensor systems may include the following: General testing of the navigational and tracking systems for Unmanned Underwater Vehicles and Unmanned Surface Vehicles of all sizes. Testing could include autonomous transit of up to 60 days for certain vehicles. Testing of unmanned vehicles with mine-hunting sensors and magnetic mine countermeasure systems in shallow water environments and in and around rocky outcroppings. This type of testing supports inert mine-hunting systems and provides training to Navy personnel on approaches to deploy, detect, and defend against mine systems using unmanned undersea vehicles. Testing of underwater surveillance systems and anti-submarine warfare systems to detect and track surface and subsurface targets in support of classification, assessment, and response scenarios. This testing may involve multiple small unmanned underwater vehicles working collectively. Testing of passive arrays for conducting submarine detection and tracking experiments and demonstrations. The arrays are composed of hydrophones to receive acoustic energy radiated by targets of interest. Testing of autonomous vehicles and sensors for oceanographic research and meteorology. Testing would include the use of oceanographic research and meteorology. Testing would include the use of oceanographic research and meteorology. Testing would include the use of oceanographic research and meteorology. Testing would include the use of oceanography sensors to sample and characterize the ocean water column properties at spatial and temporal resolutions to measure and capturebathymetry, imagery data, conductivity, temperature and depth data, and optical data. Testing the deployment of communication payloads and non-explosive objects from temporarily-placed seafloor devices, surface and subsurface vessels/vehicles and unmanned systems. 	
Typical Components	 Platforms: Glider, Moored Platform, Remotely Operated Vehicle, Small Boat, Unmanned Aerial Vehicles, Unmanned Bottom Crawler, Unmanned Surface Vehicle, Unmanned Underwater Vehicle Targets: Mine Targets Systems being Trained/Tested: Acoustic Communications, Electromagnetic Systems, Sonar Systems - Other, Unmanned Vehicle Systems Munitions: None 	
Active Sonar	LFH, MFL, MFH, HFL, HFM, VHFH	
In-Water Explosives	No	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Towed in-water devices Unmanned vehicles	

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Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL
	Hawaii Range Complex
	Transit Corridor

A.2.5 Office of Naval Research Testing Activities

A.2.5.1 Acoustic and Oceanographic Science and Technology

A.2.5.1.1 Acoustic and Oceanographic Research

Acoustic and Ocea	Acoustic and Oceanographic Science and Technology	
Acoustic and Ocea	nographic Research	
Short Description	Research involving passive acoustic and oceanographic sensing, as well as active transmissions from sources deployed from ships, aircraft, and unmanned underwater vehicles. Research sources serve as proxies for current and future Navy systems.	
Long Description	Active acoustic transmissions used for engineering tests of acoustic sources, validation of ocean acoustic models, tests of signal processing algorithms, and characterization of acoustic interactions with the ocean bottom, fish and ocean surface. Standard oceanographic research sensing (acoustic Doppler current profiler, fathometer-like systems) also to be employed.	
Typical Components	 Platforms: Moored Platform, Small Boat, Support Craft, Unmanned Underwater Vehicle, Unmanned Aerial Vehicle, Unmanned Surface Vehicle, Ocean Bottom Lander Targets: Sub-surface Targets – Stationary, Anti-Submarine Warfare Targets – Expended Systems being Trained/Tested: Air Gun, Oceanographic - Other, Sonar Systems - Other Munitions: Signal Underwater Sound Devices, 	
Active Sonar	LFM, LFH, MFM, MFH, HFM, HFH, VHFM	
In-Water Explosives	E1, E3	
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Active acoustic sources Manned surface vessels Unmanned vehicles Explosive sonobuoys and research-based sub-surface explosives	
Parameters for Analysis	Research activities may take place anywhere in the Study Area. Air guns not to be used within 3 nm of land. Explosives not to be used within 12 nm of land. Activity in marine sanctuaries limited to de minimis acoustic sources only.	
	Phase IV Requirement 2025-2032	
	NOCAL	
Location (typical specific location	PMSR	
where applicable)	SOCAL	
	Hawaii Range Complex	

A.2.5.1.2 Large Displacement Unmanned Underwater Vehicle Testing

Acoustic and Ocean	nographic Science and Technology
Large Displacemen	t Unmanned Undersea Vehicle Testing
Short Description	Autonomy testing and environmental data collection with Large Displacement Unmanned Undersea Vehicles.
Long Description	Large Displacement Unmanned Undersea Vehicle (LDUUV)testing includes launch, autonomous transit (up to 60 days), environmental data collection (e.g., bathymetry, water column properties, ocean surface properties) and retrieval. LDUUV testing throughout the study area will include de minimis acoustic sources (modems, imaging sonars, and fathometers) for safe navigation and data collection.
Typical Components	Platforms: Large Displacement Unmanned Underwater Vehicle Targets: Sub-surface Targets - Stationary Systems being Trained/Tested: –None Munitions: None
Active Sonar	Νο
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Unmanned vehicles
Parameters for Analysis	Any acoustic sources used during this activity would be de minimis and not quantitatively analyzed and therefore are not included under systems.
	Phase IV Requirement 2025-2032
Location (typical	NOCAL
where applicable)	SOCAL
	Hawaii Range Complex

A.2.5.1.3 Long Range Acoustic Communications

Acoustic and Oceanographic Science and Technology	
Long Range Acoustic Communications	
Short Description	Bottom mounted acoustic source will transmit a variety of acoustic communications sequences.
Long Description	Bottom mounted acoustic source will transmit a variety of acoustic communications sequences that will be recorded by a variety of fixed and mobile platforms at ranges from the 100s to the 1,000s of kilometers.
Typical Components	Platforms: Moored Platform, Small Boat Targets: None Systems being Trained/Tested: Oceanographic - Other Munitions: None
Active Sonar	LFM
In-Water Explosives	No
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Manned surface vehicles
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	Hawaii Range Complex

A.2.5.1.4 Mine Countermeasure Technology Research

Acoustic and Oceanographic Science and Technology	
Mine Countermeasure Technology Research	
Short Description	Test involves the use of broadband acoustic sources on unmanned underwater vehicles.
Long Description	Mine countermeasure system testing on unmanned underwater vehicles to take place offshore and in coastal waters. Broadband acoustic sources on unmanned underwater vehicles will use downward directed acoustic transmissions to characterize the ocean bottom. Inert objects will be placed on the bottom to test system performance.
Typical Components	Platforms: Unmanned Underwater Vehicle Targets: Sub-surface Targets - Maneuvering, Surface Targets - Maneuvering Systems being Trained/Tested: Acoustic Communications, Sonar Systems - Other Munitions: None
Active Sonar	MFH
In-Water Explosives	Νο
Mitigation Involving Visual Observations for Marine Species	Mitigation is required for the following stressors as described in Section 5.6 (Activity- based Mitigation): Unmanned vehicles Active acoustic sources
Parameters for Analysis	None
Location (typical specific location where applicable)	Phase IV Requirement 2025-2032
	SOCAL
	Hawaii Range Complex

A.3 Modernization and Sustainment of Ranges

This section provides additional information about Modernization and Sustainment activities proposed in this EIS/OEIS. Examples of Modernization (upgrading or expanding) range and testing/training areas, systems, and associated components include expanding special use airspace and installing permanent in-water structures, such as cables and platforms. Sustainment activities include maintenance and repair of and around existing and upgraded structures within the Study Area.

A.3.1 Special Use Airspace Modification

The Navy proposes to expand the Study Area in the SOCAL Range Complex with a corresponding increase in special use airspace proximate to the current Warning Area 291 (W-291). The Navy is coordinating with the FAA in its non-rulemaking action for establishing the two new airspace areas.

A.3.1.1 Proposed Area Description

The new proposed airspace is described below and depicted in Figure A-1.

1. W-293. This 48,078.5 NM² area would include the airspace from the ocean surface to 17,000 ft. at the western end of Control 1177.

Beginning at lat. 32°12'04"N, long. 119°42'03"W. to lat. 31°50'00"N, long. 119°42'03"W, to lat. 30°40'00"N, long. 120°50'03"W, to lat. 27°30'00"N, long. 127°10'04"W, to lat. 30°23'30"N, long. 127°48'50"W, to lat. 31°54'18"N, long. 121°33'12"W, to lat. 31°18'54"N, long. 121°10'59"W, to lat. 31°41'00"N, long. 120°15'03"W to the point of beginning.

2. W-294. This 33,878 NM² area would include the airspace from the ocean surface to 80,000 ft.

Beginning at lat. 28°09'13"N, long. 120°00'00"W, to lat. 24°00'01"N, long. 120°00'00"W, to lat. 24°00'01"N, long. 125°00'03"W, to lat. 27°18'30"N, long. 121°00'00"W to the point of beginning.

The new airspace would be used intermittently when announced by Notice to Air Mission.

A.3.1.2 Need for New Airspace

The need for the additional special use airspace stems from three factors:

Tactics, Techniques, and Procedures. Additional airspace contiguous with W-291 and W-289 (PMSR) is needed to train personnel in the realistic employment of new aircraft and aerial weapon systems, unmanned aerial systems, and Tactics, Techniques and Procedures associated with Distributed Maritime





Operations. The Navy's foundation concept is built on six imperatives, including increasing distribution of the force across expanding distances. U.S. military advantages are eroding as our adversaries invest in significant technological developments, aggressive military modernization, and growing military capacity and capabilities. Proliferation of long-range precision missiles with their enhanced capabilities for extensive space denial means the United States can no longer presume security when positioning near shore operations. The air space in W-291 was originally developed to support a previous generation of aircraft, weapons, and tactics. Today, W-291 is still used as the tactical cornerstone for training and certifying all deploying Strike Groups in the Pacific. However, due to current airspace configuration constraints, W-291 no longer meets naval aviation training requirements conducted off the coast of Southern California.

Fifth Generation Aircraft. Integration of the F-35 Joint Strike Fighter (JSF) fifth generation aircraft has dramatically extended the battlefield. The F-35 is designed to replace aging fighter inventories including U.S. Air Force F-16s and A-10s, U.S. Navy F/A-18s, and U.S. Marine Corps AV-8B Harriers and F/A-18s. Traveling at Mach 1.6, the F-35 JSF is a long-range, supersonic fighter designed to gather, fuse, and distribute information far beyond ranges of current fourth generation aircraft. Onboard targeting systems provide extended range detection and precision targeting against ground targets and long-range detection of air-to-air threats. Increased range, speed and mobility, extended weapon systems, and expanded sensor capabilities of the F-35 extend hundreds of miles beyond the current size of W-291.

Consequently, the current size of W-291 restricts employment of the F-35 JSF to its full range and sensor capability and results in negative training, whereby creating habit patterns inconsistent with the full spectrum of tactical capabilities of fifth generation aircraft.

Unmanned Aerial Vehicles. Rapidly developing abilities of near-peer competitors drive the need for increased naval capability dispersed over wider areas. Unmanned Aerial Vehicles (UAVs) extend long-range warfighting capability to augment traditional combatant force, whereby providing the option for Combatant Commanders to assume greater operational risk while maintaining tactical and strategic advantage. The Navy is developing and integrating new unmanned technology to build a more lethal and distributed force. UAVs support the naval mission with enhanced technologies for maritime domain awareness with extended range and persistent Intelligence, Surveillance, Reconnaissance and Targeting capabilities.

Large UAVs are capable of significantly greater ranges than the smaller systems, so leveraging this technology with dispersed Command and Control (C2) forces requires expanding existing Special Use Airspace (SUA) in the SOCAL Range Complex. These systems provide assets capable of supporting long-range ordnance delivery. The use of ordnance poses a hazard to non-participating aircraft, so special use airspace is required to alert non-participants of potential dangers.

The Navy is expanding the Study Area to include PMSR and NOCAL Warning Areas W-283, W-285, W-260 and W-513 (Figure A-2). The expansion will support Distributed Maritime Operations via a continuous, inter-connected network of SUA and surface OPAREA from San Diego to Fort Bragg area. Establishing low level SUA between W-291 and W-289 (PMSR) establishes an UAV corridor aligning Fleet operations in W-291 to expanding Fleet operations on PMSR and north to the Central California Warning Areas.





A.3.2 Southern California Offshore Anti-Submarine Warfare Range Modernization

The Navy proposes to upgrade the existing, deep-water SOAR, located west of SCI, by installing new hydrophones and undersea cables. Maintenance of the deep-water SOAR is needed to sustain the SOAR capabilities.

The SOAR provides tactical range training and testing services to U.S. Navy units of the Pacific Fleet. Fleet readiness is a direct function of quality training, and the SOAR was designed to provide Fleet operators with this essential training. Anti-submarine warfare training is accomplished utilizing a mix of in-air and underwater instrumentation. The SOAR encompasses approximately 670 NM² of threedimensional underwater tracking areas, located just west of SCI (Figure A-4). The underwater tracking range (UTR) routinely supports air, surface, and subsurface unit-level torpedo firing exercises as well as strike group training.

A.3.2.1 Proposed In-Water System Design

There are two types of sensors that will be installed during this modernization: hydrophones and underwater telephones (UWTs). Hydrophones are used to convert acoustic energy into electrical energy, and are used to receive and record sounds on the range. UWTs are used for two-way underwater communications. A node is defined as the electronic package that is deployed on the sea floor and contains one or two sensors. A node containing a single hydrophone sensor is referred to as unidirectional. A node containing two sensors (hydrophone and UWT) is referred to as bi-directional. Several nodes and the associated cabling form an array. A junction box (J-box) is the terminus of the arrays, providing the mechanical and signal interface between the internode cables for the sensor arrays and the trunk cable. The trunk cable is the section of cable from the J-box to the onshore cable termination facility at SCI.

The SOAR Refurbishment would consist of installing new arrays and leaving the old arrays in place. The exact configuration would be determined following underwater surveys of the SOAR, but would be similar to the existing SOAR layout.

All arrays will connect to the existing near-shore junction box and no additional on-shore construction is anticipated. From the underwater junction box, the existing single trunk cable will connect to the onshore cable termination shelter via Sea Shore Interface (SSI) components including four horizontal directionally drilled conduits and their underwater exit points (Figure A-3). Only one of the four conduits is used for SOAR cables, the other three are unused, containing only a corrosion inhibitor solution. These existing components (junction box, trunk cable, and cable termination shelter) will remain in use and will not be replaced. Only the arrays, nodes, and hydrophones will be replaced.

The new nodes would be overlayed approximately within the existing node locations on the seafloor. Due to the configuration of nodes on an array (some of the existing nodes are individually cabled), the cable routes in water depths greater than about 4,000 ft. (deep water) would not be exactly the same as the existing arrays. Previous installation planning and successful historical cable deployments indicates that the seafloor within SOAR is mostly flat and of constant depth with little if any underwater obstructions or seafloor anomalies. The majority of the deep water cable and node deployment would be in the overseas environment, beyond 12 NM from shore.

The array cables would follow the same general path of the existing range, avoiding steep terrains. The spreading out or turning of cables is planned to occur at a constant depth, thus avoiding placing any cables at angles to the downward slope. Historically, there have been no cable failures or installation

impediments along the existing mid-water cable route. Given proven success and existing oceanographic data, following the existing cable routes would yield successful results for the new arrays. A second reason for following the existing cables is that this route proceeds shoreward within the West Cove Restricted Area (no anchorage) where anchoring is prohibited (33 CFR 334.921).

The underwater J-box is equivalent to a distribution panel, connecting the trunk cable to the arrays. It would contain pressure housings and a bottom-mounted structure to enclose the transition between the trunk cable and the internode cables. The J-box would contain pre-terminated internode cable "pigtails" or "branching units." These pigtails shall be coiled in the box and individually raised to the surface for connecting to an individual array.



Figure A-3: SOAR Sea Shore Interface (SSI)

A.3.2.2 Cable Characteristics

Internode cable is defined as the cable sections from the J-box to the first node and all subsequent sections between nodes. The design of the internode cable would be similar to that of standard submarine telecommunication cables, including up to 6 fibers encased in multiple layers of protective sheathing steel, nylon, and/or HDPE, and waterblocking material, plus a copper conductor.

A.3.2.3 Description of the Installation

The deployment of the cables would utilize conventional cable laying machinery including a linear cable engine (LCE) and cable pans. The cable from the J-box to the first node would be double-armored and approximately 2 in. in diameter. The new SOAR cables may follow the existing cable routes as the sensors are deployed. The intent is to laterally adjust the sensor positions slightly for the new hydrophones. It is expected that the new cables would lie across existing cables as they are deployed. This is not a concern because the undersea cables for the original SOAR sensors would continue to be used to allow continuous range operations during installation and verification activities and would provide redundancy as long as the cables are operational.

During the offshore deployment of the arrays, the bi-directional and uni-directional nodes would be tested to ensure that the sensors are functional. After the installation is complete, a positional survey would be performed to locate the exact geodetic locations of the sensors on the range. The verification equipment used for the deployment verification and for the survey would use existing SOAR resources that are routinely used during normal range maintenance activities.

A.3.2.4 Maintenance

During SOAR refurbishment and recurring maintenance, divers will replace old zinc anodes from the four existing electrical seafloor cable conduits and replace corrosion inhibitor solutions in the three unused conduits (Figure A-3).

To replace the zinc anodes, divers will remove a bolt, clean the area with a wire brush, to ensure electrical connectivity, and then place a new zinc anode on the conduit. There are two zinc anodes on each conduit; all eight will be replaced. The life expectancy of the anode is typically 24-months.

There is a valve on the underwater termination point of each conduit at approximately 90 ft. depth underwater. To replace corrosion inhibitor solutions, divers will open up the valve to drain the existing corrosion inhibitor solution (0.95 percent CORTEC Vapor Phase Corrosion Inhibitor [VpCI] S-69; 99.05 percent potable water, or similar makeup) from the three unused conduits. After a majority of the conduit is drained, the divers will close the valve and the new corrosion inhibitor solution (1.5 percent CORTEC VpCI-649 BD; 98.5 percent potable water, or similar) will be pumped into the conduits from the onshore cable vaults (Figure A-3). The solution is in a concentrated liquid form and will be mixed with potable water to achieve the desired percent solution. Solutions are effective for approximately 24 months and need to be replaced on a recurring basis. For the three conduits, there is approximately 6,160 gallons of solution that will be replaced every 2 years. For each event, it is estimated this work can be completed in approximately one week during daytime hours.

The corrosion inhibitor products selected for the proposed action are routinely used for this type of application in offshore areas because of its environmentally friendly properties. Manufacturer hydrotests of the product as depicted in Holden et al. (2010) have yielded low toxicity levels and waters containing the product remain safe for many species, allowing the product to be discharged according to local specifications.

A.3.2.5 Special Conservation Measures

The following special conservation measures would be implemented to reduce potential environmental impacts during the refurbishment activities:

- 1. All activities would occur at sea; no on-land construction is required. SCI may be used to stage equipment and materials.
- 2. The Navy would maintain oversight of all contractor activities in the offshore waters throughout the installation. The Navy would conduct a safety and environmental briefing for all contractor personnel prior to installation activities. The briefing would explain existing policies regarding the sensitive biological and cultural resources at SCI and illustrate the need to minimize disturbance to cultural sites and native plants, wildlife, and marine habitats.
- 3. Prior to in-water construction, the Navy would issue a Notice to Mariners alerting boaters to avoid areas of installation activity. As needed, the Navy may also identify portions of the offshore work areas as exclusive use areas on its website (www.scisland.org) to avoid conflicts.
- 4. Vessels engaged in installation would contain sorbent booms and pads for use in the unlikely event of a fuel spill, and would adhere to all Navy and Coast Guard requirements regarding the containment, cleanup, and reporting of spills.
- 5. To prevent any potential impacts to abalone during cable anchoring activities, divers would not place an anchor or the cable between the anchors within 3 ft. of any abalone species.
- 6. Any lighting associated with the Proposed Action would be directed downward to minimize the illumination of surrounding areas.

A.3.3 Shallow Water Training Ranges Installation

The proposed action would include the installation of underwater hydrophone instrumentation systems that would establish two Shallow Water Training Ranges (SWTRs) to enhance training in conjunction with the SOAR shown in Figure A-4. The proposed instrumentation would be in the form of undersea cables and sensor nodes, similar to instrumentation currently in place in SOAR. The cables and sensors would be similar to those that instrument the current deep water SOAR. The new areas would form an integral SWTR capability for SOAR. The combination of deep water and shallow water instrumentation would support a seamless tracking interface from deep to shallow water, which is an essential element of effective ASW training. The instrumented area would be connected to shore via multiple trunk cables.

The SWTR instrumentation would be an undersea cables system integrated with hydrophone and underwater telephone sensors, called nodes, connected to each other and then connected by up to eight trunk cables to a land-based facility where the collected range data would be used to evaluate the performance of participants in shallow water training exercises. The proposed range dimensions are shown in Figure A-4 and the basic proposed features of the instrumentation and construction follow.



Figure A-4: Shallow Water Training Range

A.3.3.1 Background

In 1999, the Navy formally identified the requirement for a SWTR on the West Coast of the United States to improve the U.S. Navy's shallow water ASW capabilities through more effective training on an instrumented range in shallow water. The Navy completed an analysis of impacts for the construction and use of the SWTR in the 2008 SOCAL EIS/OEIS (U.S. Department of the Navy, 2008). The Record of Decision for the 2008 SOCAL EIS/OEIS (U.S. Department of the Navy, 2009) included the installation of the SWTR but the installation of the underwater hydrophone array was delayed. In 2019, the proposed SWTR boundaries were re-evaluated and slightly modified from the 2008 boundaries. Though the boundaries are slightly revised, the original requirement for deep-to-shallow water tracking and communication is still valid.

The SWTR would provide underwater instrumentation for two shallow water extensions of the current deep water SOAR. Tanner Bank SWTR would encompass an area of 388 NM² and SCI SWTR would encompass an area of 129 NM². When installed, the underwater instrumentation would increase the use of these areas for ASW training involving mid-frequency active sonar.

A.3.3.2 Installation

The SWTR instrumentation would consist of a system of undersea telecommunication cables, referred to as array cables, arranged on the seafloor and connecting a series of nodes. Each node may contain one or more transducers, which enable the transmission of sound; or a hydrophone, which receives sound and converts it into an electrical signal. The array cables would be connected to an existing underwater junction box close to shore and pulled through existing bores on the western side of SCI. The cables would terminate in the cable termination shelter where data would be transmitted to the range and used to evaluate participant performance in shallow water training exercises. Each range would require a new trunk cable and a new junction box, thus the installation of three trunk cables and three junction boxes would be a part of the Proposed Action. The basic features of the proposed instrumentation and construction are described in this appendix.

The transducer nodes are capable of both transmitting and receiving acoustic signals from ships operating within the instrumented areas of SOAR (a transducer is an instrument that converts one form of energy into another, in this case, underwater sound into an electrical signal or vice-versa). Some nodes are configured to only support receiving signals, some can both transmit and receive, and others are transmit-only versions.

The acoustic signals that are sent from the exercise participants (e.g., submarines, torpedoes, ships) to the receive-capable range nodes allow the position of the participants to be determined and stored electronically for both real-time and future evaluation. The transmit-capable nodes allow communication from the range to ships or other devices that are being tracked. More specific information is described below:

The SWTR extension would consist of sensor nodes spread on the ocean floor over a 500-NM² area. The distance between nodes would vary between 0.5 NM and 3 NM, depending on water depth. Each sensor node would be similar in construction to the existing SOAR instrumentation. The sensor nodes are small spherical shapes of less than 6 inches in diameter. The sensors would be either suspended up to 15 ft. in the water column or lie flat on the seafloor. Sensor nodes located in shallow water with a presence of commercial fishing activity would have an additional protective device surrounding or overlaying a sensor. These mechanical protective devices would be 3 to 4 ft., round or rectangular, with a

shallow height. The final physical characteristics of the sensor nodes would be determined based upon local geographic conditions and to accommodate man-made threats such as fishing activity. Sensor nodes would be connected to each other by an interconnect cable (standard submarine telecommunications cable with diameters less than 1 inch).

- A series of sensor nodes would be connected via the interconnect cable to underwater junction boxes located in diver-accessible water depths. A junction box is rectangular in shape with dimensions of 10 to 15 ft. on each side. The junction boxes would connect to a shore-based facility via trunk cables (submarine cables up to 2-inch diameter with additional data capacity). The trunk cables eliminate the need to have numerous interconnect cables running to shore. Up to eight trunk cables with a combined length of 375 NM would be employed. Trunk cables would be protected in the seashore area by horizontal directionally drilled pipes running beneath the shoreline.
- The interconnecting cables and trunk cables would be deployed from a ship. The trunk cable paths would be routed through the deep water as much as is possible. The trunk cable, which passes through the seashore area, would terminate in SCORE's current cable termination facility at West Cove. From there, information gathered on the SWTR would be transmitted to the SCORE Range Operations Center. The adjacent SOAR has a single junction box located outside the nearshore area and places the trunk cable in a horizontal directionally drilled conduit that terminates onshore.
- The in-water instrumentation system would be structured to achieve a long operating life, with a goal of 20 years and minimum maintenance and repair throughout the life cycle. This is due to the high cost of performing at-sea repairs on transducer nodes and cables, the inherently long lead time to plan, permit, fund, and conduct such repairs (6 to 18 months) and the loss of range capability while awaiting completion. The long life performance would be achieved by using high-quality components, proven designs, and multiple levels of redundancy in the system design. This includes backup capacity for key electronic components and fault tolerance to the loss of individual sensors or even an entire sensor string. The use of materials capable of withstanding long-term exposure to high water pressure and salt water-induced corrosion is also important. Periodic inspection and maintenance in accessible areas also extends system life.

The Navy would submit cable area coordinates to the National Geospatial Intelligence Agency and request that the combined SWTR/SOAR area be noted on charts within the appropriate warning area. This area would be noted in the U.S. Coast Pilot as a Military Operating Area, as are other areas on the West Coast. The Navy may promulgate a Notice to Mariners and a Notice to Air Missions within 72 hours of the training activities, as appropriate.

A.3.3.3 Maintenance

Because the SWTRs would use the existing SOAR conduits described in Section A.3.2.4, and no maintenance activities would be required on the undersea cables or instrumentation, no additional maintenance activity would be required of either the Tanner Bank SWTR or SCI SWTR.

A.3.4 Sustainment of Undersea Ranges

Undersea ranges provide essential mission readiness capabilities. Range sustainment includes maintenance of systems and associated components. Maintenance may include, but is not limited to

inspections, system replacement to extend service life (e.g., anodes and clamps), replacement of corrosion inhibitor solutions, and catastrophic repairs. Sustainment activities at undersea training ranges may require the use of divers, vessels, and unmanned underwater vehicles. Vessels may be required to anchor to the seafloor. Activities may take up to several weeks at a time.

A.3.5 Deployment of Seafloor Cables and Instrumentation

The Navy proposes to deploy fiber-optic cables along the seafloor in three locations in the HCTT Study Area: south and west of SCI in the California OPAREA, to the north east of Oahu and to the west of Kauai in the Hawaii Study Area.

A.3.5.1 California Study Area Cable Expansion

In the California Study Area, an existing trunk cable (submarine fiber-optic cable) system would be expanded, involving approximately 600 kilometers (km) of fiber-optic cable with several junction boxes installed along the cable for devices under test. A submarine fiber-optic cable currently extends from SCI west into deep water (typically greater than 1,500 ft. deep). None of the installation would take place in shallow water, with the new cable starting approximately 100 NM from SCI and going further west from there (Figure A-5).

The cable allows for data transmission and would be used for a variety of tests described previously in Section A.2 (Testing Activities).



Figure A-5: California Study Area Cable Expansion (Approximate Location)

A.3.5.2 Hawaii Cable Project

A.3.5.2.1 Phase I

In the Hawaii Study Area, the Proposed Action includes maintenance and/or repair of the existing 60-70 km of undersea fiber-optic cable and communication units connected to the existing Wave Energy Test Site (WETS) off the coast of Marine Corps Base Kaneohe Bay (Figure A-6). Repair could include the replacement of the cable and communication units along with small extension of approximately 30 km at the communication node located at a depth of 4000 meters. The cable would be routed to avoid hard bottom occurring near land.

A.3.5.2.2 Phase II

In the Hawaii Study Area, the Proposed Action includes the installation of undersea fiber-optic cable and communication units to an existing undersea cable within PMRF located to the west of Kauai. The installation of the cable and communication units would be analogous to the type, length, and depth of the cable and units used in Phase I of the Hawaii Cable Project. Cable would be routed to avoid hard bottom occurring near land.



Figure A-6: Proposed Hawaii Cable Project (Phase I)

A.3.6 Installation and Maintenance of Mine Warfare and Other Training Areas

Support crews deploy, move, and retrieve mine countermeasure (MCM) targets or targets simulating adversary subsea and seabed infrastructure to include cables of varying diameters and lengths, bottom equipment, and equipment tethered to the bottom that is floating in the water column. MCM targets could be inserted on the seafloor (bottom targets) or tethered to anchors that are on the seafloor

(moored). MCM targets are non-explosive and emulate real world threats with a variety of sizes and shapes including spheres, cylinders, clamshells, and truncated cones as shown in Figure A-7. Minefields and mine training areas occur from the very shallow water (0-40 ft.) to deep water (>500 ft.). MCM targets need to be replaced every 1-2 years.

The shape and mooring line would be retrieved for refurbishment and redeployed with a new anchor nominally once per year. The concrete anchors would typically be abandoned in place on the bottom after each installation.

To seed a training minefield, MCM target shapes would be deployed from a stationary ship using precision GPS for positioning. Moored shapes are typically deployed in two stages. The shape (with attached mooring tether) is first lowered into the water and released to float on the surface. The vessel then positions over the installation site and releases the anchor to settle to the bottom. As the anchor falls, it pulls any slack out of the mooring line and then pulls the shape under. Bottom shapes are initially lowered into the water by crane, then released to settle to the bottom. Accounting for variables such as wind and current, the actual location is expected to be within approximately 100 yards of the drop point.

For underwater detonation training, individual target mines are inserted either by small boat, by diver, or both, depending on the training scenario.

Depending on the training scenario, a mine installation could consist of one or two mines or involve an entire minefield including a mix of 30 or more bottom and tethered mine shapes.

Existing and proposed minefield locations include:

- Southern California (Figure A-8, Figure A-9, and Figure A-10)
 - Point Mugu Sea Range
 - Tanner Bank Mine Training Range (includes the Tanner/Cortes Banks outside the Mine Training Range)
 - Pyramid Cove Mine Training Range
 - Training Area (TA)-Kilo
 - SSTC-North and South Boat Lanes
 - Imperial Beach Minefield
 - Ocean Beach Mine Training Area
 - Camp Pendleton Amphibious Assault Area
 - o Advance Research Projects Agency Training Minefield
- Oahu, Hawaii (Figure A-11)
 - Naval Defense Sea Area
 - o Puuloa Underwater Range
 - Ewa Beach Training Minefield
 - o Barbers Point Underwater Range
 - Barbers Point Harbor to Lighthouse Training Area (potential)
 - Kaneohe Bay (potential)
 - Bellows Beach (potential)
- Maui, Hawaii (Figure A-12)
 - Kahoolawe Sub Training Minefield
 - Penguin Bank
 - Kalohi Channel

•

- o Pailolo Channel
- o Maui Basin
- Alalakeiki Channel
- Kauai, Hawaii (Figure A-13)
 - PMRF Training Area (potential)
 - Waiapuaa Beach (potential)
 - Niihau Kingfisher Range

Other temporary training areas can be established by installing devices that could include hydrophones anchored to the seafloor similarly to anchored mine training shapes or other subsea/seabed targets. When training or testing is completed in the temporary range, or when onboard batteries run out, the instrumentation is recovered and where feasible, anchors are removed along with the mine shape.





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Figure A-8: Southern California Range Complex

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Figure A-9: San Clemente Island Training Areas



Figure A-10: San Diego Mine Warfare Training Areas



Figure A-11: Oahu Training Areas


Figure A-12: Maui Mine Training Areas

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Figure A-13: Kauai and Niihau Mine Training Areas

A.3.7 Installation and Maintenance of Underwater Platforms

An underwater landing platform is required to facilitate underwater vehicle pilot proficiency training in the SOCAL and Hawaii range complexes. The platform to be installed in SOCAL is new, but the platform to be installed in Hawaii was previously approved in 1999, installed in 2001, and removed in 2009. The 2001 installation approval included a Categorical Exclusion, informal consultation with NMFS Pacific Islands Area Office, and approval by the Army pursuant to Section 10 of the Rivers and Harbors Act. The intent is to reinstall a newly designed platform in the previously approved location.

Situated in the non-restrictive, flat, sandy seafloor training areas, the platforms would be permanently mounted, but removable for maintenance. The landing platforms would be approximately 40 ft. by 20 ft. and stand 15 ft. high, with a weight of approximately 16 tons, situated at a depth between 60–100 ft. (Figure A-14). Prior to the installation, numerous pre-poured concrete blocks would be installed in a pre-surveyed area to create a positive anchor point to keep the platforms stationary.

To support navigation to the training platforms, two high-frequency transponders are required to affixed to each platform. The transponders are only designed to be used during training evolutions and would be installed and removed within 24 hours prior to and after each series of scheduled training evolutions. The transponders would only be turned on during active training periods of approximately 4–6 hours.

The platform in SOCAL would be located just west of the Silver Strand Training Complex (SSTC) boat lanes (Figure A-10), and the Hawaii installation would be south of the entrance to Pearl Harbor (Figure A-11).

The underwater vehicles would deploy from their basing location and begin navigation to each respective geographic training platform location. Small surface craft would typically accompany and loiter the training area for safety. Pilots would follow their flight plans until they are within transponder range to which they would then train their equipment for precision navigation. Upon arrival at the training platform, pilots would accomplish repeated take-off and landing evolutions. Once landed, personnel may also practice a variety of insertion or extraction exercises, which may include using nearby training boat lanes for Over-the-Beach activities.

The landing platform would require routine inspections which would be accomplished by divers prior to each training evolution, during transponder installations. Each platform would be preserved in an antifouling coating that is similar to the bottom of a surface ship. Furthermore, a floating crane would be used approximately every five years to remove each platform from the ocean floor and then be taken to a ship repair facility to accomplish in-depth structural inspections, repairs, and preservation. Upon completion the platform would be returned and installed to their approved locations.



Figure A-14: Depiction of a Notional Underwater Platform

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Appendix B Activity Stressor Matrices

Environmental Impact Statement/

Overseas Environmental Impact Statement

Hawaii-California Training and Testing

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APPENDIX B ACTIVITY STRESSOR MATRICES

This appendix contains four matrices. The first two matrices in this appendix list the training and testing activities that occur in the Hawaii-California Training and Testing Study Area and their associated stressors. The third matrix shows the stressors associated with the Modernization and Sustainment of Ranges activities. The fourth matrix lists the resources analyzed in this Environmental Impact Statement/Overseas Environmental Impact Statement and the stressors they are potentially affected by.

Table B-1: Stressors by Training Activity

										Biolo	gical	Resour	ces								Phy	vsical	Resou	irces				Hum	an Re	sourc	ces		
		Acc	oustic	Stres	sors		Expl Stre	osive ssors	Energy	Stres	sors	Physi	ical Di Strike	isturbo Stres	ance a sors	and	Entang Stres	lement ssors	Inge Stre	estion essors	Air Quality Stressors	Se V	edime Vater Stre	ents ar Qualit ssors	nd Ty	Cultu Resou Stress	iral irce sors	Socio Re Sti	econo sourc ressoi	omic e s	Publ & Sti	ic Hea Safety ressor	ilth V 's
Hawaii-California Training Activity	Sonar & Other Transducers	Pile Driving	Vessel Noise	Aircraft Noise	Weapons Noise	Air Guns	Explosions in Water	Explosions in Air	In-Water Electromagnetic Devices	In-Air Electromagnetic Devices	High-Energy Lasers	Vessels & In-water Device Strike	Aircraft & Aerial Target Strike	Military Expended Material	Seafloor Devices	Pile Driving	Wires & Cables	Decelerators/Parachutes	Military Expended Materials – Munitions	Military Expended Materials – Other than Munitions	Air Pollutants	Explosives	Metals	Chemicals (Not Explosives)	Other Materials	Explosives	Physical Disturbance & Strike	Accessibility	Airborne Acoustics	Physical Disturbance & Strike	Underwater Energy	In-Air Energy	Physical Interactions
U.S. NAVY AND MARINE CORPS								_	_			_		_		_	_	_	_	_				_		_							
MAJOR TRAINING EXERCISES – LARGE INTEGRATED ANTI-	-SUB	SMAR		VARF	ARE	T	T								1							1								-			
Composite Training Unit Exercise (Strike Group)	 ✓ ✓ 		✓	 ✓ ✓ 						✓		•	✓	•			√	✓		v	v		✓	•	•								
Rim of the Pacific Exercise	✓		-	✓						~		✓	-	✓			✓	 ✓ 		✓	✓		-	 ✓ 	✓		✓	~	~	✓	~	~	✓
MAJOR TRAINING EXERCISES – MEDIUM INTEGRATED AN	ITI-S	UBM	ARIN	E WA	RFAR	RE																											
Task Force/Sustainment Exercise	✓		✓	✓						✓		✓	~	✓			✓	✓		✓	✓		✓	✓	✓								
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Independent Deployer Certification Exercise/Tailored Surface Warfare Training			✓	✓						✓		~	✓								~												
Medium Coordinated Anti-Submarine Warfare	\checkmark		\checkmark	\checkmark						\checkmark		\checkmark	\checkmark	\checkmark			\checkmark	\checkmark		✓	✓		\checkmark	\checkmark	\checkmark		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Small Coordinated Anti-Submarine Warfare	\checkmark		\checkmark	\checkmark						\checkmark		\checkmark	\checkmark	\checkmark			\checkmark	\checkmark		✓	\checkmark		\checkmark	\checkmark	\checkmark								
INTEGRATED/COORDINATED TRAINING - OTHER	-																	_	-	_		_											
Composite Training Unit Exercise (ARG/MEU)	✓		\checkmark	\checkmark						\checkmark		\checkmark	\checkmark	\checkmark			✓	✓		✓	✓		✓	✓	✓								
Innovation and Demonstration Exercise	\checkmark		\checkmark	\checkmark	\checkmark		\checkmark	\checkmark		\checkmark		\checkmark	\checkmark	\checkmark	\checkmark		\checkmark	\checkmark	\checkmark	✓	✓	\checkmark	\checkmark	\checkmark	\checkmark								
Integrated Air Missile Defense Exercise			\checkmark	\checkmark	\checkmark			\checkmark		\checkmark		\checkmark	\checkmark	\checkmark				\checkmark	\checkmark		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark								
Large Amphibious Exercise			\checkmark	\checkmark						\checkmark		\checkmark	\checkmark		\checkmark						✓						\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Multi-Warfare Exercise	\checkmark		\checkmark	\checkmark	\checkmark					\checkmark		\checkmark	\checkmark	\checkmark			\checkmark	\checkmark		✓	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark								
AIR WARFARE																																	
Air Combat Maneuvers				✓						✓			✓								✓							✓	✓	✓			
Air Defense Exercise			✓	✓						✓		✓	✓								✓							✓	✓	✓			
Gunnery Exercise Air-to-Air Medium and Small Caliber				✓	✓					✓			✓	✓					✓		✓		✓				✓	✓	✓	✓			✓
Gunnery Exercise Surface-to-Air Large and Medium Caliber			✓		✓					✓		✓		✓							✓		✓		✓								✓
High-Energy Laser Exercise (Surface-to-Air)			✓								✓	✓									✓												
Medium Range Interceptor Capability				✓	✓			✓					✓	✓					✓		✓	✓	✓	✓	✓		✓	✓	✓	✓	✓	✓	✓
Missile Exercise (Air-to-Air)				\checkmark	✓			\checkmark		\checkmark			\checkmark	\checkmark				✓	\checkmark	✓	✓	✓	\checkmark	\checkmark	\checkmark								
Missile Exercise – Man-Portable Air Defense System				\checkmark	✓			\checkmark					✓	\checkmark	\checkmark				✓		✓	✓	✓	\checkmark	\checkmark		\checkmark	\checkmark	\checkmark	\checkmark		\checkmark	\checkmark
Missile Exercise (Surface-to-Air)			\checkmark	\checkmark	\checkmark			\checkmark		\checkmark		\checkmark	\checkmark	\checkmark					\checkmark		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark

										Bio	logical	Resour	ces									Phy.	sical F	Resou	rces				Hun	nan Re	esour	ces		
		Acc	oustic	Stres	sors	1	Expl Stre	osive ssors	Ener	gy Stro	essors	Phys	ical D Strike	isturb Stres	ance ssors	e and	Entai Sti	nglemen ressors	t Ing Sti	estion ressors	Qu Stre	Air Iality Essors	Se W	edime /ater Stre:	nts aı Quali ssors	nd ty	Cult Reso Stres	ural ource ssors	Socia Ra St	oecon esour tresso	omic ce rs	Pub & St	lic Hea Safet ressoi	alth 'y rs
Hawaii California Training Activity	Sonar & Other Transducers	Pile Driving	Vessel Noise	Aircraft Noise	Weapons Noise	Air Guns	Explosions in Water	Explosions in Air	In-Water Electromagnetic	Devices In-Air Electromagnetic Devices	High-Energy Lasers	Vessels & In-water Device Strike	Aircraft & Aerial Target Strike	Military Expended Material	Seafloor Devices	Pile Driving	Wires & Cables	Decelerators/Parachutes	Military Expended Materials – Munitions	Military Expended Materials –		Criteria Air Pollutants	Explosives	Metals	Chemicals (Not Explosives)	Other Materials	Explosives	Physical Disturbance & Strike	Accessibility	Airborne Acoustics	Physical Disturbance & Strike	Underwater Energy	In-Air Energy	Physical Interactions
AMPHIBIOUS WARFARE	1	1			1	1	1	1	T		-			1	1	-	T		1				1		1	1	1							
Amphibious Assault			 ✓ 	 ✓ 			<u> </u>			√	_	✓	 ✓ 						,			✓ 				,		✓	✓	✓	✓	✓	✓	✓
Amphibious Operations in a Contested Environment			✓	 ✓ 	✓			~			_	✓	✓	✓	√		_		~			√		✓	✓	✓		~	✓	✓	✓	✓	~	✓
Amphibious Raid			✓	~						~		~	✓									✓						\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓
Amphibious Vehicle Maneuvers			✓									✓			✓							\checkmark						\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓
Expeditionary Fires Exercise/Supporting Arms Coordination Exercise			~	~						~		~	~									✓						~	~	✓	~	✓	✓	✓
Naval Surface Fire Support Exercise – At Sea			✓		✓		\checkmark			✓		✓		\checkmark					\checkmark			✓	\checkmark	>			\checkmark	✓	~	\checkmark	✓	\checkmark	\checkmark	\checkmark
Naval Surface Fire Support Exercise – Land-Based Target			✓		\checkmark					✓		✓		\checkmark					✓			√	\checkmark	>				✓	\checkmark	\checkmark	✓	\checkmark	\checkmark	\checkmark
Non-Combat Amphibious Operation			✓	\checkmark						✓		✓	✓									√						✓	\checkmark	\checkmark	✓	\checkmark	\checkmark	\checkmark
Shore-to-Surface Artillery Exercise			✓		✓		✓	✓		✓		✓		✓					✓	✓		√	✓	~	✓		✓		~	✓	✓			✓
Shore-to-Surface Missile Exercise			✓		✓		✓	✓		✓		✓		✓					✓	✓		✓	✓	~	✓		✓		~	✓	✓			✓
ANTI-SUBMARINE WARFARE		-				_		_					-												-	-		-						
Anti-Submarine Warfare Torpedo Exercise – Helicopter	\checkmark		\checkmark	\checkmark						✓		✓	\checkmark	\checkmark			\checkmark	\checkmark		✓		\checkmark		\checkmark	\checkmark	\checkmark								<u> </u>
Anti-Submarine Warfare Torpedo Exercise – Maritime Patrol Aircraft	~		~	~						~		~	~	~			~	~		~		✓		✓	~	~								l
Anti-Submarine Warfare Torpedo Exercise – Ship	✓		✓							✓		✓		✓			✓			√		√		>	✓	✓								
Anti-Submarine Warfare Torpedo Exercise – Submarine	\checkmark		✓							✓		\checkmark		\checkmark			\checkmark					√		>	\checkmark	✓								
Anti-Submarine Warfare Tracking Exercise – Helicopter	\checkmark		✓	✓						✓		\checkmark	✓	\checkmark			\checkmark	✓		√		✓		>	\checkmark	✓								
Anti-Submarine Warfare Tracking Exercise –Unmanned Surface Vessel	~		~		~					~		~		~			~	~	~	~		√		~	~	~		~	~	✓	~	✓	✓	~
Anti-Submarine Warfare Tracking Exercise – Maritime Patrol Aircraft	~		~	~						~		~	~	~			~	~		~		✓		~	~	~								
Anti-Submarine Warfare Tracking Exercise – Ship	✓		✓							✓		\checkmark		\checkmark			✓					\checkmark		\checkmark	\checkmark	\checkmark								
Anti-Submarine Warfare Tracking Exercise – Submarine	\checkmark		\checkmark							\checkmark		\checkmark		\checkmark			\checkmark					\checkmark		\checkmark	\checkmark	\checkmark								
Training and End-to-End Mission Capability Verification - Torpedo	~		~				~			~		~		~	~		~		~			✓	~	~	~	~								

										Biolo	gical	Resourd	ces								Phy	sical I	Resou	rces				Hun	nan R	esour	ces		
		Acc	oustic	Stres	sors		Explo Stre	osive ssors	Energ	y Stres	sors	Physi	cal Di Strike	isturbo Stres	ance a sors	and	Entang Stres	lement ssors	Inge Stre	estion ssors	Air Quality Stressors	Se И	edime Vater Stres	nts an Qualit ssors	id Sy	Cult Reso Stres	ural ource ssors	Socia Ra St	pecon esour tresso	omic ce rs	Pub & St	lic He Safet resso	alth Y rs
Hawaii California Training Activity	Sonar & Other Transducers	Pile Driving	Vessel Noise	Aircraft Noise	Weapons Noise	Air Guns	Explosions in Water	Explosions in Air	In-Water Electromagnetic Devices	In-Air Electromagnetic Devices	High-Energy Lasers	Vessels & In-water Device Strike	Aircraft & Aerial Target Strike	Military Expended Material	Seafloor Devices	Pile Driving	Wires & Cables	Decelerators/Parachutes	Military Expended Materials – Munitions	Military Expended Materials – Other than Munitions	Criteria Air Pollutants	Explosives	Metals	Chemicals (Not Explosives)	Other Materials	Explosives	Physical Disturbance & Strike	Accessibility	Airborne Acoustics	Physical Disturbance & Strike	Underwater Energy	In-Air Energy	Physical Interactions
ELECTRONIC WARFARE	-	1	1		1	1	1				1				1			T				1											
Counter Targeting Chaff Exercise – Aircraft			,	✓						 ✓ 			✓	 ✓ 						√	✓		 ✓ 	 ✓ 	✓								
Counter Targeting Chaff Exercise – Ship			✓							 ✓ 		\checkmark		 ✓ 						 ✓ 	√		✓	✓	✓								
Counter Targeting Flare Exercise				✓						 ✓ 			✓	✓						~	✓		✓	\checkmark	✓								
Electronic Warfare Operations			\checkmark	\checkmark						\checkmark		✓	\checkmark								✓												
EXPEDITIONARY WARFARE	1	т	1	1	1	1	r —						1	T	ſ	1	-	r —	1	1		1	r										
Dive and Salvage Operations			\checkmark							✓		\checkmark									✓						\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓
Gunnery Exercise Ship-to-Shore			\checkmark		\checkmark							\checkmark		\checkmark					✓		✓		\checkmark				\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓
Obstacle Loading			\checkmark				\checkmark					\checkmark		\checkmark	\checkmark						✓	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓
Personnel Insertion/Extraction – Air			\checkmark	\checkmark	\checkmark		\checkmark			\checkmark		\checkmark	\checkmark	\checkmark					\checkmark		✓	\checkmark	\checkmark			\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓
Personnel Insertion/Extraction – Surface and Subsurface			\checkmark	\checkmark	\checkmark		\checkmark					\checkmark	\checkmark	✓					\checkmark	\checkmark	✓	\checkmark	\checkmark	\checkmark	\checkmark	✓	✓	\checkmark	\checkmark	✓	✓	\checkmark	✓
Personnel Insertion/Extraction – Swimmer/Diver			\checkmark		\checkmark		✓					\checkmark		\checkmark					\checkmark	✓	✓	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓
Port Damage Repair		\checkmark	\checkmark									\checkmark			\checkmark	\checkmark					✓						\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓
Small Boat Attack			\checkmark		\checkmark					\checkmark		\checkmark		\checkmark					✓		\checkmark		\checkmark				\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓
MINE WARFARE	-	-				-	-						•									•	-										
Airborne Mine Countermeasure – Mine Detection			\checkmark	\checkmark						\checkmark		\checkmark	\checkmark	\checkmark	✓		\checkmark				✓		\checkmark		\checkmark		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓
Airborne Mine Laying			\checkmark	\checkmark						\checkmark		\checkmark	\checkmark	\checkmark			\checkmark				✓		\checkmark	\checkmark	\checkmark		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Amphibious Breaching Operations			\checkmark				\checkmark			\checkmark		\checkmark		\checkmark							✓	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓
Civilian Port Defense – Homeland Security Anti- Terrorism/Force Protection Exercise	~		~	~			~			~		\checkmark	~	~	~		\checkmark		~		~	~	~	✓	✓	✓	✓	~	~	~	~	✓	✓
Mine Countermeasure Exercise – Ship Sonar	✓		✓							\checkmark		\checkmark									✓						✓	✓	✓	✓	✓	\checkmark	\checkmark
Mine Countermeasures Mine Neutralization Remotely Operated Vehicle Operations	~		~	~			~			~		\checkmark	~	~	~		\checkmark		~		~	~	~	~	✓	~	~	>	>	~	~	~	~
Mine Countermeasures – Towed Mine Neutralization			\checkmark	\checkmark					\checkmark	\checkmark		\checkmark	\checkmark								\checkmark						\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Mine Neutralization Explosive Ordnance Disposal			\checkmark				\checkmark			\checkmark		\checkmark		\checkmark	\checkmark		\checkmark		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Submarine Mine Avoidance Exercise	\checkmark		\checkmark							\checkmark		\checkmark		✓			\checkmark		\checkmark	✓	\checkmark		\checkmark		\checkmark		✓	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Submarine Mobile Mine and Mine Laying Exercise	\checkmark		✓							\checkmark		\checkmark		✓							✓		\checkmark		\checkmark		✓	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Surface Ship Object Detection	\checkmark		\checkmark							\checkmark		\checkmark		\checkmark	\checkmark		\checkmark				✓		\checkmark		\checkmark		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark

										Biolo	paical	Resour	ces								Phy	sical I	Resou	ırces				Hum	nan Re	esour	ces		
	-						Fxnl	osive			<u> </u>	Phys	ical D	isturh	ance	and	Entanc	alement	Inge	stion	Air	Se	edime	ents a	nd	Cult	ural	Socio	econ	omic	Publ	lic Hec	alth
		Acc	oustic	Stres	sors		Stre	ssors	Energ	y Stre	ssors	i nys	Strike	Stres	sors	unu	Stre	ssors	Stre	ssors	Quality	И	/ater	Quali	ity	Reso	ource	Re	esouro	:e	&	Safety	y
								[S	T T		0)	T	1	T		1	1	1	Stressors		Stre	ssors	1	Stre	ssors	51	resso	's	St	ressor	S
Hawaii California Training Activity	Sonar & Other Transducers	Pile Driving	Vessel Noise	Aircraft Noise	Weapons Noise	Air Guns	Explosions in Water	Explosions in Air	In-Water Electromagnetic Devices	In-Air Electromagnetic Device	High-Energy Lasers	Vessels & In-water Device Strike	Aircraft & Aerial Target Strike	Military Expended Material	Seafloor Devices	Pile Driving	Wires & Cables	Decelerators/Parachutes	Military Expended Materials - Munitions	Military Expended Materials - Other than Munitions	Criteria Air Pollutants	Explosives	Metals	Chemicals (Not Explosives)	Other Materials	Explosives	Physical Disturbance & Strike	Accessibility	Airborne Acoustics	Physical Disturbance & Strike	Underwater Energy	In-Air Energy	Physical Interactions
MINE WARFARE (cont.)		T.	T	1	T.	1	1	F	1	1	1		1	1	1		I	T	1	1	Т	1	1	1	1	1	1					<u> </u>	
Training and End-to-End Mission Capability Verification – Mobile Mine and Mine Laying Exercise			~							~		\checkmark		~			~				~		~	~	~								L .
Underwater Demolition Qualification and Certification			\checkmark				✓			\checkmark		\checkmark			\checkmark						~	\checkmark	✓	\checkmark	\checkmark	\checkmark	~	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Underwater Demolition Multiple Charge – Large Area Clearance			~				~					~		~	~						~	~				~	~	~	~	~	~		~
Underwater Mine Countermeasure Raise, Tow, Beach, and Exploitation			~	~						~		~	~	~	~		~				~		~		~		~	~	~	~	~	~	~
SURFACE WARFARE						•	•		1	•					4								•	•									
Bombing Exercise Air-to-Surface			\checkmark	\checkmark			✓			\checkmark		✓	\checkmark	\checkmark					✓	✓	✓	✓	✓	\checkmark	\checkmark								
Gunnery Exercise Air-to-Surface – Medium-Caliber			\checkmark	✓	\checkmark		\checkmark			\checkmark		~	✓	\checkmark					\checkmark	✓	\checkmark	✓	✓	\checkmark	\checkmark					1			
Gunnery Exercise Air-to-Surface – Small-Caliber			✓	\checkmark	✓					✓		~	✓	✓					✓	✓	\checkmark		✓	✓	\checkmark								
Gunnery Exercise Surface-to-Surface Boat – Medium-Caliber			\checkmark		\checkmark		\checkmark					\checkmark		\checkmark					✓	✓	✓	✓	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Gunnery Exercise Surface-to-Surface Boat – Small-Caliber			\checkmark		\checkmark							\checkmark		\checkmark					\checkmark	\checkmark	✓		\checkmark	\checkmark	\checkmark		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Gunnery Exercise Surface-to-Surface Ship – Large Caliber			\checkmark		\checkmark		\checkmark			\checkmark		\checkmark		\checkmark					\checkmark		\checkmark	\checkmark	\checkmark		\checkmark					1			
Gunnery Exercise Surface-to-Surface Ship – Medium Caliber			\checkmark		\checkmark		\checkmark			\checkmark		\checkmark		\checkmark					\checkmark		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark					ł			
Gunnery Exercise Surface-to-Surface Ship – Small-Caliber			\checkmark		\checkmark					\checkmark		\checkmark		\checkmark					\checkmark		\checkmark		\checkmark		\checkmark					ł			
Laser Targeting – Aircraft			\checkmark	\checkmark						\checkmark	\checkmark	~	✓	\checkmark							\checkmark		✓	\checkmark	\checkmark					1			
Laser Targeting – Ship			\checkmark	\checkmark	\checkmark					\checkmark	\checkmark	\checkmark	\checkmark	\checkmark							\checkmark									l			
Maritime Security Operations			\checkmark	✓	\checkmark					\checkmark		~	✓	\checkmark					\checkmark		\checkmark		✓	\checkmark	\checkmark		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Missile Exercise Air-to-Surface			✓	✓	✓		✓			✓		\checkmark	✓	✓					✓	✓	✓	✓	✓	✓	✓								
Missile Exercise Air-to-Surface Rocket				✓			✓			\checkmark			✓	\checkmark					✓	✓	✓	✓	✓	✓	✓								
Missile Exercise Surface-to-Surface			\checkmark		\checkmark		✓			\checkmark		\checkmark		\checkmark					√	✓	✓	✓	✓	\checkmark	\checkmark								
Sinking Exercise	✓		\checkmark	✓	✓		✓			✓		✓	✓	✓			✓		✓		✓	✓	✓	✓	✓								
Surface Warfare Torpedo Exercise – Submarine	✓		✓									✓		\checkmark			✓				✓		✓	✓	✓								
Training and End-to-End Mission Capability Verification – Submarine Missile Maritime					~		~					~		~					~	~	~	\checkmark	~	~	~								

										Biol	ogical	Resour	rces									Phys	sical I	Resou	rces				Hur	nan F	Resou	rces		
							Exp	losive				Phys	ical D	Disturk	bance	e and	Ento	inaleme	nt	Inaes	stion	Air	Se	edime	nts a	nd	Cul	tural	Soci	oecor	nomic	Pu	blic H	ealth
		Acc	oustic	Stres	sors		Stre	ssors	Energ	y Stre	ssors		Strike	e Stre	ssors		Si	ressors		Stres	sors	Quality	И	Vater	Quali	ity	Res	ource	R	esoui trocci	rce		& Safe	ety
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Hawaii California Training Activity	Sonar & Other Transducers	Pile Driving	Vessel Noise	Aircraft Noise	Weapons Noise	Air Guns	Explosions in Water	Explosions in Air	In-Water Electromagnetic Devices	In-Air Electromagnetic Device	High-Energy Lasers	Vessels & In-water Device Strike	Aircraft & Aerial Target Strik	Military Expended Material	Seafloor Devices	Pile Driving	Wires & Cables	Decelerators/Parachutes		Military Expended Materials Munitions	Military Expended Materials Other than Munitions	Criteria Air Pollutants	Explosives	Metals	Chemicals (Not Explosives)	Other Materials	Explosives	Physical Disturbance & Strike	Accessibility	Airborne Acoustics	Physical Disturbance & Strike	Underwater Energy	In-Air Energy	Physical Interactions
OTHER TRAINING EXERCISES		Ī	I	I	T	T	I	I	1	I	I	I	ī	I	I	I	1	1	I				ſ	I	Ĩ	Ī		T		Ī	I	I		
Aerial Firefighting				✓					✓				✓									✓												
At-Sea Vessel Refueling Training			\checkmark									\checkmark										✓												
Combat Swimmer/Diver Training and Certification			\checkmark									\checkmark										✓						\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Kilo Dip	\checkmark			\checkmark						\checkmark			\checkmark	\checkmark			√			\checkmark		✓		\checkmark		\checkmark								
Multi-Domain Unmanned Autonomous Systems	\checkmark		\checkmark	✓			\checkmark			\checkmark		\checkmark	\checkmark	\checkmark							\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Precision Anchoring			\checkmark							\checkmark		\checkmark			✓							✓		\checkmark				\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Ship-to-Shore Fuel Transfer Training			\checkmark							\checkmark		\checkmark										✓						\checkmark	\checkmark	✓	\checkmark	✓	\checkmark	✓
Submarine and UUV Subsea and Seabed Warfare Exercise	\checkmark		\checkmark		✓		\checkmark							✓	✓		√			\checkmark		✓	✓	\checkmark	✓	✓	✓	✓	✓	✓	✓	✓		✓
Submarine Navigation Exercise	\checkmark											✓										✓						✓	\checkmark	✓	\checkmark	\checkmark	\checkmark	✓
Submarine Sonar Maintenance and Systems Checks	\checkmark											✓										✓						✓	✓	✓	✓	✓	✓	✓
Submarine Under Ice Training and Certification	\checkmark											✓		✓			✓					✓		\checkmark	✓	✓								
Surface Ship Sonar Maintenance and Systems Checks	\checkmark		\checkmark							✓		✓										✓						✓	✓	✓	\checkmark	✓	✓	✓
Training and End-to-End Mission Capability Verification – Subsea and Seabed Warfare Kinetic Effectors			~		~		~							~			~			~		~	~	~	~	~								
Training and End-to-End Mission Capability Verification – UAV			\checkmark	✓	✓		✓						✓	✓	√		√			\checkmark	\checkmark	✓	✓	✓	✓	✓							T	
Underwater Survey			\checkmark									✓			√							✓						✓	✓	✓	✓	✓	✓	✓
Unmanned Aerial System Training			\checkmark	✓						\checkmark		✓	✓	✓								✓		✓	✓	✓							T	
Unmanned Underwater Vehicle Training -Certification and Development Exercises	~		~	~						~		~	~	~	~		~					~												
Waterborne Training			\checkmark									\checkmark										✓						\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark

										Biolo	paical	Resour	ces								Phy	vsical	Resou	irces				Hum	an Re	sourc	ces		
											<u> </u>						_				Air	Se	edime	ents a	nd	Cult	ural	Socio	econd	omic	Publ	ic Heal	lth
		Ac	oustic	Stres	sors		Expl	osive	Energ	y Stre	ssors	Phys	ical D Strike	isturb Stroc	ance	and	Entang	glement	Inge	stion	Quality	И	Vater	Quali	ity	Reso	urce	Re	sourc	e	&	Safety	-
		-	-	-	-	-	5070	33073		<u> </u>	1			- 50/65		-	5000		500		Stressors		Stre	ssors	1	Stres	sors	St	ressor	rs	Str	ressors	;
Hawaii California Training Activity	Sonar & Other Transducers	Pile Driving	Vessel Noise	Aircraft Noise	Weapons Noise	Air Guns	Explosions in Water	Explosions in Air	In-Water Electromagnetic Devices	In-Air Electromagnetic Devices	High-Energy Lasers	Vessels & In-water Device Strike	Aircraft & Aerial Target Strike	Military Expended Material	Seafloor Devices	Pile Driving	Wires & Cables	Decelerators/Parachutes	Military Expended Materials – Munitions	Military Expended Materials – Other than Munitions	Criteria Air Pollutants	Explosives	Metals	Chemicals (Not Explosives)	Other Materials	Explosives	Physical Disturbance & Strike	Accessibility	Airborne Acoustics	Physical Disturbance & Strike	Underwater Energy	In-Air Energy	Physical Interactions
U.S. COAST GUARD	-	-	_	-	-	-	-	-		-	-		-	_	-						_	_	-	-	-		_	_	-	-	_		
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Gunnery Exercise Surface-to-Air Large Caliber			 ✓ ✓ 		✓ ✓					✓ ✓		√		 ✓ 					√		 ✓ 	~	 ✓ 		 ✓ 								
Gunnery Exercise Surface-to-Air Medium Caliber			~		~					~		✓		~					✓		✓		~		~								_
	<u> </u>	1		1	1	1	1	1	1		1		1		1	1	1	1															
Counter Targeting Chaff Exercise – Ship			√							 ✓ 		✓		√		_				√	√		 ✓ 	 ✓ 	 ✓ 								
Counter Targeting Flare Exercise			 ✓ 	✓						✓		✓	✓	✓						✓	~		✓	✓	✓								_
EXPEDITIONARY WARFARE	r	т		r –	T	1	T	r –	1	T	r –		T	1		1	1					Т	T	1	1	1							
Underwater Construction Team Training			 ✓ 									✓			✓						~						\checkmark	✓	~	~	~	✓	<u>~</u>
SURFACE WARFARE	-	1	1	1 /		1		1	1	1	1		1 /		1	-	1	1			T ,	1		1	1	1							
Gunnery Exercise Air-to-Surface Medium Caliber			✓	 ✓ 	✓		✓			✓		✓	✓	✓					~	\checkmark	✓	✓	✓	✓	✓								
Gunnery Exercise Surface-to-Surface Boat Medium Caliber			✓		✓		✓					\checkmark		~					\checkmark	✓	✓	✓	\checkmark	✓	✓								
Gunnery Exercise Surface-to-Surface Boat Small Caliber			 ✓ 		✓							\checkmark		✓					\checkmark	\checkmark	✓		\checkmark	\checkmark	\checkmark								
Gunnery Exercise Surface-to-Surface Ship Large Caliber			✓		\checkmark		\checkmark			\checkmark		\checkmark		✓					✓		✓	\checkmark	\checkmark		\checkmark								
Gunnery Exercise Surface-to-Surface Ship Medium Caliber			✓		\checkmark		\checkmark			\checkmark		\checkmark		✓					✓		✓	\checkmark	\checkmark	\checkmark	\checkmark								
Gunnery Exercise Surface-to-Surface Ship Small Caliber			\checkmark		\checkmark					\checkmark		\checkmark		✓					\checkmark		✓		\checkmark		✓								
Laser Targeting – Ship			\checkmark							\checkmark	\checkmark	\checkmark									✓												
Maritime Security Operations			\checkmark	\checkmark	\checkmark					\checkmark		\checkmark	\checkmark	\checkmark					\checkmark		✓		\checkmark	\checkmark	\checkmark		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓	✓
OTHER TRAINING ACTIVITIES	-							-			-								-	_				-	-								
Precision Anchoring			\checkmark							\checkmark		\checkmark			\checkmark						\checkmark		\checkmark				\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓	✓
Search and Rescue			\checkmark	\checkmark						\checkmark		\checkmark	\checkmark	\checkmark						\checkmark	\checkmark						\checkmark	\checkmark	\checkmark	\checkmark		✓	✓
Unmanned Aerial System Training			\checkmark	\checkmark						\checkmark		\checkmark	\checkmark	\checkmark							\checkmark		\checkmark	\checkmark	\checkmark								
Unmanned Underwater Vehicle Training –Certification and Development Exercises	~		~	~						~		~	~	~	~		~				\checkmark												
Waterborne Training			✓									\checkmark									\checkmark						✓	\checkmark	\checkmark	\checkmark	\checkmark	 ✓ 	✓

										Biolo	gical	Resour	ces								Phy	sical I	Resol	ırces				Hun	nan Re	esour	ces		
		Acc	oustic	Stre	ssors		Expl Stre	osive ssors	Energy	/ Stres	sors	Phys	ical D Strike)isturb e Stres	ance sors	and	Entang Stre	glement essors	Inge Stre	estion essors	Air Quality Stressors	Se M	edime Vater Stre	ents a Quali	nd ity	Cul Reso	tural ource	Socie Re	econ esourc	omic ce rs	Publ & St	ic Hec Safet	alth y rs
Hawaii California Training Activity	Sonar & Other Transducers	Pile Driving	Vessel Noise	Aircraft Noise	Weapons Noise	Air Guns	Explosions in Water	Explosions in Air	In-Water Electromagnetic Devices	In-Air Electromagnetic Devices	High-Energy Lasers	Vessels & In-water Device Strike	Aircraft & Aerial Target Strike	Military Expended Material	Seafloor Devices	Pile Driving	Wires & Cables	Decelerators/Parachutes	Military Expended Materials – Munitions	Military Expended Materials – Other than Munitions	Criteria Air Pollutants	Explosives	Metals	Chemicals (Not Explosives)	Other Materials	Explosives	Physical Disturbance & Strike	Accessibility	Airborne Acoustics	Physical Disturbance & Strike	Underwater Energy	In-Air Energy	Physical Interactions
U.S. ARMY																																	
AIR WARFARE	-												•											-									
Missile Exercise – Man Portable Air Defense System				✓	✓			✓					✓	✓					✓		✓	✓	✓	✓	✓		✓	✓	✓	✓		✓	✓
AMPHIBIOUS WARFARE	-												•											-									
Shore-to-Surface Artillery Exercise			✓		✓		✓	✓		✓		✓		✓					✓	✓	✓	✓	✓	✓		✓		✓	✓	✓			✓
Shore-to-Surface Missile Exercise			✓		✓		✓	✓		✓		✓		✓					1	✓	✓	✓	✓	✓		✓		✓	✓	✓			✓
SURFACE WARFARE																																	
Gunnery Exercise Surface-to-Surface Boat Medium Caliber			✓		1		✓					1		✓					~	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓		✓
Gunnery Exercise Surface-to-Surface Boat Small Caliber			✓		✓							√		✓					✓	✓	✓		✓				✓	✓	✓	✓			✓
U.S. AIR FORCE																																	
AIR WARFARE																																	
Air Combat Maneuvers				✓						✓			✓								✓		✓			✓		✓	✓	✓			✓
Gunnery Exercise (Air-to-Air) Medium Caliber				✓	✓					✓			✓	✓					✓		✓		\checkmark				✓	✓	✓	✓			✓

Table B-2: Stressors by Testing Activity

										Biolo	gical	Resour	ces								Phy	vsical	Resou	irces				Hum	an Re	sourc	es		
		Aco	oustic	Stres	sors		Expl Stre	osive ssors	Energy	Stres	sors	Phys	ical D Strike	isturb Stres	ance sors	and	Entang Stre	lement ssors	Inge Stre	stion ssors	Air Quality Stressors	Se V	edime Vater Stre	ents ar Quali ssors	nd ty	Cult Reso Stres	ural ource ssors	Socio Re St	econo source ressor:	mic e s	Publ & Sti	ic Hea Safety ressor	alth Y rs
Hawaii California Testing Activity	Sonar & Other Transducers	Pile Driving	Vessel Noise	Aircraft Noise	Weapons Noise	Air Guns	Explosions in Water	Explosions in Air	In-Water Electromagnetic Devices	In-Air Electromagnetic Devices	High-Energy Lasers	Vessels & In-water Device Strike	Aircraft & Aerial Target Strike	Military Expended Material	Seafloor Devices	Pile Driving	Wires & Cables	Decelerators/Parachutes	Military Expended Materials – Munitions	Military Expended Materials – Other than Munitions	Criteria Air Pollutants	Explosives	Metals	Chemicals (Not Explosives)	Other Materials	Explosives	Physical Disturbance & Strike	Accessibility	Airborne Acoustics	Physical Disturbance & Strike	Underwater Energy	In-Air Energy	Physical Interactions
NAVAL AIR SYSTEMS COMMAND	_	_	_	_	_	_	_	_		_	_		_	_	_						_	_	_	_	_		_	_			_		
	r –	1	1			1	T								T	1										1	1						
Air Combat Maneuver Test				 ✓ 	✓			~		✓			√	~				✓	~	✓	✓	✓	~	~	✓					\rightarrow		\rightarrow	
Air Platform-Vehicle Test				 ✓ 						✓			 ✓ 								✓									\rightarrow		\rightarrow	
Air Platform Weapons Integration Test			✓ ✓	 ✓ 	√ √			,		√		✓	 ✓ 	 ✓ 				✓		,	✓		 ✓ 	 ✓ 	 ✓ 					\rightarrow		\rightarrow	
Air-to-Air Missile Test			✓	 ✓ 	✓		~	~		✓		✓	√	~				✓	~	✓	✓	✓	~	~	✓								
Intelligence, Surveillance, and Reconnaissance Test				 ✓ 						✓			√								✓						✓ ✓	 ✓ 	✓ ✓	✓ 		✓ 	✓
Large Force Test Event			✓ ✓	 ✓ 				,		√		✓	 ✓ 	 ✓ 						✓	✓			,			~	\checkmark	~	~		~	✓
Surface-to-Air Gunnery Test – Large Caliber			✓ ✓	 ✓ 	√ √			✓		√		✓	 ✓ 	 ✓ 				✓	✓		✓	 ✓ 	 ✓ 	 ✓ 	 ✓ 					\rightarrow		\rightarrow	
Surface-to-Air Gunnery Test – Medium Caliber			✓	 ✓ 	 ✓ 			~		√		✓	 ✓ 	 ✓ 				✓	~		✓	✓	 ✓ 	✓	✓							\rightarrow	
Surface-to-Air High-Energy Laser Test			 ✓ 	 ✓ 	\checkmark					√	 ✓ 	✓	 ✓ 	✓				✓		✓	✓		✓	✓	✓							$ \rightarrow $	
Surface-to-Air High-Power Microwave Test			✓	 ✓ 						✓	\checkmark	✓	 ✓ 								✓											$ \rightarrow $	
Surface-to-Air Missile Test			✓	✓	\checkmark		\checkmark	\checkmark		\checkmark		~	 ✓ 	✓				✓	\checkmark	✓	~	\checkmark	\checkmark	✓	✓								
	-		1	I .	T	1	1	1		. 1			Γ.	I .	1	-		I .	1	I .	T .	1	Τ.	I .	. .								
Anti-Submarine Warfare Torpedo Test (Aircraft)	 ✓ 			 ✓ 						√		√	 ✓ 	 ✓ 			√	✓		√	✓		✓	 ✓ 	 ✓ 							$ \rightarrow $	
Anti-Submarine Warfare Tracking Test (Fixed-Wing)	 ✓ 			 ✓ 						✓		✓	 ✓ 	 ✓ 			√	✓		√	✓		✓	 ✓ 	 ✓ 							$ \rightarrow $	
Anti-Submarine Warfare Tracking Test (Rotary-Wing)	\checkmark			\checkmark						\checkmark		\checkmark	~	✓			\checkmark	√		✓	~		\checkmark	\checkmark	✓					$ \rightarrow $		\rightarrow	
Kilo Dip Test	\checkmark			\checkmark						\checkmark			✓								✓											$ \rightarrow $	
Sonobuoy Lot Acceptance Test	\checkmark		\checkmark	\checkmark				\checkmark		\checkmark		✓	\checkmark	\checkmark			\checkmark	\checkmark	✓	✓	✓	\checkmark	\checkmark		\checkmark								
ELECTRONIC WARFARE	1	1	1		1	1	1	1		. 1			1		1			1	1	1		1	1 .	I .	I .	-	1						
Chaff Test				✓						\checkmark			✓	√				ļ		✓	✓		✓	✓	✓				\square	\square		$ \rightarrow $	
Electronic Systems Test				✓						\checkmark			✓	√				✓			✓		✓	✓	✓		✓	\checkmark	\checkmark	✓		\checkmark	✓
Flare Test				\checkmark						\checkmark			\checkmark	\checkmark						\checkmark	✓		\checkmark	\checkmark	\checkmark								

										Biolo	ogical	Resour	ces								Phy	sical F	Resou	rces				Hum	an Re	sourc	ces		
		Acc	oustic	: Stres	sors		Expl Stre	osive ssors	Energy	/ Stre:	ssors	Phys	ical Di Strike	isturb Stres	ance sors	e and	Entan <u>e</u> Stre	glement ssors	Inge Stre	stion ssors	Air Quality Stressors	Se N	edime /ater Stre:	nts ar Qualit ssors	nd ty	Culto Reso Stres	ıral urce sors	Socio Re St	econo sourc ressoi	omic e rs	Publ & Sti	ic Hea Safety ressor	ılth y rs
Hawaii California Testing Activity	Sonar & Other Transducers	Pile Driving	Vessel Noise	Aircraft Noise	Weapons Noise	Air Guns	Explosions in Water	Explosions in Air	In-Water Electromagnetic Devices	In-Air Electromagnetic Devices	High-Energy Lasers	Vessels & In-water Device Strike	Aircraft & Aerial Target Strike	Military Expended Material	Seafloor Devices	Pile Driving	Wires & Cables	Decelerators/Parachutes	Military Expended Materials – Munitions	Military Expended Materials – Other than Munitions	Criteria Air Pollutants	Explosives	Metals	Chemicals (Not Explosives)	Other Materials	Explosives	Physical Disturbance & Strike	Accessibility	Airborne Acoustics	Physical Disturbance & Strike	Underwater Energy	In-Air Energy	Physical Interactions
MINE WARFARE	1	1	1	1.	1	1	.	1	1				1	1	1	-	1	1	1	1	1 ,	1	1	1		. I		· · · · · ·					
Airborne Dipping Sonar Minehunting Test	✓			✓		_				 ✓ 			✓			_					✓												
Airborne Laser Mine Detection System Test			, .	 ✓ 		_				 ✓ 			V				, .		,		✓		,				~	\checkmark	✓	✓		~	✓
Airborne Mine Neutralization System Test			✓	✓		_	✓			 ✓ 		\checkmark	✓	 ✓ 	✓		 ✓ 		✓		✓	✓	✓	✓	✓								
Airborne Minehunting Test – Sonobuoy	✓			✓						 ✓ 			 ✓ 	 ✓ 	√		✓	✓		✓	✓		 ✓ 		 ✓ 							\rightarrow	
Mine Laying Test				✓						 ✓ 			✓	 ✓ 	✓						✓		✓		✓		~	✓	~	✓			✓
SURFACE WARFARE	-	1	1 .	I .	1	-	1.	1		. .			Ι.	Ι.	1	-	1				T .												
Air-to-Surface Bombing Test			√	 ✓ 		_	 ✓ 			 ✓ 		✓	√	 ✓ 		_			√	√	 ✓ 	 ✓ 	✓	 ✓ 	✓								
Air-to-Surface Gunnery Test			 ✓ 	✓	✓		✓			 ✓ 		✓	✓	 ✓ 		_			√	 ✓ 	√	✓	✓	✓	✓					$ \rightarrow $		\rightarrow	
Air-to-Surface High-Energy Laser Test			✓	✓						\checkmark	\checkmark	~	\checkmark	~						✓	✓				✓					$ \rightarrow $		\rightarrow	
Air-to-Surface High-Power Microwave Test			✓	✓						\checkmark	✓	\checkmark	\checkmark	~						✓	✓				✓					$ \rightarrow $		\rightarrow	
Air-to-Surface Laser Targeting Test				✓						\checkmark			\checkmark	~						✓	✓		✓	\checkmark	✓					$ \rightarrow $		\rightarrow	
Air-to-Surface Missile Test			✓	✓	\checkmark		✓			\checkmark		\checkmark	\checkmark	✓				✓	\checkmark	✓	✓	\checkmark	✓	\checkmark	✓					$ \rightarrow $		$ \rightarrow $	
Long-Range Weapons Delivery Systems (Over-the-Horizon)/ Hypersonic Vehicle Test				✓	✓		~			~			✓	✓					✓		~	✓	~	✓	✓								
Rocket Test			\checkmark	\checkmark	\checkmark		\checkmark			\checkmark		\checkmark	\checkmark	\checkmark					\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark								
Subsurface-to-Surface Missile Test					\checkmark		\checkmark					\checkmark		\checkmark					✓		\checkmark	✓	\checkmark	✓	\checkmark								
Surface-to-Surface Gunnery Test – Large-Caliber			✓		\checkmark		\checkmark			✓		\checkmark		\checkmark					\checkmark	\checkmark	\checkmark	\checkmark	✓	✓	\checkmark								
Surface-to-Surface Gunnery Test – Medium-Caliber			✓		\checkmark		\checkmark			✓		\checkmark	\checkmark	\checkmark				\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓	✓	\checkmark								
Surface-to-Surface Gunnery Test – Small-Caliber			✓		\checkmark					✓		\checkmark		\checkmark					\checkmark	\checkmark	\checkmark		\checkmark	\checkmark	\checkmark								
Surface-to-Surface High-Energy Laser Test			✓	✓	✓					\checkmark	\checkmark	\checkmark	\checkmark	\checkmark				✓		✓	\checkmark		✓	\checkmark	~								
Surface-to-Surface High-Power Microwave Test			✓	✓						✓	✓	\checkmark		\checkmark						✓	✓				\checkmark								
Surface-to-Surface Missile Test			✓		✓		✓			✓		\checkmark		\checkmark					✓	✓	\checkmark	✓	✓	✓	~								
OTHER TESTING ACTIVITIES																																	
Acoustic and Oceanographic Research			\checkmark	\checkmark						\checkmark		\checkmark	\checkmark								\checkmark				\checkmark		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Air Platform Shipboard Integration Test			\checkmark	\checkmark						\checkmark		\checkmark	\checkmark								\checkmark						\checkmark	\checkmark	\checkmark	\checkmark		\checkmark	\checkmark
Undersea Range System Test	\checkmark		\checkmark							\checkmark		\checkmark		\checkmark	\checkmark						\checkmark												

										Biolo	paical	Resour	Ces								Phy	isical F	Resou	rces				Hum	nan Re	soure	<u>.</u>		
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		Aco	oustic	Stres	sors		Expl	osive	Energ	v Stre	ssors	Phys	ical D	isturb	ance (and	Entang	lement	Inge	estion	Quality	N N	Vater	Quali	ity	Resc	ource	Re	esourc	e l	8	Safety	v
							Stre	ssors	5				Strike	e Stres	sors		Stre	ssors	Stre	ssors	Stressors		Stre	sors	ľ.	Stre	ssors	St	ressoi	rs	Sti	ressor	s
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Hawaii California Testing Activity	quc								net	tic D		evi	get	late				ute	late	late Is	ι,γ			osive			8			8			
	ans						ter		mag	gnet	ers	er D	Tar	2 P				rach	2 P	tion	tani			yple			nce		S	nce	gy		ions
	er Ti			0	ise		Wa	Air	ctro	mai	rase	wat	rial	puge	ices		es	/Pai	puge	luni	ollu			ot E	ials		urbo		usti	urbc	Ene		ract
	Othe	вu	oise	lois	NO		is in	is in	Elec	ctro	rgy	-ul	s Ae	spe	Dev	рu	Cabl	tors	s s	stpe n N	ir P	s		s (N	iteri	S	Dist	lity	Aco	Dist	ter	rgy	ntei
	8	rivii	I NC	ıft N	suo	sur	sion	sion	ater es	Ele	Ene	ls &	ı∱t 8	ıry E	or	rivii	& (erat	iry E tion	the	ia A	sive	ls	ical	Mc	sive	cal I	idis	rne	cal I	rwa	Ene	cal I
	nai	le D	esse	ircre	leap	ir Gi	cplo	cplo	-Wc	-Air	igh-	esse Trike	ircro	illito	safle	le D	/ires	ecel	lilito Iuni	lilito	iter	cplo	leta	mər	the	cplo	hysi	sacces	irbo	hysi	nde	-Air	hysi
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NAVAL FACILITIES ENGINEERING AND EXPEDITIONARY W	/ARF/	ARE C	ENTE	ER	-		-	-	-	-	-	-		-	-	-	_	_	_	_	_	-						-			-	-	_
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UTHER TESTING ACTIVITIES	-	1		1			1			1	<u> </u>		1			1		1		1	1		1					1					_
Undersea Range System Testing			v									• 		•	•		•								`	──′	×		 	×	•		
Underwater Search, Deployment, and Recovery			~						~			•		•	~		✓						~		<u> </u>		L ~			<u> </u>	~		~
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ANTI-SUBIVIARINE WARFARE		1					1				<u> </u>				1	1																	
Anti-Submarine Warfare Mission Package Testing	•		v	v	v					•		• 	•	•			•	v		•	•		•	v	`	──′	⊢ ×	v	~	<u> </u>	v	×	•
At-sea Sonar Testing	•		v	v					v	•		v	v	v	•		v	v		v	•		v	v	`	──′	┝──			\rightarrow			
Pierside Sonar Testing	•		✓							v					~						▼				–	′		v	×		•	• 	<u> </u>
Surface Ship Sonar Testing/Maintenance	•		v							•		•									v					′	×	v	~	~	~	~	•
Torpedo (Explosive) Testing	✓		✓	 ✓ 			V			✓		✓	 ✓ 	✓	 ✓ 		✓	√	V	v	✓	~	✓ ✓	 ✓ 	v	<u> </u>					1		
Torpedo (Non-Explosive) Testing	✓		✓	~						~		✓	✓	~	~		~	~		~	~		~	✓	_ ✓		<u> </u>	✓	✓	~	~	~	~
	-	1					1									1																	
Radar and Other System Testing			✓	✓	~			~	✓	 ✓ 	✓	~	✓	~	~		~	✓	✓	~	~	✓	✓	✓	_ ✓	<u> </u>	L ~	✓	<u> </u>	~	~	~	~
MINE WARFARE	1	1			1	1	<u> </u>	1								1			· ·	1													
Mine Countermeasure and Neutralization Testing			✓	 ✓ 			 ✓ 		✓	 ✓ 	✓	✓	√	 ✓ 	 ✓ 		✓	✓	√		√	✓	✓	✓	√	 ✓ 	√	 ✓ 	✓	✓	√	✓	✓
Mine Countermeasure Mission Package Testing	✓		✓	✓			✓		✓	✓		√	✓	✓	✓		✓		✓		✓	✓	✓	✓	 ✓ 	✓	√	 ✓ 	✓	✓	✓	✓	<u>√</u>
Mine Detection and Classification Testing	✓		✓	\checkmark					\checkmark	\checkmark		~	\checkmark	\checkmark	\checkmark		\checkmark	✓		✓	✓		\checkmark	\checkmark	 ✓ 	<u> </u>	_ ✓	\checkmark	✓	✓	\checkmark	\checkmark	✓
SURFACE WARFARE	-	1	T	1	1	1	1	1	1	.	r - 1		1	T	1	1 1	-	T	1	Т	T		r	1				1 1					
Gun Testing – Large Caliber	\checkmark		\checkmark	\checkmark	\checkmark		\checkmark			\checkmark	\checkmark	\checkmark	\checkmark	\checkmark				✓	\checkmark	\checkmark	✓	\checkmark	✓	\checkmark	✓		<u> </u>						
Gun Testing – Medium Caliber			\checkmark	\checkmark	\checkmark			\checkmark		\checkmark		\checkmark	\checkmark	\checkmark					\checkmark		✓	\checkmark	\checkmark		✓		<u> </u>						
Gun Testing – Small Caliber			✓		\checkmark					\checkmark		\checkmark		\checkmark					\checkmark	✓	✓		✓	\checkmark	\checkmark								
Missile and Rocket Testing			\checkmark		\checkmark		\checkmark	\checkmark		\checkmark		\checkmark	\checkmark	\checkmark				\checkmark	\checkmark	\checkmark	✓	\checkmark	\checkmark	\checkmark	\checkmark								
UNMANNED SYSTEMS																																	
Underwater Search, Deployment, and Recovery			✓	\checkmark					\checkmark	\checkmark		\checkmark	\checkmark	\checkmark							✓						\checkmark	\checkmark	\checkmark	\checkmark		\checkmark	✓

										Biolo	ogical	Resour	ces								Phy	sical I	Resou	irces				Hun	nan Re	sour	ces		
		_		. .			Expl	osive				Phys	ical D	isturb	ance	and	Entang	glement	Inge	estion	Air	Se	edime	ents a	nd	Cult	ural	Socio	pecono	omic	Publ	ic Hec	alth
		Ace	oustic	Stress	sors		Stre	ssors	Energ	y Stre	ssors		Strike	e Stres	sors		Stre	ssors	Stre	ssors	Stressors		vater Stre	Quali ssors	ty	Stre	ource ssors	Ri St	esourc ressoi	e rs	& St	Safety ressoi	y rs
										sə			e					ets									ا س			- -			
Hawaii California Testing Activity	Sonar & Other Transducers	Pile Driving	Vessel Noise	Aircraft Noise	Weapons Noise	Air Guns	Explosions in Water	Explosions in Air	In-Water Electromagnetic Devices	In-Air Electromagnetic Devic	High-Energy Lasers	Vessels & In-water Device Strike	Aircraft & Aerial Target Strik	Military Expended Material	Seafloor Devices	Pile Driving	Wires & Cables	Decelerators/Parachutes/Ne	Military Expended Materials Munitions	Military Expended Materials Other than Munitions	Criteria Air Pollutants	Explosives	Metals	Chemicals (Not Explosives)	Other Materials	Explosives	Physical Disturbance & Strike	Accessibility	Airborne Acoustics	Physical Disturbance & Strike	Underwater Energy	In-Air Energy	Physical Interactions
Unmanned Surface Vehicle System Testing			✓							✓		\checkmark		\checkmark							\checkmark				\checkmark		\checkmark	✓	\checkmark	\checkmark		\checkmark	\checkmark
Unmanned Underwater Vehicle Testing	✓		✓							✓		\checkmark		✓	✓		✓			✓	✓		\checkmark	\checkmark	\checkmark		\checkmark	✓	✓	\checkmark	✓	\checkmark	\checkmark
VESSEL EVALUATION																																	
Air Defense Testing			✓	\checkmark	✓			\checkmark		\checkmark		\checkmark	\checkmark	\checkmark	✓			\checkmark	✓	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark								
In-Port Maintenance Testing	~		\checkmark							✓		\checkmark									✓						\checkmark	✓	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Propulsion Testing			\checkmark		✓					✓		\checkmark			✓						✓						\checkmark	\checkmark	\checkmark	\checkmark		\checkmark	\checkmark
Signature Analysis Operations	\checkmark		\checkmark						✓	\checkmark		\checkmark		\checkmark	\checkmark		✓				✓		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Small Ship Shock Trial			\checkmark	✓			✓			✓		\checkmark	\checkmark								✓	\checkmark	\checkmark	\checkmark	\checkmark								
Submarine Sea Trials – Weapons System Testing	~		\checkmark							✓		\checkmark		\checkmark	✓		✓				✓	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Surface Warfare Testing	~		\checkmark	✓	✓		✓	✓		✓		\checkmark	\checkmark	\checkmark			✓	✓	✓	\checkmark	✓	\checkmark	\checkmark	\checkmark	\checkmark								
Undersea Warfare Testing	~		\checkmark	✓	✓			✓		✓		\checkmark	\checkmark	\checkmark	✓		✓	✓	✓	\checkmark	✓	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Vessel Signature Evaluation			\checkmark						✓			\checkmark									✓						\checkmark	✓	\checkmark	\checkmark		\checkmark	\checkmark
OTHER TESTING ACTIVITIES																																	
Acoustic and Oceanographic Research	\checkmark		\checkmark							\checkmark		\checkmark		\checkmark							✓						\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Countermeasure Testing	✓		✓	\checkmark					✓	\checkmark		\checkmark	✓	\checkmark			✓	✓		✓	\checkmark		\checkmark	\checkmark	\checkmark		\checkmark	✓	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Insertion/Extraction	✓		✓							✓		\checkmark		✓			✓	✓			✓		\checkmark		✓		✓	✓	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Non-Acoustic Component Testing			✓	\checkmark						\checkmark		\checkmark	\checkmark								✓						\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Semi-Stationary Equipment Testing	\checkmark						\checkmark			\checkmark				\checkmark	✓						✓	✓	✓	✓	✓	\checkmark	✓	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Simulant Testing			\checkmark	✓						\checkmark		\checkmark	\checkmark								✓												
NAVAL INFORMATION WARFARE SYSTEMS COMMAND																																	
ACOUSTIC AND OCEANOGRAPHIC SCIENCE AND TECHNO	LOG	Y																															
Acoustic, Oceanographic, and Energy Research	\checkmark		\checkmark							\checkmark		\checkmark			\checkmark						✓						\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓
OTHER TESTING ACTIVITIES																								1									
Communications	\checkmark		\checkmark	✓						\checkmark		\checkmark	\checkmark		✓		✓				✓						\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Intelligence, Surveillance, Reconnaissance	✓		✓	✓	✓	\checkmark				\checkmark		✓	✓	✓	✓		✓				✓	\checkmark	✓	\checkmark	✓	✓	✓	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Vehicle Testing	\checkmark		\checkmark							\checkmark		\checkmark	\checkmark	\checkmark	\checkmark						✓		\checkmark		\checkmark		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark

										Biolo	gical	Resour	rces								Phys	sical I	Resou	rces				Hun	nan Re	esour	ces		
		Acc	oustic	Stres	sors		Explo Stres	osive ssors	Energ	y Stres	sors	Phys	ical D Strike	Disturk e Stre	oance ssors	e and	Entar Str	iglement essors	Inge Stre	estion essors	Air Quality Stressors	Se И	edime /ater Stres	nts ar Quali ssors	nd ty	Cult Reso Stre	ural ource ssors	Socio Re St	econo esourc ressoi	omic ce rs	Publ & St	lic He Safet resso	alth y rs
Hawaii California Testing Activity	Sonar & Other Transducers	Pile Driving	Vessel Noise	Aircraft Noise	Weapons Noise	Air Guns	Explosions in Water	Explosions in Air	In-Water Electromagnetic Devices	In-Air Electromagnetic Devices	High-Energy Lasers	Vessels & In-water Device Strike	Aircraft & Aerial Target Strike	Military Expended Material	Seafloor Devices	Pile Driving	Wires & Cables	Decelerators/Parachutes	Military Expended Materials – Munitions	Military Expended Materials – Other than Munitions	Criteria Air Pollutants	Explosives	Metals	Chemicals (Not Explosives)	Other Materials	Explosives	Physical Disturbance & Strike	Accessibility	Airborne Acoustics	Physical Disturbance & Strike	Underwater Energy	In-Air Energy	Physical Interactions
OFFICE OF NAVAL RESEARCH																																	
ACOUSTIC AND OCEANOGRAPHIC SCIENCE AND TECHNO	LOGY	1																															
Acoustic and Oceanographic Research	\checkmark		✓		\checkmark	~	\checkmark			~		~		✓	✓				✓		✓	~	~		~	~	✓	~	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
Large Displacement Unmanned Underwater Vehicle Testing														✓							✓						✓	✓		\checkmark			\checkmark
Long-Range Acoustic Communications	\checkmark		\checkmark									\checkmark			✓						✓												
Mine Countermeasure Technology Research	\checkmark		\checkmark									\checkmark									\checkmark						\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark

										Biolo	gical	Resou	rces								Phy	vsical	Resou	ırces				Hun	nan R	esourd	ces		
		Acc	oustic	Stress	sors		Explo. Stress	sive sors	Energy	y Stres	sors	Phys	sical D Strike	isturb Stres	ance sors	and	Entang Stre	glement essors	Ing Stre	estion essors	Air Quality Stressors	S.	edime Vater Stre	ents a Qual sssors	ınd ity	Cul Res Stre	tural ource ssors	Socie R Si	oecon esour tresso	omic ce rs	Publ & St	ic Hea Safet ressoi	alth y rs
Hawaii California Testing Activity	Sonar & Other Transducers	Pile Driving	Vessel Noise	Aircraft Noise	Weapons Noise	Air Guns	Explosions in Water	Explosions in Air	In-Water Electromagnetic Devices	In-Air Electromagnetic Devices	High-Energy Lasers	Vessels & In-water Device creites	Aircraft & Aerial Target Strike	Military Expended Material	Seafloor Devices	Pile Driving	Wires & Cables	Decelerators/Parachutes	Military Expended Materials – Munitions	Military Expended Materials – Other than Munitions	Criteria Air Pollutants	Explosives	Metals	Chemicals (Not Explosives)	Other Materials	Explosives	Physical Disturbance & Strike	Accessibility	Airborne Acoustics	Physical Disturbance & Strike	Underwater Energy	In-Air Energy	Physical Interactions
AIRSPACE						-													_					-					_				
Special Use Airspace Modification				✓									✓																				
SEASPACE						-													_					-				_					
Southern California Offshore Anti-Submarine Warfare Range Modernization			~						✓			~			~		✓				✓			~			~	1		~	~		✓
Shallow Water Training Ranges Installation			✓						√			✓			✓		✓				✓			✓			✓	✓		✓	✓		✓
Sustainment of Undersea Ranges			✓									✓			✓		✓				✓			✓				✓		✓			✓
Deployment of Seafloor Cables and Instrumentation			✓						✓			✓			✓		✓				✓						✓	✓		✓	✓		✓
Installation and Maintenance of Mine Warfare and Other Training Areas			~									1			~		~				✓						~	~		~	~		✓
Installation and Maintenance of Underwater Platforms			✓									✓			✓						✓						✓	✓		✓			✓

Table B-3: Stressors by Modernization and Sustainment of Ranges Action

											Biolog	ical Re	source	s								P	hysica	l Resou	ırces				Н	uman l	Resour	ces		
			Ad	coustic	: Stress	ors		Expl Stre	losive ssors	Ener	rgy Stre	ssors	Ph	ysical Stril	Disturk ke Stre	bance a ssors	and	Entang Stre	glement essors	Inge Stre	estion essors	Air Quality Stressors	Ha Q	ıbitat o uality	and Wa Stressa	nter ors	Cult Reso Stre	tural ource ssors	Soci F S	ioecon Resour Stresso	omic ce ors	Publ Safe	lic Heal ty Stre	th & ssors
	Stressors vs. Resources	Sonar & Other Transducers	Pile Driving	Vessel Noise	Aircraft Noise	Weapons Noise	Air Guns	Explosions in Water	Explosions in Air	In-Water Electromagnetic Devices	In-Air Electromagnetic Devices	High-Energy Lasers	Vessels & In-water Device Strike	Aircraft & Aerial Target Strike	Military Expended Material	Seafloor Devices	Pile Driving	Wires & Cables	Decelerators/Parachutes	Military Expended Materials – Munitions	Military Expended Materials – Other than Munitions	Criteria Air Pollutants	Explosives	Metals	Chemicals (Not Explosives)	Other Materials	Explosives	Physical Disturbance & Strike	Accessibility	Airborne Acoustics	Physical Disturbance & Strike	Underwater Energy	In-Air Energy	Physical Interactions
ical	Air Quality								~												~	~												
Phys	Sediments and Water Quality							~															~	~	~	~								
	Vegetation							~					~		~	1	~						~	~	1	~								
	Invertebrates	~	1				~	~		~	~	1	~		~	1	~	~	1	1			~	~	1	~								
Ы	Habitats							~					~		~	1	~																	
ologic:	Fishes	~	~	~		1	~	~		~		1	~		~	1		~		1			~	~	1	~								
Bi	Marine Mammals	~	~	~	~	1	~	~		~		1	~		~	1		~	~	1			~	~	1	~								
	Reptiles	~	~	~	~	1	~	~		~		1	~		~	1		~	~	1			~	~	1	~								
	Birds	~		~	✓	~	~	~	✓		1	1	~	~	~					1	✓	~												
	Cultural Resources				✓			~							~	~											~	✓						
Human	Socioeconomic Resources and Environmental Justice	~		~	~	~	~	~					~	~	~			~					~	~	~	~			~	~	~			
	Public Health and Safety	~				✓	✓	✓				1	~	✓	✓	✓																✓	✓	✓

Table B-4: Stressors by Resource

Appendix C Biological Resources Supplemental Information

Environmental Impact Statement/

Overseas Environmental Impact Statement

Hawaii-California Training and Testing Activities

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APPENDIX C Biological Resources Supplemental Information

C.1 Sediments and Water Quality

C.1.1 Introduction

C.1.1.1 Regulatory Environment

C.1.1.1.1 State Standards and Guidelines

State-level standards for sediments and water quality standards and guidelines begins with each state establishing a use for the water, which is referred to as its "designated" use. Examples of such uses of marine waters include fishing, shellfish harvesting, and recreation. For this appendix, a water body is considered "impaired" if any one of its designated uses is not met. The designated uses are declared under the Clean Water Act (CWA) by the states, because they are directed by the law, or allow the United States Environmental Protection Agency (USEPA) to designate the uses for them. Designating impaired waters comes under section 401 of the CWA and is delegated to the state by the USEPA. Applicable state standards and guidelines specific to each stressor are detailed in their respective subsections.

C.1.1.1.2 Federal Standards and Guidelines

Federal jurisdiction regarding sediments and water quality extends to 200 nautical miles (NM) along the Hawaiian Islands and the Pacific coast of the United States (U.S.). These standards and guidelines are mainly the responsibility of the USEPA, specifically ocean discharge provisions of the CWA (33 United States Code [U.S.C.] section 1343). The USEPA sets the water quality standards that include designated uses, criteria for pollutants that would protect those designated uses, establishes antidegradation policy and methods, and then implements the standards through permitting and other regulatory processes. Ocean disposal regulation is one of those implementation tools. The states or tribes may assume responsibility for implementing the water quality standards and they may establish more rigorous standards if that are science based, but the states must at minimum meet the USEPAs standards (with special process being available in the case where variances are needed). Ocean disposal may not result in: (1) unreasonable degradation on human health; (2) unacceptable negative effects on the marine ecosystem; (3) unacceptable negative persistent or permanent effects due to the particular volumes or concentrations of the dumped materials; and (4) unacceptable negative effects on the ocean for other uses as a result of direct environmental impact (40 Code of Federal Regulations [CFR] section 125.122). Proposed training and testing activities also occur beyond 200 NM. Even though CWA regulations may not apply, pertinent water quality standards are used as accepted scientific standards to assess potential impacts on sediments and water quality from the Proposed Action.

The International Convention for the Prevention of Pollution from Ships (Convention) addresses pollution generated by normal vessel operations. The Convention is incorporated into U.S. law as 33 U.S.C. sections 1901–1915. The Convention includes six annexes: Annex I, oil discharge; Annex II, hazardous liquid control; Annex III, hazardous material transport; Annex IV, sewage discharge; Annex V, plastic and garbage disposal; and Annex VI, air pollution. The U.S. Department of the Navy (Navy) is required to comply with the Convention; however, the U.S. is not a party to Annex IV. The discharge of sewage by military vessels is regulated by Section 312(d) of the CWA. The Convention contains handling requirements and specifies where materials can be discharged at sea, but it does not contain standards related to sediments or water quality.

The National Defense Authorization Act (NDAA) of 1996 amended section 312 of the CWA, directing the USEPA and the Department of Defense (DoD) to jointly establish the Uniform National Discharge Standards for discharges (other than sewage) incidental to the normal operation of military vessels. The Uniform National Discharge Standards program establishes national discharge standards for military vessels in U.S. coastal and inland waters extending seaward to 12 NM. Twenty-five types of discharges were identified as requiring some form of pollution control (e.g., a device or policy) to reduce or eliminate the potential for impacts. The discharges addressed in the program include, ballast water, deck runoff, and seawater used for cooling equipment. For a complete list of discharges refer to 40 CFR part 1700.4.

These national discharge standards reduce the environmental impacts associated with vessel discharges, stimulate the development of improved pollution control devices aboard vessels, and advance the development of environmentally sound military vessels.

C.1.1.2 Sediments

C.1.1.2.1 Characteristics of Sediment

Sediments consist of solid fragments of organic and inorganic matter forming the bottom, or substrate, of bodies of water. Sediments in the marine environment (e.g., in ocean basins) are either terrigenous, meaning that they originate from land, or are biogenic (i.e., formed from the remains of marine organisms). Terrigenous sediments come from the weathering of rock and other land-based substrates and are transported by water, wind, and ice (glaciers) to the seafloor. Biogenic sediments are produced in the oceans by the skeletal remains of single-celled benthic and planktonic organisms (e.g., foraminiferans and diatoms). When an organism dies, its remains are deposited on the seafloor. The remains are composed primarily of either calcium carbonate (e.g., a shell) or silica, and mixed with clays, form either a calcareous or siliceous ooze (Chester, 2003). Sediments in the Atlantic Ocean are predominantly composed of calcareous oozes and the Pacific Ocean has more siliceous oozes (Kennett, 1982). In addition to composition, sediments are also classified by size. Blott and Pye (2012) reviewed commonly used historical classification systems and offered a refined system that is adopted for describing sediments in this section. Sediments are grouped into five size classes: boulders, gravel, sand, silt, and clay. Sands range in size from 0.063 millimeter (mm) (very fine sands) to 2 mm (very coarse sands) (Figure C-1). For comparison, the thickness of a nickel is approximately 2 mm. Sediment types smaller than sands are silts (0.0020.063 mm in diameter) and clays (particles less than 0.002 mm in diameter). Sediments larger than sands are various types of gravel ranging in size from 2 mm (granules) to 64 mm (cobbles). Sediments greater than 64 mm in diameter are defined as boulders and range up to 2,048 mm (Blott & Pye, 2012; U.S. Department of Agriculture, 1993). Fine-grained silts and clays are often found mixed together in areas beyond the continental slope, such as on abyssal plains, and are referred to generally as mud (Kennett, 1982). Sediments in nearshore waters and on the continental shelf contain more sands that are primarily terrigenous, and sediments farther from shore in deep ocean basins are primarily biogenic. As organic and inorganic particles move downward through the water column and ultimately to the seafloor, many substances, including contaminants, that adhere to the particles and that are otherwise scarce in the water column become concentrated in bottom sediments (Chapman et al., 2003; Kszos et al., 2003).



Figure C-1: Sediment Particle Size Comparison

C.1.1.2.2 Factors Affecting Marine Sediment Quality

The quality of sediments is influenced by their physical, chemical, and biological components; by where they are deposited; by the properties of seawater; and by other inputs and sources of contamination. Sediments tend to be dynamic, where factors affecting marine sediments often interact and influence each other. These factors are summarized below.

C.1.1.2.2.1 Physical Characteristics and Processes

At any given site, the texture and composition of sediments are important physical factors that influence the types of substances that are retained in the sediments, and subsequent biological and chemical processes. For example, clay-sized and smaller sediments and similarly sized organic particles tend to bind potential sediment contaminants and potentially limit their movement in the environment (U.S. Environmental Protection Agency, 2009). Conversely, fine-grained sediments are easily disturbed by currents and bottom-dwelling organisms, dredging, storms, and bottom trawling (Eggleton & Thomas, 2004; Hedges & Oades, 1997). Disturbance is also possible in deeper areas, where currents are minimal (Carmody et al., 1973), from mass wasting events such as underwater slides and debris flows (Coleman & Prior, 1988). If re-suspended, fine-grained sediments (and any substances bound to them) can be transported long distances.

C.1.1.2.2.2 Chemical Characteristics and Processes

The concentration of oxygen in sediments strongly influences sediment quality through its effect on the binding of materials to sediment particles. At the sediment surface, the level of oxygen is usually the same as that of the overlying water. Deeper sediment layers, however, are often low in oxygen (i.e., hypoxic) or have no oxygen (i.e., anoxic), and have a low oxidation-reduction potential, which predicts the stability of various compounds that regulate nutrient and metal availability in sediments. Certain substances combine in oxygen-rich environments and become less available for other chemical or biological reactions.

C.1.1.2.2.3 Biological Characteristics and Processes

Organic matter in sediment provides food for resident microbes. The metabolism of these microbes can change the chemical environment in sediments and thereby increase or decrease the mobility of various substances and influence the ability of sediments to retain and transform those substances (Mitsch et al., 2009a; U.S. Environmental Protection Agency, 2008a). Bottom-dwelling animals often rework sediments in the process of feeding or burrowing. In this way, marine organisms influence the structure, texture, and composition of sediments, as well as, the horizontal and vertical distribution of substances in the sediment (Boudreau, 1998). Moving substances out of or into low or no-oxygen zones in the sediment may alter the form and availability of various substances. The metabolic processes of bacteria also influence sediment components directly. For example, sediment microbes may convert mercury to methyl mercury, increasing its toxicity (Mitchell & Gilmour, 2008). However, it is more common that biological processes break down contaminants and reduce toxicity in sediments (White et al., 1997).

C.1.1.2.2.4 Location

The quality of coastal and marine sediments is influenced substantially by inputs from adjacent watersheds (Turner & Rabalais, 2003). Proximity to watersheds with large cities or intensively farmed lands often increases the amount of both inorganic and organic contaminants that find their way into coastal and marine sediments. A wide variety of metals and organic substances, such as polycyclic aromatic hydrocarbons, polychlorinated biphenyls (PCBs), and pesticides—often referred to collectively as "persistent organic pollutants"—are discharged into coastal waters by urban, agricultural, and industrial point and non-point sources in the watershed (U.S. Environmental Protection Agency, 2008a). Location on the ocean floor also influences the distribution and concentration of various elements through local geology and volcanic activity (Demina & Galkin, 2009), as well as through landslides and debris flow events (Coleman & Prior, 1988).

C.1.1.2.2.5 Other Contributions to Sediments

While the greatest mass of sediments is carried into marine systems by rivers (U.S. Environmental Protection Agency, 2008a), wind and rain also deposit materials in coastal waters and contribute to the mass and quality of sediments. For example, approximately 80 percent of the mercury released by human activities comes from coal combustion, mining and smelting, and solid waste incineration (Agency for Toxic Substances and Disease Registry, 1999). These activities are generally considered to be the major sources of mercury in marine systems (Fitzgerald et al., 2007). Atmospheric deposition of lead is similar in that human activity is a major source of lead in sediments (Wu & Boyle, 1997).

C.1.1.3 Water Quality

The discussion of water quality begins with an overview of the characteristics of marine waters, including pH (a measure of acidity), temperature, oxygen, nutrients (e.g., chlorophyll), salinity, and dissolved elements. The discussion then considers how those characteristics of marine waters are influenced by physical, chemical, and biological processes.

C.1.1.3.1 Characteristics of Marine Waters

The composition of water in the marine environment is determined by complex interactions among physical, chemical, and biological processes. Physical processes include region-wide currents and tidal flows, seasonal weather patterns and temperature, sediment characteristics, and unique local conditions, such as the volume of fresh water delivered by large rivers. Chemical processes involve salinity, pH, dissolved minerals and gases, particulates, nutrients, and pollutants. Biological processes

involve the influence of living things on the physical and chemical environment. The two dominant biological processes in the ocean are photosynthesis and respiration, particularly by microorganisms. These processes involve the uptake, conversion, and excretion of waste products during growth, reproduction, and decomposition (Mann & Lazier, 1996).

C.1.1.3.2 Influence of Marine Properties and Processes on Seawater Characteristics

Ocean currents and tides mix and redistribute seawater. In doing so, they alter surface water temperatures, transport and deposit sediment, and concentrate and dilute substances that are dissolved and suspended in the water. These processes operate to varying degrees from nearshore areas to the abyssal plain. Salinity also affects the density of seawater and, therefore, its movement relative to the sea surface (Libes, 2009). Upwelling brings cold, nutrient-rich waters from deeper areas, increasing the productivity of local surface waters (Mann & Lazier, 1996). Storms and hurricanes also cause strong mixing of marine waters (Li et al., 2008).

Temperature and pH influence the behavior of trace metals in seawater, such as the extent to which they dissolve in water (i.e., the metal's solubility) or their tendency to adsorb to organic and inorganic particles. However, the degree of influence differs widely among metals (Byrne, 1996). The concentration of a given element may change with position in the water column. For example, some metals (e.g., cadmium) are present at low concentrations in surface waters and at higher concentrations at depth (Bruland, 1992), while others decline quickly with increasing depth below the surface (e.g., zinc and iron) (Morel & Price, 2003; Nozaki, 1997). On the other hand, dissolved aluminum concentrations are highest at the surface, lowest at mid-depths, and increase again at depths below about 1,000 meters (m) (Li et al., 2008).

Substances, such as nitrogen, carbon, silicon, and trace metals are extracted from the water by biological processes. Others, like oxygen and carbon dioxide (CO₂), are produced by biological processes. Metabolic waste products add organic compounds to the water, and may also absorb trace metals, removing those metals from the water column. Those organic compounds may then be consumed by biological organisms, or they may aggregate with other particles and sink (Mann & Lazier, 1996; Wallace et al., 1977).

Runoff from coastal watersheds influences local and regional coastal water conditions, especially large rivers. Influences include increased sediments and pollutants, and decreased salinity (Rabalais et al., 2002; Turner & Rabalais, 2003; Wiseman & Garvine, 1995). Coastal bays and large estuaries serve to filter river outflows and reduce total discharge of runoff to the ocean (Edwards et al., 2006; Mitsch et al., 2009a). Depending on their structure and components, estuaries can directly or indirectly affect coastal water quality by recycling various compounds (e.g., excess nutrients), sequestering elements in more inert forms (e.g., trace metals), or altering them, such as the conversion of mercury to methyl mercury (Mitchell & Gilmour, 2008; Mitsch & Gosselink, 2007).

C.1.1.3.3 Coastal Water Quality

Most water quality problems in coastal waters of the U.S. are from degraded water clarity or increased concentrations of phosphates or chlorophyll-*a* (U.S. Environmental Protection Agency, 2012). Water quality indicators measured are dissolved inorganic nitrogen, dissolved inorganic phosphorus, water clarity or turbidity, dissolved oxygen (DO), and chlorophyll-*a*. Chlorophyll-*a* is an indicator of microscopic algae (phytoplankton) abundance used to judge nutrient availability (i.e., phosphates and nitrates). Excess phytoplankton blooms can decrease water clarity and, when phytoplankton die off following blooms, lower concentrations of DO. Most sources of these impacts arise from on-shore point and non-

point sources of pollution. Point sources are direct water discharges from a single source, such as industrial or sewage treatment plants, while non-point sources are the result of many diffuse sources, such as runoff caused by rainfall.

C.1.2 Methods

The following four stressors may impact sediments or water quality: (1) explosives and explosives byproducts, (2) metals, (3) chemicals other than explosives, and (4) other materials (e.g., plastics). The term "stressor" is used because the military expended materials in these four categories may affect sediments or water quality by altering their physical or chemical characteristics. The potential impacts of these stressors are evaluated based on the extent to which the release of these materials could directly or indirectly impact sediments or water quality such that existing laws or standards would be violated or recommended guidelines would be exceeded. The differences between standards and guidelines are described below.

- Standards are established by law or through government regulations that have the force of law. Standards may be numerical or narrative. Numerical standards set allowable concentrations of specific pollutants (e.g., micrograms per liter [µg/L]) or levels of other parameters (e.g., pH) to protect the water's designated uses. Narrative standards describe water conditions that are not acceptable.
- Guidelines are non-regulatory, and generally do not have the force of law. They reflect an
 agency's preference or suggest conditions that should prevail. Guidelines are often used to
 assess the condition of a resource to guide subsequent steps, such as the disposal of
 dredged materials. Terms such as screening criteria, effect levels, and recommendations are
 also used.

C.1.2.1 Intensity and Duration of Impact

The intensity or severity of impacts is defined as follows (listed by increasing level of impact):

- Chemical, physical, or biological changes in sediment or water quality would not be detectable as a result of the use of military materials.
- Chemical, physical, or biological changes in sediments or water quality would be measurable, but total concentrations would not violate applicable standards, regulations, and guidelines. Sediment and water quality would be equivalent to existing conditions, and designated uses of the water body or substrate would not change.
- Chemical, physical, or biological changes in sediments or water quality would be measurable and readily apparent but total concentrations would not violate applicable standards, regulations, and guidelines. Sediment or water quality would be altered compared to the historical baseline or desired conditions, and designated uses of the water body or substrate would be changed. Mitigation would be necessary and would likely be successful.
- Chemical, physical, or biological changes in sediment or water quality would be readily measurable, and some standards, regulations, and guidelines would be periodically approached, equaled, or exceeded as measured by total concentrations. Sediment or water quality would be frequently altered from the historical baseline or desired conditions, and designated uses of the water body or substrate would be changed. Mitigation measures would be necessary to limit or reduce impacts on sediment or water quality, although the efficacy of those measures would not be assured.

Duration is characterized as either short-term or long-term. Short-term is defined as days or months. Long-term is defined as months or years, depending on the type of activity or the materials involved.

C.1.2.2 Measurement and Prediction

Many of the conditions discussed above often influence each other, so measuring and characterizing various substances in the marine environment is often difficult (Byrne, 1996; Ho et al., 2007). For instance, sediment contaminants may change over time. Valette-Silver (1993) reviewed several studies that demonstrated the gradual increase in a variety of contaminants in coastal sediments that began as early as the 1800s, continued into the 1900s, peaked between the 1940s and 1970s, and declined thereafter (e.g., lead, dioxin, PCBs). After their initial deposition, normal physical, chemical, and biological processes can re-suspend, transport, and redeposit sediments and associated substances in areas far removed from the source (Hameedi et al., 2002; U.S. Environmental Protection Agency, 2012). The conditions noted above further complicate predictions of the impact of various substances on the marine environment.

C.1.2.3 Sources of Information

Relevant literature was systematically reviewed to complete this analysis of sediments and water quality. The review included journals, technical reports published by government agencies, work conducted by private businesses and consulting firms, U.S. DoD reports, operational manuals, natural resource management plans, and current and prior environmental documents for facilities and activities in the Study Area.

Because of the proximity of inshore and nearshore areas to humans, information on the condition of sediments and water quality in those areas tends to be relatively readily available. However, much less is known about deep ocean sediments and open ocean water quality. Since sediments and water quality in inshore and nearshore areas tend to be affected by various human social and economic activities, two general assumptions are used in this discussion: (1) sediments and water quality generally improve as distance from the shore increases; and (2) sediments and water quality generally improve as depth increases.

C.1.3 General Background

C.1.3.1 Sediments

C.1.3.1.1 Sediment Quality in the Nearshore and Offshore Regions of the Hawaiian Islands

The 2012 National Coastal Condition Report IV is the most recent, comprehensive sediment quality analysis of nearshore and offshore Hawaiian Islands. The two sites receiving a poor rating were in Waimea Bay, Kauai where chromium concentrations exceeded the level where adverse effects are likely to occur in 50 percent of samples. Sampling sites in Pearl Harbor, Keehi Lagoon on Oahu, Hilo Bay on Hawaii, and other harbor areas exceeded effects levels for individual metals. For total organic carbon, 12 percent of coastal waters were rated poor and 18 percent were rated fair. Some of the same areas with relatively high concentrations of contaminants in sediments also had higher concentrations of total organic carbon, including Keehi Lagoon and Hilo Bay. Suburban development east of Honolulu contributed to higher levels of total organic carbon in adjacent coastal waters. Higher levels of total organic carbon in sediments can be an indicator of higher concentrations of chemical pollutants and poor sediment quality (U.S. Environmental Protection Agency, 2012).

Some metals naturally occur at elevated concentrations in the volcanic soils of Hawaii. Natural concentrations of copper, zinc, nickel, and chromium are high compared to soils in the mainland U.S.

Pearl Harbor receives a substantial amount of metal contamination because it serves as a natural trap for sediment particles (U.S. Environmental Protection Agency, 2008b). See Table C-1 for sediment quality criteria and index by site and by region.

Deremeter		Site Criteria			Regional Criteri	а
Parameter	Good	Fair	Poor	Good	Fair	Poor
Sediment Toxicity	Amphipod ¹ survival rate ≥ 80%	n/a	Amphipod ¹ survival rate < 80%	< 5% of coastal area in poor condition	n/a	≥ 5% of coastal area in poor condition
Sediment Contaminants	No ERM ² concentration exceeded, and < 5 ERL ³ concentrations exceeded	No ERM ² concentration exceeded and ≥ 5 ERL ³ concentrations exceeded	An ERM ² concentration exceeded for one or more contaminants	< 5% of coastal area in poor condition	5–15% of coastal area in poor condition	> 15% of coastal area in poor condition
Excess Sediment TOC	TOC concentration < 2%	TOC concentration 2% to 5%	TOC concentration > 5%	< 20% of coastal area in poor condition	20–30% of coastal area in poor condition	> 30% of coastal area in poor condition
Sediment Quality Index	No poor ratings, sediment contaminants criteria are rated "good"	No poor ratings, sediment contaminants criteria are rated "fair"	One or more individual criteria rated poor	< 5% of coastal area in poor condition, and > 50% in good condition	5–15% of coastal area in poor condition, and > 50% in combined fair and poor condition	> 15% of coastal area in poor condition

Table C-1: Sediment Quality Criteria and Index, United States West Coast and HawaiianIslands

Source: (U.S. Environmental Protection Agency, 2009, 2012); State of California (2009)

¹Amphipods are small animals found in a wide variety of aquatic habitats. Because they are so widely distributed, they are often used as an indicator of toxicity in sediments and water bodies.

²ERM (effects range-median) is the level measured in the sediment below which adverse biological effects were measured 50 percent of the time.

³ERL (effects range-low) is the level measured in the sediment below which adverse biological effects were measured 10 percent of the time Long et al. (1995).

Notes: % = percent. \geq = equal to or greater than, < = less than, > = greater than, n/a = not applicable, TOC = total organic carbon

Anthropogenic activities within and around Pearl Harbor, including Navy activities and private industrial, commercial, and agricultural activities, contribute pollutants through point and non-point sources. These activities release numerous pollutants into Pearl Harbor, where sediments can act as a sink or repository for chemicals. The Navy conducted a Remedial Investigation/Feasibility Study of the sediments in Pearl Harbor from March to June 2009. The results of the Remedial Investigation indicated that eight metals (antimony, cadmium, copper, lead, mercury, selenium, silver, and zinc), total high molecular weight polycyclic aromatic hydrocarbons, total PCBs, and two chlorinated pesticides (dieldrin and total endosulfan) exceeded the project screening criteria (Table C-2) (U.S. Department of the Navy,

2010a). Surface weighted-average concentrations in sediment were below project screening criteria in Middle Loch and West Loch and above project screening criteria in Southeast Loch, Bishop Point, northwest shoreline of Ford Island, Aiea Bay, shoreline of Oscar 1 and 2, and off the Waiau Power Plant (U.S. Department of the Navy, 2010a).

In 2012, the Space and Naval Warfare Systems Command conducted field measurements on the resuspension of sediments from propeller wash in DoD harbors, including Pearl Harbor (Wang et al., 2014a). Background concentration of contaminants were measured in sediments prior to conducting the study (Table C-2). In an earlier study, (Wang et al., 2009), estimated that transiting Navy (and other military) vessels in Pearl Harbor resuspended 54 tons of sediments per day, which amounts to more than 10 percent of the sediment load from the entire Pearl Harbor watershed. Wang et al. (2014a) measured sediment resuspension and associated metal contaminants from a tugboat propeller wash at two piers, Bravo Pier and Oscar Pier in Pearl Harbor; measurements included the concentrations of the metals chromium, nickel, copper, zinc, arsenic, silver, cadmium, and lead, in the sediment plume. The concentrations of chromium and nickel were the only ones consistently above USEPA water quality criteria following the resuspension events (Wang et al., 2014a). Between 65 and 90 percent of metal concentrations, depending on the metal, were in the dissolved phase, rather the particle-bound phase, contributing to greater dispersion within the harbor. The data were used as input and validation of a fate and transport model, which predicted that resuspended metals can be transported and dispersed far from the piers, and, over several days, throughout much of the harbor, potentially resulting in recontamination of remediated areas as well as increased contaminant concentrations in more remote areas of the harbor (Wang et al., 2014a).

The Hawaii Undersea Military Munitions Assessment is a comprehensive effort to characterize the potential impacts of chemical and conventional munitions disposed of at sea in a deepwater environment (Edwards et al., 2016). The program collected data in a location south of Pearl Harbor, Oahu between Barber's Point and Diamond Head from 2007 to 2012 with the goals of defining the bounds of the disposal site, characterizing the state of the munitions found on the seafloor, and assessing the potential impacts that degrading munitions may have on the benthic environment. Researchers mapped the disposal site using high-resolution acoustic imaging, took thousands of digital photos and recorded hundreds of hours of video, and collected physical samples within two meters of munitions to assess sediment contamination. Concentrations of metals detected in sediments at the disposal sites were similar to samples taken from nearby (within 50 m) control sites (Briggs et al., 2016). The chemical warfare agent sulfur mustard and its degradation products were detected as a thin dust-like coating on bottom sediments near chemical munitions. There appeared to be no vertical mixing with adjacent sediments, and the combination of the chemical's low water solubility, the formation of a protective coating by the products of hydrolysis, and near freezing temperatures at the site (greater than 250 m depth), likely resulted in the chemical's persistence as a thin coating (Briggs et al., 2016). There were very few detections of energetic compounds (e.g., explosive materials) at the disposal sites, leading researchers to conclude that the compounds remain contained within the munitions casing or were widely dispersed or degraded before samples were taken.

Following these studies and reports, in September of 2018, the Final Record of Decision Pearl Harbor Sediment for Joint Base Pearl Harbor-Hickan (JBPHH) Oahu, Hawaii was released for the remediation of the Pearl Harbor Sediment Site 19 (Naval Facilities Engineering Command Pacific, 2018). Selected remediation activities selected for the site include focused dredging, institutional controls, long-term
monitoring, inspections, and five-year reviews. At the time of publication of this report, remedial action was ongoing at the site.

In 2019, the Naval Facilities Engineering Command Pacific published the Basis of Design, Field Investigation Report for Pearl Harbor sediment. This report supports the development of remediation activities by detailing condition of focus areas within the harbor. Sediments were found to have harmful concentrations of chemicals of concern in six locations within the harbor: Southeast Loch, Oscar 1 and 2 Piers Shoreline, Off Ford Island Landfill and Camel Refurbishing Area, Bishop Point, Off Waiau Power Plant, and Aiea Bay. Chemicals of concern identified in these locations include metals and PCBs. For these locations, remedial alternatives may include focused dredging, enhanced natural recovery, in-situ treatment with activated carbon amendment, and monitored natural recovery (AECOM Technical Services, 2019).

Parar	neter	Pier in Pearl Harbor	Background Concentrations (ppm)	Sediment Screening Criteria (mg/kg [ppm], dry weight)	
	Antimony	Bravo	Not Measured	8.4	
	, and mony	Oscar	Not measured	Sediment Screening Criteria (mg/kg [ppm], dry weight) 8.4 27.5 3.2 2777 214 119 0.71 660 3.8 1.8 330 35,253 (> 2 m water depth) 29	
	Arsenic	Bravo	13.0	27.5	
		Oscar	10.5	27.5	
	Cadmium	Bravo	0.82	3.2	
	Cauman	Oscar	0.41	5.2	
	Chromium	Bravo	86.4	777	
	Chronnum	Oscar	51.8	277	
	Coppor	Bravo	97.8	214	
	Copper	Oscar	49.0	214	
N 4 - t - l -	Lead	Bravo	53.0	110	
IVIELAIS		Oscar	41.8	119	
	Manaum	Bravo	Not Measured	0.71	
	wiercury	Oscar	Not Measured	0.71	
	Nickel	Bravo	54.0	660	
		Oscar	33.2	000	
	Colonium	Bravo	Not Massurad	2.0	
	Selenium	Oscar	Not Weasured	5.8	
	Cilver	Bravo	0.67	1.0	
	Silver	Oscar	0.32	1.8	
		Bravo	290	220	
	ZIIIC	Oscar	225	550	
Organic Compounds	HMW-PAHs	N/A	Not Measured	35,253	
	Total PCBs	Bravo/Oscar	ND	92 (> 2 m water depth) 29 (< 2 m water depth)	

Table C-2: Sediment Screening Criteria and Background Concentrations for Pearl Harbor Sediment Remedial Investigation

Parameter		Pier in Pearl Harbor	Background Concentrations (ppm)	Sediment Screening Criteria (mg/kg [ppm], dry weight)	
Pesticides	Total DDT	Bravo/Oscar	Not Measured	106.6	
	Dieldrin	Bravo/Oscar	ND	14.4	
	Total BHC	Bravo/Oscar	Not Measured	1,215	
	Total Chlordane	Bravo/Oscar	Not Measured	174	
	Heptachlor Epoxide	chlor Epoxide Bravo/Oscar N		174	
	Total Endosulfan	Bravo/Oscar	ND	1.09	
Dioxins	2,3,7,8-TCDD	Bravo/Oscar	Not Measured	0.36	

Sources: U.S. Department of the Navy (2010a), Wang et al. (2014a)

Notes: mg = milligram, kg = kilogram, ppm = parts per million, HMW-PAH = high molecular weight-polyaromatic hydrocarbons, PCBs = polychlorinated biphenyls, DDT = dichlorodiphenyltrichloroethane, BHC = benzene hexachloride, TCDD = tetrachlorodibenzo-p-dioxin, < = less than, > = greater than, N/A = not applicable, ND = Not Detected

C.1.3.1.2 Sediment Quality in the Nearshore and Offshore Regions of the California Study Area

Within the West Coast Region, only two sites, both in the Channel Islands, received a poor rating for total organic carbon. Although these sites are located adjacent to the Study Area neither fall within the Study Area boundaries.

In a report on the *Southern California Bight 2018 Regional Monitoring Program*, the Southern California Coastal Water Research Project found that 79 percent of sediments in the Southern California Bight have minimal or low contamination, and less than 1 percent have high contamination, the worst category (Du et al., 2018). The Study Area overlaps with approximately the southern half of the Bight, from just north of Santa Catalina Island to the U.S.-Mexico border. Higher levels of sediment contamination occurred generally in nearshore embayments rather than in offshore sediments on the continental shelf and slope, and the distribution of contaminants was dependent on the location of the source of the contaminant. For example, concentrations of dichlorodiphenyltrichloroethane (DDT) are higher in sediments off Los Angeles due to long-term discharges from the Los Angeles sanitation district ocean outfall, whereas copper concentrations are higher in sediments in San Diego Bay, which is home to several large marinas, due to the use of anti-fouling paints on recreational and commercial vessels (Du et al., 2018).

Overall, trends for the entire Bight have been stable since 2003, but the sediment condition for some habitats within the Bight has changed. For example, the spatial extent of sediments with acceptable chemistry in ports, bays, and marinas steadily improved from 40 percent in 1998 to 72 percent in 2013, then decreased 53 percent in 2018. The extent of acceptable sediment chemistry in estuaries and continental shelf sediments remained generally unchanged from 2003 to 2018 (Du et al., 2018).

In 2018, for the first time, the Southern California Coastal Water Research Project surveyed for fipronil, a new pesticide product. Overall, fipronil pesticides were not widely detected (Du et al., 2018).

C.1.3.1.2.1 Sediment Quality off San Clemente Island and the Silver Strand Training Complex

Sediment quality in the waters surrounding San Clemente Island (SCI) was tested in 2006 (U.S. Department of the Navy, 2006a); concentrations for all contaminants were well below USEPA sediment quality guidelines (Effects Range Median values) (Table C-3). The 10-day solid-phase amphipod bioassay tests of the sediments also indicated high survival and no substantial toxicity. The results indicate that ocean bottom sediment quality is good off SCI, including areas were training and testing activities occur.

An Area of Special Biological Concern has been designated by the California State Water Resources Control Board to include nearshore waters around SCI out to 1 NM from shore or to the 300 feet (ft.) isobath, whichever is greater, along the island's 58-mile (mi.) coastline. The designation prohibits all waste discharges, both point and non-point, with the exception of a 1,000 ft. radius area at Wilson Cove where the wastewater treatment plant is located (U.S. Department of the Navy, 2013d). A 2011 survey of intertidal habitat and associated biological communities noted no substantial differences between species richness at a discharge site and a reference site, supporting the 2006 data indicating that low contaminant levels good sediment quality (U.S. Department of the Navy, 2013d).

Constituent	Sediment Concentration at SCI Reference Sampling Site (ppm)	USEPA Sediment Quality Guidelines (ERM Values) (ppm)
Arsenic	2.87	70
Cadmium	0.11	9.6
Chromium	8.56	370
Copper	7.48	270
Lead	2.19	218
Mercury	0.275	0.71
Nickel	4.6	51.6
Selenium	0.56	n/a
Silver	0.09	3.7
Zinc	19.2	410
Polychlorinated biphenyls	ND (< 0.005)	180
Phenols	ND (< 0.1)	n/a
Dioxins (TEQ)	0.0–0.028	n/a

Sources: (National Oceanic and Atmospheric Administration, 1999; U.S. Department of the Navy, 2006a) Notes: ppm = parts per million, ERM = Effects Range Median, ND = not detectable concentration, n/a = not available, TEQ = toxicity equivalency factor, SCI = San Clemente Island, USEPA = United States (U.S.) Environmental Protection Agency, < = less than

Pacific Ocean sediments offshore of Silver Strand have above-average levels of organic loading and concentrations of some metals (aluminum, arsenic, chromium, copper, iron, manganese, and zinc), but these substances are not present at concentrations that pose a risk to public health or the environment. Traces of synthetic organic contaminants (e.g., chemicals released from the burning of coal) are occasionally detected in sediments, but have been well below a threshold of concern (U.S. Army Corps of Engineers, 2002, 2012). Concentrations of contaminants and particulate organic matter are highly variable due to changes in the outflow from the Tijuana River, which can increase substantially following heavy rainfall events (Svejkovsky et al., 2010). Sediment sampling in San Diego Bay near Silver Strand Training Complex-North indicates that—while concentrations of some contaminants are elevated above background levels—no contaminants were present at concentrations which would adversely affect marine organisms (U.S. Department of the Navy, 2013d).

C.1.3.1.2.2 Sediment Quality in San Diego

While multiple sources of pollution contribute to contaminants in the bay, including recreational, commercial, and Navy vessels urban runoff is the largest source of pollutants in the bay, contributing more heavy metals than all other sources combined. Despite reductions in the production and use of polybrominated diphenyl ether flame retardants, some of the highest concentrations of the contaminant in the Southern California Bight were reported in San Diego Bay (Dodder et al., 2016). In the past, sources of sediment contamination other than urban runoff in San Diego Bay have included sewage, industrial wastes, discharges from ships, and accidental spills of contaminants (e.g., oil or fuel). Progress has been made to eliminate or reduce the likelihood of these sources of pollutants entering the bay; however, many residual contaminants remain imbedded in bay sediments (Thompson et al., 2009; Wang et al., 2014a; Wang et al., 2000). Current sources of pollutants (other than urban runoff) include resuspension of sediments, industries surrounding and using the bay, Navy installations and activities in the bay, underwater hull cleaning, and vessel anti-fouling paints (Wang et al., 2006; Wang et al., 2000).

Known contaminants found in sediments in San Diego Bay include arsenic, copper, chromium, lead, cadmium, selenium, mercury, tin, manganese, silver, zinc, polycyclic aromatic hydrocarbons, petroleum hydrocarbons, PCBs, chlordane, dieldrin, and DDT (Dodder et al., 2016; Neira et al., 2009; U.S. Department of the Navy, 2000). Sediment sampling in the 1990s revealed that sediment quality indicators were exceeded at all San Diego Bay sampling stations and the number of exceedances was high at most stations (U.S. Department of the Navy, 2013d). Chlordane, polycyclic aromatic hydrocarbons, and PCBs were the pollutants most often found at elevated concentrations. Copper, lead, mercury and zinc were often found at elevated levels in Naval Shipyard areas, although the data indicate the probability of metal toxicity was low in those areas (U.S. Department of the Navy, 2013d).

Copper concentrations in marinas in San Diego Bay have frequently exceeded water quality standards (Biggs & D'Anna, 2012). Increasing copper concentrations in sediments at Shelter Island marina, a small, manmade basin with only one opening to the bay, coincided spatially with a higher concentration of boats in the marina (Neira et al., 2009). A second study measured copper concentrations before and after boat slips were occupied at the Pier 32 Marina near the middle of San Diego Bay and adjacent to the Sweetwater National Wildlife Refuge (Biggs & D'Anna, 2012). This study provided further confirmation that elevated concentrations of copper in water and sediments are primarily due to copper leaching from boat paints used on recreational and commercial vessels (Biggs & D'Anna, 2012). A follow-on study in the Shelter Island marina by Neira et al. (2009) showed that the elevated copper levels in sediments had widespread impacts on the benthic faunal community in the marina. While the proposed Navy training and testing activities would not use either marina, the studies indicate that elevated copper concentrations in sediments continues to be a concern and is likely to occur in other locations within the bay.

The San Diego Regional Water Quality Control Board assessed sediment contamination data from 161 sampling stations across San Diego Bay to determine the effects of sediment contamination on benthic macrofauna at-large and previously identified sediment clean-up sites (Thompson et al., 2012). The concentrations of 10 contaminants, 5 metals (Cadmium, copper, lead, mercury and zinc) and 5 organic compounds (total chlordanes, DDT, PCBs, high molecular weight polycyclic aromatic hydrocarbons, and low molecular weight polycyclic aromatic hydrocarbons), were analyzed and ranked on a scale of 1 to 5; sediments receiving a score of 1 were un-impacted and sediments receiving a score of 5 were clearly impacted. The impact score rated the likelihood that the level of contamination would impact benthic macrofauna. Thompson et al. (2012) cites several studies that show sediment toxicity and the

probability of associated impacts on biological resources are better represented by indicators that represent mixtures of contaminants rather than concentrations of individual contaminants (see, for example, (Carr et al., 1996; Thompson et al., 2009). One such indicator is the mean Effects Range Median Quotient, which Thompson et al. (2012) uses to evaluate sediment quality in the bay.

With the exception of polycyclic aromatic hydrocarbons, the mean concentrations of contaminants in impacted sediments were between the Effects Range Low and Effects Range Median concentrations (Table C-4). The mean concentrations of chlordanes, copper, DDT, and mercury in sediment samples characterized as "un-impacted" exceeded the Effects Range Low value, suggesting some tolerance by biota. Biological impacts correlated more closely with high concentrations of mixtures of contaminants rather than individual contaminants, leading Thompson et al. (2012) to recommend using an indicator such as the mean Effects Range Median quotient as an indicator of sediment quality rather than basing an impacts assessment on the concentrations of individual contaminants in sediments. Based on USEPA guidelines for sediment chemistry using the mean Effects Range Median quotient, the sediment quality in San Diego Bay would be considered fair (i.e., mERMq is between 0.1 and 0.5) (U.S. Environmental Protection Agency, 2016).

Contaminant	Units	N	Mean Concentration of Un-impacted Samples (Score 1 to 2)	N	Mean Concentration of Impacted Samples (Score 3 to 5)	ERL	ERM
Cadmium	μg/g	72	0.209	89	0.342	1.2	9.6
Chlordane	ng/g	57	1.393	71	4.995	0.5	6
Copper	μg /g	72	77.302	89	153.159	34	270
DDTs	ng/g	57	2.362	72	7.302	1.58	46.1
НРАН	ng/g	72	407.126	89	1234.824	1,700	9,600
Lead	μg /g	72	30.528	89	62.71	46.8	218
LPAH	ng/g	72	99.0169	89	202.978	552	3,160
Mercury	μg /g	72	0.314	89	0.489	0.15	0.71
PCBs	ng/g	72	19.72	89	58.68	22.7	180
Zinc	μg /g	72	136.38	89	256.448	150	410
mERMq	ng/g	72	0.166	89	0.332	NA	NA

 Table C-4: Mean Concentration of Contaminants in San Diego Bay for Un-Impacted and

 Impacted Sediments with Comparison to Effects Ranges

Source: Thompson et al. (2012)

Notes: DDT = dichlorodiphenyltrichloroethane, HPAH = high molecular weight polycyclic aromatic hydrocarbons, LPAH = Low PAH, PCB = polychlorinated biphenyls, ERM = Effects Range Median, mERMq = mean ERM quotient, ERL = Effects Range Low, $\mu g / g$ = micrograms per gram, ng/g = nanograms per gram, N = Number of Samples, NA = Not Applicable

Wang et al. (2000; 2014b), use field measurements and a fate and transport model to estimate that docking Navy vessels in San Diego Bay resuspends approximately 26 tons of sediments per day. Wang et al. (2014a) measured sediment resuspension and associated metal contaminants from a tugboat propeller wash at Pier 4–5 in San Diego Bay; measurements included the concentrations of the metals chromium, copper, silver, cadmium, and nickel in the sediment plume. Only copper concentrations exceeded USEPA water quality criteria. However, all metal concentrations, with the exception of

cadmium, were increased above ambient levels following resuspension events. Transport of sediments and dissolved or particle-bound metals as a results of propeller wash can potentially result in recontamination of remediated areas as well as increased contaminant concentrations in areas far from piers where docking occurs (Wang et al., 2014a).

C.1.3.1.3 Marine Debris in Nearshore and Offshore Areas off the Hawaiian Islands

A comprehensive review of anthropogenic marine debris, particularly plastics, and their worldwide distribution highlights the growing concern over global environmental impacts and the need for continued scientific research and improved waste disposal management practices (Bergmann et al., 2015). Marine debris in the North Pacific Ocean has been well documented in numerous publications since the early 1970s when Venrick et al. (1973) estimated that there were approximately 4.2 pieces of debris/square kilometers (km²), most of which were made from plastic, northeast of Hawaii in an area now known as the "North Pacific Garbage Patch" (Bergmann et al., 2015; Venrick et al., 1973). Nearly 40 years later, Titmus and Hyrenback (2011) recorded a density of 459 pieces/km² in the same region with over 95 percent of the debris composed of plastic. Analysis of 11 years of data from plankton net tows in the eastern North and South Pacific have allowed researchers to better define the scale of plastic distribution and density (Law et al., 2014). The accumulation of plastic and other debris is largely driven by surface ocean circulation patterns. Large-scale ocean surface currents driven by winds and geostrophic circulation converge in the subtropical North Pacific and result in an accumulation zone for plastic (i.e., the Garbage Patch). The accumulation zone occurs between latitude 25 to 41°N and longitude 130 to 180°W, which is north and primarily east of the Hawaiian Islands (19° 43' N, 155° 05' W). The median concentration of plastics within the accumulation zone was 33,090 pieces/km²; outside of the zone the median concentration was 0 pieces/km². Plastic was collected on some tows outside of the zone. If considering only those tows and not the tows during which no plastic was collected, the median concentration outside of the zone was 1,485 pieces/km², approximately 22 times less than within the accumulation zone (Law et al., 2014). Nearly half of all net tows within the accumulation zone collected over 50,000 pieces/km², with the area of highest concentrations located between latitude 30 to 35°N and longitude 135 to 140°W, which is farther to the northeast from Hawaii.

Because of their buoyancy, many types of plastic float, and may be transported thousands of mi. in the ocean (U.S. Commission on Ocean Policy, 2004). Although plastics are highly resistant to degradation, plastics exposed to ultraviolet radiation from the sun gradually break down into smaller particles through a process called photo oxidation (Law et al., 2010). However, once plastic sinks below the photic zone, degradation rates become very slow, and once plastic reaches the seafloor degradation rates are further reduced. Microbial degradation of plastics in the marine environment does occur, but has a negligible impact on the amount of plastic that persists in the environment, because the process is slow and often occurs in low-oxygen environments on the seafloor (Andrady, 2015). Plastics can take hundreds of years to degrade and some plastics may never fully degrade and would persist in the environment indefinitely (Bergmuller et al., 2007).

The Hawaii Undersea Military Munitions Assessment documents various types of chemical, explosive, and non-explosive munitions and other military expended materials (MEM) located on the seafloor in a munitions disposal site south of Pearl Harbor, Oahu (Briggs et al., 2016; Koide et al., 2016).

In 2018 the Pacific Islands Fisheries Science Center evaluated the marine debris in the Northwestern Hawaiian Islands. In the greater Northern Pacific Grye it is estimated that approximately 52 tons of fishing gear is accumulated in the shallow waters. The greatest marine debris include derelict fishing gear, plastic, and other marine debris (Pacific Islands Fisheries Science Center, 2018).

Marine Debris in the Nearshore and Offshore Areas of the California Study Area C.1.3.1.4

The Southern California 2018 Regional Monitoring Program conducted a comprehensive regional assessment of trash and marine debris in streams and nearshore waters of the Southern California bight (McLaughlin et al., 2022). The study found that 75 percent of stream kilometers and 30 percent of offshore areas has trash present during sampling. Between 1994 and 2018, marine debris is estimated to have increased from 4 percent to 17 percent.

The study evaluated macro-marine debris (particles 5 mm or less in diameter) imbedded in seafloor sediments. The study analyzed 138 benthic trawl samples and found that one-third of the seafloor in the SOCAL contained anthropogenic macro-debris with plastics being the most widespread type of debris. The most common debris consisted of wrappers, paper/cardboard, plastic, bags, and foam. Changes in the amount of marine debris did not vary significantly from the 2013 report (Moore et al., 2016). However, there was a decrease in plastic bags in the marine environment, likely due California's ban of single use plastic bags in 2016.

Watters et al. (2010) conducted a visual survey of the seafloor that included a portion of the Navy's Southern California (SOCAL) Range Complex as part of a 15-year quantitative assessment of marine debris on the seafloor off the California coast. Watters et al. (2010) found that plastics were the most abundant material and, along with recreational monofilament fishing line, dominated the debris encountered on the seafloor. The visual survey of the seafloor by Watters et al. (2010) encountered only a single object that was potentially "military" in origin (it appeared to be a shell casing). Navy vessels have a zero-plastic discharge policy and return all plastic waste to appropriate disposal or recycling sites on shore.

In a study of marine debris along the U.S. West Coast, Keller et al. (2010) characterized the composition and abundance of man-made marine debris at 1,347 randomly selected stations during Groundfish Bottom Trawl Surveys that took place in 2007 and 2008. The sample sites included some locations within the California Study Area. A subset of the sites sampled included historically used post-World War II dump sites. Recovered items identifying the sites as post-World War II-era dump sites included equipment described as "helmets," "gas masks," "uniforms," and other miscellaneous and diverse items such as "plastic," "file cabinets," and "buckets." Since approximately the 1970s, items such as these are no longer disposed of at sea. The items listed here are not military expended material and would not be expended during training and testing activities in the Hawaii-California Training and Testing (HCTT) Study Area. For this reason, the characterization of "military debris" in Keller et al. (2010) has little if any relevance to the Proposed Action or to present-day standard Navy conduct that (among other procedures) restricts the discharge of plastic at sea.

Overall, fourteen ocean disposal sites were utilized in Southern California waters between 1930 and 1970. Disposal sites are in deep water and includes waste from drilling and military activities as well as other chemicals and garbage. Since 2021, the USEPA and collaborating agencies are currently developing plans to evaluate threats to the environment and human health. Ocean Disposal Site #2 is located halfway between Palos Verdes Peninsula and Santa Catalina Island at a depth of 3,200 ft. USEPA identified that water activities near the surface would likely not be impacted by the disposal site (U.S. Environmental Protection Agency, 2024).

C.1.3.1.5 **Climate Change and Sediment Quality**

Aspects of climate change that influence sediments include increasing ocean acidity (pH), increasing sea surface water temperatures, and increasing storm activity. Breitbarth et al. (2010) referred to seawater

temperature and pH as "master variables for chemical and biological processes," and noted that effects of changes on trace metal biogeochemistry "may be multifaceted and complex." Under more acidic conditions, metals tend to dissociate from particles to which they are bound in sediments, become more soluble, and potentially more available.

The effects of climate change over the next century will impact water and sediment quality within coastal protected areas within the study area in a variety of ways. Most notably will be the effects of sea level rise and increased tidal surges on natural resources and shore infrastructure, and a diminution of freshwater inputs (U.S. Department of the Navy, 2013d). However, more frequent or intense storms due to climate change can have effects on nearshore water due to freshwater input (De Carlo et al., 2007). Marginal bay habitats without protective buffers are most at risk, especially those that require special salinity conditions, intermittent inundation, or light penetration. Changes in water temperature affect mud temperature (Stillman & Paganini, 2015 (Stillman, 2015 #13757) and influence nutrient processing.

As noted in the beginning of this section, tropical storms can have significant impacts on the resuspension and distribution of bottom sediment (Wren & Leonard, 2005). However, no consensus appears to exist on whether climate change will generate more tropical storms or whether those storms will be more intense. If storm frequency and intensity increase, the additional disturbance of sediment may impact water quality in nearshore and coastal areas.

C.1.3.2 Water Quality

C.1.3.2.1 Water Quality in the Nearshore and Offshore Waters of the Hawaiian Islands

Pearl Harbor is on Hawaii's CWA Section 303(d) list of impaired waters. The Pearl Harbor Water Quality Limited Segment includes the entire harbor and the mouths of perennial streams discharging into the harbor. Beneficial uses of Pearl Harbor include bait fish and shellfish propagation in West and East Lochs, shipping navigation and industrial water in East Loch, and water fowl habitat in Middle and West Lochs (Hawaii State Department of Health, 2000).

Contaminants are introduced into Pearl Harbor via point source and non-point source discharges. Surface runoff from urban, industrial, and agricultural activities carries variable levels of herbicides, pesticides, and other contaminants, in addition to natural loads of sediment, dissolved metals, and other soluble constituents (Agency for Toxic Substances and Disease Registry, 2005). Water quality criteria that are frequently violated in Pearl Harbor include maximum nitrogen, phosphorous, fecal coliform, and chlorophyll-*a* concentrations, and turbidity and temperature limits (Hawaii State Department of Health, 2000). The Hawaii State Department of Health assessment of water quality in 160 marine water bodies included an evaluation of water quality in Pearl Harbor (State of Hawaii Department of Health, 2014). Waters in Pearl Harbor were in non-attainment for total phosphorous, total nitrogen, and chlorophyll-*a*, but were in attainment for turbidity. The presence of contaminants including PCBs, pesticides, and lead continue to restrict the consumption of fish and shellfish caught in Pearl Harbor. Table C-5 provide the water quality criteria and an associated index for the U.S. West Coast and the Hawaiian Islands, respectively.

Critorion		Site Criteria		Regional Criteria			
cincerioii	Good	Fair	Poor	Good	Fair	Poor	
Dissolved Inorganic Nitrogen	< 0.5 mg/L	0.5–1.0 mg/L	> 1.0 mg/L				
Dissolved Inorganic Phosphorus	< 0.01 mg/L	0.01–0.1 mg/L	> 0.1 mg/L				
Water Clarity	Sites with naturally high turbidity: > 10% light at 1 meter Sites with normal turbidity: > 20% light at 1 meter Sites that support submerged aquatic vegetation: > 40% light at 1 meter	Sites with naturally high turbidity: 5–10% light at 1 meter Sites with normal turbidity: 10–20% light at 1 meter Sites that support submerged aquatic vegetation: 20–40% light at 1 meter	Sites with naturally high turbidity: < 5% light at 1 meter Sites with normal turbidity: < 10% light at 1 meter Sites that support submerged aquatic vegetation: < 20% light at 1 meter	Less than 10% of the coastal area is in poor condition, and more than 50% of the coastal area is in good condition.	10–25% of the coastal area is in poor condition, or more than 50% of the coastal area is in combined poor and fair condition.	More than 25% of the coastal area is in poor condition.	
Dissolved Oxygen	> 5.0 mg/L	2.0–5.0 mg/L	< 2.0 mg/L	Less than 5% of the coastal area is in poor condition and more than 50% of the coastal area is in good condition.	5–15% of the coastal area is in poor condition, or more than 50% of the coastal area is in combined poor and fair condition.	More than 15% of the coastal area is in poor condition.	
Chlorophy Il-a	< 5 μg/L	5–20 μg/L	> 20 μg/L	Less than 10%	10–20% of the coastal area is in		
Water Quality Index	A maximum of one indicator is rated fair, and no indicators are rated poor.	One of the indicators is rated poor, or two or more indicators are rated fair.	Two or more of the five indicators are rated poor.	area is in poor condition, and more than 50% of the coastal area is in good condition.	poor condition, or more than 50% of the coastal area is in combined poor and fair condition.	More than 20% of the coastal area is in poor condition.	

Table C-5: Water Quality Criteria and Index, United States West Coast

Source: U.S. Environmental Protection Agency (2009)

Notes: < = less than, > = greater than, mg/L = milligram per liter, μ g/L = microgram per liter

Critorion		Site Criteria		Regional Criteria		
Citterion	Good	Fair	Poor	Good	Fair	Poor
Dissolved Inorganic Nitrogen	< 0.05 mg/L	0.05–0.1 mg/L	> 0.1 mg/L			
Dissolved Inorganic Phosphorus	< 0.005 mg/L	0.005– 0.01 mg/L	> 0.01 mg/L			
Water Clarity	Sites with naturally high turbidity: > 10% light at 1 meter Sites with normal turbidity: > 20% light at 1 meter Sites that support submerged aquatic vegetation: > 40% light at 1 meter	Sites with naturally high turbidity: 5–10% light at 1 meter Sites with normal turbidity: 10–20% light at 1 meter Sites that support submerged aquatic vegetation: 20–40% light at 1 meter	Sites with naturally high turbidity: < 5% light at 1 meter Sites with normal turbidity: < 10% light at 1 meter Sites that support submerged aquatic vegetation: < 20% light at 1 meter	Less than 10% of the coastal area is in poor condition, and more than 50% of the coastal area is in good condition.	10–25% of the coastal area is in poor condition, or more than 50% of the coastal area is in combined poor and fair condition.	More than 25% of the coastal area is in poor condition.
Dissolved Oxygen	> 5.0 mg/L	2.0–5.0 mg/L	< 2.0 mg/L	Less than 5% of the coastal area is in poor condition and more than 50% of the coastal area is in good condition.	5%-15% of the coastal area is in poor condition, or more than 50% of the coastal area is in combined poor and fair condition.	More than 15% of the coastal area is in poor condition.
Chlorophyll-a	< 0.5 µg/L	0.5–1.0 μg/L	> 1.0 µg/L	Less than 10%	10%-20% of the	
Water Quality Index	A maximum of one indicator is rated fair, and no indicators are rated poor.	One of the indicators is rated poor, or two or more indicators are rated fair.	Two or more of the five indicators are rated poor.	of the coastal area is in poor condition, and more than 50% of the coastal area is in good condition.	coastal area is in poor condition, or more than 50% of the coastal area is in combined poor and fair condition.	More than 20% of the coastal area is in poor condition.

Table C-6: Water Quality Criteria and Index, Hawaiian Islands

Source: U.S. Environmental Protection Agency (2009)

Notes: < = less than, > = greater than, mg/L= milligram per liter, μ g/L = microgram per liter

C.1.3.2.2 Water Quality in the Nearshore and Offshore Waters of the California Study Area

Water quality in the nearshore waters of SCI, which are affected by baseline at-sea and ashore training and testing activities, has been tested (U.S. Department of the Navy, 2006a), and was reassessed for the 2010 SCI Range Condition Assessment (U.S. Department of the Navy, 2010b). Surface water and nearshore sediments just beyond the surf zone were sampled for metals, cyanide, chlorine, ammonia, phenols, pesticides, gross alpha/beta, perchlorate, and dioxin. Both acute and chronic toxicity tests were conducted with test organisms that included algae (kelp), an invertebrate (mussel), and a fish (topsmelt larvae). Two sample locations were in close proximity to the island's land-based shore bombardment area located on the southern end of the island. Samples from these two locations would be the most likely to show signs of munitions constituents entering the marine environment. Results indicated that most chemicals were not detected in receiving water and sediment samples, and in the cases where chemicals were detected and criteria were available, results fell well below all chemistry-related numerical objectives. The assessment concluded that only traces of the explosive compound HMX were detected in surface water—no other munitions constituents were detected, and HMX was detected only in a duplicate sample at five orders of magnitude below the threshold requiring that some level of action be taken. Therefore, although it appears that some munitions constituents may be migrating into the Pacific Ocean, they are doing so at concentrations well below levels of concern and well below concentrations that would be detectable in ocean water. Furthermore, no statistically significant toxicity was observed in topsmelt, giant kelp, or bivalve bioassays. These data suggest that Navy discharges from SCI do not compromise protection of ocean waters for beneficial uses around SCI.

Based on *California Ocean Plan* objectives for protection of aquatic life, concentrations of potential water pollutants are low, and have no substantial effects on marine water quality in a portion of the SOCAL Study Area where training and testing activities are most concentrated (U.S. Department of the Navy, 2013a).

Major contaminants found in San Diego Bay include chlorinated hydrocarbons, PCBs, toxic components of petroleum hydrocarbons, polycyclic aromatic hydrocarbons, heavy metals, and organotins such as tributyltin (U.S. Department of the Navy, 2013d). The sources of these compounds include effluents from non-point-source storm drain runoff (municipal and industrial); contaminants from vessel maintenance; antifouling paints (military, commercial, and private vessels); marina discharges; and residues of prior industrial discharges. These contaminants have generally been incorporated into bottom sediments in the bay, and are periodically re-suspended in the water column when bottom sediments are disturbed by natural or human activities.

Water quality in north and central San Diego Bay is affected primarily by tidal flushing and currents. Water quality also is influenced locally by freshwater inflows. The watershed that contributes to San Diego Bay has a number of Total Maximum Daily Loads established for Chollas Creek and Shelter Island for criteria such as diazinon, dissolved metals, and indicator bacteria (U.S. Department of the Navy, 2013d). Gross water quality characteristics (e.g., salinity, temperature, and DO) form a gradient within San Diego Bay. Waters in northern San Diego Bay are similar to ocean conditions; waters in southern San Diego Bay are strongly affected by shallow depths, fresh water inflows, and solar insolation; waters in central San Diego Bay are intermediate in character.

Beach closures for Silver Strand Shoreline and Coronado are common from frequent water quality monitoring and high levels of harmful bacteria. Since December 8, 2021, the Tijuana Slough Shoreline has been closed due bacterial levels that exceed health standards.

C.1.3.2.3 Marine Debris and Water Quality

The National Marine Debris Monitoring Program developed three categories of marine debris for its study of the extent of man-made materials in the oceans: land-based, ocean-based, and general (i.e., origin unspecified) (Sheavly, 2007). Land-based debris may blow in on the wind, be washed in with storm water, arise from recreational use of coastal areas, and be generated by extreme weather such as tsunamis. Ocean-based sources of marine debris include commercial shipping and fishing, private boating, offshore mining and extraction, and legal and illegal dumping at sea. Ocean current patterns, weather and tides, and proximity to urban centers, industrial and recreational areas, shipping lanes, and fishing grounds influence the types and amount of debris found (U.S. Environmental Protection Agency, 2010). These materials are concentrated at the near-surface and in the water column.

According to the U.S. Environmental Protection Agency (2010), land-based sources account for about half of marine debris, and ocean/waterway-based sources contribute another 18 percent. Bergmuller et al. (2007) confirm that the majority of marine debris originates from land. Land-based debris included items like syringes, condoms, metal beverage cans, motor oil containers, balloons, six-pack rings, straws, tampon applicators, and cotton swabs. Ocean-based debris included gloves, plastic sheets, light bulbs and tubes, oil and gas containers, pipe-thread protectors, nets, traps and pots, fishing line, light sticks, rope, salt bags, fish baskets, cruise line logo items, and floats and buoys. Plastics, generally referring to petroleum-based, manmade materials, make up the vast majority of marine debris (Bergmuller et al., 2007; Law & Thompson, 2014).

Within the HCTT Study Area, Currie et al. (2017b) conducted surveys for marine mammals and floating marine debris in the waters around the island of Lanai and waters between Lanai and the islands of Maui and Kahoolawe from April 2013 to April 2016. The survey encountered, collected, and categorized 1,027 pieces of marine debris. Items categorized as "plastic" were the predominant type of debris encountered and accounted for 86 percent of total debris. Plastics consisted mainly of plastic bottles, tubs, baskets, foamed polystyrene disposable plates, cups, fragments, plastic bags, and other soft plastic films. A smaller portion of the plastic (13 percent; 11 percent of the total amount of material) were fishing-related and included items such as buoys, netting, rope, and fishing lines. Milled lumber and rubber accounted for 10 percent of total debris, and the remaining 4 percent consisted of metal, glass, and clothing/fabric.

Microscopic plastic fragments enter the marine environment from use as scrubbers in hand cleaning and other cosmetic products, abrasive beads for cleaning ships, and deterioration of macroscopic plastics (Teuten et al., 2007). Microplastic beads commonly used in cosmetic products such as facial scrubs and other exfoliants are not broken down in wastewater treatment facilities and are largely not filtered out of the waste stream before they are flushed into the marine environment (Chang, 2015; Napper et al., 2015). These microbeads are found worldwide in marine sediments, persist in the marine environment, and accumulate up the food chain (Cole & Galloway, 2015). On December 18, 2015, the *Microbead-Free Waters Act of 2015* (21 U.S.C 301) was passed prohibiting the manufacturing, packing, and distribution of rinse-off cosmetics containing plastic microbeads.

Plastics may serve as vehicles for transport of various pollutants, whether by binding them from seawater or from the constituents of the plastics themselves. Mato et al. (2001) noted that polypropylene resin pellets (precursors to certain manufactured plastics) collected from sites in Japan contained PCBs, dichlorodiphenyldichloroethylene (a breakdown product of DDT), and the persistent organic pollutant nonylphenol (a precursor to certain detergents). PCBs and DDT were adsorbed from seawater and accumulated on the surface of plastics. The original source of nonylphenol was less clear;

it may have originated from the pellets themselves or may have been adsorbed from the seawater. Microbeads have also been shown to adsorb hydrophobic chemical contaminants, such as DDT, from seawater, allowing for the accumulation and transport of these often toxic chemicals to widely dispersed areas of the oceans. While the impacts on the marine ecosystem are largely unknown, some examples illustrating potential widespread impacts have been discussed. For example, it has been suggested that white and blue microplastic beads, common in many exfoliants, resemble plankton and may be mistakenly ingested by plankton-feeding fishes, which rely on visual cues to find prey (Napper et al., 2015; Wright et al., 2013). The long-term effects on the environment from the proliferation of microbeads and other micro plastics are still being researched. Since there is no way of effectively removing micro plastics from the marine environment, and given that plastics are highly resistant to degradation, it is likely that the quantity of micro plastics in the marine environment will only continue to increase, and therefore the likelihood of environmental impacts can only increase (Napper et al., 2015). The only way to reduce long-term impacts is to reduce or eliminate the use of micro plastics, a course of action that is gaining recognition (Chang, 2015).

Because of their buoyancy, many types of plastic items float and may travel thousands of miles in the ocean (U.S. Commission on Ocean Policy, 2004). Exceptions include heavy nets and ropes. Although plastics are resistant to degradation, they do gradually break down into smaller particles due to sunlight and mechanical wear (Law et al., 2010). A study by Teuten et al. (2007) indicated that the water-borne phenanthrene (a type of polycyclic aromatic hydrocarbon) adhered preferentially to small pieces of plastic ingested by a bottom-dwelling marine lugworm and incorporated into its tissue. Marine microbes and fungi are known to degrade biologically produced polyesters, such as polyhydroxyalkanoates, a bacterial carbon and energy source (Doi et al., 1992). Marine microbes also degrade other synthetic polymers, although at slower rates (Shah et al., 2008).

Annex V of the International Convention for the Prevention of Pollution from Ships prohibits the discharge of plastic waste from vessels at sea, and the U.S. Act to Prevent Pollution from Ships brought U.S. public vessels in alignment with the international convention. The NDAA of 1996 specifically directed the Navy to install plastic waste processors aboard the surface fleet. The Navy's plastics waste processors compress and melt shipboard-generated plastic waste into dense, sanitary disks of compressed plastics that can be stored over long at-sea deployments. The plastic wastes items include lightly contaminated food containers as well as clean plastics and other materials that may be combined with, or contain, plastic components that cannot be processed in the normal solid waste stream. The plastic waste disks are offloaded for proper disposal once a ship comes into port. The plastic compression technology enables Navy ships to operate at sea over long time periods without discharging plastics into the oceans.

C.1.3.2.4 Climate Change and Water Quality

According to the U.S. Global Change Research Program, the rise in ocean temperature over the last century will continue into the reasonably foreseeable future, with continued and perhaps increasing impacts on ocean circulation, marine chemistry, and marine ecosystems. Because the ocean currently absorbs about a quarter of human-produced CO₂ emissions, increasing CO₂ absorption will increase acidification of ocean waters. This in turn will alter the distribution, abundance, and productivity of many marine species (Melillo et al., 2014).

Key findings of the 2014 National Climate Assessment that may pertain to waters surrounding the Hawaiian Islands include:

- Warmer oceans are leading to increased coral bleaching events and disease outbreaks in coral reefs, as well as changed distribution patterns of tuna fisheries. Ocean acidification will reduce coral growth and health. Warming and acidification, combined with existing stresses, will strongly affect coral reef fish communities.
- Saltwater intrusion associated with sea level rise will reduce the quantity and quality of freshwater in coastal aquifers, especially on low islands.
- Rising sea levels, coupled with high water levels caused by storms, will incrementally increase coastal flooding and erosion, damaging coastal ecosystems, infrastructure, and agriculture, and indirectly affecting tourism.

Key findings of the 2014 National Climate Assessment that may pertain to waters off California include:

- With the decreases in snowpack and streamflow expected to continually decline, freshwater inputs into California's coastal estuaries will decrease, with subsequent losses of ecosystem services that estuaries provide (e.g., nutrient cycling, filtration).
- Sea level rise is projected to increase, resulting in major damage as wind-driven waves ride upon higher seas and reach farther inland.

The Paris Agreement builds upon the Convention and – for the first time – brings all nations into a common cause to undertake ambitious efforts to combat climate change and adapt to its effects, with enhanced support to assist developing countries to do so. As such, it charts a new course in the global climate effort.

At the 2015 Paris Climate Conference, 195 parties to the United Nations Framework Convention on Climate Change adopted the first-ever universal, global climate agreement, referred to as the Paris Agreement in which all countries voluntarily set and committed to individual carbon reduction goals. The Agreement marks the latest step in the evolution of the United Nations climate change initiative and builds on the work undertaken under the Convention over the past several decades.

The Paris Agreement seeks to accelerate and intensify the actions and investment needed for sustaining low carbon emissions into the future. Its central aim is to strengthen the global response to the threat of climate change and greenhouse gas emissions by limiting a global temperature rise over this century to no more than 2 degrees Celsius (°C)above pre-industrial levels. The Paris Agreement also includes a commitment to pursue efforts to limit the temperature increase even further to 1.5 °C.

The U.S. signed the Paris Agreement on April 22, 2016, and on September 3, 2016, the U.S. accepted ratification of the Agreement. The U.S. withdrew from the Paris Agreement in 2020 but reentered under the Biden Administration in January of 2021.

C.2 Vegetation

C.2.1 General Background

C.2.1.1 Taxonomic Overview

Vegetation includes diverse taxonomic/ecological groups of marine algae throughout the Study Area, as well as flowering plants in the coastal and inland waters. Vegetation can be divided into eight groups that encompass taxonomic categories, distributions, and ecological relationships. These groups include blue-green algae (phylum Cyanobacteria), dinoflagellates (phylum Dinophyta), green algae (phylum Chlorophyta), coccolithophores (phylum Haptophyta), diatoms (phylum Ochrephyta), brown algae

(phylum Phaeophyta), red algae (phylum Rhodophyta), and vascular plants (phylums Tracheophyta and Spermatophyte). Furthermore, the analysis considers the distribution of vegetation based on oceanic features and vertical distribution. Open-ocean oceanographic features of the Study Area include the North Pacific Subtropical Gyre and the North Pacific Transition Zone. Additionally, vertical distribution within the water column or the bottom substrate is considered.

C.2.1.2 General Threats

Human-made stressors that act on marine vegetation include excessive nutrient input (such as fertilizers), siltation (the addition of fine particles to the ocean), pollution (oil, sewage, trash) (Mearns et al., 2011), climate change (Arnold et al., 2012; Doney et al., 2012; Martinez et al., 2012; Olsen et al., 2012), fishing practices (Mitsch et al., 2009b; Steneck et al., 2002), shading from structures (National Marine Fisheries Service, 2002), harvesting (Wilson, 2002), habitat degradation from construction and dredging, and introduced or invasive species (Hemminga & Duarte, 2000; Spalding et al., 2003). The seagrass, cordgrass, and mangrove taxonomic group is often more sensitive to stressors than the algal taxonomic groups. The great diversity of algae makes generalization difficult, but overall, algae are resilient and colonize disturbed environments created by stressors (Levinton, 2009b).

Marine algae and vascular plants are important ecologically and economically, providing an important source of food, essential ecosystem services (e.g., coastal protection, nutrient recycling, food for other animals, and habitat formation), and income from tourism and commercial fisheries (Spalding et al., 2001).

C.2.1.2.1 Development and Human Activities

Green seaweed is harvested for human consumption in Hawaii's coastal waters. Common species harvested include *Ulva fasciata, Enteromorpha prolifera,* and *Codium edule* (Preskitt, 2002a, 2010). Edible brown seaweeds that are collected in Hawaii include *Sargassum echinocarpum* and *Dictyopteris plagiograma* (Preskitt, 2002b). The State of Hawaii Department of Land and Natural Resources regulates the collection of seaweeds.

Although historically important, large-scale harvesting of kelp beds no longer occurs along the California coast. Small-scale commercial operations, however, continue to harvest kelp, primarily for abalone feed (Wilson, 2002). The California Department of Fish and Game, which issues exclusive leases to harvest designated beds for up to 20 years, manages kelp harvesting. Although they are not limited in the amount, California regulations prohibit commercial harvesters from cutting attached *Macrocystis pyrifera* and *Nereocystis luetkeana* (giant and bull) kelp from deeper than 4 ft. (1.2 m) below the water's surface (14 California Code of Regulations 165[c][2]), which protects the reproductive structures at the kelp's base and allows vegetative re-growth (Wilson, 2002).

C.2.1.2.2 Water Quality Degradation

Water quality in the Study Area may be impacted by the introduction of harmful contaminants from diverse sources unrelated to either action alternative. Common ocean pollutants include toxic compounds such as metals, pesticides, herbicides, and other organic chemicals, excess nutrients from fertilizers and sewage, detergents, oil, plastics, and other solids. Coastal pollution and agricultural runoff may cause toxic red tide events in the Study Area (Hayes et al., 2007). Coastal development and pollution, particularly storm water runoff and point source discharges, affect water quality of bays and coastal areas throughout the world. Depending on the proximity to and nature of the discharge, sediment and water quality may be degraded, which in turn can impact marine vegetation communities.

Erosion and sedimentation may also affect sediment and water quality of coastal areas during storm runoff from urban streets into rivers and streams.

Oil in runoff from land-based sources, natural seeps, and accidental spills (such as offshore drilling and oil tanker leaks) are some of the major sources of oil pollution in the marine environment (Levinton, 2009b). The type and amount of oil spilled, weather conditions, season, location, oceanographic conditions, and the method used to remove the oil (containment or chemical dispersants) are some of the factors that determine the severity of the impacts. Sensitivity to oil varies among species and within species (Hayes et al., 1992). The tolerance to oil pollutants varies among the types of marine vegetation, but their exposure to sources of oil pollutants makes them all vulnerable.

Oil pollution, as well as chemical dispersants used in response to oil spills, can impact seagrasses directly by smothering the individuals, or indirectly by lowering their ability to combat disease and other stressors (U.S. National Response Team, 2010). Seagrasses that are totally submerged are less susceptible to oil spills since they largely escape direct contact with the pollutant. Depending on various factors, oil spills can result in a range of effects from no impact to long-lasting impacts, such as decreases in eelgrass density (Kenworthy et al., 1993; Peterson, 2001). Algae are relatively resilient to oil spills, while mangroves are highly sensitive to oil exposure. Contact with oil can cause death, leaf loss, and failure to germinate (Hoff et al., 2002). Salt marshes can also be severely impacted by oil spills, with long-term effects (Culbertson et al., 2008).

C.2.1.2.3 Climate Change

The impacts of anthropogenically induced climate change on the marine environments include rising sea levels, ocean acidification, increased sea temperature, and an increase in severe weather events. All of these changes may have impacts on vegetation in the Study Area.

Rising sea levels will alter the amount of sunlight reaching various areas, which may decrease the photosynthetic capabilities of vegetation in those areas. However, the fast growth and resilient nature of vegetation may enable most species to adapt to these changes (Harley et al., 2006). Increased sea temperature may lead to several impacts that could affect vegetation. Warmer waters may lead to a greater stratification in the water column, which may support harmful algal blooms (Lehmköster, 2015). The stratification may also inhibit upwelling, as seen during El Niño events, which would prevent nutrients from circulating to the surface (Lehmköster, 2015). Additionally, increased sea temperatures may lead to changes in the composition of vegetation communities (Schiel et al., 2004). These changes in community composition could impact biological interactions, including the mutualism between reefbuilding corals and algae (Doney et al., 2012). These indirect and direct impacts of climate change that decrease coral reef habitat may enable vegetation to overtake areas that were previously biogenic reef habitat (Hughes et al., 2007; Pandolfi et al., 2005). Increases in severe weather events may lead to increased erosion and sedimentation in the marine environments and higher energy wave action that could increase impacts on vegetation by physical disturbance, such as marine vascular plants becoming unrooted.

Vegetation is susceptible to water quality changes from erosion and disturbances from storm events. Increased storm events are expected to impact species diversity in kelp ecosystems (Byrnes et al., 2011). The impacts of ocean acidification on vegetation are poorly understood (Harley et al., 2006). Ocean acidification may impact the ecological function of coralline algae by decreasing habitat-forming capabilities (Ragazzola et al., 2016).

C.2.1.2.4 Diseases and Parasites

Marine algae and vascular plants may be susceptible to disease caused by other marine organisms, which may impact individuals or populations. In particular, eelgrass is vulnerable to a wasting disease caused by a marine pathogen that has caused devastating population loss in the past (Ralph & Short, 2002). Certain species of microscopic algae (e.g., dinoflagellates and diatoms) can form algal blooms, which can pose serious threats to human health and wildlife species. Harmful algal blooms can deplete oxygen within the water column and block sunlight that other organisms need to live, and some algae within algal blooms release toxins that are dangerous to human and ecological health (Center for Disease Control and Prevention, 2004). These algal blooms have a negative economic impact of hundreds of millions of dollars annually worldwide (National Centers for Coastal Ocean Science, 2010). Additional information on harmful algal blooms can be accessed on the Centers for Disease Control and Atmospheric Administration (NOAA) websites.

C.2.1.2.5 Invasive Species

Invasive vegetation species are present throughout the Study Area. The red mangrove (*Rhizophora mangle*) is an invasive species in Hawaii and various resource agencies and organizations (e.g., Hawaii Department of Land and Natural Resources, Pacific Cooperative Studies Unit, Malama O Puna) have eradication programs targeting the red mangrove and other mangrove infestations (Figure C-2). First introduced primarily to stabilize coastal flats in the early 1900s (Allen, 1998), the red mangrove is native to Florida and the Caribbean. Since the introduction of this species, mangroves have invaded intertidal areas formerly devoid of trees. In 2013 and 2014, the Navy completed several mangrove removal actions in Pearl Harbor (Figure C-2), which enhanced native sedge growth among other environmental benefits (U.S. Department of the Navy, 2014).

Invasive marine green algal species are found in coastal waters of the Study Area. The invasive green algae, *Avrainvillea amadelpha*, has been recorded in the main Hawaiian Islands (Preskitt, 2010). Invasive green algae represent a serious threat to coral reefs, and may displace, outcompete, or hybridize with non-invasive native green algae species, resulting in the loss of native biodiversity or alteration of ecosystem processes. Representative non-native invasive species of red algae in the Hawaii Study Area include *Acanthophora spicifera*, *Gracilaria salicornia*, *Hypnea musciformis*, *Kappaphycus alvarezii*, and *Gracilaria tikvahiae* (Smith et al., 2002).

Caulerpa taxifolia and *Codium fragile tomentosoide* are invasive green algal species found in the California Study Area (Dobroski et al., 2015; Gagnon et al., 2015). In addition, *Sargassum muticum* (Japanese wireweed) and *Sargassum horneri* (devil weed) are invasive brown algal species found within the California Study Area (Dobroski et al., 2015; Marks et al., 2015). *Undaria pinnatifida* (or wakame), which is an edible seaweed native to Japan, is an invasive species that is also found along the California coast (Dobroski et al., 2015; Global Invasive Species Database, 2005). Devil weed and wakame are found in San Diego County and have exhibited characteristics of successful invaders such as establishing in new areas, spreading locally, and persisting through multiple generations. They primarily occur in harbors but have also been found in open coast sites. This rapid and uncontrolled spread has ecological and economic consequences that will require further research (Kaplanis et al., 2016).



Figure C-2: Areas Subject to Mangrove Removal in Pearl Harbor

The DoD has implemented projects to control invasive microalgae at critical control points (specific areas where spread and transport of invasive species are likely to occur). For example, in 2011, an experimental macroalgae cleanup occurred in an infested area of Mokapu Peninsula, at the sea plane ramps. Lessons learned from this experiment were discussed with Sikes Act partners and provided the basis for tackling more ambitious projects in the future. A slow and steady phased approach is often the most successful in making progress with controlling invasive species, based on the experiences of the Marine Corps Base at Mokapu Peninsula (Marine Corps Base Hawaii, 2011).

C.2.1.2.6 Marine Debris

Marine debris (especially plastics) is a threat to many marine ecosystems, particularly in coastal waters adjacent to urban development. Microplastics (generally considered to be particles less than 5 mm in size), which may consist of degraded fragments of larger plastic items or intentionally manufactured items (e.g., microbeads), are of concern because of their durability, long lifespan, and potential to enter marine food webs (Setala et al., 2016). Marine debris may injure marine vegetation if it is large and is pulled around by tidal influences and currents (Gregory, 2009). Refer to Section C.1.3.1.3 (Marine Debris in the Nearshore and Offshore Areas off the Hawaiian Islands) and Section C.1.3.1.4 (Marine Debris in the Nearshore and Offshore Areas of the California Study Area) for a more detailed discussion of marine debris and the associated effects on water quality.

C.2.2 Species Not Listed under the Endangered Species Act

For the following discussion, vegetation has been divided into eight major phyla that have distinct morphological, biochemical, physiological, and life history traits that reflect their evolutionary history and influence their distributions and ecological relationships.

C.2.2.1 Blue-Green Algae (Phylum Cyanobacteria)

Blue-green algae are single-celled, photosynthetic bacteria that inhabit the photic zone and seafloors of the world's oceans (Roskov et al., 2015). Blue-green algae are key primary producers in the marine environment and provide valuable ecosystem services such as producing oxygen and nitrogen. The blue-green algae, *Prochlorococcus* species, is responsible for a large portion of the global oxygen production by photosynthetic organisms. Other species of blue-green algae have specialized cells that convert nitrogen gas into a form that can be used by other marine plants and animals (nitrogen fixation) (Hayes et al., 2007). In the nutrient-poor waters of coral reef ecosystems within the Hawaii Study Area, blue-green algae are an important source of food for marine species. Diverse grazers, particularly large grazers such as sea urchin and fish, as well as mesoherbivores (e.g., small fish and crabs) and microherbivores (e.g., amphipods, gastropods, and polychaetes) are known to feed on blue-green algae and may influence algal community structures. Physical and biological disturbances to algae may, ultimately, shift the algal community structure to more disturbance-tolerant forms of algae (e.g., turfs and crusts) (Cheroske et al., 2000).

C.2.2.2 Dinoflagellates (Phylum Dinophyta)

Dinoflagellates are single-celled organisms with two flagella (whip-like structures used for locomotion) in the phylum Dinophyta (Roskov et al., 2015). Dinoflagellates are predominantly marine algae, with an estimated 1,200 species living in surface waters of the ocean worldwide (Castro & Huber, 2007). Most dinoflagellates can use the sun's energy to produce food through photosynthesis and can ingest small food particles. Photosynthetic dinoflagellates are important primary producers in coastal waters (Waggoner & Speer, 1998). Organisms such as zooplankton (microscopic animals that drift passively in the water column) feed on dinoflagellates.

Dinoflagellates are also valuable for their close relationship with some invertebrates, most notably reef-building corals. Some species of dinoflagellates (zooxanthellae) live inside corals. This mutually beneficial relationship provides shelter and food (in the form of coral waste products) for the dinoflagellates; in turn, the corals receive essential nutrients produced by dinoflagellates (Spalding et al., 2007). Dinoflagellates cause some types of harmful algal blooms, which result from sudden increases in nutrients (e.g., fertilizers) from land into the ocean or changes in temperature and sunlight (Levinton, 2009b).

C.2.2.3 Green Algae (Phylum Chlorophyta)

Green algae are single-celled organisms in the phylum Chlorophyta that may form large colonies of individual cells (Roskov et al., 2015). Green algae may be found in the water column and benthic habitats. Only 10 percent of the estimated 7,000 species of green algae are found living in the marine environment (Castro & Huber, 2000c). These species are important primary producers that play a key role at the base of the marine food web. Green algae are found in areas with a wide range of salinity, such as bays and estuaries, and are eaten by various organisms, including zooplankton and snails.

C.2.2.4 Coccolithophores (Phylum Haptophyta)

Coccolithophores are single-celled phytoplankton that are especially abundant in tropical oceans but also bloom seasonally at higher latitudes. Up to 200 species have been described in the scientific record, 30–40 of which are common in the sedimentary record (Giraudeau & Beaufort, 2007). Coccolithophores are found in the water column as free-floating phytoplankton. They are nearly spherical and covered with plates made of calcite (calcium carbonate), which account for approximately one-third of calcium carbonate production in the entire ocean. They are an often-abundant component of the phytoplankton and account for a large fraction of primary production and carbon sequestration in the ocean. Blooms produce a strong bluish-white reflection that may cover thousands of square miles (Levinton, 2013).

C.2.2.5 Diatoms (Phylum Ochrophyta)

Diatoms are single-celled organisms with cell walls made of silicon dioxide. Two major groups of diatoms are generally recognized, centric diatoms and pinnate diatoms. Centric diatoms exhibit radial symmetry (symmetry about a point), while the pinnate diatoms are bilaterally symmetrical (symmetry about a line). Diatoms are found in the water column and benthic habitats in coastal areas. Diatoms such as *Coscinodiscus* species commonly occur throughout the Study Area. Some strains of another genus of diatoms, Pseudonitzschia, produce a toxic compound called domoic acid. Humans, marine mammals, and seabirds become sick or die when they eat organisms that feed on Pseudonitzschia strains that produce the toxic compound. The California Study Area, off the coasts of Los Angeles and Orange Counties, had some of the highest concentrations of the toxic compound ever recorded in U.S. waters (Schnetzer et al., 2007). *Pseudo-nitzschia* blooms in the Southern California Bight during 2003 and 2004 were linked to stranding over 1,400 marine mammals (Schnetzer et al., 2007). Pollutants carried from land to the ocean by rainwater (Kudela & Cochlan, 2000), and decreases in the movement of cool, nutrient-rich waters by the wind are believed to be the main causes of these harmful algal blooms in the California Study Area (Kudela et al., 2004).

C.2.2.6 Brown Algae (Phylum Phaeophyta)

Brown and golden-brown algae are large multi-celled marine species with structures varying from fine filaments to thick leathery forms (Castro & Huber, 2000c). Most species are attached to the seafloor in coastal waters (such as kelp), although a species with both attached and free-floating forms (*Sargassum muticum* [invasive]) occurs within the California Study Area.

C.2.2.6.1 Kelp

Kelp is a general term that refers to brown algae of the order Laminariales. Kelp plants are made of three parts: the leaf-like blade(s), the stipe (a stem-like structure), and the holdfast (a root-like structure that anchors the plant to the bottom). The following five species of canopy-forming kelp occur in the coastal waters of the California coast: giant kelp, bull kelp, elk horn kelp (*Pelagophycus porra*), feather boa kelp (*Egregia menziesii*), and chain bladder kelp (*Stephanocystis osmundacea*). The dominant kelp in the California Study Area is giant kelp. Since the first statewide survey in 1967, the total area of kelp canopies has generally declined; the greatest decline occurred along the mainland coast of southern California (Wilson, 2002; Young et al., 2016b). The canopy coverage of kelp beds varies under changing oceanographic conditions, and is also influenced by the level of harvesting, invasive species, coastal pollution, and development (Wilson, 2002).

Kelp is the most conspicuous brown algae occurring extensively along the coast in the California Study Area. The giant kelp can live up to eight years and can reach lengths of 197 ft. (60 m). The leaf-like fronds can grow up to 23.6 inches (in.) (60 centimeters [cm]) per day (Leet et al., 2001). Bull kelp

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(*Nereocystis luetkeana*) growth can exceed 3.9 in. (10 cm) per day. Bull kelp attaches to rocky substrates and can grow up to 164 ft. (50 m) in length in nearshore areas. In turbid waters, the offshore edge of kelp beds occurs at depths of 49–59 ft. (15–18 m), which can extend to a depth of 98.4 ft. (30 m) in the clear waters around the Channel Islands off the coast of southern California (Wilson, 2002). The kelp beds along the California coast and off the Channel Islands are the most extensive and elaborate submarine forests in the world (Rodriguez et al., 2001). El Niño events tend to have a direct influence on the region and have the potential to affect kelp populations, especially when these events are major (Grove et al., 2002).

C.2.2.6.2 Sargassum

Sargassum is a genus of brown algae that generally inhabits shallow waters and coral reefs within the Study Area. Sargassum echinocarpum (Limu kala) is a native species of Hawaii and is usually found within tide pools and on reef flats. Meanwhile, Sargassum agardhianum is native to California.

Two introduced species of *Sargassum* also inhabit the California Study Area—*Sargassum muticum* and *Sargassum horneri*. The brown alga *Sargassum muticum* was introduced from the Sea of Japan and now occupies portions of the California coast (Dobroski et al., 2015; Monterey Bay Aquarium Research Institute, 2009). *Sargassum horneri* is native to western Japan and Korea. Since *Sargassum horneri* was first discovered in Long Beach Harbor in 2003, the species continues to increase its spatial extent and can now be found near harbors and anchorages from Santa Barbara, California, to Isla Natividad in Baja California (Mexico) (Marks et al., 2015). Specifically, *Sargassum horneri* has been found in the Study Area, in places like San Diego and the Channel Islands (U.S. Department of the Navy, 2013d). Both *Sargassum muticum* and *Sargassum horneri* are present in the Study Area.

C.2.2.7 Red Algae (Phylum Rhodophyta)

Red algae are predominately marine, with approximately 4,000 species worldwide (Castro & Huber, 2000c). Red algal species exist in a range of forms, including single and multicellular forms (Roskov et al., 2015), from fine filaments to thick calcium carbonate crusts. Within the Study Area, they occur in the water column and bottom habitats of coastal waters, primarily in reef environments and intertidal zones of Hawaii and California. Common native species in Hawaii include *Laurencia* species, *Gracilaria coronopifolia, Hypnea cervicornis,* and *Gracilaria parvispora*. Many red algae species contribute to reef formation by hardening the reef (by producing calcium carbonate) and by cementing coral fragments (Veron, 2000), and are food for various sea urchins, fishes, and chitons. In California waters, common species include *Endocladia muricata, Mastocarpus papillatus,* and species of *Mazaella*.

C.2.2.8 Seagrasses, Cordgrasses, and Mangroves (Phylum Spermatophyta)

Seagrasses, cordgrasses, and mangroves are flowering marine plants in the phylum Spermatophyta (Roskov et al., 2015). These marine flowering plants create important habitat and are a food source for many marine species. These marine vascular plants are found only in coastal waters, attached to the bottom.

C.2.2.8.1 Seagrasses

Seagrasses are unique among flowering plants because they grow submerged in shallow marine environments. Except for some species that inhabit the rocky intertidal zone, seagrasses grow in shallow, subtidal, or intertidal sediments, and can extend over a large area to form seagrass beds (Garrison, 2004; Phillips & Meñez, 1988). Seagrass beds provide important ecosystem services as a structure-forming keystone species (Arnold et al., 2012; Buhl-Mortensen et al., 2010; U.S. National

Response Team, 2010). They provide suitable nursery environment for commercially important organisms (e.g., crustaceans, fish, and shellfish) and are also a food source for numerous species (e.g., turtles) (Nagaoka et al., 2012). Seagrass beds combat coastal erosion, promote nutrient cycling through the breakdown of detritus (Dawes, 1998; Dawes et al., 1997), and improve water quality. Seagrasses also contribute a high level of primary production to the marine environment, which supports high species diversity and biomass (Spalding et al., 2003). Seagrasses are uprooted by dredging and scarred by boat propellers (Hemminga & Duarte, 2000; Spalding et al., 2003), which can take years to recover. In Hawaii, the most common seagrasses are Hawaiian seagrass (*Halophila hawaiiana*) and paddle grass (*Halophila decipiens*). Hawaiian seagrass is a native species found at less than 3.3 ft. (1 m) in subtidal, sandy areas surrounding reefs, in bays, or in fishponds. It occurs in coastal waters of Oahu near Mamala Bay (southern coast), in Maunalua Bay (southern coast), in Kaneohe Bay (northeast coast), in coastal waters of Maui, in the inner reef flats of southern Molokai, at Anini Beach on the northern shore of Kauai, and at Midway Atoll in the Northwestern Hawaiian Islands (Phillips & Meñez, 1988). Paddle grass is possibly a nonnative species that occurs only on Oahu in waters to 114.8 ft. (35 m) deep; it is apparently restricted to the southern shore of Oahu (Preskitt, 2001, 2002b).

Seagrasses that occur in the coastal areas of the California Study Area in the California Current Large Marine Ecosystem include eelgrass (*Zostera marina* and *Zostera pacifica*), surfgrass (*Phyllospadix scouleri* and *Phyllospadix torreyi*), widgeon grass (*Ruppia maritima*), and shoal grass (*Halodule wrightii*) (Jones et al., 2013; Spalding et al., 2003). The distribution of underwater vegetation is patchy along the California coast. In the California Study Area, eelgrass and surfgrass are the dominant native seagrasses (Wyllie-Echeverria & Ackerman, 2003).

Eelgrass covers most of the available nearshore area in San Diego Bay (Figure C-3). Beds of eelgrass (*Zostera marina*) form an important and productive benthic habitat in San Diego Bay. Eelgrass habitats rank among the most productive habitats in the ocean (Nybakken, 1993) and are an important component of the San Diego Bay food web. As has occurred in bays and estuaries all along the Pacific coast and elsewhere in the world, eelgrass beds have suffered substantial losses and impacts due to their location in sheltered waters where human activity is concentrated. However, these losses were historic due to bay fill and deepening.

Today, various state and federal regulatory frameworks protect eelgrass beds, and any impacts are fully mitigated. For example, National Marine Fisheries Service (NMFS) policy recommends no net loss of eelgrass habitat function in California and encourages the use of eelgrass mitigation banking and in-lieu fee programs when impacts on eelgrass habitat cannot be avoided (National Marine Fisheries Service, 2014a). In San Diego Bay, the range of eelgrass bed growth is from surface to depths of approximately 10 m, depending on light levels and turbidity; eelgrass bed losses have ceased (U.S. Department of the Navy, 2013d). The recovery of the eelgrass habitat within San Diego Bay is largely attributed to restoration efforts as well as reduction in waste discharges since the 1970s. San Diego Bay currently supports approximately 15 percent of the eelgrass habitat and 50 percent of total eelgrass resources for the State of California (Merkel & Associates Inc., 2014). The Navy established an eelgrass mitigation bank in San Diego Bay in 2008 as mitigation for an action that was unrelated to the Proposed Action in this Environmental Impact Statement/Overseas Environmental Impact Statement (EIS/OEIS.)



Figure C-3: Eelgrass Beds in San Diego Bay

C.2.2.8.2 Cordgrasses

Cordgrasses are temperate salt-tolerant land plants that inhabit salt marshes, mudflats, and other softbottom coastal habitats (Castro & Huber, 2000c). Cordgrasses are not present in the Hawaii Study Area. California cordgrass (*Spartina foliosa*) can be found in salt marshes and mudflats within the California Study Area. The Atlantic cordgrass (*Spartina alterniflora*), which is an invasive species in California, has not been documented within the study area (Calflora, 2016; California Invasive Plant Council, 2016). Salt marshes develop in intertidal, protected low energy environments, usually in coastal lagoons, tidal creeks, rivers, or estuaries (Mitsch & Gosselink, 2007). The structure and composition of salt marshes provide important ecosystem services. Salt marshes support commercial fisheries by providing habitat for wildlife, protecting the coastline from erosion, filtering fresh water discharges into the open ocean, taking up nutrients, and breaking down or binding pollutants before they reach the ocean (Dreyer & Niering, 1995; Mitsch et al., 2009b). Salt marshes also are carbon sinks (carbon reservoirs) and facilitate nutrient cycling (Bouillon et al., 2009; Chmura, 2009). Carbon sinks are important in reducing the impact of climate change (Laffoley & Grimsditch, 2009), and nutrient cycling facilitates the transformation of important nutrients through the environment. However, sinking salt marshes may damage cordgrasses, a process known as marsh subsidence.

C.2.2.8.3 Mangroves

Mangroves are a group of woody plants that have adapted to brackish water environments (where salt water and freshwater mix) (Ruwa, 1996). All mangrove trees have root systems that stick up in the air for oxygen intake in oxygen-poor soils and secrete salts from the leaves to process fresh water from the saline environment. Mangroves can trap sediments and pollution from terrestrial environments and can shield and stabilize coastlines from wave action. There are no native mangroves in the Hawaii Study Area. The red mangrove (*Rhizophora mangle*) and several other species of mangroves were introduced to Hawaii (Chimner et al., 2006); these species are invasive species. No mangroves are known to occur within California coastal environments.

C.3 Invertebrates

C.3.1 General Background

C.3.1.1 Habitat Use

Marine invertebrates live in all of the world's oceans, from warm shallow waters to cold deep waters. They inhabit the bottom and all depths of the water column in both large marine ecosystems (Insular Pacific-Hawaiian and California Current) and the open-ocean area (North Pacific Subtropical Gyre) that occur in the Study Area (Brusca & Brusca, 2003a). Many species that occur in the water column are either microscopic or not easily observed with the unaided eye (e.g., protozoans, copepods, and the larvae of larger invertebrate species). Many invertebrates migrate to deeper waters during the day, presumably to decrease predation risk. However, some invertebrates, such as some jellyfish and squid species, may occur in various portions of the water column, including near the surface, at any time of day. In addition, under certain oceanographic conditions, other types of invertebrates (e.g., pelagic crabs and by-the-wind sailors [*Velella velella*]) may occur near the surface during the day. The Study Area extends from the bottom up to the mean high tide line (often termed mean high water (MHW) in literature). The description of habitat use in this section pertains to common marine invertebrates found in the different habitats. This section also identifies marine invertebrates that form persistent habitats, which are structures that do not quickly disintegrate or become incorporated into soft or mixed substrate after the death of the organism. The principal habitat-forming invertebrates are corals and

shellfish species (e.g., oysters, mussels). In a strict sense, individual invertebrates with hard shells (e.g., molluscs), outer skeletons (e.g., crabs), tubes (e.g., annelid worms), or cavities (e.g., sponges) also may be habitat-forming, providing attachment surfaces or living spaces for other organisms.

Marine invertebrate distribution in the Study Area is influenced by habitat (e.g., abiotic substrate, topography, biogenic [formed by living organisms] features), ocean currents, and physical and water chemistry factors such as temperature, salinity, and nutrient content (Levinton, 2009a). Distribution is also influenced by distance from the equator (latitude) and distance from shore. In general, the number of marine invertebrate species (species richness) increases toward the equator (Cheung et al., 2005; Macpherson, 2002). Species richness and overall biomass are typically greater in coastal water habitats compared to the open ocean due to the increased availability of food and protection that coastal habitats provide (Levinton, 2009a).

The diversity and abundance of Arthropoda (e.g., crabs, lobsters, and barnacles) and Mollusca (e.g., snails, clams, and squid) are highest on the bottom over the continental shelf due to high productivity and availability of complex habitats relative to typical soft bottom habitat of the deep ocean (Karleskint et al., 2006). Organisms occurring in the bathyal and abyssal zones of the ocean are generally small and have sparse populations (Nybakken, 1993). The deep ocean has a limited food supply for sedentary deposit or filter feeders. The only areas of the deep ocean known to be densely populated are hydrothermal vents and cold seeps.

Sandy coastal shores are dominated by species that are adapted to living in shifting substrates, many of which are highly mobile and can burrow. In Hawaii, mole crabs (species name was not provided in the report, but was presumably the Pacific mole crab, Hippa pacifica), polychaete worms, and auger snails (Terebra species) were identified as common species in the swash zone of sandy beaches (Hawaii Department of Land and Natural Resources, 1980). Studies of coastal locations on Molokai (primarily rocky intertidal areas but also including some sand patches) identified various crabs, amphipods, isopods, worms, and molluscs as observed or expected species (Godwin & Bolick, 2006; Minton & Carnevale, 2006). Common invertebrates of southern California beaches include common sand crab (Emerita analoga) and a variety of isopods, amphipods, bivalves, snails, worms, and insects (Dugan et al., 2000; Dugan et al., 2015). Inland soft shores consist of mud flats and sand flats that occur in areas sheltered from strong currents and waves. Soft shore habitats may support a wide variety of invertebrate species including crabs, shrimp, clams, snails, and numerous species of worms. Polychaete worms and crabs are common invertebrates on tidal mud flats in Hawaii (U.S. Fish and Wildlife Service, 2011c). Invertebrates documented in tidal flats in southern California include numerous taxa of worms, crustaceans, and molluscs (Talley et al., 2000; Thompson et al., 1993). California horn snail (Cerithidea californica) is the dominant invertebrate of mud flats.

Mixed (e.g., cobble, gravel) and rocky shores provide habitat for a variety of marine invertebrates (e.g., sea anemones, barnacles, chitons, limpets, mussels, urchins, sea stars, sponges, tunicates, and various worms). Rocky intertidal invertebrates may be attached or free living/mobile, and use various feeding strategies (filter-feeders, herbivores, carnivores, scavengers). Many invertebrates occurring in rocky intertidal zones are preyed upon by fish, birds, and other invertebrates. The black abalone (*Haliotis cracherodii*) and white abalone (*Haliotis sorenseni*), which are listed as endangered species under the Endangered Species Act (ESA), occur infrequently in southern California rocky intertidal and subtidal habitats. Hard artificial structures such as pier pilings and seawalls can have a community of invertebrates that is similar to that of rocky habitats.

Vegetated habitats, such as eelgrass in embayments and protected soft bottom coastal areas, surfgrass on rocky intertidal and nearshore subtidal habitat, and kelp forests in nearshore subtidal habitats, support a wide variety of marine invertebrate species. Eelgrass provides important habitat for invertebrates in southern California (Bernstein et al., 2011). More than 50 species of invertebrates occur in surfgrass beds of San Diego County (Stewart & Myers, 1980). Surfgrass also serves as the primary nursery habitat for the commercially important California spiny lobster (*Panuliris interruptus*). Several hundred species of invertebrates have been reported in giant kelp forests of California, in association with rocky substratum, kelp holdfasts, and as epiphytes on kelp blades (Foster & Schiel, 1985). Conspicuous or commonly observed invertebrates in kelp forests include cnidarians (sea anemones, gorgonian sea fans), sponges, arthropod crustaceans (crabs, California spiny lobster), molluscs (abalone, keyhole limpet, octopus, nudibranchs, sea hares), echinoderms (sea cucumbers, sea stars, sea urchins), and tunicates.

Rocky reefs and other rocky habitats may occur in subtidal zones. Invertebrate species composition associated with rocky subtidal habitats may be influenced by depth, size, and structural complexity of the habitat. Hundreds of invertebrate species may occur in rocky habitats, which provide attachment sites for sessile (attached to the bottom) species such as barnacles, bryozoans, limpets, sea anemones, sea fans, sponges, and tunicates, among others. Other invertebrates move about or shelter in crevices, including crustaceans (e.g., crabs, lobsters), echinoderms (e.g., brittle stars, sea cucumbers, sea urchins, sea stars), and molluscs (e.g., snails, nudibranchs, sea hares, octopus).

Shallow-water coral reefs are formed by individual corals with symbiotic, structure-forming algae that require both light and a mean annual water temperature greater than about 64 degrees Fahrenheit (°F) (National Ocean Service, 2016b; Nybakken, 1993). Shallow-water corals occur in the euphotic zone, which is the upper layer of the ocean where light levels are sufficient to support photosynthesis in the symbiotic algae. Shallow-water coral species typically occur in water depths less than 30 m. Shallowwater coral reefs occur on hard substrate throughout the Hawaii Study Area. In addition to the presence of many individual corals, coral reefs also support hundreds of other marine invertebrate species, including representatives of most taxa. The amount of hard reef structure covered by living corals, species richness, and species diversity in the Main Hawaiian Islands remained steady over the time period of 1999 to 2012, with total coverage estimated at about 24 percent, although there was notable variation at individual islands (Rodgers et al., 2015). Coral coverage is below 20 percent at most surveyed locations in the Northwestern Hawaiian Islands, and the coverage appears to have remained stable over the time period of 1981 to 2005, based on survey results at established monitoring sites (Friedlander et al., 2008a). Coral bleaching and mortality events were documented in portions of the Hawaiian archipelago in 2014, 2015, and 2019 (Bahr et al., 2015a; Bahr et al., 2017; National Marine Fisheries Service, 2022b), reducing the amount of live coral coverage in some areas. Surveyed areas that were affected by coral bleaching generally appeared to recover by the end of 2016, but researchers caution that potential future increases in severity and frequency of bleaching events could result in decreased coral coverage in the region (Bahr et al., 2015b; Bahr et al., 2017). Seven species of shallowwater corals dominate waters of the Main Hawaiian Islands: lobe coral (Porites lobata), finger coral (P. compressa), rice coral (Montipora capitata), sandpaper rice coral (M. patula), blue rice coral (M. flabellata), cauliflower coral (Pocillopora meandrina), and corrugated coral (Pavona varians) (Friedlander et al., 2008b). Lobe coral is the dominant species at numerous locations in the Northwestern Hawaiian Islands, while table coral (Acropora cytherea), cauliflower coral, and rice coral are abundant at some locations (Friedlander et al., 2008a).

Deep-water corals occur in water depths where there is low or no light penetration and therefore typically lack symbiotic algae. As such, deep-water corals do not typically form biogenic reefs, but rather form mounds of mixed (cobble-sized) substrate termed "lithoherms" over hard bottom areas (Lumsden et al., 2007). Differences in water clarity and the resulting light penetration at various locations affect the specific depth at which deep-water corals are found. However, in general, deep-water species are considered to occur at depths below 50 m (National Ocean and Atmospheric Administration, 2016; National Oceanic and Atmospheric Administration & National Marine Fisheries Service, 2008). To build their supporting structures, stony corals require calcium carbonate in the form of aragonite or calcite, which they obtain from seawater where carbonate is in solution. Combinations of temperature and pressure result in a boundary, often called the saturation depth, below which aragonite and calcite tend to dissolve. Therefore, corals (and other invertebrates) occurring below this boundary have difficulty forming persistent structures that contain calcium carbonate, and the aragonite saturation boundary imposes a depth limit for stony coral occurrence. The depth of the saturation boundary varies in different locations, ranging from about 200 to 3,000 m. Accordingly, deep-water corals are found in the depth range of about 50 to 3,000 m (Bryan & Metaxas, 2007; Lumsden et al., 2007; Quattrini et al., 2015; Tittensor et al., 2009). The primary taxa of deep-water corals include hexacorals (stony corals, black corals, and gold corals), octocorals (e.g., true soft corals, gorgonians, and sea pens), and hydrocorals (e.g., lace corals) (Hourigan et al., 2017a). Of the approximately 600 coral species that occur at depths below 50 m, about 20 are considered structure forming (Hourigan et al., 2017a). Stony corals such as Enallopsammia rostrata provide three-dimensional structure that may be utilized by other marine species. However, taxa such as black corals, gorgonians, and sea pens may also provide habitat for other marine species, particularly when they occur in dense aggregations. With the exception of sea pens, which occur in soft substrate, deep-water corals generally attach to hard or mixed substrates exposed to strong currents that provide a steady supply of plankton (algae and small animals that drift in the water) to feed on, and that reduce sedimentation that would inhibit colonization and growth of these slow-growing species (Bryan & Metaxas, 2007; Tsao & Morgan, 2005).

A transition zone of reduced light levels, called the mesophotic zone, occurs between the water depths typically associated with shallow-water and deep-water corals. Mesophotic coral communities are composed of stony corals, soft corals, and other structure-forming organisms such as algae and sponges. Some corals with symbiotic, photosynthetic algae occur in the mesophotic zone, although the algae often undergo photosynthesis at reduced rates and the corals, therefore, rely more heavily on planktonic food capture compared to individuals that occur in the euphotic zone. Black corals and octocorals, which do not contain photosynthetic algae, are also characteristic of mesophotic communities. The depth range of the mesophotic zone depends on water clarity, but it is generally considered to extend from 30 m to about 100 to 150 m. Mesophotic communities may occur as deeper extensions of shallow-water reefs or other hard bottom communities (typically in the coastal zone), or they may occur in offshore locations with no connection to shallow-water communities. Mesophotic reefs are usually not detectable on satellite images, which increases the difficulty of identifying and mapping these features. The highest concentrations of stony corals typically occur on persistent, highrelief bottom features that represent a small subset of the hard and, to a lesser extent, mixed substrates of the Study Area. In the Study Area, mesophotic coral communities occur throughout the Hawaiian Archipelago (Baker et al., 2016a). Due to water clarity, corals containing photosynthetic algae occur at depths up to about 150 m in some portions of the Hawaii region.

Chemosynthetic communities may support a relatively high biomass of marine invertebrates. Instead of using photosynthesis driven by sunlight, chemosynthetic organisms derive energy from chemicals

originating from the earth's crust. The primary types of habitats supporting chemosynthetic communities are hydrothermal vents and cold seeps. Hydrothermal vents form when seawater permeates downward through the earth's crust and upper mantle, becomes superheated, and removes minerals and chemicals from the crust. The heated fluid may then rise through fissures in the crust and reach cold ocean water at the seafloor, where metals and other minerals precipitate out to form mounds or chimneys. Communities of microbes, such as bacteria, may colonize these structures and use chemicals occurring in the fluid (primarily hydrogen sulfide or methane) to make energy. The microbes may then become the base of a food web that contains invertebrates such as crabs, clams, mussels, worms, snails, and shrimp (Ross et al., 2012; Woods Hole Oceanographic Institution, 2015). Cold seeps are similar to hydrothermal vents, but the fluid exiting the crust is cooler, typically moves at a slower rate, and may spread over a larger area. Methane hydrates (ice-like structures that contain methane) are associated with some chemosynthetic communities. Cold seeps are generally associated with hard substrate on offshore shelf breaks, submarine canyons, and seamounts.

In the Hawaiian Islands, a hydrothermal vent field was documented on the summit of Lo'ihi Seamount (renamed in 2021 to Kama'ehuakanaloa) is located near the Hawaii Island (Garcia et al., 2005). In 1996, seismic events formed a large crater on the summit and destroyed the vent area; however, new vents later re-formed (Wheat et al., 2000). Cold seeps have been found in association with multiple fault systems off southern California, including the San Clemente (Bernardino & Smith, 2010; Torres et al., 2002), San Pedro (Paull et al., 2008), and San Diego Trough faults (Grupe et al., 2015).

C.3.1.2 Movement and Behavior

Marine benthic and epibenthic (animals that live on the surface of the substrate) invertebrates may be sessile, sedentary (limited mobility), or highly mobile (but typically slower than large vertebrates). Several beach invertebrates (e.g., sand crabs, Pismo clams [*Tivela stultorum*], polychaete worms) recruit to beaches during spring and summer and seasonally move to shallow nearshore waters during late fall and winter. Some subtidal epibenthic invertebrates undergo seasonal onshore-offshore migrations associated with reproduction (e.g., California spiny lobster).

Pelagic marine invertebrates include plankton (organisms that do not swim or generally cannot swim faster than water currents) and nekton (active swimmers that can generally swim faster than water currents). Planktonic animals commonly undergo daily migrations to surface waters at dusk and return to deeper waters at dawn. This includes small, microscopic zooplankton and larvae, larger crustaceans (e.g., small shrimp), and jellyfish. Planktonic organisms vary in their swimming abilities, ranging from weak (e.g., larvae) to substantial (e.g., box jellyfish). Nekton such as prawns, shrimps, and squid have relatively strong swimming ability, although they are typically slower than most vertebrate animals.

C.3.1.3 Sound Sensing and Production

In general, organisms may detect sound by sensing either the particle motion or pressure component of sound, or both (refer to Appendix D, Acoustic and Explosive Concepts, for an explanation of these sound components). Aquatic invertebrates probably do not detect pressure since many are generally the same density as water and few, if any, have air cavities that would respond to pressure (Budelmann, 1992b; Popper et al., 2001). Marine invertebrates are generally thought to perceive sound via either external sensory hairs or internal statocysts. Many aquatic invertebrates have ciliated "hair" cells that may be sensitive to water movements, such as those caused by currents or water particle motion very close to a sound source (Budelmann, 1992a, 1992b; Mackie & Singla, 2003). This may allow sensing of nearby prey or predators, or help with local navigation. Detection of particle motion is thought to occur in mechanical receptors found on various body parts (Roberts et al., 2016). Aquatic invertebrates that are

able to sense local water movements with ciliated cells include cnidarians, flatworms, segmented worms, molluscs, and arthropods (Budelmann, 1992a, 1992b; Popper et al., 2001). Crustaceans in particular seem to have extensive occurrence of these structures. The sensory capabilities of adult corals are largely limited to detecting water movement using receptors on their tentacles (Gochfeld, 2004), and the exterior cilia of coral larvae likely help them detect nearby water movements (Vermeij et al., 2010).

Some aquatic invertebrates have specialized organs called statocysts that enable an animal to determine orientation, balance, and, in some cases, linear or angular acceleration. Statocysts allow the animal to sense movement and may enable some species, such as cephalopods and crustaceans, to be sensitive to water particle movements associated with sound or vibration (Hu et al., 2009; Kaifu et al., 2008; Montgomery et al., 2006; Normandeau Associates, 2012; Popper et al., 2001). Because any acoustic sensory capabilities, if present, are apparently limited to detecting the local particle motion component of sound (Edmonds et al., 2016), and because water particle motion near a sound source falls off rapidly with distance, aquatic invertebrates are probably limited to detecting nearby sound sources rather than sound caused by pressure waves from distant sources.

In addition to hair cells and statocysts that allow some marine invertebrates to detect water particle motion, some species also have sensory organs called chordotonal organs that can detect substrate vibrations. Chordotonal organs are typically attached to connective tissue of flexible appendages such as antennae and legs (Edmonds et al., 2016). The structures are connected to the central nervous system and can detect some movements or vibrations that are transmitted through substrate.

Available information indicates that aquatic invertebrates are primarily sensitive to low-frequency sounds. Both behavioral and auditory brainstem response studies suggest that crustaceans may sense sounds up to 3 kilohertz (kHz), but greatest sensitivity is likely below 200 hertz (Hz) (Goodall et al., 1990; Lovell et al., 2005; Lovell et al., 2006). Most cephalopods (e.g., octopus and squid) likely sense low-frequency sound below 1 kHz, with best sensitivities at lower frequencies (Budelmann, 1992b; Mooney et al., 2010; Packard et al., 1990). A few cephalopods may sense frequencies up to 1.5 kHz (Hu et al., 2009). Squid did not respond to playbacks of odontocete (e.g., toothed whales) ultrasonic echolocation clicks, likely because these clicks were outside of squid hearing range (Wilson et al., 2007). Although information on the frequency range of the clicks was not provided, ultrasonic sound typically refers to high frequency sounds above the limit of human hearing (greater than about 20 kHz). Similarly, squid did not respond to killer whale echolocation clicks ranging from 199 to 226 decibels (dB) referenced to 1 micropascal (dB re 1 µPa) (Wilson et al., 2007) (refer to Appendix D, Acoustic and Explosive Concepts, for an explanation of this and other acoustic terms). The frequency of the clicks was not provided. However, killer whale echolocation clicks have been reported to be mostly between 45 and 80 kHz (Au et al., 2004). Some researchers have suggested sensitivity to sounds of higher frequencies in some species, although study results are inconclusive. European spiny lobsters (Palinurus elephas), some of which were exposed to predators, were found to produce ultrasound signals up to about 75 kHz (Buscaino et al., 2011). The investigators speculated that the signals might have an antipredator function or might be used in intraspecific communication, although these functions (particularly communication) were considered hypothetical. The results of another study suggest that European spiny lobsters likely use acoustic signals to aggregate (frequency was not specified, although lobsters in the study produced sounds of up to 30 kHz) (Filiciotto et al., 2014). However, information currently available indicates that invertebrates are likely sensitive only to local water movement and to

low-frequency particle accelerations generated in their close vicinity (Normandeau Associates, 2012; Solé et al., 2023).

Although many types of aquatic invertebrates produce sound and at least some species have the ability to detect low-frequency particle motion, little is known about the use of sound or whether all sound production is purposeful or merely incidental in some cases (Hawkins et al., 2015; Normandeau Associates, 2012). Some invertebrates have structures that appear to be designed specifically for sound production, and the results of various studies (summarized in the following paragraphs) indicate that sound is used for communication or other behaviors in some species. For example, it has been suggested by numerous researchers that the larvae of some marine species (e.g., crustaceans, molluscs, and corals) use sound cues for directional orientation (Budelmann, 1992a, 1992b; Montgomery et al., 2006; Popper et al., 2001).

Aquatic invertebrates may produce and use sound in territorial behavior, to detect or deter predators, and in reproduction (Popper et al., 2001). Some crustaceans produce sound by rubbing or closing hard body parts together (Au & Banks, 1998; Heberholz & Schmitz, 2001; Latha et al., 2005; Patek & Caldwell, 2006). The snapping shrimp chorus makes up a significant portion of the ambient noise in many locations (Au & Banks, 1998; Cato & Bell, 1992; Heberholz & Schmitz, 2001). Each snapping shrimp click is up to 215 dB re 1 µPa at 1 m (root mean square [rms] is implied, but the authors did not explicitly state sound pressure level or peak sound pressure level), with a peak around 2 to 5 kHz. Some crustaceans, such as the American lobster (*Homarus americanus*) and California mantis shrimp (*Hemisquilla californiensis*), may also produce sound by vibrating the carapace (Henninger & Watson, 2005; Patek & Caldwell, 2006). Spiny lobsters typically produce low-frequency rasps by moving a structure at the base of the antennae over a rigid file (Buscaino et al., 2011). Other crustaceans make low-frequency rasping or rumbling noises, perhaps used in defense or territorial display (Patek & Caldwell, 2006; Patek et al., 2009), or perhaps used incidental to a visual display. The aquatic isopod *Cymodoce japonica* produces sound by rubbing body parts together (Nakamachi et al., 2015).

Reef noises, such as fish pops and grunts, sea urchin grazing (around 1 kHz), parrotfish grazing, and snapping shrimp noises (around 5 kHz) (Radford et al., 2010), may be used as a cue by some aquatic invertebrates. Nearby reef noises were observed to affect movements and settlement behavior of coral and crab larvae (Jeffs et al., 2003; Radford et al., 2007; Stanley et al., 2010; Vermeij et al., 2010), although chemical cues and substrate color are also used by some species (Foster & Gilmour, 2016). Larvae of other crustacean species, including pelagic and nocturnally emergent species that benefit from avoiding coral reef predators, appear to avoid reef noises (Simpson et al., 2011). Detection of reef noises is likely limited to short distances. Low-frequency sound pressure and particle motion have been measured near a coral reef off Maui, Hawaii (Kaplan & Mooney, 2016). Results indicate that adult cephalopod species would not be able to detect the low level of particle acceleration at the measurement point nearest the reef (50 m). The specific particle acceleration levels detected by marine invertebrate larvae are unknown, but the authors suggest that invertebrate larvae would be unlikely to detect particle acceleration at distances beyond 150 m at this reef. Playback of reef sounds increased the settlement rate of eastern oyster (Crassostrea virginica) larvae (Lillis et al., 2013). Green-lipped mussel (Perna canaliculus) larvae settlement rate increased when exposed to underwater noise produced by a ferry (Wilkens et al., 2012).

C.3.1.4 General Threats

General threats to marine invertebrates include overexploitation and destructive fishing practices (Halpern et al., 2008b; Jackson et al., 2001; Kaiser et al., 2002; Miloslavich et al., 2011; Pandolfi et al.,

2003), habitat degradation resulting from pollution and coastal development (Cortes & Risk, 1985; Downs et al., 2009; Mearns et al., 2011), disease (Porter et al., 2001), invasive species (Bryant et al., 1998; Galloway et al., 2009; Wilkinson, 2002) (which may be introduced as a result of growth on vessel hulls or bilge water discharge), oil spills (Yender et al., 2010), global climate change and ocean acidification (Hughes et al., 2003), and possibly human-generated noise (Brainard et al., 2011; Vermeij et al., 2010). A relatively new threat to marine invertebrates is bioprospecting, which is the collection of organisms in pursuit of new compounds for development of pharmaceutical products (Radjasa et al., 2011). Numerous bioactive products have been isolated from marine invertebrates collected in the Hawaii Exclusive Economic Zone (EEZ) (Leal et al., 2012).

Compared to many other invertebrate taxa, the threats to corals are well-studied. Numerous natural and human-caused stressors may affect corals of the Main Hawaiian Islands, including thermal stress, disease, tropical storms, coastal development and pollution, erosion and sedimentation, tourism/recreation, fishing, trade in coral and live reef species, vessel anchoring or groundings, marine debris, predation, invasive species, military and other security-related activities, and hydrocarbon exploration (Center for Biological Diversity, 2009; National Oceanic and Atmospheric Administration, 2008a, 2008b). Stressors associated with the Northwestern Hawaiian Islands are similar but, in the case of direct human-caused impacts, lesser in degree because the islands are more remote.

Coral bleaching, which occurs when corals expel the symbiotic algae living in their tissues, is a stress response to changes in environmental parameters such as temperature or light. Compared to other regions of the world, few major coral bleaching events have occurred in the Hawaiian Islands. The first known large-scale bleaching event occurred in 1996, primarily affecting portions of the Main Hawaiian Islands. A second event occurred in 2002 in the Northwestern Hawaiian Islands (Jokiel & Borwn, 2004). More recently, bleaching events were documented at Kane'ohe Bay on the northeast coast of Oahu in 2014 (Bahr et al., 2015b) and other portions of the Main Hawaiian Islands in 2014, 2015, and 2019 (National Oceanic and Atmospheric Administration, 2015b, 2022). In Kane'ohe Bay, susceptibility to bleaching, severity of impacts, and recovery time was strongly influenced by the type of symbiotic algae, varying coping mechanisms in individual corals, and abiotic (e.g., hydrodynamics) factors (Cunning et al., 2016).

Factors that seem to be important for coral reef resilience (ability of a reef to resist and recover from environmental disturbance) were identified by McClanahan et al. (2012). Some factors are large in scale and difficult to manage, while others, such as fishing methods and adjacent watershed pollution, are more easily affected by local management practices. NOAA's Pacific Islands Fisheries Science Center evaluated numerous areas of the Main Hawaiian Islands in relation to these factors and developed composite resiliency scores. Generally, the highest scores were associated with sparsely populated areas (e.g., Ni'ihau, portions of Maui), while the lowest scores were associated with densely populated areas (e.g., portions of O'ahu) (Pacific Islands Fisheries Science Center, 2014). Primary threats to deep-water or cold-water corals include bottom fishing, hydrocarbon exploration, cable and pipeline placement, and waste disposal (e.g., discarded or lost rope and fishing equipment, dredged sediments) (Freiwald et al., 2004).

Threats related to water quality, marine debris, and climate change are further described in the subsections below.

Water Quality

Invertebrates may be affected by changes in water quality resulting from pollution, turbidity and increased particle deposition that may occur as a result of sediment disturbance, and waste discharge. Stormwater runoff and point source discharges associated with coastal development may introduce pollutants into bays and other nearshore coastal areas. The pollutants may degrade sediment and water quality, which in turn can impact marine invertebrate communities. Sediment disturbance may result from activities such as dredging, which can affect sensitive species such as some corals (Erftemeijer et al., 2012). In addition to dredging, erosion due to storm runoff may cause changes in the frequency or magnitude of sedimentation in areas in proximity to ocean outfalls, estuarine inlets, and major river discharges.

Ship discharges may affect water quality and invertebrates associated with the impacted water. Discharged materials include sewage, bilge water, graywater, ballast water, and solid waste (e.g., food and garbage). Discharges may originate from military, commercial, and recreational vessels. Under provisions of the CWA, the USEPA and the DoD have developed Uniform National Discharge Standards to address discharges from U.S. military vessels.

Marine invertebrates can be impacted by exposure to oil due to runoff from land, natural seepage, or accidental spills from offshore drilling/extraction or tankers (White et al., 2012). Reproductive and early life stages are especially sensitive to oil exposure. Factors such as oil type, quantity, exposure time, and season can affect the toxicity level. Experiments using corals indicate that oil exposure can result in death, decreased reproductive success, altered development and growth, and altered behavior (White et al., 2012; Yender et al., 2010).

C.3.1.4.1 Climate Change

The primary concerns of climate change in the context of impacts on marine invertebrates include increased water temperature, ocean acidification, increased frequency or intensity of cyclonic storm events, and sea level rise.

Increases in ocean temperature can lead to coral stress, bleaching, and mortality (Lunden et al., 2014). Bleaching of corals and other invertebrates that contain symbiotic algae in their tissues (e.g., some anemones and clams) is often tied to atypically high sea temperatures (Lough & van Oppen, 2009; National Ocean Service, 2016a). Bleaching events have increased in frequency in recent decades. Coral bleaching on a global scale occurred during the summers of 2014, 2015, 2016, and 2023-2024 (Eakin et al., 2016; National Oceanic and Atmospheric Administration, 2024b). In addition to elevated sea temperatures, atypically low sea temperatures may also cause mortality to corals and most other reef organisms (Colella et al., 2012; Lirman et al., 2011; National Ocean Service, 2016a), suggesting that widening climate extremes could cause more coral bleaching. In one experiment, three coral species that experienced bleaching had reduced ability to remove sediments from their tissue surface (Bessell-Browne et al., 2017). Response to thermal stress may differ across species or within different environmental contexts, with some species or taxa being more tolerant than others (Bahr et al., 2016; Guest et al., 2016; Hoadley et al., 2015). For example, in the Caribbean Sea, while numerous stony corals may be negatively affected by increased water temperature, some gorgonian corals have been found to persist or increase in abundance under similar conditions (Goulet et al., 2017). The results of one study suggest that some corals may acclimate to increased water temperature over time, exhibiting less temperature sensitivity and resulting bleaching activity (McClanahan, 2017). Skeletal formation of postsettlement individuals of the plate coral Acropora spicifera was not affected by increased water

temperature (Foster et al., 2016). However, exposure to lowered pH was found to increase the potential for negative effects associated with subsequent water temperature increase in one stony coral species (Towle et al., 2016). In addition to potential physiological effects, the distribution of some invertebrates may be affected by changing water temperature. Northern and southern shifts in the geographic center of abundance of some benthic invertebrates along the U.S. Atlantic coast have occurred over the last 20 years, presumably in response to increased water temperature (Hale et al., 2017).

Ocean acidification has the potential to reduce calcification and growth rates in species with calcium carbonate skeletons, including shellfish (e.g., clams, oysters), corals, and sponges (Clark & Gobler, 2016; Cohen et al., 2009), and crustose coralline algae that contain calcite in their cell walls (Roleda et al., 2015). For example, newly settled individuals of the plate coral *A. spicifera* that were exposed to elevated CO₂ and lowered pH levels showed decreased mineral deposition and evidence of skeletal malformation (Foster et al., 2016), and water acidification decreased the survival, size, and weight of bay barnacles (*Balanus improvises*) (Pansch et al., 2018). The results of one study suggest that community-level effects to corals can be more evident than effects to individual corals (Carpenter et al., 2018). Many species within these taxa are important structure-building organisms. In addition to corals and shellfish, acidification may also affect weakly calcified taxa such as lobsters and sea cucumbers (Small et al., 2016; Verkaik et al., 2016).

Some climate change models predict that the depth below which corals are unable to form calcium carbonate skeletons will become limited as the oceans acidify and temperatures increase, potentially decreasing the occurrence and habitat-forming function of corals and other invertebrates. Deep-sea scleractinian stony corals could be particularly vulnerable due to habitat loss and decreased larvae dispersal (Miller et al., 2011). However, a recent study of successive generations of shallow-water reef-building corals exposed to increased water temperature and acidification suggests some corals may be able to tolerate rapidly changing environmental conditions better than previously thought (Putnam & Gates, 2015).

In addition to physical effects, increased acidity may result in behavioral changes in some species. For example, acidification of porewater was found to affect burrowing behavior and juvenile dispersal patterns of the soft-shell clam (*Mya arenaria*) (Clements et al., 2016), and increased acidity caused a reduction in the loudness and number of snaps in the snapping shrimp *Alpheus novaezelandiae* (Rossi et al., 2016). As discussed for thermal stress, some invertebrate species may be more tolerant of changing acidity levels than others (Bahr et al., 2016). One study found that lowered pH caused a significant decrease in black band disease progression in mountainous star coral (Muller et al., 2017). Another study of three Arctic marine bivalves concluded that at least two of the species are generally resilient to decreased pH (Goethel et al., 2017). A study of the deep-water stony coral *Desmophyllum dianthus* found that the species was not affected by increased acidity under conditions of ambient water temperature but that stress and decreased calcification occurred when acidity and water temperature were both increased (Murray et al., 2016). Gelatinous invertebrates such as jellyfish generally seem to be tolerant of increased water acidity (Treible et al., 2018).

Although the potential effects that climate change could have on future storm activity is uncertain, numerous researchers suggest that rising temperatures could result in little change to the overall number of storms, but that storm intensity could increase (Voiland, 2013). Increased storm intensity could result in increased physical damage to individual corals and reefs constructed by the corals (which support numerous other invertebrate taxa), overturning of coral colonies, and a decrease in structural complexity due to disproportionate breakage of branching species (Heron et al., 2008; The Nature

Conservancy, 2015). However, large storms such as hurricanes may also have positive impacts on corals, such as lowering the water temperature and removing less resilient macroalgae from reef structures, which can overgrow corals.

Sea level rise could affect invertebrates by modifying or eliminating habitat, particularly estuarine and intertidal habitats bordering steep and artificially hardened shorelines (Fujii, 2012). It is possible that intertidal invertebrates would colonize newly submerged areas over time if suitable habitat were present. Coral reef growth may be able to keep pace with sea level rise because accretion rates of individual corals are generally greater than projected potential rates of sea level rise (The Nature Conservancy, 2016). Corals are currently subjected to tidal fluctuations of up to several meters (The Nature Conservancy, 2015; U.S. Geological Survey, 2016). However, the overall net accretion rate of coral reefs may be much slower than the rate of individual corals, decreasing the overall ability of reefs to keep pace with rising water levels. In addition, the compounding effect of other stressors (e.g., ocean acidification) is unknown. In an evaluation of threats to corals previously petitioned for listing under the ESA, sea level rise was considered a low to medium influence on extinction risk (Brainard et al., 2011).

Additional concerns include the potential for changes in ocean circulation patterns that affect the planktonic food supply of filter- and suspension-feeding invertebrates (e.g., corals) (Etnoyer, 2010). An increase in the future incidence of diseases in marine organisms is also theorized (Harvell et al., 2002). In addition, there is concern that cumulative effects of threats from fishing, pollution, and other human disturbance may reduce the tolerance of corals to global climate change (Ateweberhan et al., 2013; Ateweberhan & McClanahan, 2010).

C.3.1.4.2 Marine Debris

Marine debris (especially plastics) is a threat to many marine ecosystems, particularly in coastal waters adjacent to urban development. Microplastics (generally considered to be particles less than 5 mm in size), which may consist of degraded fragments of larger plastic items or intentionally manufactured items (e.g., microbeads), are of concern because of their durability and potential to enter marine food webs (Setala et al., 2016). Field and laboratory investigations have documented ingestion of microplastics by marine invertebrates including bivalve molluscs; crustacean arthropods such as lobsters, shore crabs, and amphipods; annelid lugworms; and zooplankton (Browne et al., 2013; Setala et al., 2014; Von Moos et al., 2012; Watts et al., 2014). While animals with different feeding modes have been found to ingest microplastics, laboratory studies suggest that filter-feeding and deposit feeding benthic invertebrates are at highest risk (Setala et al., 2016).

Marine debris, including large amounts of plastic, is present in surface waters around the Main Hawaiian Islands and Northwestern Hawaiian Islands, and is found on coral reefs as well (Cooper & Corcoran, 2010; Dameron et al., 2007). The Hawaiian Archipelago is located within the North Pacific Gyre, which consolidates debris originating in various areas of the Pacific Ocean. However, there have been no surveys specifically conducted to investigate marine debris on the seafloor in Hawaii. A visual survey of the seafloor that included a portion of the Navy's SOCAL Range Complex was conducted as part of a 15-year quantitative assessment of marine debris on the seafloor off the California coast (Watters et al., 2010). Plastics were the most abundant material found and, along with recreational monofilament fishing line, dominated the debris encountered on the seafloor. U.S. Navy vessels have a zero-plastic discharge policy and return all plastic waste to appropriate disposal or recycling sites on shore. The visual survey encountered only a single object that was potentially "military" in origin (it appeared to be a shell casing). A survey conducted at Monterey Canyon off California found that items of military origin were among the least frequently encountered types of identified debris (Schlining et al., 2013).

Recent studies in the Southern California Bight found that marine debris (primarily plastic) occurred in about one-third of seafloor areas surveyed (McLaughlin et al., 2022; Moore et al., 2016). Microplastic particles were more prevalent in shallow nearshore areas (ports, marinas, bays, and estuaries) than in offshore areas. Another study of marine debris along the U.S. West Coast characterized the composition and abundance of man-made marine debris at 1,347 randomly selected stations during groundfish bottom trawl surveys that took place in 2007 and 2008 (Keller et al., 2010). The sample sites included some locations within the California portion of the HCTT Study Area. A subset of the sites sampled included historically used post-WWII dump sites. Recovered items identifying the sites as post-WWII era dump sites included equipment described as "helmets," "gas masks," "uniforms," and other miscellaneous and diverse items such as "plastic," "file cabinets," and "buckets." Since approximately the 1970s, items such as these are no longer disposed of at sea. The items listed here are not military expended materials and would not be expended during training and testing activities in the HCTT Study Area. For this reason, the characterization of "military debris" in the study has little if any relevance to the Proposed Action or to present-day standard Navy conduct that includes (among other procedures) restrictions on the discharge of plastics at sea.

C.3.1.4.3 Invasive Species

Introduction of invasive species is considered one of primary threats to ESA-listed species (Anttila et al., 1998; Costante, 2021; Dueñas et al., 2018; Noss et al., 2020; Pimentel et al., 2004; Wilcove & Chen, 1998). As early as 2001, 343 aquatic invasives species were documented as occurring within Hawaiian waters, with the origin of many of these species coming from Indo-Pacific and Philippine Islands region (Eldredge & Carlton, 2002; Eldredge & Smith, 2001). In the Hawaii Study Area, invasive marine invertebrates include Mediterranean mussel (*Mytilus galloprovincialis*), orange keyhole sponge (*Mycale armata*), upside-down jellyfish (*Cassiopea andromeda*), Samoa crab (*Scylla serrata*), American oyster (*Crassostrea virginica*), pulse coral (*Unomia stolonifera*), cabbage coral (*Montipora foliosa*), finger coral (*Montipora digitata*), and the Manjano anemone (*Anemonia manjano*) (Carlton & Eldredge, 2015; Carlton & Schwindt, 2024; Eldredge & Carlton, 2002; Eldredge & Smith, 2001). Many of these nonindigenous species are known to predate upon and outcompete species native to the Hawaiian region of the Study Area (Eldredge & Smith, 2001; Garcia et al., 2021; Kueffer et al., 2010).

Since at least 2001, non-indigenous species of octocorals have been identified in Hawaiian waters (Kahng, 2006; Kahng & Grigg, 2005). At that time, the octocoral *Carijoa riisei* was discovered overgrowing black coral in the Au'au Channel, which separates Maui and Lanai (Kahng & Grigg, 2005). In May 2020, three new nonindigenous species of coral (*Montipora foliosa, Montipora digitata*, and the third species either *Montipora stellata* or *Monitipora carinata*) and an anemone (*Anemonia manjano*) were confirmed in Kāne'ohe Bay (Division of Aquatic Resources, 2021). Even more recently, colonies of the invasive octocorals *Unomia stolonifera* and *Capnella cf. spicata* were detected in the southern region of the Main Channel at JBPHH, Hawaii in the vicinity of Bishop Point (Miller et al., 2023). The Navy funded combined remotely operated vehicle, drop camera, and diver surveys to define the extent of their colonization, which could be used to assist in determining appropriate control measures. These surveys estimated that the total area where these two nonindigenous octocorals occur was approximately 336,000 square meters (Miller et al., 2023).

California's extensive coastline and diverse marine ecosystems make it particularly vulnerable to marine invasive species. Certain areas along the coast, referred to as hotspots, are at a higher risk of invasion due to factors such as increased shipping activity, aquaculture operations, and recreational use (California Department of Fish and Wildlife, 2024b). Located off the coast of Southern California, the Channel Islands

are also at risk of marine invasions (California Department of Fish and Wildlife, 2024b). Notable invasive species in the area include the Mediterranean fanworm (*Sabella spallanzanii*) and the clubbed tunicate (*Styela clava*) (California Department of Fish and Wildlife, 2024b).

C.3.2 Endangered Species Act-Listed Species

C.3.2.1 Black Abalone (Haliotis cracherodii)

C.3.2.1.1 Status and Management

The black abalone (*Haliotis cracherodii*) was listed as endangered under the ESA in 2009. A dramatic decline in abundance, likely caused by a disease known as withering syndrome (explained in more detail below), prompted closure of both the commercial and recreational fisheries in California. The State of California imposed a moratorium on black abalone harvesting throughout California in 1993 and on all abalone harvesting in central and southern California in 1997 (Butler et al., 2009). Numerous California State Marine Protected Areas provide additional protection for abalone. An Abalone Recovery Management Plan was adopted by the State of California in 2005.

NMFS prepared a status review for this species in 2009 (Butler et al., 2009), 2017 (National Marine Fisheries Service, 2018e), and announced in 2023 the intent to prepare an updated status review (Endangered and Threatened Species; Initiation of 5-Year Review for the Endangered Black Abalone and the Endangered White Abalone, 88 *Federal Register* [FR] 43308 [July 7, 2023]). Critical habitat was designated for black abalone by NMFS in 2011 (Endangered and Threatened Wildlife and Plants: Final Rulemaking to Designate Critical Habitat for Black Abalone, 76 FR 66806–66844 [October 27, 2011]).

Various projects are in place to monitor the status of the species, to understand and address withering disease, to improve reproduction, and to minimize illegal harvest. For instance, the Navy monitors black abalone populations on SCI and San Nicolas Islands (SNI) and Point Loma, San Diego, and the species is managed under both the SCI Integrated Natural Resources Management Plan (INRMP) and SNI INRMP. The Navy has conducted and continues to provide funding for ongoing surveys of rocky intertidal areas on SCI, SNI, and Point Loma, including surveys specifically for black abalone (Fletcher et al., 2021; Graham et al., 2014; Hong et al., 2023a; Hong et al., 2023b; Kenner & Yee, 2022; Tierra Data, 2008; U.S. Department of the Navy, 2022).

Critical Habitat

Critical habitat for black abalone was designated on November 28, 2011, and includes approximately 360 km^2 of rocky intertidal and subtidal habitat within five segments of the California coast between the Del Mar Landing Ecological Reserve to the Palos Verdes Peninsula, as well as on the Farallon Islands, Año Nuevo Island, San Miguel Island, Santa Rosa Island, Santa Cruz Island, Anacapa Island, Santa Barbara Island, and Santa Catalina Island (76 FR 66806). This designation also includes rocky intertidal and subtidal habitats from the MHW to a depth of - 6 m (relative to the mean lower low water line), as well as the coastal marine waters encompassed by these areas (76 FR 66806). In addition, two specific areas, SNI and SCI, are excluded from the designation, based on INRMPs for these areas that provide benefits to black abalone.

Based on the best available scientific information, the following primary constituent elements essential for the conservation of black abalone include:

- 1. Rocky substrate
- 2. Food resources
- 3. Juvenile settlement habitat
- 4. Suitable water quality
- 5. Suitable nearshore circulation patterns

Recovery Goals

In 2020, NMFS finalized the recovery plan for black abalone (National Marine Fisheries Service, 2020b). The goal of the recovery plan is to restore black abalone populations in the wild such that the species can be downlisted to threatened status and subsequently delisted (i.e., removed from the Endangered Species List). NMFS also developed recovery objectives used to describe the conditions necessary to achieve the recovery goal. These objectives include:

- Increase the abundance, productivity, spatial structure, and diversity of black abalone populations to levels that support the species' long-term survival, viability, and resilience to threats.
- Sufficiently address the threats of concern (e.g., contaminant spills, spill response activities, illegal harvest, and potential introductions of pathogens).

C.3.2.1.2 Habitat and Geographic Range

The distribution of black abalone ranges approximately from Point Arena in northern California to Bahia Tortugas and Isla Guadalupe in Mexico (Butler et al., 2009). Although the geographic range of black abalone extends to northern California, the most abundant populations historically have occurred in the Channel Islands (Butler et al., 2009). A map of the black abalone range can be accessed on NMFS Office of Protected Resources website.

Black abalone live on rocky substrates in the high to low intertidal zone (with most animals found in the middle and lower intertidal) within the California portion of the HCTT Study Area. They occur among other invertebrate species, including California mussels (*Mytilus californianus*), gooseneck barnacles (*Pollicipes polymerus*), and sea anemones (e.g., giant green anemone (*Anthopleura xanthogrammica*). Of the species of abalone in the waters of California, the black abalone inhabits the shallowest areas. It is rarely found deeper than 6 m, and smaller individuals generally inhabit the higher intertidal zones. Complex surfaces with cracks and crevices may be crucial habitat for juveniles, and appear to be important for adult survival as well (Butler et al., 2009).

The black abalone diet varies with life history stage. As larvae, black abalone receive nourishment from their egg yolks and do not actively feed. Settled abalone clamp tightly to rocky substrates and feed on crustose coralline algal matter that they scrape from the rocks. Young juveniles feed on bottom-dwelling diatoms, bacterial films, and microflora. As they increase in size and become less vulnerable to predation, abalone move into more open locations on rocks (though still cryptic) to forage. Adult black abalone feed primarily on drifting plant fragments and attached macroalgae (Butler et al., 2009; Smith et al., 2003). The primary predators of abalone are fish, sea otters, sea stars, and a variety of invertebrates, as well as humans through illegal harvesting (National Oceanic and Atmospheric Administration Fisheries, 2018; Smith et al., 2003).

C.3.2.1.3 Population Trends

Black abalone were generally abundant before 1985 in the coastal waters throughout the species' range, although abundance has historically not been considered high north of San Francisco. Substantial populations also occurred in the coastal waters of the Channel Islands of southern California. In the early

1970s, the black abalone constituted the largest abalone fishery in California. Black abalone populations south of Monterey County, California, have experienced 95 percent or greater declines in abundance since the mid-1980s as a result of fishing pressure in combination with withering syndrome (Neuman et al., 2010). Withering syndrome is caused by the bacteria species *Candidatus Xenohaliotis californiensis*, which attacks the lining of the abalone's digestive tract, inhibiting the production of digestive enzymes, which ultimately causes the muscular "foot" to wither and atrophy. This impairs the abalone's ability to adhere to rocks (Butler et al., 2009), making it more vulnerable to predation or starvation.

Major declines in abundance in the Channel Islands, the primary fishing grounds for this species before closure of the abalone fishery, have severely reduced the population as a whole (Butler et al., 2009). Surveys of rocky intertidal habitat at SCI have resulted in a total population estimate of approximately 100 to 300 individuals of black abalone, representing less than 0.1 percent of historical levels on the island (Raimondi et al., 2012; Tierra Data, 2008). Surveys of rocky shores between 2016 and 2020 indicate black abalone continue to be rare at SCI (Fletcher et al., 2021).

In 2018, the Black Abalone Status Review Team noted that some locations that were historically impacted by overfishing and more recently severely impacted by withering syndrome, showed increased recruitment and increased numbers (National Marine Fisheries Service, 2018a). They indicated that successful fertilization and recruitment is possible in populations that are below this minimum density. SNI is one of the only locations in southern California where black abalone have been increasing and where multiple recruitment events have occurred since 2005 (Butler et al., 2009). However, the Review Team concluded that the status of black abalone largely remains the same as it was at the time of the listing, and therefore recommended the classification of endangered remains the same (National Marine Fisheries Service, 2018a).

C.3.2.1.4 Population Threats

The black abalone population is declining because of historical overfishing and ongoing threats of withering syndrome, illegal harvest, pollution, and natural predation. The spread of withering syndrome is enhanced by periods of ocean warming, such as El Niño events (Neuman et al., 2010). Although there is no documented causal link between withering syndrome and long-term climate change, historical patterns suggest that ocean warming may increase the susceptibility of black abalone to the disease. Decreased population density is an additional factor in the species decline (Neuman et al., 2010). The black abalone is a broadcast spawner (gametes released into the water and fertilization occurs externally), and simultaneous spawning by males and females in close proximity (within a few ft.) is required for successful reproduction. In areas where black abalone have been overfished or otherwise reduced, the distance between adult males and females may be too great or the population density too low to sustain local populations (Butler et al., 2009; Neuman et al., 2010). There is some concern that the invasive macroalga Sargassum horneri, first documented off southern California in 2003 and currently distributed in coastal waters from Santa Barbara to central Baja California, Mexico, has the potential to affect black abalone populations. Long-term ecological implications of the presence of the invasive species are uncertain but potentially include displacement of native kelp (Kaplanis et al., 2016; Marks et al., 2015), which is a food source for black abalone.

C.3.2.2 White Abalone (Haliotis sorenseni)

C.3.2.2.1 Status and Management

The white abalone (*Haliotis sorenseni*) was listed as endangered under the ESA in 2001 (66 FR 29046) and is recognized as one stock (Hobday & Tegner, 2000). Overfishing in the 1970s reduced the

population to such low densities that successful reproduction was severely restricted. White abalone populations continue to be threatened primarily by reproductive failure (Hobday et al., 2001; National Marine Fisheries Service & Southwest Regional Office, 2008b). Critical habitat is not designated for this species.

The State of California suspended all forms of harvesting of the white abalone in 1996 and, in 1997, imposed an indefinite moratorium on the harvesting of all abalone in central and southern California (National Marine Fisheries Service & Southwest Regional Office, 2008b). NMFS determined that informing the public of the locations of critical habitat, which includes areas where white abalone still exist, would increase the risk of illegal harvesting of white abalone (National Marine Fisheries Service & Southwest Regional Office, 2008b). Potential habitat may exist between Point Conception, California, and the California/Mexico border, with much of it occurring in the isolated, deep waters off the Channel Islands. In reaction to concerns over the status of white abalone, the White Abalone Restoration Consortium was formed to propagate a captive-reared stock to enhance the depleted wild stock (National Marine Fisheries Service & Southwest Regional Office, 2008b). There is now a captive breeding program at the Bodega Bay Marine Laboratory, University of California Davis, in partnership with several facilities throughout California.

The Navy's INRMP for Naval Auxiliary Landing Field SCI (U.S. Department of the Navy, 2013b) includes specific management mandates for black and white abalone, including conducting periodic island-wide nearshore surveys, multibeam sonar nearshore habitat surveys, and quantification of suitable deep rocky habitats. The Navy cooperates with white abalone co-managers California Department of Fish and Wildlife and NMFS to monitor white abalone populations and habitat at SCI.

In July 2016, the Navy and NMFS entered into a 7-year Memorandum of Agreement to fund projects benefitting white abalone recovery (U.S. Department of the Navy & National Oceanic and Atmospheric Administration, 2016). The activities, which included field and laboratory projects, focused on Tanner and Cortes Banks, but also occurred at SCI and Point Loma. Programs included in the agreement consisted of field surveys and management assessments, development of tagging methods, disease studies, genetic evaluation, and outplanting monitoring. In November 2019, experimental outplanting of white abalone occurred (National Marine Fisheries Service, 2024h). Captive-bred juvenile white abalone were released for the first time into coastal waters off southern California. Since then, additional juveniles have been outplanted and monitored to assess their survival, movements, and growth over time.

Critical Habitat

Critical habitat has not been designated for white abalone.

Recovery Goals

In 2008, NMFS finalized a white abalone recovery plan (National Marine Fisheries Service & Southwest Regional Office, 2008a). The goal of the recovery plan is to increase wild white abalone abundance in California to viable and self-sustaining levels such that the species can be downlisted to threatened status and subsequently removed from the Endangered Species List. NMFS also developed recovery objectives used to describe the conditions necessary to achieve the recovery goal. These objectives include the following:

- Improve our knowledge of the current status of white abalone in the wild so that extinction risks can be estimated, and a plan can be developed for carrying out recovery actions in a way that will most efficiently achieve the delisting criteria.
- Reduce or eliminate existing threats to white abalone in the wild.
- Downlist and eventually delist white abalone by defining a safe population level (i.e., delisting criteria) which includes viable/sustainable subpopulations at a number of locations throughout the former range of the species.

C.3.2.2.2 Habitat and Geographic Range

The white abalone is a well-concealed, sessile, bottom-dwelling species that prefers reefs and rock piles with low relief areas surrounded by sandy areas (Hobday & Tegner, 2000). White abalone in the Southern California Bight typically inhabit depths ranging from about 20 to 60 m, with the highest densities occurring between 40 and 50 m (Butler et al., 2006a). White abalone were found in waters deeper than other west coast abalone species (Hobday et al., 2001). Overall, habitat associations of white abalone depend on its main food sources, drift macroalgae and a variety of red algae (National Oceanic and Atmospheric Administration, 2018b). Thus, depth distribution is limited by water clarity and light penetration as well as by the availability of hard substrate or anchoring points on the bottom (Butler et al., 2006a). Evidence suggests that white abalone prefer the sand and rock interface at the reef's edge, rather than the middle sections of reefs. Sand channels may be important for movement and concentration of drifting fragments of macroalgae and red algae (National Marine Fisheries Service & Southwest Regional Office, 2008b). Postlarval and juvenile individuals often occur in sheltered areas to decrease susceptibility to predation, while adults occur in more open areas.

White abalone were historically found between Point Conception, California, and Punta Abreojos, Baja California, Mexico, at depths as shallow as 5 m (National Marine Fisheries Service & Southwest Regional Office, 2008b). The northern portion of the range includes the San Clemente (Navy-owned) and Santa Catalina Islands in the northeastern corner of the California portion of the HCTT Study Area (Butler et al., 2006a; National Marine Fisheries Service & Southwest Regional Office, 2008b). On the southern end of the range, the species was common around a number of islands, including Isla Cedros and Isla Natividad, Mexico (Hobday & Tegner, 2000). The current range in California appears similar to that of the historical range, although the species occurs in extremely reduced numbers. Information on the current range off Baja California is not available (National Marine Fisheries Service & Southwest Regional Office, 2008b).

Except for some isolated survivors, within the Study Area, the species is largely only distributed around the Channel Islands and along various banks (Behrens & Lafferty, 2005; Butler et al., 2006b; Hobday & Tegner, 2000; Raimondi, 2016; Rogers-Bennett et al., 2002; Stierhoff et al., 2014b). The species is known to occur off SCI, Santa Catalina, and Santa Barbara Islands and at Tanner and Cortes Banks (approximately 50 mi southwest of SCI). Both these banks are underwater mountains that occur off the coast of southern California. One study documented 5 square miles (mi.²) of available white abalone habitat at Tanner Bank, 4 mi.² at Cortes Bank, and 3 mi.² on the western side of SCI (Butler et al., 2006a).

The white abalone diet varies with life history stage. As larvae, white abalone do not actively feed while in the planktonic stage. After settling on suitable substrate, abalone clamp tightly to rocky substrates and feed on algal matter scraped from the rocks or trapped under their shells. Young juveniles feed on bottom-dwelling diatoms, bacterial films, and benthic microflora. As they increase in size and become less vulnerable to predation, abalone leave their sheltered habitat to forage. Adult white abalone feed primarily on drifting fragments and attached macroalgae (National Marine Fisheries Service &

Southwest Regional Office, 2008b). Predators of white abalone include sea otters, fish, sea stars, crabs, spiny lobsters, and octopuses, as well as humans through illegal harvesting (Hobday & Tegner, 2000).

C.3.2.2.3 Population Trends

White abalone were once abundant throughout their range but were more common and abundant along the coast in the northern and southern portions. Since the 1970s, the white abalone population has experienced a 99 percent reduction in density (National Marine Fisheries Service & Southwest Regional Office, 2008b), with an annual decline in the population estimated at 12 percent (Catton et al., 2016). An increase in the size distribution over this same time period suggests individuals in the white abalone population are growing larger (which indicates increased age) with little or no indication of adequate recruitment success (Catton et al., 2016). With a dispersed population of aging individuals, prospects for reproduction, and therefore recruitment, remain low without management intervention, such as outplanting of healthy, captive-bred white abalone in suitable habitat (National Marine Fisheries Service, 2018e; Stierhoff et al., 2012). Captive breeding programs are currently in place to develop white abalone for introduction into the ocean (National Oceanic and Atmospheric Administration, 2018b; University of California Davis, 2017).

Various researchers have conducted submersible surveys off Tanner and Cortes Banks to map abalone habitat structure, examine distribution, and estimate the population size (Butler et al., 2006a; Davis et al., 1998a; Hobday & Tegner, 2000). They recorded 258 animals, with 168 recorded on Tanner Bank in 2002, at depths ranging from 32 to 55 m. In 2004, 35 individuals were recorded at Tanner Bank, 12 at Cortes Bank, and 5 off SCI. The 2012 population estimate of 564 individuals at SCI represented a moderate increase from the estimate of 353 individuals in 2005 (Stierhoff et al., 2014a).

C.3.2.2.4 Population Threats

White abalone face similar threats to those of the black abalone (i.e., historical overharvesting, current low population densities, withering syndrome, competition with urchins and other abalone species for food, and illegal harvest). Low population density and illegal harvest are considered the primary current threats (National Marine Fisheries Service & Southwest Regional Office, 2008b). However, because of the small population of white abalone, impacts on the remaining population are magnified.

C.3.2.3 Sunflower Sea Star (Pycnopodia helianthoides)

C.3.2.3.1 Status and Management

The sunflower sea star (*Pycnopodia helianthoides*) is proposed for listing (as Threatened) under the ESA (88 FR 21600).

C.3.2.3.2 Habitat and Geographic Range

Sunflower sea stars are found throughout the Northeastern Pacific Ocean, from the Aleutian Islands to Baja California (Sakashita, 2021). The large geographic range of sunflower sea star suggests this species is well adapted for a wide variety of environmental conditions and habitat types (Lowry et al., 2022), including kelp forests and rocky intertidal habitats. Sunflower sea stars also occupy a wide range of benthic substrates, including mud, sand, shell, gravel, and rocky bottoms (Konar et al., 2019; Lambert, 2000). They inhabit the low intertidal and subtidal zones to a depth of 435 m (1,427 ft) but are most common at depths less than 25 m (82 ft.) and rare in waters deeper than 120 m (394 ft) (Gravem et al., 2021; Hemery et al., 2016; Lambert, 2000). The sunflower sea star is among the largest sea stars in the world, reaching over 1 m (3 ft.) in total diameter from ray tip to ray tip across the central disk (88 FR 16212). Very few predators are known to consume adult sunflower sea stars (Lowry et al., 2022). Predation risk is likely highest during the planktonic larval phase when indiscriminate filter feeders consume small larvae and selective pickers target larger, more developed individuals. Additionally, while the fecundity of the sunflower sea star is not well known, even conservative estimates suggest that an individual female likely produces millions of eggs in a single spawning event. As such, predation is not likely to substantially contribute to extinction risk, now or in the foreseeable future (Lowry et al., 2022).

The diet of adult sunflower sea stars generally consists of benthic and mobile epibenthic invertebrates, including sea urchins, snails, crab, sea cucumbers, and other sea stars (Mauzey et al., 1968; Shivji et al., 1983), and appears to be driven largely by prey availability.

C.3.2.3.3 Population Trends

The global abundance of sunflower sea star prior to 2013 was estimated at several billion animals, but from 2013 to 2017, sea star wasting syndrome (SSWS) reached pandemic levels, killing an estimated 90 percent of the population (Hamilton et al., 2021; Heady et al., 2022; Lowry et al., 2022). While population impacts varied by region across the range of the species, SSWS generally progressed from south to north and by 2017, sunflower sea stars became rare south of Cape Flattery (Washington), in areas where it had long been a conspicuous and ecologically important component of benthic marine ecosystems (Lowry et al., 2022). Most authors cited above comment that sunflower sea star is functionally extinct (greater than 99.2 percent) in its southern range from Baja Mexico to Washington state.

Within southern California, sunflower sea stars were frequently seen historically at low numbers at all sites during kelp forest monitoring surveys at SNI within the California portion of the HCTT Study Area (Kenner & Tomoleoni, 2021). In 2014, sunflower sea stars disappeared from all kelp forest monitoring sites due to SSWS and have not been observed since (Kenner & Tomoleoni, 2021). In addition, no sunflower sea stars were observed in the 2012–2013 subtidal surveys off SCI (Pondella et al., 2015). During 18 surveys at SCI from 2014 to 2022, no sunflower sea stars were sighted (Navy, unpublished data).

C.3.2.3.4 Population Threats

Species-specific threats to the sunflower sea star largely come from habitat destruction and modification in nearshore areas, overutilization from commercial, artisanal, and recreational fisheries (including bycatch), trade, and disease (Lowry et al., 2022). Disease, specifically SSWS, is the single greatest threat affecting the persistence of *P. helianthoides* now and into the foreseeable future (Lowry et al., 2022).

C.3.2.4 Globiceps Coral (Acropora globiceps)

C.3.2.4.1 Status and Management

Acropora globiceps was listed as threatened under the ESA in 2014 (79 FR 53852) and critical habitat was proposed for this species on November 30, 2023 (88 FR 83644).

C.3.2.4.2 Habitat and Geographic Range

A. globiceps has a relatively broad distribution, occurring in 39 marine ecosystems throughout the world (National Marine Fisheries Service, 2024b). In the U.S., this species occurs in Guam, the Commonwealth

of the Northern Mariana Islands (CNMI), American Samoa, the Pacific Remote Island Area, and the Northwestern Hawaiian Islands.

C.3.2.4.3 Population Trends

Current information indicates that *A. globiceps* has a rangewide relative abundance of uncommon to common and current information suggests that abundances of this species is decreasing across all the ecoregions (National Marine Fisheries Service, 2024b).

C.3.2.4.4 Predator and Prey Interactions

The only known predator on A. globiceps is the crown-of-thorns seastar (79 FR 53852).

C.3.2.4.5 Species-Specific Threats

The threats that contributed to the listing of *A. globiceps* include ocean warming, ocean acidification, disease, fishing, predation, and inadequacy of existing regulatory mechanisms (79 FR 53851). In addition, current information indicates that collection and trade is also impacting the status of the species (National Marine Fisheries Service, 2024b).

C.3.3 Species Not Listed under the Endangered Species Act

C.3.3.1 Foraminifera, Radiolarians, Ciliates (Kingdom Protozoa)

Foraminifera, radiolarians, and ciliates are miniscule singled-celled organisms, sometimes forming colonies of cells, belonging to the kingdom Protozoa (Appeltans et al., 2010; Castro & Huber, 2000b). They are found in the water column and on the bottom of the world's oceans, and while most are microscopic, some species grow to approximately 20 cm (Hayward et al., 2016). In general, the distribution of foraminifera, radiolarians, and ciliates is patchy, occurring in regions with favorable growth conditions.

Foraminifera such as the genus *Globergerina* occur in the waters of the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems. Foraminifera form diverse and intricate shells out of calcium carbonate, organic compounds, or sand or other particles cemented together (University of California Berkeley, 2010c). The shells of foraminifera that live in the water column eventually sink to the bottom, forming soft bottom sediments known as foraminiferan ooze. Foraminifera feed on diatoms and other small organisms. Their predators include copepods and other zooplankton.

Radiolarians are microscopic zooplankton that form shells made of silica. Radiolarian ooze covers large areas of soft bottom habitat on the ocean floor (Pearse et al., 1987; University of California Berkeley, 2010e). Many radiolarian species contain symbiotic dinoflagellates (a type of single-celled organism) or algae. Radiolarians may also trap small particles or other organisms (e.g., diatoms) that drift in the water column.

Ciliates are protozoans with small hair-like extensions that are used for feeding and movement. They are a critical food source for primary consumers and are considered important parasites of many marine invertebrates. Ciliates feed on bacteria and algae, and some species contain symbiotic algae.

C.3.3.2 Sponges (Phylum Porifera)

Sponges include approximately 8,550 marine species worldwide and are classified in the Phylum Porifera (Van Soest et al., 2012; World Register of Marine Species Editorial Board, 2015). Sponges are bottom-dwelling, multicellular animals that can be best described as an aggregation of cells that perform different functions. Sponges are largely sessile, and are common throughout the Study Area at

all depths. Sponges are typically found on mixed bottoms (unconsolidated substrate that is mostly gravel or cobble-sized) to hard bottoms, artificial structures, and biotic reefs. Sponges reproduce both sexually and asexually. Water flow through the sponge provides food and oxygen, and removes wastes (Pearse et al., 1987; University of California Berkeley, 2010a). This filtering process is an important coupler of processes and ecological function that occur in the water column and on the bottom (Pawlik & McMurray, 2020; Perea-Blázquez et al., 2012). Many sponges form calcium carbonate or silica spicules or bodies embedded in cells to provide structural support (Castro & Huber, 2000b; Van Soest et al., 2012). Sponges provide homes for a variety of animals including shrimp, crabs, barnacles, worms, brittle stars, sea cucumbers, and other sponges (Colin & Arneson, 1995b). Common native species in the Insular Pacific-Hawaiian Large Marine Ecosystem include lobate sponge (*Suberites zeteki*) and *Spongia oceania* (De Laubenfels, 1950, 1951), although some introduced species have become widespread as well. Sponges in the genera *Farrea, Hyalonema*, and *Suberites* occur in the waters of the California Current Large Marine Ecosystem (Clarke et al., 2015). Some sponge species are harvested commercially.

C.3.3.3 Corals, Hydroids, Jellyfish (Phylum Cnidaria)

There are over 10,000 marine species within the phylum Cnidaria worldwide (World Register of Marine Species Editorial Board, 2015), although there is taxonomic uncertainty within some groups (Veron, 2013). Cnidarians are organized into four classes: Anthozoa (corals, sea anemones, sea pens, sea pansies), Hydrozoa (hydroids and hydromedusae), Scyphozoa (true jellyfish), and Cubozoa (box jellyfish, sea wasps). Individuals are characterized by a simple digestive cavity with an exterior mouth surrounded by tentacles. Microscopic stinging capsules known as nematocysts are present (especially in the tentacles) in all cnidarians and are a defining characteristic of the phylum. The majority of species are carnivores that eat zooplankton, small invertebrates, and fishes. However, many species feed on plankton and dissolved organic matter, or contain symbiotic dinoflagellate algae (zooxanthellae) that produce nutrients by photosynthesis (Brusca & Brusca, 2003b; Dubinsky & Berman-Frank, 2001; Lough & van Oppen, 2009; National Oceanic and Atmospheric Administration & NOAA's Coral Reef Conservation Program, 2016). Representative predators of cnidarians include sea slugs, snails, crabs, sea stars, coral-and jellyfish-eating fish, and marine turtles. Cnidarians may be solitary or may form colonies.

Cnidarians have many diverse body shapes, but may generally be categorized as one of two basic forms: polyp and medusa. The polyp form is tubular and sessile, attached at one end with the mouth surrounded by tentacles at the free end. Corals and sea anemones are examples of the polyp form. The medusa form is bell- or umbrella-shaped (e.g., jellyfish), with tentacles typically around the rim. The medusa form generally is pelagic, although there are exceptions. Many species alternate between these two forms during their life cycle. All cnidarian species are capable of sexual reproduction, and many cnidarians also reproduce asexually. The free-swimming larval stage is usually planktonic, but is benthic in some species.

A wide variety of cnidarian species occur throughout the Study Area at all depths and in most habitats, including hard and mixed shores; soft, mixed, and hard bottom; aquatic vegetation beds; and artificial substrates. Some cnidarians form biotic habitats that harbor other animals and influence ecological processes, the primary examples being shallow-water and deep-water stony corals. In this section, corals are discussed in terms of individual coral polyps or early life stages, where "coral" is defined as follows: Species of the phylum Cnidaria, including all species of the orders Antipatharia (black corals), Scleractinia (stony corals), Gorgonacea (horny corals), Stolonifera (organ pipe corals and others), Alcyonacea (soft corals), and Helioporacea (blue coral) of the class Anthozoa; and all species of the families Milleporidea (fire corals) and Stylastreridae (*stylasterid hydrocorals*) of the class Hydrozoa.

Precious corals are non-reef building and inhabit depth zones below the euphotic zone. They are found on solid substrate in areas that are swept relatively clean by moderate-to-strong (greater than 25 cm/second) bottom currents. Precious corals may be divided into deep- and shallow-water species. Deep-water precious corals are generally found between 350 and 1,500 m and include pink coral (*Corallium secundum*), gold coral (*Gerardia* spp. and *Parazoanthus* spp.), and bamboo coral (*Lepidisis olapa*). Shallow water species occur between 30 and 100 m and consist primarily of three species of black coral: *Antipathes dichotoma*, *Antipathes grandis*, and *Antipathes ulex*.

Corals occur throughout the Hawaiian Archipelago. Approximately 250 species of corals are found in the region, including 59 scleractinian stony corals, 137 species of octocorals, 14 genera of black coral, 12 species of soft coral, and 4 species of stylasterid hydrocorals (Maragos et al., 2004). Dominant coral species in the Main Hawaiian Islands include *M. capitata*, *M. flabellata*, *M. patula*, *P. meandrina*, *P. compressa*, *P. lobata*, and *P. varians* (Franklin et al., 2013; Friedlander et al., 2008b). Common scleractinian corals of mesophotic reefs (Spalding et al., 2019) include several species of the genus *Leptoseris* (Kahng & Maragos, 2006). Coral coverage is generally highest in the southern portion of the archipelago (Friedlander et al., 2008b). However, more species of stony corals have been documented in the Northwestern Hawaiian Islands (57) than in the Main Hawaiian Islands (50) (Friedlander et al., 2008b; Jokiel, 2008).

Although corals in temperate waters are not reef-building, the corals provide vertical relief and habitat that supports many organisms. For example, a single dead colony of Christmas tree black coral (*Antipathes dendrochristos*) observed by submersible off southern California was colonized by over 2,500 individual invertebrates, including other cnidarians (sea anemones and corals), crustaceans, echinoderms, molluscs, and polychaete worms (Love et al., 2007). Surveys using trawls, submersibles, and remotely operated vehicles conducted on outer continental shelf bank and rock outcrops off southern California have documented numerous coral species, including scleractinian stony corals, antipatharian black corals, gorgonian octocorals (sea fans), alcyonacean soft corals, pennatulacean octocorals (sea pens), and stylasterine hydrocoral (Etnoyer & Morgan, 2003; Whitmire & Clarke, 2007; Yoklavich et al., 2013).

Corals that are associated with tropical shallow reefs and temperate rocky habitats are vulnerable to a range of threats, including fishing impacts, pollution, erosion/sedimentation, coral harvesting, vessel damage, temperature increase, and climate change. Fishing practices such as blast fishing and trapping may be particularly destructive to coral reefs. In addition, removal of herbivorous fishes may result in overgrowth of coral reefs by algae (DeMartini & Smith, 2015). Because corals are slow growing and can survive for hundreds of years (Love et al., 2007; Roberts & Hirshfield, 2003), recovery from damage could take many years. Corals that occur in association with shallow-water coral reefs are protected by Executive Order [EO] 13089, *Coral Reef Protection*, and managed by the Coral Reef Task Force (EO 13089, *Coral Reef Protection*, 63 *FR* 32701–32703 [June 16, 1998]). The Navy is the DoD representative to the U.S. Coral Reef Task Force and also carries out the Coral Reef Protection Implementation Plan (Lobel & Lobel, 2000).

Deep-water corals are azooxanthellate (lack symbiotic algae) and thus do not form consolidated biogenic substrate, but rather form mounds of mixed substrate over hard bottom areas. Deep-water coral taxa in the Study Area consist primarily of hexacorals (stony corals, black corals, and gold corals), octocorals (e.g., true soft corals, gorgonians, sea pens), and hydrocorals (e.g., lace corals) (Hourigan et al., 2017a). Deep-water corals are widely distributed throughout the U.S. Pacific Island region, including the Hawaiian Archipelago (Parrish et al., 2015b; Parrish et al., 2022). In general, deep corals in the

Hawaii region do not form the extensive three-dimensional reef structures observed in the Atlantic and South Pacific. Octocorals and antipatharians (black corals) have been found in high densities at numerous sites, particularly on topographically high areas. Deep-sea coral communities are prevalent throughout the entire Hawaiian Archipelago (Etnoyer & Morgan, 2003) and have been found at all depths investigated (maximum of about 1,800 m) where suitable substrate exists (Baco, 2007). Approximately 200 species of deep corals (octocorals, antipatharians, and zoanthids) have been found in the Hawaiian Archipelago region (Parrish & Baco, 2007; Parrish et al., 2015a). Precious corals, black corals, and various octocoral species appear to be the most numerous deep-water corals at depths less than about 600 m, while octocorals dominate below 600 m (Parrish et al., 2015a). Study results indicate that stony corals are relatively rare at all depths and that most species are solitary (non-colonial). Gorgonians are the most common group of deep-sea corals in the Hawaiian Islands.

Most of the habitat-forming deep-sea corals in the California portion of the Study Area are anthozoans and hydrozoans (Etnoyer & Morgan, 2003; Etnoyer & Morgan, 2005). Deep-water corals have been documented throughout the SOCAL Bight (generally considered to be the area between Point Conception and San Diego, California), although the corals appear to be more restricted in the region near San Diego. Deep-water areas off the California coast, including the Channel Islands National Marine Sanctuary, support numerous corals such as sea fans (gorgonians), Lophelia pertusa, scleractinians such as the cup coral Caryophyllia arnoldi, and black corals (National Oceanic and Atmospheric Administration Fisheries & Southwest Fisheries Science Center, 2010; Whitmire & Clarke, 2007). At least 26 taxa of deep corals were recorded at a site within the Channel Islands sanctuary (Clarke et al., 2015). Large populations of hydrocorals occur at Tanner, Cortes, and Farnsworth Banks, offshore of southern California (Southern California Marine Institute, 2016). Much of the rocky area of Farnsworth Bank to depths of 66 m was found to be covered by the hydrocoral Stylaster californicus (Clarke et al., 2015). Surveys of a rocky bank south of Anacapa Island (depths of 97 to 314 m) found gorgonians and the black coral A. dendrochristos to be relatively abundant. Additional surveys of a nearby bank at depths of 275 to 900 m documented numerous corals, primarily including A. dendrochristos, the soft mushroom coral Heteropolypus ritteri, several sea fan species, L. pertusa, the cup coral Desmophyllum dianthus, and the sea pen Halipteris californica (on soft sediment only). Numerous species, including gold coral species, have been documented during various other surveys of banks off southern California.

The greatest threat to deep-water coral is physical strike and disturbance resulting from human activities. Deep corals are susceptible to physical disturbance due to the branching and fragile growth form of some species, slow growth rate (colonies can be hundreds of years old), and low reproduction and recruitment rates. Fishing activities, particularly trawling, are the primary threats to deep corals (Boland et al., 2016; Hourigan et al., 2017b; Packer et al., 2017; Rooper et al., 2016; Yoklavich et al., 2017). Marine debris is also a potential threat. For example, during one study in the Atlantic Ocean, a fishing trap, fishing line, balloon remnants, and ribbon was observed either lying on or wrapped around deep-sea corals located off the northeastern U.S. (Quattrini et al., 2015). Other potential human-caused threats to deep-water corals include coral harvesting (e.g., black corals), hydrocarbon exploration and extraction, cable and pipeline installation, and other bottom-disturbing activities (Boland et al., 2016; Clarke et al., 2015; Parrish et al., 2015a). Natural threats consist of sedimentation and bioerosion of the substrate.

C.3.3.4 Flatworms (Phylum Platyhelminthes)

Flatworms include between 12,000 and 20,000 marine species worldwide (World Register of Marine Species Editorial Board, 2015) and are the simplest form of marine worm (Castro & Huber, 2000b). The largest single group of flatworms are parasites commonly found in fishes, seabirds, and marine

mammals (Castro & Huber, 2000b; University of California Berkeley, 2010d). The life history of parasitic flatworms plays a role in the regulation of populations of the marine vertebrates they inhabit. Ingestion by the host organism is the primary dispersal method for parasitic flatworms. Parasitic forms are not typically found in the water column outside of a host organism. The remaining groups are non-parasitic carnivores, living without a host. Flatworms are found throughout the Study Area living on rocks in tide pools and reefs, or within the top layer of sandy areas. Dominant genera of flatworms in the Insular Pacific-Hawaiian Large Marine Ecosystem include *Pseudobiceros* and *Pseudoceros*. Flatworms in the genera *Waminoa* and *Freemania* occur in the waters around the California Current Large Marine Ecosystems. Several species of wrasses and other reef fish prey on flatworms (Castro & Huber, 2000a, 2000b).

C.3.3.5 Ribbon Worms (Phylum Nemertea)

Ribbon worms include over 1,300 marine species worldwide (World Register of Marine Species Editorial Board, 2015). Ribbon worms, with their distinct gut and mouth parts, are more complex than flatworms (Castro & Huber, 2000b). A unique feature of ribbon worms is the extendable proboscis (an elongated, tubular mouth part), which can be ejected to capture prey, to aid in movement, or for defense (Brusca & Brusca, 2003b). Most ribbon worms are active, bottom-dwelling predators of small invertebrates such as annelid worms and crustaceans (Brusca & Brusca, 2003b; Castro & Huber, 2000b). Some are scavengers or symbiotic (parasites or commensals). Some ribbon worms are pelagic, with approximately 100 pelagic species identified from all oceans (Roe & Norenburg, 1999). Pelagic species generally drift or slowly swim by undulating the body. Ribbon worms exhibit a variety of reproductive strategies, including direct development with juveniles hatching from egg cases and indirect development from planktonic larvae (Brusca & Brusca, 2003b). In addition, many species are capable of asexual budding or regeneration from body fragments. Ribbon worms have a relatively small number of predators, including some birds, fishes, crabs, molluscs, squid, and other ribbon worms (McDermott, 2001). Ribbon worms are found throughout the Study Area. They occur in most marine environments, although usually in low abundances. They occur in embayments; soft, mixed, and rocky shores and subtidal habitats of coastal waters; and deep-sea habitats. Some are associated with biotic habitats such as mussel clumps, coral reefs, kelp holdfasts, seagrass beds, and worm burrows (Thiel & Kruse, 2001). Approximately 10 species of ribbon worms from the classes Anopla and Enopla are known from Hawaii (Hawaiisfishes, 2017), and a total of 64 species have been identified in intertidal habitats of California (Bernhardt, 1979).

C.3.3.6 Round Worms (Phylum Nematoda)

Round worms include over 7,000 marine species (World Register of Marine Species Editorial Board, 2015). Round worms are small and cylindrical, abundant in sediment habitats such as soft to mixed shores and soft to mixed bottoms, and also found in host organisms as parasites (Castro & Huber, 2000b). Round worms are some of the most widespread marine invertebrates, with population densities of up to 1 million or more organisms per square meter of sediment (Levinton, 2009a). This group has a variety of food preferences, including algae, small invertebrates, annelid worms, and organic material from sediment. Like parasitic flatworms, parasitic nematodes play a role in regulating populations of other marine organisms by causing illness or mortality. Species in the family Anisakidae infect marine fish, and may cause illness in humans if fish are consumed raw without proper precautions (Castro & Huber, 2000b). Round worms are found throughout the Study Area.

C.3.3.7 Segmented Worms (Phylum Annelida)

Segmented worms include approximately 14,000 currently accepted marine species worldwide in the phylum Annelida, although the number of potentially identified marine species is nearly 25,000 (World Register of Marine Species Editorial Board, 2015). Most marine annelids are in the class Polychaeta. Polychaetes are the most complex group of marine worms, with a well-developed respiratory and gastrointestinal system (Castro & Huber, 2000b). Different species of segmented worms may be highly mobile or burrow in the bottom (soft to mixed shore or bottom habitats) (Castro & Huber, 2000b). Polychaete worms exhibit a variety of life styles and feeding strategies, and may be predators, scavengers, deposit-feeders, filter-feeders, or suspension feeders (Jumars et al., 2015). The variety of feeding strategies and close connection to the bottom make annelids an integral part of the marine food web (Levinton, 2009a). Burrowing and agitating the sediment increases the oxygen content of bottom sediments and makes important buried nutrients available to other organisms. This allows bacteria and other organisms, which are also an important part of the food web, to flourish on the bottom. Benthic polychaetes also vary in their mobility, including sessile attached or tube-dwelling worms, sediment burrowing worms, and mobile surface or subsurface worms. Some polychaetes are commensal or parasitic. Many polychaetes have planktonic larvae.

Polychaetes are found throughout the Study Area inhabiting rocky, sandy, and muddy areas of the bottom, vegetated habitats, and artificial substrates. Some are associated with biotic habitats such as mussel clumps, coral reefs, and worm burrows. Some species of worms build rigid (e.g., *Diopatra* spp.) or sand-encrusted (*Phragmatapoma* spp.) tubes, and aggregations of these tubes form a structural habitat. Giant tube worms (*Riftia pachyptila*) are chemosynthetic (using a primary production process without sunlight) reef-forming worms living on hydrothermal vents of the abyssal oceans. Their distribution is poorly known in the Study Area. A total of 20 taxa of annelid worms were documented at intertidal locations of Oahu, compared to 71 taxa in central California (Zabin et al., 2013).

C.3.3.8 Bryozoans (Phylum Bryozoa)

Bryozoans include approximately 6,000 marine species worldwide (World Register of Marine Species Editorial Board, 2015). They are small box-like, colony-forming animals that make up the "lace corals." Colonies can be encrusting, branching, or free-living. Bryozoans may form habitat similar in complexity to sponges (Buhl-Mortensen et al., 2010). Bryozoans attach to a variety of surfaces, including mixed and hard bottom, artificial structures, and algae, and feed on particles suspended in the water (Hoover, 1998b; Pearse et al., 1987; University of California Berkeley, 2010b). Bryozoans are of economic importance for bioprospecting (the search for organisms for potential commercial use in pharmaceuticals). As common biofouling organisms, bryozoans also interfere with boat operations and clog industrial water intakes and conduits (Hoover, 1998b; Western Pacific Regional Fishery Management Council, 2001). Bryozoans occur throughout the Study Area but are not expected at depths beyond the continental slope (Ryland & Hayward, 1991). Habitat-forming species are most common on temperate continental shelves with relatively strong currents (Wood et al., 2012). Common species in the Insular Pacific-Hawaiian Large Marine Ecosystem are violet encrusting bryozoan (Disporella violacea) and lace bryozoan (Reteporellina denticulata). Species that occur in the California Current Large Marine Ecosystem include arborescent bryozoans of the genus Bugula and encrusting bryozoans of the genus Schizoporella.

C.3.3.9 Squid, Bivalves, Sea Snails, Chitons (Phylum Mollusca)

The phylum Mollusca includes approximately 45,000 marine species worldwide (World Register of Marine Species Editorial Board, 2015). These organisms occur throughout the Study Area, including open ocean areas, at all depths. Sea snails and slugs (gastropods), clams and mussels (bivalves), chitons (polyplacophorans), and octopus and squid (cephalopods) are examples of common molluscs in the Study Area. Snails and slugs occur in a variety of soft, mixed, hard, and biogenic habitats. Chitons are typically found on hard bottom and artificial structures from the intertidal to littoral zone but may also be found in deeper water and on substrates such as aquatic plants. Many molluscs possess a muscular organ called a foot, which is used for mobility. Many molluscs also secrete an external shell (Castro & Huber, 2000b), although some molluscs have an internal shell or no shell at all (National Oceanic and Atmospheric Administration Fisheries, 2015). Sea snails and slugs eat fleshy algae and a variety of invertebrates, including hydroids, sponges, sea urchins, worms, other snails, and small crustaceans, as well as detritus (Castro & Huber, 2000b; Colin & Arneson, 1995a; Hoover, 1998b). Clams, mussels, and other bivalves are filter feeders, ingesting suspended food particles (e.g., phytoplankton, detritus) (Castro & Huber, 2000b). Chitons, sea snails, and slugs use rasping tongues, known as radula, to scrape food (e.g., algae) off rocks or other hard surfaces (Castro & Huber, 2000b; Colin & Arneson, 1995a). Squid and octopus are active swimmers at all depths and use a beak to prey on a variety of organisms including fish, shrimp, and other invertebrates (Castro & Huber, 2000b; Hoover, 1998b; Western Pacific Regional Fishery Management Council, 2001). Octopuses mostly prey on fish, shrimp, eels, and crabs (Wood & Day, 2005).

Important commercial, ecological, and recreational species of molluscs in the Insular Pacific-Hawaiian Large Marine Ecosystem include: various species of squid, the endemic cuttlefish (*Euprymna scolopes*), bivalves (clams and mussels), and limpets (*Cellana exarata* and *Cellana sandwicensis*) (Western Pacific Regional Fishery Management Council, 2001). Important commercial, ecological, and recreational species of molluscs in the California Current Large Marine Ecosystem include multiple abalone species, California market squid (*Doryteuthis opalescens*) (Clark et al., 2005), keyhole limpet (*Megathura crenulata*), Kellet's whelk (*Kelletia kelletia*), various species of octopus, sea hare (*Aplysia* spp.), snails (*Lithopoma undosum, Tegula* spp.), and Pismo clam (*Tivela stultorum*). Only one species of abalone, the red abalone (*Haliotis rufescens*), is currently fished recreationally, north of San Francisco County. The abalone fishery is closed to all commercial fishing. Black abalone and white abalone are listed under the ESA, while the green abalone (*Haliotis fulgens*) and pink abalone (*Haliotis corrugata*) are designated as species of concern.

C.3.3.10 Shrimp, Crab, Lobster, Barnacles, Copepods (Phylum Arthropoda)

Shrimp, crabs, lobsters, barnacles, and copepods are animals with an exoskeleton, which is a skeleton on the outside of the body (Castro & Huber, 2000b), and are classified as crustaceans in the Phylum Arthropoda. The exoskeletons are made of a polymer called chitin, similar to cellulose in plants, to which the animals add other compounds to achieve flexibility or hardness. There are over 57,000 marine arthropod species, with about 53,000 of these belonging to the subphylum Crustacea (World Register of Marine Species Editorial Board, 2015). These organisms occur throughout the Study Area at all depths. Crustaceans may be carnivores, omnivores, predators, or scavengers, preying on molluscs (primarily gastropods), other crustaceans, echinoderms, small fishes, algae, and seagrass (Waikiki Aquarium, 2009a, 2009b, 2009c; Western Pacific Regional Fishery Management Council, 2009). Barnacles and some copepods are filter feeders, extracting algae and small organisms from the water (Levinton, 2009a). Copepods may also be parasitic, affecting most phyla of marine animals (Walter & Boxshall, 2017). As a group, arthropods occur in a wide variety of habitats. Shrimp, crabs, lobsters, and copepods may be associated with soft to hard substrates, artificial structures, and biogenic habitats. Barnacles inhabit hard and artificial substrates.

Important commercial, ecological, and recreational species of Crustacea in the Hawaii Study Area include several lobster species from the taxonomic groups Palinuridae (spiny lobsters) and Scyllaridae (slipper lobsters) (Western Pacific Regional Fishery Management Council, 2009). Lobsters occur primarily within the subtidal zone, although their range can extend slightly deeper. Most species occur throughout the tropical oceans of the world, while the endemic Hawaiian spiny lobster is found only in Hawaii and Johnston Atoll (Polovina et al., 1999). Important commercial, ecological, and recreational species of Crustacea in the California Current Large Marine Ecosystem include the spot shrimp (*Pandalus platyceros*), ridgeback rock shrimp (*Sicyonia ingentis*), rock crab (*Cancer* species), sheep crab (*Loxorhynchus grandis*), and California spiny lobster (Clark et al., 2005).

C.3.3.11 Sea Stars, Sea Urchins, Sea Cucumbers (Phylum Echinodermata)

Organisms in this phylum include over 7,000 marine species, such as sea stars, sea urchins, and sea cucumbers (World Register of Marine Species Editorial Board, 2015). Asteroids (e.g., sea stars), echinoids (e.g., sea urchins), holothuroids (e.g., sea cucumbers), ophiuroids (e.g., brittle stars and basket stars), and crinoids (e.g., feather stars and sea lilies) are symmetrical around the center axis of the body (Mah & Blake, 2012). Echinoderms occur at all depth ranges from the intertidal zone to the abyssal zone and are almost exclusively benthic, potentially found on all substrates and structures. Most echinoderms have separate sexes, but a few species of sea stars, sea cucumbers, and brittle stars have both male and female reproductive structures. Many species have external fertilization, releasing gametes into the water to produce planktonic larvae, but some brood their eggs and release free-swimming larvae (Mah & Blake, 2012; McMurray et al., 2012). Many echinoderms are either scavengers or predators on sessile organisms such as algae, stony corals, sponges, clams, and oysters. Some species, however, filter food particles from sand, mud, or water (Hoover, 1998a). Predators of echinoderms include a variety of fish species (e.g., triggerfish, eels, rays, sharks), crabs, shrimps, octopuses, birds, and other echinoderms (sea stars).

Echinoderms are found throughout the Study Area. Important commercial, ecological, and recreational species in the Insular Pacific-Hawaiian Large Marine Ecosystem include helmet urchin (*Colobocentrotus atratus*), burrowing sea urchin (*Echinometra mathaei*), sea cucumbers, and sea stars. The crown-of-thorns sea star (*Acanthaster planci*) is a carnivorous predator that feeds on coral polyps and can devastate coral reefs. In 1969, crown-of-thorns sea stars infested reefs off southern Molokai but did not cause extensive damage to living coral polyps of cauliflower coral (Gulko, 1998; Hoover, 1998b). Important commercial, ecological, and recreational species of echinoderms in the California Current Large Marine Ecosystem include California sea cucumbers (*Parastichopus californicus*), sea stars (*Pisaster* spp.), red sea urchin (*Strongylocentrotus franciscanus*), and purple sea urchin (*S. purpuratus*) (Clark et al., 2005). Beginning in 2013, large numbers of sea stars have died along the west coast of North America due to sea-star wasting disease (Hewson et al., 2014; Miner et al., 2018). The virus causing the disease has also been found in sea urchins and sea cucumbers, although mass die-offs have not been documented for these taxa.

C.4 Habitats

C.4.1 General Background

Abiotic marine habitats vary according to geographic location, underlying geology, hydrodynamics, atmospheric conditions, and suspended particles and associated biogenic features. Sediments may be derived from material eroded from land sources associated with coastal bluff erosion and sediment flows from creeks and rivers, which may create channels, tidal deltas, intertidal and subtidal flats, and shoals of unconsolidated material along the shorelines and estuaries. Sediments derived from volcanic rock are common in the Hawaiian Islands and occur in localized areas of southern California (i.e., SCI) within the Study Area. In the Hawaiian Islands, nearshore sediments also are derived from living sources (i.e., corals).

The influence of land-based nutrients on habitat type and sediment increases with proximity to streams, bays and harbors, and nearshore waters. In the open ocean, gyres, eddies, and oceanic currents influence the distribution of organisms. Major bottom features in the offshore areas of the range complexes include shelves, banks, breaks, slopes, canyons, plains, and seamounts. Geologic features such as these affect the hydrodynamics of the ocean water column (i.e., currents, gyres, upwellings) as well as living resources present.

C.4.1.1 Shore Habitats

C.4.1.1.1 Description

C.4.1.1.1.1 Soft Shores

Soft shores include all aquatic habitats that have three characteristics: (1) unconsolidated substrates with less than 25 percent areal cover of stones, boulders, or bedrock, (2) unconsolidated sediment composed of predominantly sand or mud, and (3) primarily intertidal water regimes (Cowardin et al., 1979). Note that a shoreline covered in vegetation (e.g., marsh) could still have a soft substrate foundation. Soft shores include beaches, tidal flats/deltas, and streambeds of the tidal riverine and estuarine systems.

Intermittent or intertidal channels of the riverine system and intertidal channels of the estuarine system are classified as streambed. Intertidal flats, also known as tidal flats or mudflats, consist of loose mud, silt, and fine sand with organic-mineral mixtures that are regularly exposed and flooded by the tides (Karleskint et al., 2006). Muddy and fine sediment tends to be deposited where wave energy is low, such as in sheltered bays and estuaries (Holland & Elmore, 2008). Mudflats are typically unvegetated, but may be covered with encrusting microscopic algae (e.g., diatoms) or sparsely vegetated with low-growing aquatic plants (e.g., macroalgae/seaweed, seagrass). Muddy intertidal habitat occurs most often as part of a patchwork of intertidal habitats that may include rocky shores, tidal creeks, sandy beaches, salt marshes, and mangroves. A flat area of unconsolidated sediment that is covered in aquatic plants could be considered an aquatic bed growing on soft shore habitat. While river deltas are created by soil deposits forming from the outflow of the water, such as at the mouth of the Mississippi River, tidal deltas are depositions of sediment left by the diurnal tides and their resulting currents. Therefore, tidal (or tide-dominated) deltas typically occur in locations of large tidal ranges or high tidal current speeds (SEPM Strata, 2018).

Beaches form through the interaction of waves and tides, as particles are sorted by size and are deposited along the shoreline (Karleskint et al., 2006). Wide flat beaches with fine-grained sands occur where wave energy is limited. Narrow steep beaches of coarser sand form where energy and tidal

ranges are high (Speybroeck et al., 2008). Three zones characterize beach habitats: (1) dry areas above the MHW, (2) wrack lines (the area where seaweed and debris is deposited at high tide) and (3) a highenergy intertidal zone (area between high and low tide).

C.4.1.1.1.2 Mixed Shores

Mixed shores include all aquatic habitats with the following three characteristics: (1) substrates with at least 25 percent cover in particles smaller than stones, (2) unconsolidated substrate is predominantly gravel or cobble-sized, and (3) primarily intertidal water regimes. These areas may or may not be stable enough for attached vegetation or invertebrates, depending on overlying hydrology and water quality. Note that a shoreline with vegetation (e.g., macroalgae, seagrass) could still have a mixed substrate foundation. Hard corals may grow in these habitats in the Hawaiian Islands.

C.4.1.1.1.3 Hard Shores

Rocky shores include intertidal aquatic habitats characterized by bedrock, stones, and/or boulders that cover 75 percent or more of an area (Cowardin et al., 1979). Note that a shoreline covered in vegetation could still have a hard substrate foundation. Rocky intertidal shores are areas of bedrock occupying the area between high and low tide lines (Menge & Branch, 2001). Extensive rocky shorelines can be interspersed with sandy areas, estuaries, or river mouths.

Environmental gradients between hard shorelines and subtidal habitats are determined by wave action, depth, frequency of tidal inundation, and stability of substrate (Cowardin et al., 1979). Where wave energy is extreme, only rock outcrops may persist. In lower energy areas, a mixture of rock sizes will occur in the intertidal zone. Intertidal rocky shores provide substrate for attached macroalgae and sessile invertebrates.

C.4.1.1.2 Distribution

C.4.1.1.2.1 Soft Shores

Tidal flats occur on a variety of scales in virtually all estuaries and bays in the Hawaii and California Study Areas. In the Hawaiian portion of the Study Area, beaches are common along the lagoon reaches of atoll islets, along the coasts, and in embayment's of the main and Northwestern Hawaiian Islands. Significant sandy beach habitat occurs primarily on the western and southern sides of the islands (Maragos, 2000). About 82 percent of Southern California's coastline is sandy beach habitat (Allen & Pondella, 2006). The California Study Area has extensive beaches, although few stretches are undisturbed by human activity (U.S. Department of Commerce et al., 2008).

C.4.1.1.2.2 Mixed Shores

In the Hawaii Study Area, mixed intertidal habitat, including unconsolidated limestone and volcanic rock, occurs throughout the Hawaiian Islands in localized areas, typically near hard shorelines where physical conditions prevent sand from accumulating (Maragos, 2000). Mixed intertidal habitats occur on the Channel Islands and along the mainland within the Study Area. The majority of mixed shores occur in transitional areas between hard shores and soft shores. Mixed shorelines also may occur at beaches where hard substrate underlies sand and rocks become exposed during periods of shoreline erosion (e.g., several beaches in San Diego County).

C.4.1.1.2.3 Hard Shores

In the Hawaii Study Area, rocky intertidal habitat including limestone and volcanic rock occurs throughout the Hawaiian Islands in localized areas wherever physical conditions prevent sand from

accumulating (Maragos, 2000). In the Southern California portion of the Study Area, rocky intertidal habitat is most extensive on the offshore Channel Islands. Hard shores are localized in distribution along the mainland of southern California. In numerous locations within the HCTT Study Area, artificial hard substrates (e.g., rock riprap, seawalls) have been placed to reduce storm damage and erosion along shorelines and in estuaries.

C.4.1.2 Artificial Structures

C.4.1.2.1 Distribution

Offshore artificial structures in the Hawaii Study Area include shipwrecks, sunken military vessels and aircraft, and artificial reefs. Shipwrecks located near the Island of Hawaii are concentrated along its northwestern coast and within Hilo Bay. Well-documented examples of the numerous submerged structures in the waters surrounding Oahu include the largely intact Sea Tiger, a World War II-era Japanese midget submarine; *Mahi*, a Navy minesweeper/cable layer scuttled off the Waianae Coast; and the YO-257, a Navy yard oiler built in the 1940s that was intentionally sunk off Waikiki in 1989 to create an artificial reef. Major sunken vessels in Pearl Harbor include the USS ARIZONA, the USS UTAH, and the USS BOWFIN, which are listed in the National Register of Historic Places. There may be as many as 60 vessels known lost among the atolls and at least 67 naval aircraft sunk in the Northwestern Hawaiian Islands (National Oceanic and Atmospheric Administration, 2017b). At least 14 ships have run aground in the Northwestern Hawaiian Islands since 1957 (Friedlander et al., 2009).

Most artificial structures in the California Study Area include shipwrecks and artificial reefs. A prominent artificial structure area offshore San Diego County, known as Wreck Alley, includes several types of structures, including six vessels (*El Rey, Ruby E., Shooter's Fantasy, Strider, Yukon,* and a barge), a P-38 aircraft, old Naval Ocean Systems Center tower, and dumped bridge and roadway materials (California Wreck Divers, 2017). The largest artificial reef in the Study Area was built offshore San Clemente; the Wheeler North Artificial Reef mostly consists of boulder-sized quarry rock deposited in a module design that covers a 174-acre area (Reed et al., 2010). Most artificial reefs in marine waters have been placed and monitored by individual state programs.

C.5 Fishes

C.5.1 General Background

Marine fishes can be broadly categorized by their distributions within the water column or habitat usage. Moyle and Cech (2004) define the major marine habitat categories as estuaries, coastal habitats, reefs, the epipelagic zone, the deep sea, and the Polar regions. In the Study Area, the major habitat categories include all the aforementioned except the Polar regions. Many marine fishes that occur in the Study Area are either demersal species (i.e., close to the seafloor) associated with nearshore coastal reefs, or are more oceanic and live in surface waters (pelagic) further offshore (Schwartz, 1989). The highest number and diversity of fishes typically occur where the habitat has structural complexity (reef systems, continental slopes, deep canyons), biological productivity (areas of nutrient upwelling), and a variety of physical and chemical conditions (water flow, nutrients, DO, and temperature) (Bergstad et al., 2008; Helfman et al., 2009; Moyle & Cech, 2004; Parin, 1984; Pyle et al., 2019). Some of the marine fishes that occur in the coastal zone migrate between marine and freshwater habitats (Helfman et al., 2009). Other distribution factors, including predator/prey relationships, water quality, and refuge (e.g., physical structure or vegetation cover) operate, on more regional or local spatial scales (Reshetiloff, 2004). Also, fishes may move among habitats throughout their lives based on changing needs during different life stages (Schwartz, 1989).

Some fish species in the U.S. are protected under the ESA and are managed by either the U.S. Fish and Wildlife Service (USFWS) or NMFS. The recreational and commercial fisheries are managed within a framework of overlapping international, federal, state, interstate, and tribal authorities. Individual states and territories generally have jurisdiction over managed fisheries located in marine waters within 3 NM of their coast. Federal jurisdiction includes managed fisheries in marine waters inside the U.S. EEZ. The area stretches from the outer boundary of state waters out to 200 NM offshore of any U.S. coastline, except where intersected closer than 200 NM by bordering countries.

The Magnuson-Stevens Fishery Conservation and Management Act and Sustainable Fisheries Act led to the formation of eight regional fishery management councils that coordinate with NMFS to manage and conserve certain fisheries in federal waters. Together with NMFS, the councils maintain fishery management plans for species or species groups comprised of fish, invertebrates, and vegetation to regulate commercial and recreational harvest within their geographic regions. The Study Area overlaps with the jurisdiction of two regional fishery management councils, as well as the range of the highly migratory species (e.g., sharks, billfishes, swordfish, and tunas), which are managed directly by NMFS.

- The Western Pacific Regional Fishery Management Council includes Hawaii, American Samoa, Guam, and the Northern Mariana Islands.
- The Pacific Fishery Management Council includes Washington, Oregon, and California.
- **NMFS, Office of Sustainable Fisheries** includes all federally managed waters of the U.S. where highly migratory species occur.

C.5.1.1 Habitat Use

Fishes inhabit most of the world's oceans, from warm shallow coastal habitat to cold deep-sea waters, and are found on the surface, in the water column, and at the bottom in the Study Area. The description of habitat use in this section pertains to common fishes found in the different habitats.

Fish distribution is restricted by biotic factors (competition or predation) or by abiotic components, such as temperature, salinity, DO, and pH. A species can be excluded from a suitable habitat by competitors, predators, parasites, or a lack of available prey (Moyle & Cech, 2004). For example, Catano et al. (2015) found that a loss of corals and the resulting decline in structural complexity, as well as management efforts to protect reefs, could alter the territory dynamics and reproductive potential of important herbivorous fish species.

Marine and diadromous fishes inhabit the diverse coastal habitats on or near the edges of the continents, from the intertidal regions to the edge of the continental shelf (Moyle & Cech, 2004). The most abundant and conspicuous types of coastal habitats are hard bottom (e.g., rocky reefs which can include shell beds), soft bottom (e.g., sand, mud, silt), submerged aquatic vegetation (e.g., mangroves, salt marshes, seagrass beds, macroalgae beds), and floating macroalgae. Each of these coastal habitats has distinct types of fishes associated with it. Common fishes inhabiting hard bottom habitats in the Study Area include gobies (Gobiidae), rockfishes (Scorpaenidae), and sculpins (Cottidae), while flounder (Bothidae) and stingrays (Dasyatidae) are found on soft bottoms. Pipefishes (Syngnathidae) and kelpfish (Clinidae) are common inhabitants of submerged aquatic vegetation habitat. Species commonly found under offshore floating macroalgae include ocean sunfishes, tunas, sharks, and mahi mahi.

Somewhere between 30 and 40 percent of all fish species are associated with hard bottom habitats (tropical and subtropical) such as reefs, and anywhere from 250 to 2,200 species are likely to be found in, on, or near a major complex of reefs. Coral reef habitats are found between latitudes 30° North (N)

and 30° South (S) in shallow water (usually less than 164 ft.) that is warm enough to support the growth of corals and clear enough to allow photosynthesis at moderate depths. Most reef habitats are surrounded by nutrient-poor oceanic waters. Compared to the total number of species of carnivorous fishes that inhabit low-latitude coral reefs, the number of herbivores is small (20 percent), but they are often the most noticeable fishes (Moyle & Cech, 2004). Damselfishes (Pomacentridae), parrotfishes (Scaridae), and surgeonfishes (Acanthuridae) are examples of herbivorous fishes found in reef habitat (Moyle & Cech, 2004). In the Study Area, commonly recognized reef fishes include butterflyfishes (Chaetodontidae), puffers (Tetraodontidae), tangs (Acanthuridae), triggerfishes (Balistidae), and wrasses (Labridae).

The upper 200 m of the ocean is known as the photic or epipelagic zone. Sunlight penetrates sufficiently to support the growth of phytoplankton or macro algae. The area between 200 m and 1,000 m is referred to as the mesopelagic zone, where light penetration is minimal. Below the mesopelagic zone is the bathypelagic or aphotic zone, where sunlight does not penetrate. A lack of habitat complexity can limit the number of fish species that inhabit the epipelagic zone. Less than two percent of all fish species inhabit the nutrient-poor waters, with most occurring in the upper 100 m of the water column, where light can penetrate and permit phytoplankton growth and visual predators to see their prey. Epipelagic fishes are divided for convenience into nearshore and oceanic groups. Nearshore epipelagic fishes are overall the most commercially valuable group of fishes to humans because they typically occur in large schools, such as herring (Clupeidae) and anchovies (Engraulidae), or are particularly favored as food, such as tunas (Scombridae) and salmon (Salmonidae). Predators on nearshore epipelagic fishes include billfishes and swordfishes (Xiphiidae), sharks (Carcharhinidae), and others. Epipelagic fishes that inhabit the open ocean spend their entire life cycle either free swimming or associated with drifting seaweed e.g., kelp (Moyle & Cech, 2004). In the Study Area, examples of epipelagic open ocean fishes include sharks, tunas, sauries (Scomberesocidae), and ocean sunfish (Molidae).

Mesopelagic habitats are found below the well-lighted, well-mixed epipelagic zone. Between about 120 m and 1,000 m in depth, light gradually fades to extinction, and the water temperatures decreases to 39°F. Below 1,000 m, bathypelagic habitats are characterized by complete darkness, low temperatures, low nutrients, low DO, and great pressure. This environment is the most extensive aquatic habitat on earth. The vastness of the deep-sea habitat, coupled with its probable stability through geological time, has led to the development of a diverse fish community, which accounts for 11 percent of all recorded fish species in the oceans. Lanternfishes (Myctophidae), with about 240 species, are an important group of mesopelagic deep sea fishes in terms of diversity, distribution, and numbers of individuals (Helfman et al., 2009). These species make up a large fraction of the deep scattering layer, so-called because the sonic pulses of a sonar can reflect off the millions of swim bladders, often giving the impression of a false bottom (Moyle & Cech, 2004). Generally, deep-sea fishes are divided into two groups, those that are found in the water column and others associated with the seafloor. In the Study Area, the cookie cutter shark (Dalatiidae), fangtooths (Anoplogastridae), hatchetfishes (Sternoptychidae), and lanternfishes inhabit the water column while the seafloor is inhabited with grenadiers or rattails (Macrouridae), hagfishes (Myxinidae), rays (Rajidae), and some rockfishes (Sebastidae).

Some fishes use one habitat type over their entire life cycle, while others associate with different habitat types by life stage. Anadromous fishes, such as Pacific salmon, hatch and rear in freshwater rivers as fry, with early juveniles inhabiting estuaries for short periods as they transition into late-juvenile life stages before entering the ocean to mature into adults. Many other marine fishes inhabit the water column as larvae, settling onto soft bottom habitat as juveniles and remaining there as adults (e.g., flatfishes). The

reef-associated Pacific seahorse (*Hippocampus ingens*) and oceanic Pacific bluefin tuna (*Thunnus orientalis*) provide examples of species closely connected to one habitat category across their life cycle.

C.5.1.2 Movement and Behavior

Fishes exhibit a rich array of sophisticated behavior (Meyer et al., 2010). Fishes have been shown to cooperate in a variety of ways during foraging, navigation, reproduction, and predator avoidance (Fitzpatrick et al., 2006; Huntingford et al., 2006; Johnstone & Bshary, 2004). Some examples of the common types of behavior exhibited by fishes include movement or migration, schooling, feeding, and resting (Moyle & Cech, 2004).

Migratory behavior consists of mass movements from one place to another and can range in occurrence from daily to seasonal, depending on the species. Tunas, salmonids, and eels migrate thousands of miles in short periods of time (e.g., a few months). Daily or seasonal migrations are typically for feeding and/or predator avoidance and can also be referred to as movement patterns. Some common movement patterns include coastal migrations, open ocean migrations, onshore/offshore movements, vertical water column movements, and life stage-related migrations (e.g., eggs and larvae as part of the plankton/nekton). Migratory behavior occurs in response to changing environmental conditions, particularly temperature, or the movement and abundance of food organisms. The destinations of migratory events are often feeding or reproductive grounds. Many fishes have the ability to find their way back to a "home" area and some species use olfactory and visual cues, as well as chemicals released by the other fishes to return home. Highly migratory species such as hammerhead shark (*Sphyrna* species), albacore (*Thunnus alalunga*), wahoo (*Acanthocybium solandri*) and swordfish (*Xiphias gladius*), may move across thousands of miles of open ocean (Beamish et al., 2005; Duncan et al., 2006; Theisen et al., 2008). Other migratory species such as Pacific salmonids exhibit seasonal movement patterns throughout coastal continental shelf waters and beyond.

A shoal is defined as any group of fishes that remain together for social reasons, while a school is a polarized, synchronized shoal (Moyle & Cech, 2004), often swimming together in tight formations. Schools can change shape when traveling, feeding, resting, or avoiding predators. Vision and the lateral-line system play roles in assisting schooling by allowing fish to visually orientate to one another and also sense water movements when visibility is reduced. Schooling behavior may provide protection against predators. Schooling may also be beneficial in terms of reproduction since little energy has to be expended to find a mate when sexes school together (Moyle & Cech, 2004).

Feeding behavior of fishes is influenced by many factors, including characteristics of the environment, predators, and prey. When food is scarce, individual fish have been observed capturing prey items of all sizes, for which there is likely to be a net gain of energy for the fish. However, when food is abundant, a fish will typically seek the prey item that produces the most energy for the least amount of effort. The body shape of a fish species, specifically the mouth, reflects the general method of feeding. Many fishes must swallow their prey whole and have mouths specialized for their prey depending on the prey's size and shape (Price et al., 2015). Fishes with their mouth on the underside of their body (e.g., sturgeon, rays, skates, etc.) are typically bottom feeders, while fishes with their mouths near the top of their head (e.g., mullets, halfbeaks, etc.) are typically surface feeders. Fishes that typically feed in the water column, which includes most species, have mouths that are centered in their head. Common types of feeding behavior include ambushing, drift feeding, and filter feeding; fishes may regularly switch between two or more modes of feeding behavior depending on the abundance of prey (Moyle & Cech, 2004).

C.5.1.3 Hearing and Vocalization

Refer to Appendix D (Acoustic and Explosive Effects Supporting Information) for a summary and details regarding the hearing and vocalization of fishes.

C.5.1.4 General Threats

Fish populations can be influenced by various natural factors and human activities. There can be direct effects, from disease or from commercial and recreational activities such as fishing, or indirect effects, such as those associated with reductions in prey availability or lowered reproductive success of individuals. Human-made impacts are widespread throughout the world's oceans, such that very few habitats remain unaffected by human influence (Halpern et al., 2008a). Direct and indirect effects have shaped the condition of marine fish populations, particularly those species with large body size, late maturity ages, or low fecundity such as sharks, Pacific cod (*Gadus macrocephalus*), and Pacific bluefin tuna, making these species especially vulnerable to habitat losses and fishing pressure (Reynolds et al., 2005). Human-induced stressors (e.g., threats) can be divided into four components, which often act on fish populations simultaneously: habitat alteration, exploitation, introduction of non-native species, and pollution (Moyle & Cech, 2004). Climate change and its resulting effects on the marine environment are additional stressors on fish populations.

Coastal development, deforestation, road construction, dam development, water control structures, and agricultural activities are types of habitat alteration that can affect fishes and their environment. These activities may affect the water quality of the nearshore marine environment.

C.5.1.4.1 Water Quality

Parameters such as temperature, DO, salinity, turbidity, and pH define the water quality as a component of habitat quality for fishes. Some land-based activities can directly and indirectly impact water quality in rivers, estuaries, and in the coastal waters. Sediment from activities on land may be transported to the marine environment. Sediment can impact water quality by increasing turbidity and decreasing light penetration into the water column, as well as transport contaminants into the marine environment (Allen, 2006). Increases in sediment can decrease the survival and reproduction of plankton and have food web and ecosystem level effects.

Hypoxia (low DO concentration) is a major impact associated with poor water quality. Hypoxia occurs when waters become overloaded with nutrients such as nitrogen and phosphorus, which enter oceans from agricultural runoff, sewage treatment plants, bilge water, and atmospheric deposition. An overabundance of nutrients can stimulate algal blooms, resulting in a rapid expansion of microscopic algae (phytoplankton) and can cause anoxic events leading to fish kills (Corcoran et al., 2013). Over the last several decades, coastal regions throughout the world have experienced an increase in the frequency of algal blooms that are toxic or otherwise harmful. Commonly called red tides, these events are now grouped under the descriptor harmful algal blooms (Anderson et al., 2002). Harmful algal blooms can produce toxins, causing human illness and massive fish and other animal mortalities.

C.5.1.4.1.1 Pollution

Chemicals and debris are the two most common types of pollutants in the marine environment. Global oceanic circulation patterns result in the accumulation of a considerable amount of pollutants and debris scattered throughout the open ocean and concentrated in gyres and other places (Crain et al., 2009). Pollution initially impacts fishes that occur near the sources of pollution, but may also affect future generations from effects to reproduction and increased mortality across life stages.

Chemical pollutants in the marine environment that may impact marine fishes include organic pollutants (e.g., pesticides, herbicides, polycyclic aromatic hydrocarbons, flame retardants, and oil) and inorganic pollutants (e.g., heavy metals) (Pew Oceans Commission, 2003). High chemical pollutant levels in marine fishes may cause behavioral changes, physiological changes, or genetic damage (Goncalves et al., 2008; Moore, 2008; Pew Oceans Commission, 2003). Bioaccumulation is the net buildup of substances (e.g., chemicals or metals) in an organism from inhabiting a contaminated habitat or from ingesting food or prey containing the contaminated substance (Newman, 1998), or from ingesting the substance directly (Moore, 2008). Biomagnification can also be a concern for fishes. Biomagnification occurs when higher trophic organisms (predators) consume many lower trophic organisms that have accumulated toxins, potentially resulting in a higher toxin load for higher trophic organisms. Bioaccumulation and biomagnification of pollutants (e.g., metals and organic pollutants) is also a concern to human health because people consume top predators with high pollutant loads.

C.5.1.4.1.2 Oil Spills

Groups of fish typically impacted by oil spills include surface-oriented or surface dwelling species, nearshore (within 3 NM of the shoreline) species, and species whose spawning time coincided with an oil spill (Yender et al., 2010). Fishes can be impacted by the oil directly through the gills, or by consuming oil or oiled prey. Potentially harmful physiological effects to fishes from oil spills include reduced growth, enlarged livers, changes to heart and respiration rate, fin erosion, and reproductive impairment. The most damaging effects of oil on fish populations may be in harming eggs and larvae, because these stages are highly sensitive to oil at the surface, in the water column, or on the seafloor, and are subject to increased mortality and morphological deformities and impaired growth (Greer et al., 2012; Ingvarsdottir et al., 2012; National Oceanic and Atmospheric Administration, 2014; Ocean Conservancy, 2010a; Restore the Gulf, 2010). Discharges from ballast water and bilge water during routine ship operations and illegal dumping of solid waste are other sources of oil in the marine environment.

C.5.1.4.2 Commercial and Recreational Activities

Exploitation by commercial and recreational fishing is the single biggest cause of changes in fish populations and communities (Moyle & Cech, 2004). Historic and current overfishing largely contributed to the listing of ESA-protected marine species (Crain et al., 2009; Kappel, 2005). Overfishing of a fishery resource results from both legal and illegal fishing (poaching) and bycatch of resources in quantities above a sustainable level. At the end of 2017, 30 managed fish stocks in the U.S. were on the overfishing list and 35 stocks were on the overfished list, while the number of rebuilt fish stocks since 2000 increased to 44 (National Marine Fisheries Service, 2016v, 2018d).

In recent decades, commercial fisheries have targeted the larger, predatory, and sometimes higher-priced fish species. Gradually, this fishing pressure could make the larger species more scarce, and fishing will move towards the smaller species (Pauly & Palomares, 2005). Other factors, such as fisheries-induced evolution and intrinsic vulnerability to overfishing, have been shown to reduce the abundance of some populations (Kauparinen & Merila, 2007). Fisheries-induced evolution is a change in genetic composition of the population that results from intense fishing pressure, such as a reduction in the overall size and growth rates of fishes in a population. Intrinsic vulnerability is when certain life history traits (e.g., large body size, late maturity age, low growth rate, low offspring production) result in a species being more susceptible to overfishing than others (Cheung et al., 2007).

Other threats from commercial industries to fishes include vessel strikes, sea farming, and energy production activities. Large commercial passenger vessels (e.g., cruise liners) pose threats to large,

slow-moving open ocean fishes while moving along the sea surface. Whale sharks (*Rhincodon typus*), basking sharks (*Cetorhinus maximus*), sturgeons (Acipenseridae), manta rays (*Manta* spp), and ocean sunfish (*Mola mola*) are vulnerable to ship strikes (National Marine Fisheries Service, 2010a; Rowat et al., 2007; Stevens, 2007).

The threats of aquaculture operations on wild fish populations include reduced water quality, competition for food, predation by escaped or released farmed fishes, spread of disease and parasites, and reduced genetic diversity (Kappel, 2005). These threats become apparent when farmed fish escape and enter the natural ecosystem (Hansen & Windsor, 2006; Ormerod, 2003). NOAA (2011) published the Marine Aquaculture Policy which provides direction to enable the development of sustainable marine aquaculture.

Energy production and offshore activities associated with power-generating facilities results in direct and indirect injury and/or mortality of fishes. Injury and mortality sources include entrainment of eggs and larvae during water withdrawal and impingement of juveniles and adults (U.S. Environmental Protection Agency, 2004). Acoustic impacts from offshore wind energy development are additional sources of injury and mortality (Madsen et al., 2006).

C.5.1.4.3 Disease and Parasites

Fishes in poor quality environments have higher incidences of disease, due to increased stress levels and decreased immune system function and are less resilient to fight the disease. Parasites, bacteria, aquaculture conditions, environmental influences, and poor nourishment contribute to fish disease levels (National Oceanic and Atmospheric Administration, 2016a). Disease outbreaks in fishes are influenced by environmental conditions, which typically are more variable in inland waters compared to the open ocean (Snieszko, 1978). Areas with higher density fish populations, such as marine protected areas and fish farms, are at higher risk for disease compared to areas with lower densities (National Oceanic and Atmospheric Administration, 2016c; Wootton et al., 2012). Additionally, introduced species may expose native species to new diseases and parasites. In Hawaii, the introduction of the bluestripe snapper (*Lutjanus kasmira*) native to the Indian Ocean introduced a parasitic nematode (*Procamallanus istiblenni*) that has spread to native fish species (Gaither et al., 2013).

C.5.1.4.4 Invasive Species

Native fish populations are affected by invasive (introduced, non-native) species by predation, competition and hybridization (Moyle & Cech, 2004). Non-native fishes pose threats to native fishes when they are introduced into an environment lacking natural predators and then either compete with native marine fishes for resources or prey upon the native marine fishes (Coleman et al., 2014; Crain et al., 2009). Marine invasions by other non-fish species also may impact fish populations. Invasive marine algae have been found to alter the health status of native fishes feeding on the algae, which could impact the reproduction success of those populations (Felline et al., 2012).

In the Study Area, some of the invasive species include the peacock grouper (*Cephalopholis argus*), introduced to Hawaii, the yellowfin goby (*Acanthogobius flavimanus*), and the rainwater killifish (*Lucania parva*). The yellowfin goby is native to eastern Asia and the rainwater killifish is native to the U.S. Atlantic coast. Both of these fishes have also been introduced to the San Diego Bay (Gaither et al., 2013).

C.5.1.4.5 Climate Change

Global climate change is impacting and will continue to impact marine and estuarine fish and fisheries (Giddens et al., 2022; Intergovernmental Panel on Climate Change, 2014; Johnson et al., 2020; Roessig et al., 2004). Climate change is contributing to a shift in fish distribution from lower to higher latitudes

(Blanchard & Novaglio, 2024; Brander, 2010; Brander, 2007; Dufour et al., 2010; Giddens et al., 2022; Popper & Hastings, 2009; Wilson et al., 2010). Warming waters over the past quarter-century have driven fish populations in the northern hemisphere northward and to deeper depths (Asch, 2015; 2012; Heuer & Grosell, 2014; Inman, 2005; Peterson et al., 2014a).

Fishes with shifting distributions have faster life cycles and smaller body sizes than non-shifting species (Perry et al., 2005). In addition to affecting species ranges, increasing temperature has been shown to alter the sex-ratio in fish species that have temperature-dependent sex determination mechanisms (Ospina-Alvarez & Piferrer, 2008). Further temperature rises are likely to have profound impacts on commercial fisheries through continued shifts in distribution and alterations in community interactions (Perry et al., 2005). It appears that diadromous and benthic fish species are most vulnerable to climate change impacts (Hare et al., 2016).

Ocean acidification, the process whereby increasing atmospheric CO₂ concentrations reduces ocean pH and carbonate ion concentrations, may have serious impacts on fish development and behavior (Raven et al., 2005). Physiological development of fishes can be affected by increases in pH that can increase the size, density, and mass of fish otoliths (e.g., fish ear stones), which would affect sensory functions (Bignami et al., 2013b). Ocean acidification may affect fish larvae behavior and could impact fish populations (Munday et al., 2009). A range of behavioral traits critical to survival of newly settled fish larvae are affected by ocean acidification. Settlement-stage larval marine fishes exposed to elevated CO² were less responsive to threats than controls. This decrease in sensitivity to risk might be directly related to the impaired olfactory ability (Munday et al., 2009).

Beyond direct impacts on fishes from increasing pH, ocean acidification can cause changes to the ocean chemistry, which leads to increased algal blooms (Anderson et al., 2002). Ocean acidification can also lead to reef impacts, such as coral bleaching, and can also lead to reduced larval settlement and abundance (Doropoulos et al., 2012). Plankton are important prey items for many fish species and are also impacted by ocean acidification. Ocean acidification may cause a shift in phytoplankton community composition and biochemical composition that can impact the transfer of essential compounds to predators that eat the plankton (Bermudez et al., 2016) and can cause shifts in community composition (Anderson et al., 2002; Bermudez et al., 2016; Doropoulos et al., 2012; Fabry et al., 2008; Kroeker et al., 2013).

Another climate change effect is ocean deoxygenation. Netburn and Koslow (2015) found that the depth of the lower boundary of the deep scattering layer (so-called because the sonic pulses of a sonar can reflect off the millions of fish swim bladders) is most strongly correlated with DO concentration, and irradiance and oxygen concentration are the key variables determining the upper boundary. This study estimated the corresponding annual rate of change of deep scattering layer depths and hypothesized that if past trends continue, the upper boundary is expected to rise at a faster rate than the lower boundary, effectively widening the deep scattering layer. Cao et al. (2014) modeled different sensitivities of ocean temperature, carbonate chemistry, and oxygen, in terms of both the sign and magnitude to the amount of climate change. Model simulations in this study found by the year 2500, every degree increase of climate sensitivity will warm the ocean by 0.8 °C and will reduce ocean-mean DO concentration by 5.0 percent. Conversely, every degree increase of climate sensitivity buffers CO₂induced reduction in ocean-mean carbonate ion concentration and pH by 3.4 percent and 0.02 units, respectively. These results have great implications for understanding the response of ocean biota to climate change. Keller et al. (2015b) suggested that within the California Current System, shoaling of the oxygen minimum zone is expected to produce complex changes and onshore movement of the oxygen minimum zone could lead to habitat compression for species with higher oxygen requirements while allowing expansion of species tolerant of low bottom DO.

C.5.1.4.6 Marine Debris

Marine debris is a widespread global pollution problem, and trends suggest that accumulations are increasing as plastic production rises (Rochman et al., 2013). Debris includes plastics, metals, rubber, textiles, derelict fishing gear, vessels, and other lost or discarded items. Debris such as abandoned nets and lines also pose a threat to fishes. Due to body shape, habitat use, and feeding strategies, some fishes are more susceptible to marine debris entanglement than others (Musick et al., 2000; Ocean Conservancy, 2010b). Entanglement in abandoned commercial and recreational fishing gear has caused declines for some marine fishes.

Microplastics (i.e., plastics less than 5mm in size) in the marine environment are well documented, and interactions with marine biota, including numerous fish species have been described worldwide (Lusher et al., 2016). Plastic waste in the ocean chemically attracts hydrocarbon pollutants such as PCB and DDT, which accumulate up to one million times more in plastic than in ocean water (Mato et al., 2001). Fishes and zooplankton can mistakenly consume these wastes containing elevated levels of toxins instead of their prey. Rochman et al., (2015) found marine debris in 28 percent of the individual fish examined and in 55 percent of all fish species analyzed. According to the California Coastal Commission, only 20 percent of the items found in the ocean can be linked to ocean-based sources, like commercial fishing vessels, cargo ships (discharge of containers and garbage), or pleasure cruise ships, while 80 percent of the debris is land based from sources like litter, industrial discharges, and garbage management (California Coastal Commission, 2018).

C.5.2 Endangered Species Act-Listed Species

ESA-listed fishes in the Study Area include three Evolutionarily Significant Units (ESU) of Chinook salmon, three ESUs of coho salmon, five Distinct Population Segments (DPS) of steelhead, green sturgeon, eulachon, oceanic whitetip shark, scalloped hammerhead shark (*Sphyrna lewini*), and giant manta (*Manta birostris*).

C.5.2.1 Chinook Salmon (Oncorhynchus tshawytscha)

Three ESA-listed ESUs of Chinook salmon have the potential to occur in the NOCAL Range Complex portion of the Study Area, including the California Coastal ESU, Central Valley Spring-Run ESU, and Sacramento River Winter-Run ESU.

C.5.2.1.1 California Coastal ESU

C.5.2.1.1.1 Status and Management

The California Coastal Chinook Salmon ESU was listed as threatened on September 16, 1999 (64 FR 50394); that status was reaffirmed on June 28, 2005 (70 FR 37160) and subsequently updated on April 14, 2014 (79 FR 20802). This ESU includes naturally spawned Chinook salmon originating from rivers and streams south of the Klamath River to and including the Russian River (79 FR 20802). No hatchery programs are currently included as part of this ESU.

Critical Habitat

NMFS designated critical habitat for the California Coastal Chinook salmon on September 2, 2005 (70 FR 52488). It includes multiple CALWATER hydrological units north from Redwood Creek and south to Russian River. The physical and biological features required by Chinook salmon are applicable to

freshwater and estuaries (i.e., spawning sites, rearing sites, and migration corridors) and are outside the Study Area (Figure C-4). Therefore, designated critical habitat for the California Coastal ESU of Chinook salmon does not overlap spatially with the HCTT Study Area.

Recovery Goals

Recovery goals, objectives and criteria for the California Coastal Chinook salmon are fully outlined in NMFS (National Marine Fisheries Service, 2016l). Recovery plan objectives are to: 1) Reduce the present or threatened destruction, modification, or curtailment of habitat or range; 2) Ameliorate utilization for commercial, recreational, scientific, or educational purposes; 3) Abate disease and predation; 4) Establish the adequacy of existing regulatory mechanisms for protecting California Coastal Chinook salmon now and into the future (i.e., post-delisting); 5) Address other natural or manmade factors affecting the continued existence of California Coastal Chinook salmon; and 6) Ensure the status of California Coastal Chinook salmon is at a low risk of extinction based on abundance, growth rate, spatial structure and diversity.

C.5.2.1.1.2 Habitat and Geographic Range

Geographic range of spawning systems for this ESU: Naturally spawned Chinook salmon originating from rivers and streams south of the Klamath River to and including the Russian River (79 FR 20802).

Juvenile outmigrants

With the extirpation of spring-runs in this ESU, California Coastal Chinook are comprised almost entirely of ocean-type, fall-run fish (Crozier et al., 2019; Moyle et al., 2017; National Marine Fisheries Service, 2016e). The majority of California Coastal fall-run Chinook emerge from the gravel in the late winter or spring, then outmigrate to estuaries from March through August of their first year. Most of these fish enter marine waters by July (Chase et al., 2005; Gallagher, 2003), though in some smaller systems where sedimentation blocks their egress, they may remain until October or November (Madej et al., 2012). When these fish leave their natal systems and migrate to coastal marine habitats, marine entry occurs to the north and east of the northernmost portion of the California Study Area (Figure C-4).



Figure C-4: Designated Chinook Salmon Critical Habitat

Ocean rearing

Chinook and coho along the California Current utilize the cooler, upwelled water of the coastal shelf for feeding and migrating (Bellinger et al., 2015; Hinke et al., 2005). Upon marine entry, California Coastal Chinook stay near the coastline, with many of these fish moving north and feeding in cool waters off the Klamath-Trinidad region (Moyle et al., 2017). Older juveniles continue to rear in these productive waters, typically occurring between Pt. Reyes and southern Oregon, with highest abundances in the Fort Bragg and Klamath subareas (Bellinger et al., 2015; Satterthwaite et al., 2015; Satterthwaite et al., 2014 Crozier, 2019, #15602), north of the Study Area. In an analysis of Oregon and California coastal fish, Bellinger et al., (2015) summarized the May to September stock-specific catch per unit effort for troll caught Chinook. They found that California Coastal Chinook were broadly distributed from May to August, from northern Oregon to Monterey Bay. The greatest and most consistent stock-specific catch per unit effort (SSCPUEs) for California Coastal Chinook occurred between Crescent City and Fort Bragg. Fisher et al., (2007) found that subyearling Chinook can be abundant in nearshore waters in June and July, with their distribution more tightly associated with depth, than temperature or salinity. Though limited catch data was available for yearling Chinook, Fisher et al., (2007), found that yearling Chinook along the California coast were found in very shallow waters and were relatively absent from both the warmest and coolest waters.

To investigate the marine habitat utilization of maturing Chinook salmon in the Gulf of Alaska, Seitz and Courtney (2022, 2023, 2024) attached 20 pop-up satellite archive tags (PSATS) on large immature Chinook at each of five different locations. Each fish was tracked for approximately 2–6 months. At each location, they found that maturing Chinook tended to occupy marine habitats over the continental shelf relative to those that occurred over continental slope or basin habitats. It is likely that Chinook in other regions of the Northeast Pacific Ocean display similar at-sea life history behaviors.

Return migration

Returning fall and late-fall maturing fish from the California Coastal ESU are typically age-3 and age-4 fish, with age-2 jacks representing approximately 5–10 percent of returning fish (Crozier et al., 2019; Myers et al., 1998). These fish leave coastal marine waters and enter estuaries as early as September and as late as January (Moyle et al., 2017; Myers et al., 1998), migrating upstream to habitats where spawning typically occurs between late October and December (Moyle et al., 2017).

C.5.2.1.1.3 Population Trends

The 2016 status review for this ESU indicates that there has been a mix in population trends, with some river system population escapement numbers increasing and others decreasing. Overall, there is a lack of compelling evidence to suggest that the status of these populations has improved or deteriorated appreciably since the previous status review (Williams et al., 2011; Williams et al., 2016c). At the ESU level, the loss of the spring-run life history type represents a significant loss of diversity within the ESU, as has been noted in previous status reviews (Good et al., 2005; Williams et al., 2011). Concern remains about the extremely low numbers of Chinook salmon in most populations of the North-Central Coast and Central Coast strata, which diminishes connectivity across the ESU. In summary, the new information available since the last status review does not appear to suggest there has been a change in extinction risk for this ESU (National Marine Fisheries Service, 2016g). Although conservation efforts for Chinook salmon have reduced some threats for this ESU, the threats have, with few exceptions, remained unchanged since the last review. Poor ocean conditions, drought, and marijuana cultivation

have significant negative impacts on Chinook salmon populations in this ESU since the last review (National Marine Fisheries Service, 2016g).

C.5.2.1.1.4 Population Threats

Threats to Chinook populations are largely applicable across multiple ESUs. In addition to the primary concerns articulated in the recovery plan (National Marine Fisheries Service, 2016l), salmonids have many other concerns that affect their respective populations. Juvenile Chinook salmon are eaten by other fishes such as whiting and mackerel, and seabirds, while adult Chinook are preyed on by marine mammals such as sea lions and orcas, as well as other fishes such as sharks (National Marine Fisheries Service, 2024c; Seitz & Courtney, 2022, 2023, 2024).

Chinook salmon populations are threatened by warming temperatures and changing conditions in freshwater and ocean habitats. Ocean acidification, a climate change related process where increasing atmospheric CO₂ concentrations are reducing ocean pH and carbonate ion concentrations, may have serious impacts on fish development and behavior (Raven et al., 2005). Physiological development of fishes can be affected by increases in pH that can increase the size, density, and mass of fish otoliths (e.g., fish ear stones), which would affect sensory functions (Bignami et al., 2013a). Ocean acidification may affect fish larvae behavior and could impact fish populations (Munday et al., 2009). A range of behavioral traits critical to survival of newly settled fish larvae are affected by ocean acidification. Settlement-stage larval marine fishes exposed to elevated CO₂ were less responsive to threats than controls (Munday et al., 2009). This decrease in sensitivity to risk might be directly related to impaired olfactory ability (Munday et al., 2009). Ocean acidification may cause a shift in plankton community composition and biochemical composition that can impact the transfer of essential compounds to planktivorous organisms (Bednaršek et al., 2022; Bermudez et al., 2016; Mélançon et al., 2016) and can cause shifts in community composition up the food chain.

Another effect of climate change is ocean deoxygenation. Netburn and Koslow (2015) found that the depth of the lower boundary of the deep scattering layer (so-called because the sonic pulses of a sonar can reflect off the millions of fish swim bladders) is most strongly correlated with DO concentration. Cao et al. (2014) modeled different sensitivities of ocean temperature, carbonate chemistry, and oxygen, in terms of both the sign and magnitude, and correlated them to the amount of climate change. Model simulations in a study by Cao et al. (2014) found that, by the year 2500, every degree increase of climate sensitivity will warm the ocean by 0.8° C and will reduce ocean-mean DO concentration by 5.0 percent. Conversely, every degree increase of climate sensitivity buffers CO₂-induced reduction in ocean-mean carbonate ion concentration and pH by 3.4 percent and 0.02 units, respectively. These results have great implications for understanding the response of ocean biota to climate change. Keller et al. (2015a) suggested that within the California Current System, shoaling of the oxygen minimum zone (OMZ) is expected to produce complex changes and onshore movement of the OMZ that could lead to habitat compression for species with higher oxygen requirements while allowing expansion of species tolerant of low bottom DO. Ruz-Moreno (2023) found that alterations in region-specific OMZ are likely to have significant impacts on the zooplankton community and productivity.

C.5.2.1.2 Central Valley Spring-Run ESU

C.5.2.1.2.1 Status and Management

The Central Valley Spring-Run Chinook Salmon ESU was listed as threatened on September 16, 1999 (64 FR 50394); that status was reaffirmed on June 28, 2005 (70 FR 37160) and subsequently updated on April 14, 2014 (79 FR 20802). This ESU includes naturally spawned spring-run Chinook salmon originating

from the Sacramento River and its tributaries, and spring-run Chinook salmon from the Feather River Hatchery Spring-run Chinook Program. This ESU does not include Chinook salmon that are designated as part of an experimental population (79 FR 20802). NMFS has not proposed any changes to the hatchery listing status for this ESU in their 2016 proposed rule (81 FR 72759).

Critical Habitat

NMFS published a final rule designating critical habitat for Central Valley Spring-Run Chinook salmon on September 2, 2005 (70 FR 52488). The physical and biological features required by Chinook salmon are applicable to freshwater and estuaries (i.e., spawning sites, rearing sites, and migration corridors) and are outside the Study Area (Figure C-4). Therefore, designated critical habitat for the Central Valley Spring-Run ESU of Chinook salmon does not overlap spatially with the HCTT Study Area.

Recovery Goals

Recovery goals, objectives and criteria for the Central Valley Spring-Run Chinook salmon are fully outlined in the 2014 recovery plan (National Marine Fisheries Service, 2014e). The ESU delisting criteria for the spring-run Chinook salmon are: 1) One population in the Northwestern California Diversity Group at low risk of extinction; 2) Two populations in the Basalt and Porous Lava Diversity Group at low risk of extinction; 3) Four populations in the Northern Sierra Diversity Group at low risk of extinction; 4) Two populations in the Southern Sierra Diversity Group at low risk of extinction; and 5) Maintain multiple populations at moderate risk of extinction.

C.5.2.1.2.2 Habitat and Geographic Range

Geographic range of spawning systems for this ESU: Naturally spawned spring-run Chinook salmon originating from the Sacramento River and its tributaries. Also, spring-run Chinook salmon from the Feather River Hatchery Spring-run Chinook Program. This DPS does not include Chinook salmon that are designated as part of an experimental population (79 FR 20802).

Juvenile outmigrants

The majority of Central Valley Spring-run Chinook emerge from the gravel by March and begin their downstream migration shortly thereafter (Crozier et al., 2019; Moyle, 2002). Predictive estuary rearing time and marine entry for these different spring-run age classes is unknown, with some juveniles remaining in the estuary for extended periods, whereas others in the same age class are believed to migrate directly towards the Pacific Ocean (Brandes & McLain, 2000; California Department of Fish and Game, 1998; Crozier et al., 2019; Moyle et al., 2017; National Marine Fisheries Service, 2014e; Whipple et al., 2012). Juvenile entry into marine waters for this ESU can occur as early as age-0 spring outmigrants, as fall or winter age-O outmigrants, or as late as age-1 spring outmigrants (Cordoleani et al., 2019; Cordoleani et al., 2021a; Cordoleani et al., 2021b; Cordoleani et al., 2020; Moyle et al., 2017). Although Cordoleani et al., 2021b) noted that age-1 spring outmigrants were the rarest phenotype observed at juvenile monitoring traps (10 percent), these later migrating fish contributed to the majority of returning adult spring-run spawners (60 percent). The peak outmigration for spring-outmigrating fry occurs in April and May (Baker & Morhardt, 2001).

Ocean rearing

In a review of data from coded wire tag tags recovered in the marine environment, Weitkamp et al., (2009) found that the majority of Central Valley-origin Chinook remained in California waters, though some fish were also detected in Oregon and Washington waters. In an analysis of Oregon and California

coastal troll caught fish, Bellinger et al., (2015) summarized the May to September SSCPUEs for Chinook. They found Central Valley Spring-run Chinook first appeared in the catch records in May, just south of San Francisco Bay. By June, they were detected from north of Monterey Bay to north of San Francisco Bay. By August and September, fish from this ESU were caught from the central Oregon coast to south of Monterey Bay. However, marine spatial distribution of rare stocks, such as Central Valley Spring-run Chinook, are limited due to their infrequent detection in the marine environment (Satterthwaite et al., 2015).

As discussed for California Coastal Chinook, Seitz and Courtney (2022, 2023, 2024) found that PSATtagged Chinook salmon in the Gulf of Alaska preferred to occupy habitats over the continental shelf relative to those that occurred over continental slope or basin habitats. It is likely that Chinook in other regions of the North Pacific Ocean display similar life history behaviors.

Return migration

Returning maturing fish from the Central Valley Spring-run ESU are typically age-3 and age-4 fish (Fisher, 1994; Moyle et al., 2017; National Marine Fisheries Service, 2014e). These fish enter the estuary to migrate up the Sacramento River from late January to early February, with peak detections in the Sacramento River from April to June (Crozier et al., 2019; Moyle et al., 2017). Characteristic for spring-run Chinook, these maturing fish hold in the river until conditions are suitable for spawning in the fall, typically beginning around October (California Department of Fish and Game, 1998; Moyle et al., 2017).

C.5.2.1.2.3 Population Trends

The Central Valley Technical Recovery Team delineated 18 or 19 independent populations of Central Valley Spring-Run Chinook salmon that occurred historically, along with a number of smaller dependent populations, within four diversity groups (Lindley et al., 2004). Of these populations, only three are extant (Mill, Deer, and Butte creeks) and they occur only in the Northern Sierra Nevada Diversity Group. With a few exceptions, Central Valley Spring-Run Chinook salmon populations have increased since the previous status review (2010/2011), which has moved the Mill and Deer creek populations from the high extinction risk category, to moderate, and Butte Creek has remained in the low risk of extinction category (National Marine Fisheries Service, 2016d; Williams et al., 2016c). Additionally, the Battle Creek and Clear Creek populations have continued to show stable or increasing numbers the last five years, putting them at moderate risk of extinction based on abundance. Overall, the Southwest Fisheries Science Center concluded in their viability report that the status of Central Valley Spring-Run Chinook salmon (through 2014) has probably improved since the 2010/2011 status review and that the ESU's extinction risk may have decreased, however the ESU is still facing significant extinction risk, and that risk is likely to increase over at least the next few years as the full effects of the recent drought are realized (Williams et al., 2016c).

C.5.2.1.2.4 Population Threats

Population threats are similar across many Chinook salmon ESUs. Please see the description of these threats described for the California Coastal Chinook Salmon ESU.

C.5.2.1.3 Sacramento River Winter-Run ESU

C.5.2.1.3.1 Status and Management

The Sacramento River Winter-Run Chinook Salmon ESU was listed as threatened on August 4, 1989 (54 FR 32085) and it was downgraded to endangered in 1994; that status was reaffirmed on June 28, 2005 (70 FR 37160) and subsequently updated on April 14, 2014 (79 FR 20802). This ESU includes all naturally

spawned populations of winter-run Chinook salmon in the Sacramento River and its tributaries, as well as two conservation programs maintained at the Livingston-Stone National Fish Hatchery (79 FR 20802). NMFS has not proposed any significant changes to the hatchery listing status for this ESU in their 2016 proposed rule (81 FR 72759).

Critical Habitat

NMFS designated critical habitat for the Sacramento River Winter-Run Chinook salmon on June 16, 1993 (58 FR 33212). The physical and biological features required by Chinook salmon are applicable to freshwater and estuaries (i.e., spawning sites, rearing sites, and migration corridors) and are outside the Study Area (Figure C-4). Therefore, designated critical habitat for the Sacramento River Winter-Run ESU of Chinook salmon does not overlap spatially with the HCTT Study Area.

Recovery Goals

Recovery goals, objectives and criteria for the Sacramento River Winter-Run Chinook salmon are fully outlined in the 2014 recovery plan (National Marine Fisheries Service, 2014e). To achieve the downlisting criteria, the species would need to be composed of two populations – one viable and one at moderate extinction risk. Having a second population would improve the species' viability, particularly through increased spatial structure and abundance, but further improvement would be needed to reach the goal of recovery. The only delisting criteria for this ESU is to have three populations in the Basalt and Porous Lava Diversity Group at low risk of extinction.

C.5.2.1.3.2 Habitat and Geographic Range

Geographic range of spawning systems for this ESU: Naturally spawned winter-run Chinook salmon originating from the Sacramento River and its tributaries. Also, winter-run Chinook salmon from one artificial propagation program: the Livingston Stone National Fish Hatchery (79 FR 20802).

Juvenile outmigrants

Winter-run Chinook are unique to the Central Valley (Healey, 1991) and have significant plasticity in their life history. Sacramento River Winter-run Chinook fry emerge from July to mid-October and may rear in the lower Sacramento for a few months prior to migrating to marine waters from December to April (Crozier et al., 2019; National Marine Fisheries Service, 2014e; Phillis et al., 2018; Pyper et al., 2013).

Ocean rearing

Sacramento River Winter-run Chinook salmon have a more southerly ocean distribution relative to other California Chinook salmon populations and are primarily impacted by fisheries south of Point Arena, California (National Marine Fisheries Service, 2016f). For Central Valley Chinook, both winter-run and late fall-run fish tend to occupy waters off California, whereas fall- and spring-run fish are distributed well into Oregon waters (Satterthwaite et al., 2013). In an analysis of Oregon and California coastal troll caught fish, Bellinger et al., (2015) summarized the May to September stock-specific catch per unit effort for Chinook. Except for a few June detections south of San Francisco Bay, the authors found that winter Chinook originating from the Central Valley (including the Sacramento watershed) were absent from the catch from May to July. During August and September, when their detections were greatest, they were only caught in the vicinity of Monterey Bay, and were slightly more prevalent to the south of the bay, relative to the north (Bellinger et al., 2015). These findings might have indicated that winter-run Chinook originating from the Central Valley do not typically rear off coastal California and only occur as they are

entering or exiting the estuary. Satterthwaite et al., (2013) also reviewed coded wire tag recoveries for this region. The authors found that although winter-run Chinook recoveries were low, and the greatest number of detections occurred during three years (2000, 2004, and 2005), that they appeared to be restricted to California coastal waters south of Point Arena, with 72 percent of the age-3 winter fish detected in June occurring in this area. Taken in combination, these studies suggest winter-run Chinook appear to have a more southerly distribution than spring-run Chinook, and they appear to be more abundant in the catch record in fall months.

As discussed for California Coastal Chinook, Seitz and Courtney (2022, 2023, 2024) found that PSATtagged Chinook salmon in the Gulf of Alaska preferred to occupy habitats over the continental shelf relative to those that occurred over continental slope or basin habitats. It is likely that Chinook in other regions of the North Pacific Ocean display similar life history behaviors.

Return migration

As age-3, maturing Sacramento River Winter-run Chinook typically enter the San Francisco Bay-Delta from December through July, with peak arrival occurring in March (Crozier et al., 2019; O'Farrell et al., 2012; Satterthwaite et al., 2017; Yoshiyama et al., 1998). These fish will hold in the Sacramento River and tributaries until spawning the following spring and summer (Crozier et al., 2019; Fisher et al., 2014; Killam & Mache, 2018; National Marine Fisheries Service, 2014e; Yoshiyama et al., 1998).

C.5.2.1.3.3 Population Trends

The Central Valley Technical Recovery Team delineated four historical independent populations of this ESU. The spawning areas for three of these historical populations are above the impassable Keswick and Shasta dams, while the fourth population (Battle Creek) is presently unsuitable for Sacramento River Winter-run Chinook salmon due to high summer water temperatures. Lindley et al. (2007) developed viability criteria for Central Valley salmonids and, using data through 2004, found that the mainstem Sacramento River population was at low risk of extinction, but that the ESU as a whole remained at a high risk of extinction because there is only one naturally-spawning population, and it is not within its historical range. The ESU's status has declined since the 2010 status review, with the single spawning population on the mainstem Sacramento River no longer at a low risk of extinction (National Marine Fisheries Service, 2016r). New information indicates an increased extinction risk to Sacramento River Winter-run Chinook salmon. The larger influence of the hatchery broodstock in addition to the rate of decline in abundance over the past decade has placed the population at a moderate risk of extinction. In summary, the most recent biological information suggests that the extinction risk of this ESU has increased since the last status review largely due to extreme drought and poor ocean conditions. The best available information on the biological status of the ESU and new threats to the ESU indicate that its ESA classification as an endangered species is appropriate and should be maintained (National Marine Fisheries Service, 2016r).

C.5.2.1.3.4 Population Threats

Population threats are similar across many Chinook salmon ESUs. Please see the description of these threats described for the California Coastal Chinook Salmon ESU.

C.5.2.2 Coho Salmon (Oncorhynchus kisutch)

Three ESA-listed ESUs of coho salmon have the potential to occur in the Study Area, including the Oregon Coast ESU, Southern Oregon and Northern California Coast ESU, and Central California Coast ESU.

C.5.2.2.1 Oregon Coast ESU

C.5.2.2.1.1 Status and Management

The Oregon Coast Coho Salmon ESU was listed as threatened on February 11, 2008 (63 FR 42587); that status was retained on June 20, 2011 (76 FR 35755) and subsequently updated on April 14, 2014 (79 FR 20802). This ESU includes naturally spawned coho salmon originating from coastal rivers south of the Columbia River and north of Cape Blanco, and also coho salmon from one artificial propagation program: Cow Creek Hatchery Program (Oregon Department of Fish and Wildlife Stock #18) (79 FR 20802). NMFS has not proposed any significant changes to the hatchery listing status for this ESU in their 2016 proposed rule (81 FR 72759).

Critical Habitat

NMFS published a final rule designating critical habitat for Oregon Coast coho salmon on February 11, 2008 (73 FR 7816). Critical habitat includes freshwater spawning sites, freshwater rearing sites, freshwater migration corridors, and estuarine areas. The PBFs that characterize these sites include water quality and quantity, natural cover, forage, adequate passage conditions, and floodplain connectivity necessary to support spawning, incubation and larval development, juvenile growth and mobility, and adult survival. Designated critical habitat for the Oregon Coast ESU of coho salmon does not overlap spatially with the HCTT Study Area. The only ESA-listed coho salmon with critical habitat designated within 50 NM of the HCTT Study Area is the Central California Coast Coho ESU (Figure C-5).

Recovery Goals

See the 2016 recovery plan for detailed descriptions of the recovery goals and delisting criteria for Oregon Coast coho salmon (National Marine Fisheries Service, 2016l). In the simplest terms, NMFS will remove the Oregon Coast coho salmon from federal protection under the ESA when NMFS determines that:

- The species has achieved a biological status consistent with recovery—the best available information indicates it has sufficient abundance, population growth rate, population spatial structure, and diversity to indicate it has met the biological recovery goals.
- Factors that led to ESA listing have been reduced or eliminated to the point where federal protection under the ESA is no longer needed, and there is reasonable certainty that the relevant regulatory mechanisms are adequate to protect Oregon Coast coho salmon sustainability.

C.5.2.2.1.2 Habitat and Geographic Range

Geographic range of spawning systems for this ESU: Naturally spawned coho salmon originating from coastal rivers south of the Columbia River and north of Cape Blanco. This ESU includes coho from one artificial propagation program; the Cow Creek Hatchery Program (79 FR 20802).



Figure C-5: Designated Coho Salmon Critical Habitat

Juvenile outmigrants

The broad geographic area and highly variable environmental conditions where coho salmon spawn and rear as juveniles results in substantial variability within the life history traits displayed by individual populations in given regions, requiring generalizations, or averages of some traits (Weitkamp et al., 1995). Oregon Coast coho fry emerge in early spring, then typically rear in freshwater lakes, coastal rivers, wetlands, and estuaries for at least one year before migrating to the ocean as age-1 fish from late March through June, with peak outmigration occurring in May (National Marine Fisheries Service, 2016n; Weitkamp et al., 1995). Only a very small proportion of fish from this ESU enter the ocean as sub-yearlings (National Marine Fisheries Service, 2016n; Stout et al., 2012; Weitkamp et al., 1995).

Ocean rearing

Oregon Coast coho typically spend 18–24 months at sea, females typically return as age-3 fish, whereas males can return after only 6 months at sea as age-2 or age-3 fish (Crozier et al., 2019; National Marine Fisheries Service, 2016b, 2016n; NOAA Fisheries Protected Resources Division, 2007; Weitkamp et al., 1995). Given their relatively short period in marine waters, Oregon Coast coho are broadly distributed. This ESU has been found to range from as far south as southern Monterey Bay to as far north as the Gulf of Alaska (Morris et al., 2007; Van Doornik et al., 2007; Weitkamp & Neely, 2002) though the majority of adult ocean harvest occurs off the Oregon Coast (National Marine Fisheries Service, 2016n). Coded wire tagged (CWT) coho from this region display a more northerly marine distribution than populations to the south (Weitkamp & Neely, 2002; Weitkamp et al., 1995). The region-specific recovery of tags by percentages for Oregon Coast-origin coho, as reported by Weitkamp et al. (1995), is California (27–39 percent), Washington (2-9 percent), British Columbia (2-6 percent), and Alaska (<1 percent). During NMFS summer salmon trawl surveys conducted from 2010 to 2014, coho captured in California waters were much more abundant in more northern California waters in the Klamath-Trinidad region than the Lost Coast region, with very few coho captured in the Gulf of Farallones region (Harding, 2015). Coho captured during these surveys occurred at lower abundance for deeper offshore trawl stations relative to shallower stations (Harding, 2015).

Pearcy and Fisher (1988) evaluated 1980–1985 Washington and Oregon purse seine and gill net salmon catch data to determine characteristics of coho salmon in the marine environment. Their data indicate more northerly movement of juvenile coho early in late spring to summer (e.g., May) and more southerly movement towards the end of summer or early fall (e.g., August to September). Juveniles were larger at northern sampling locations relative to those in the south near the California border. They found that half of the juvenile coho were captured in the top 2 m of the water column, though as many as 5 percent of the catch occurred at 9–12 m depth. Pearcy and Fisher reviewed prior literature indicating that coho typically occur from 0 to 20 m depth and that 79 percent of maturing coho occurred at depths from 0 to 50 m.

Return migration

Adult return migration and spawn timing can also be highly variable, with river entry correlated with fall rains elevating river levels (Weitkamp et al., 1995). Mature Oregon Coast coho typically enter estuaries from late September through November (National Marine Fisheries Service, 2016n; Weitkamp et al., 1995) to begin their migration to upstream spawning grounds where spawning occurs from January through March (Crozier et al., 2019; National Marine Fisheries Service, 2016n; NOAA Fisheries Protected Resources Division, 2007; Weitkamp et al., 1995).
C.5.2.2.1.3 Population Trends

Many positive improvements to Oregon Coast coho salmon are described in National Marine Fisheries Service (2016m), including positive long-term abundance trends and escapement. Increases in ESU scores for persistence and sustainability also clearly indicate the biological status of the ESU is improving, due in large part to management decisions (reduced harvest and hatchery releases) and favorable environmental variation (i.e., high marine survival). Lawson (1993) cautioned that variation in ocean productivity can mask the true benefits of stream restoration projects; increased abundances are incorrectly attributed to stream restoration when the increases resulted from high marine survival. Consequently, it is only when marine survival is low that it becomes apparent whether habitat quality and quantity are sufficient to support self-sustaining populations. With marine survival rates expected to decrease for Oregon Coast coho salmon entering the ocean in 2014 (Peterson et al., 2014b; Peterson et al., 2014c), it may be advisable to wait to observe how populations fare during this potential downturn before deciding to change their status (National Marine Fisheries Service, 2015b).

C.5.2.2.1.4 Population Threats

Coho salmon on the west coast of the U.S. have experienced dramatic declines in abundance during the past several decades from human-induced and natural factors (Alaska Department of Fish and Game, 2024; National Marine Fisheries Service, 2016b, 2016n; Weitkamp et al., 2020). Water storage, withdrawal, conveyance, and diversions for agriculture, flood control, domestic, and hydropower purposes have greatly modified, reduced or eliminated historically accessible habitat (National Marine Fisheries Service, 2016b, 2016n; Weitkamp et al., 2020). Physical features of dams, such as turbines and sluiceways, have resulted in increased mortality of both adults and juvenile salmonids (Alaska Department of Fish and Game, 2024). In addition, coho salmon predators include marine mammals such as orcas, sea lions and sea otters, as well as other fishes such as sharks.

C.5.2.2.2 Southern Oregon and Northern California Coast ESU

C.5.2.2.2.1 Status and Management

The Southern Oregon and Northern California Coast Coho (SONCC) Salmon ESU was listed as threatened on May 6, 1997 (62 FR 24588); that status was reaffirmed on June 28, 2005 (70 FR 37160) and subsequently updated on April 14, 2014 (79 FR 20802). This ESU includes naturally spawned coho salmon originating from coastal streams and rivers between Cape Blanco, Oregon, and Punta Gorda, California, as well as coho salmon from three artificial propagation programs (79 FR 20802). NMFS has not proposed any significant changes to the hatchery listing status for this ESU in their 2016 proposed rule (81 FR 72759).

Critical Habitat

NMFS designated critical habitat for the SONCC ESU of coho salmon on May 5, 1999 (64 FR 24049). Critical habitat includes juvenile summer and winter rearing areas, juvenile migration corridors, areas for growth and development to adulthood, adult migration corridors, and spawning areas. The physical or biological features that characterize these sites include substrate, water quality, water quantity, water temperature, water velocity, cover/shelter, food, riparian vegetation, space, and safe passage conditions. Designated critical habitat for the SONCC ESU of coho salmon does not overlap spatially with the HCTT Study Area. The only ESA-listed coho salmon with critical habitat designated within 50 NM of the HCTT Study Area is the Central California Coast Coho ESU (Figure C-5).

Recovery Goals

See the 2014 recovery plan for detailed descriptions of the recovery goals and delisting criteria for Southern Oregon and Northern California Coast coho salmon (National Marine Fisheries Service, 2014e).

The following goals guide recovery of SONCC coho salmon as described in recovery documents from the State of Oregon, the State of California, and NMFS.

- First, each SONCC population must reach desired levels of biological viability and the recovery effort must sufficiently reduce the impact of the stresses and threats in order to warrant removal of the SONCC coho salmon ESU from the threatened and endangered species list (referred to in this plan as either delisting or ESA recovery).
- Second, the States of California and Oregon seek to rebuild wild populations to reach 'broad sense recovery' to provide for sustainable fisheries and other ecological, cultural, and social benefits.

C.5.2.2.2.2 Habitat and Geographic Range

Geographic range of spawning systems for this ESU: Naturally spawned coho salmon originating from coastal streams and rivers between Cape Blanco, Oregon, and Punta Gorda, California. This ESU includes coho from three artificial propagation programs, the Cole Rivers Hatchery Program, the Trinity River Hatchery Program, and the Iron Gate Hatchery Program (79 FR 20802).

Juvenile outmigrants

A number of the stream systems where the SONCC coho spawn are small and subject to highly variable flow regimes. As adults delay migrating into these systems until flows are sufficient, adult run-timing and spawning are highly variable within and between these coastal systems (Moyle et al., 2017). Fry typically emerge from the gravel in spring (National Marine Fisheries Service, 2014c). However, in larger watersheds like the Klamath River, fry merge from the gravel from February through July, with typical peaks in March and April. Juveniles may rear in streams or estuaries for at least a year, with some fish remaining in freshwater habitats through age-3 (Crozier et al., 2019; National Marine Fisheries Service, 2014c). Smolts migrate to the ocean as young of the year, one-year-old, or two-year-old fish (Moyle et al., 2017), typically enter marine waters in spring and summer (NMFS 2014), with peak outmigration occurring in April or May (Moyle et al., 2017; Weitkamp et al., 1995).

Ocean rearing

Upon initially entry into marine waters, SONCC coho remain within nearshore coastal waters (Crozier et al., 2019; Moyle et al., 2017; National Marine Fisheries Service, 2014c). Moyle (2002) suggests this may be due to high densities of available food resources. However, once moving away from these coastal waters, the marine distribution of SONCC coho is poorly understood (Crozier et al., 2019; Moyle et al., 2017). In general, coho distribution while at sea is wide-ranging, with distributions from California to the North Pacific (Moyle et al., 2017). The majority of coho salmon caught in California marine fisheries originate from Oregon systems, not the California stocks (Moyle et al., 2017). CWT coho from this region display a more southerly marine distribution than populations to the north (Weitkamp et al., 1995). The region-specific recovery of tags by percentages for SONCC coho as reported by Weitkamp et al. (1995) is California (65–92 percent), with some recoveries in Oregon (7–34 percent) and almost none (<1 percent) in Washington or British Columbia. During NMFS summer salmon trawl surveys conducted from 2010–2014, coho captured in California waters were much more abundant in more northern California waters

in the Klamath-Trinidad region than the Lost Coast region, with very few coho captured in the Gulf of Farallones region (Harding, 2015). Coho captured during these surveys occurred at lower abundance for deeper offshore trawl stations relative to shallower stations (Harding, 2015).

Return migration

Following 6–24 months at sea, SONCC coho return to their natal systems as age-3 fish (Weitkamp et al., 1995; (Moyle et al., 2017) NMFS 2014). Mature adult coho will wait in nearshore marine environments for suitable conditions to allow their upstream migration. Depending on fall rains and coastal river water levels, mature coho from this ESU typically enter coastal estuaries from October to March, with peak migration occurring from mid-November to January (Crozier et al., 2019; Moyle et al., 2017; National Marine Fisheries Service, 2014c). However, for some larger system like the Klamath River, the migration period is earlier and longer, extending from late-August to mid-January (National Marine Fisheries Service, 2014c).

C.5.2.2.3 Population Trends

The updated 2016 status review indicates that there has been no improvement in the status of SONCC coho salmon in the last five years (National Marine Fisheries Service, 2016h). The SONCC coho salmon ESU continues to be at risk of extinction. Twenty-four out of 31 independent populations are at high risk of extinction, six are at moderate risk of extinction, and none is at low risk of extinction. All core populations (those intended to serve as anchors for recovery) are thousands of adults short of the numbers needed for them to play their role in recovery of the entire ESU (National Marine Fisheries Service, 2016h).

C.5.2.2.2.4 Population Threats

Population threats are similar across many coho salmon ESUs. Please see the description of these threats described for the Oregon Coast Coho Salmon ESU.

C.5.2.2.3 Central California Coast ESU

C.5.2.2.3.1 Status and Management

The Central California Coast Coho Salmon ESU was listed as threatened on October 31, 1996 (61 FR 56138) and downgraded to endangered on June 28, 2005 (70 FR 37160). The ESU status was reaffirmed as endangered on April 2, 2012 (77 FR 19552) and subsequently updated on April 14, 2014 (79 FR 20802). This ESU includes naturally spawned coho salmon originating from rivers south of Punta Gorda, California to and including Aptos Creek, coho salmon originating from tributaries to San Francisco Bay, as well as coho salmon from three artificial propagation programs (79 FR 20802). NMFS has not proposed any changes to the hatchery listing status for this ESU in their 2016 proposed rule (81 FR 72759).

Critical Habitat

Critical habitat for the Central California Coast ESU of coho salmon was designated on May 5, 1999 (64 FR 24049). Critical habitat includes juvenile summer and winter rearing areas, juvenile migration corridors, areas for growth and development to adulthood, adult migration corridors, and spawning areas. The physical or biological features that characterize these sites include substrate, water quality, water quantity, water temperature, water velocity, cover/shelter, food, riparian vegetation, space, and safe passage conditions. Designated critical habitat for the Central California Coast ESU of coho salmon

does not overlap spatially with the HCTT Study Area, but does occur in freshwater systems to the east of the northern portion of the California Study Area (Figure C-5).

Recovery Goals

See the 2012 recovery plan for complete down listing/delisting criteria for each of the following recovery goals for Central California Coast coho salmon (National Marine Fisheries Service, 2012b):

- Prevent extinction by protecting existing populations and their habitats,
- Maintain current distribution of coho salmon and restore their distribution to previously occupied areas essential to their recovery,
- Increase abundance of coho salmon to viable population levels, including the expression of all life history forms and strategies,
- Conserve existing genetic diversity and provide opportunities for interchange of genetic material between and within meta populations,
- Maintain and restore suitable freshwater and estuarine habitat conditions and characteristics for all life history stages so viable populations can be sustained naturally,
- Ensure all factors that led to the listing of the species have been ameliorated, and
- Develop and maintain a program of monitoring, research, and evaluation that advances understanding of the complex array of factors associated with coho salmon survival and recovery and which allows for adaptively managing our approach to recovery over time.

C.5.2.2.3.2 Habitat and Geographic Range

Geographic range of spawning systems for this ESU: Naturally spawned coho salmon originating from rivers south of Punta Gorda, California to and including Aptos Creek, as well as such coho salmon originating from tributaries to San Francisco Bay. This DPS includes steelhead from three artificial propagation programs: the Don Clausen Fish Hatchery Captive Broodstock Program, the Scott Creek/King Fisher Flats Conservation Program, and the Scott Creek Captive Broodstock Program (79 FR 20802).

Juvenile outmigrants

Central California Coast coho fry emerge from February through June, with peak emergence occurring from March to May (National Marine Fisheries Service, 2012b). Juveniles may rear in streams or estuaries for at least a year, with some fish remaining in freshwater habitats through age-3 (Crozier et al., 2019; National Marine Fisheries Service, 2012b). Typically, coho smolt outmigration begins in March, with peak outmigration occurring from April to early July (Weitkamp et al., 1995). However, several of the estuaries utilized by this ESU are blocked by sandbars during low water flows. As a result, the outmigration timing and age of Central California Coast coho smolts migrating to marine habitats can be highly variable and dependent on sufficient water levels (Crozier et al., 2019).

Ocean rearing

Detections of Central California Coast coho in the marine environment are limited. However, tagging studies elsewhere have indicated that juvenile fish likely reside in nearshore marine waters relatively close to their natal system (Crozier et al., 2019; National Marine Fisheries Service, 2012b; Pearcy & Fisher, 1988; Quinn & Myers, 2005; Shapovalov & Taft, 1954; Weitkamp & Neely, 2002). Shapovalov and Taft (1954) found that younger Central California Coast coho stayed within approximately 90 mi of the coastline. As fish from this ESU mature and become larger they display a much broader offshore marine

environment and have been found off the coast of Oregon (National Marine Fisheries Service, 2012b; Weitkamp & Neely, 2002; Weitkamp et al., 1995).

In an effort to better understand the distribution of coho salmon from this region, beginning in 2003, Hayes et al. (2011), and others, tagged and monitored 579 Scott Creek Fish Hatchery coho smolts at least 200 mm in length (7.8 in.) with archival tags. Scott Creek is located approximately 60 mi south of San Francisco. Although the tagged fish were not included within the Central California Coast coho ESU, these hatchery fish originate from the same geographic area. These tags provided estuarine distribution, temperature, and even predation data, however, likely due to poor ocean conditions and large tag size relative to small smolt size, only one of these tags returned data indicating that the fish had entered marine waters. This lone tagged fish remained in the marine environment until it was recaptured approximately 15 mi. to the southeast of Scott Creek, near Santa Cruz six months after it was tagged and released.

During NMFS summer salmon trawl surveys conducted from 2010–2014, coho captured in California waters were much more abundant in more northern California waters in the Klamath-Trinidad region than the Lost Coast region, with very few coho captured in the Gulf of Farallones region (Harding, 2015). Coho captured during these surveys occurred at lower abundance for deeper offshore trawl stations relative to shallower stations (Harding, 2015).

Return migration

As Central California Coast coho need to mill outside of the mouth of the natal estuaries until water flows and conditions are suitable for upstream migration, their run-timing is later than for coho populations further north (Weitkamp et al., 1995). Adults begin entering these estuaries as early as late-September and as late as February, with a peak migration occurring in November to January (National Marine Fisheries Service, 2012b; Shapovalov & Taft, 1954; Weitkamp et al., 1995). Very little time is spent between river entry and spawning activity (Weitkamp et al., 1995).

C.5.2.2.3.3 Population Trends

Prior viability and stock assessments (Good et al., 2005; Spence & Williams, 2011; Williams et al., 2011; Williams et al., 2016b) indicated that all independent and dependent populations of this ESU were well below recovery targets and, in some cases, exceed high-risk thresholds established by Spence et al. (2008), with an area of particular concern being the downward trends in abundance of virtually all dependent populations across all diversity strata. Despite conservation efforts, conditions for Central California Coast coho salmon continue to decline (National Marine Fisheries Service, 2016a, 2023a), and the threats to recovery have, with few exceptions, remained unchanged since prior reviews (National Marine Fisheries Service, 2016a, 2023a). NMFS (2023a) determined that the viability of populations is progressively worse moving north to south within the Central California Coast Coho ESU. The best available information on the biological status of this ESU and the threats facing this ESU indicate that it continues to remain endangered.

Over recent years the distribution and abundance of coho salmon populations in California have been considerably reduced (California Department of Fish and Wildlife, 2024a). Although coho salmon are still found in most major river systems in the northern portion of the state, many spawning runs have declined substantially in size and were eliminated from many tributaries, including some streams in the Klamath and Eel River basins (California Department of Fish and Wildlife, 2024a).

Overall, from Humboldt County north to the Oregon border, coho salmon are now found in approximately two-thirds of the streams identified as historical habitat (California Department of Fish and Wildlife, 2024a). In the southern part of their range, coho salmon are now absent from all tributaries of San Francisco Bay and many streams south of the Bay; this is likely associated with adverse effects from increased urbanization and other human developments on watersheds and fish habitat (California Department of Fish and Wildlife, 2024a).

C.5.2.2.3.4 Population Threats

Population threats are similar across many coho salmon ESUs. Please see the description of these threats described for the Oregon Coast Coho Salmon ESU.

C.5.2.3 Steelhead (Oncorhynchus mykiss)

Five ESA-listed DPSs of steelhead have the potential to occur in the Study Area, including the Northern California DPS, California Central Valley DPS, Central California Coast DPS, South-Central California Coast and Southern California DPS.

C.5.2.3.1 Northern California DPS

C.5.2.3.1.1 Status and Management

The Northern California Steelhead DPS was listed as threatened on June 7, 2000 (65 FR 36074) and their status was updated on January 5, 2006 (71 FR 834) and April 14, 2014 (79 FR 20802). This DPS includes naturally spawned steelhead originating below natural and manmade impassable barriers in California coastal river basins from Redwood Creek to and including the Gualala River (79 FR 20802). No hatchery programs are currently included as part of this DPS.

Critical Habitat

NMFS designated critical habitat for Northern California DPS steelhead on September 2, 2005 (70 FR 52488). Critical habitat includes freshwater spawning sites, freshwater rearing sites, freshwater migration corridors, and estuarine areas. The PBFs that characterize these sites include water quality and quantity, natural cover, forage, adequate passage conditions, and floodplain connectivity necessary to support spawning, incubation and larval development, juvenile growth and mobility, and adult survival. Designated critical habitat for the Northern California DPS steelhead does not overlap spatially with the HCTT Study Area, however these habitats do occur in freshwaters to the north and east and the northernmost portion of the California Study Area (Figure C-6).

Recovery Goals

See the 2016 Recovery Plan for the Northern California Steelhead DPS for complete downlisting/delisting criteria for recovery goals for the DPS (National Marine Fisheries Service, 2016l). The recovery plan's objectives are to: (1) Reduce the present or threatened destruction, modification, or curtailment of habitat or range; (2) Ameliorate utilization for commercial, recreational, scientific, or educational purposes; (3) Abate disease and predation; (4) Establish the adequacy of existing regulatory mechanisms for protecting NC steelhead now and into the future (i.e., post-delisting); 5. Address other natural or manmade factors affecting the continued existence of NC steelhead; and 6. Ensure NC steelhead status is at a low risk of extinction based on abundance, growth rate, spatial structure and diversity.

C.5.2.3.1.2 Habitat and Geographic Range

Geographic range of spawning systems for this DPS: Naturally spawned anadromous steelhead originating below natural and manmade impassable barriers in California coastal river basins from Redwood Creek to and including the Gualala River (79 FR 20802). The Northern California steelhead DPS includes both summer- and winter-run fish (79 FR 20802), with winter-run fish being more common (Moyle et al., 2017).





Juvenile outmigrants

The designated Northern California Steelhead DPS combines numerous life history strategies into a single ESA-listed DPS (Moyle et al., 2017). In addition to being comprised of both winter-run and summer-run ecotype fish, there is considerable variability within each run designation. Much of this diversity comes numerous smaller systems that include both coastal and mountain streams, and distinct, isolated populations (Moyle et al., 2017). As Northern California steelhead spawning occurs over an expansive time period, so does fry emergence (Moyle et al., 2017; National Marine Fisheries Service, 2016i). Fry rear in river systems for months to years before migrating to estuaries as smolts. Smolts typically leave the estuaries and migrate to marine environments between March and June, though if conditions are poor, they may wait until late fall (Moyle et al., 2017). Outmigrating kelts (adult steelhead that have spawned and are migrating back downstream to the ocean) from these systems also typically leave their natal systems and migrate to marine habitats, marine entry occurs to the north and east of the northernmost portion of the California Study Area (Figure C-6).

Ocean rearing

As steelhead are infrequently captured in the marine environment, DPS-specific marine distribution for steelhead is limited. Steelhead, as a species, are broadly distributed across the North Pacific, ranging from California to Alaska in the Northeast Pacific, and west towards Russia in the Northwest Pacific (Myers et al., 1998). Further, less is known about the ocean rearing phase of California-origin steelhead than of those originating from river systems further north.

Burgner et al. (1992) conducted a review of steelhead documented in nearshore coastal waters. They found that in Oregon and Washington, young, age-0 steelhead that had recently migrated to the ocean were most abundant in the nearshore marine environment in May and were detected further offshore and further north in June and July. However, in northern Californian waters, juvenile steelhead were detected in the nearshore marine environment in July, but quickly moved offshore, with no age-0 fish caught in southern Oregon or northern California by August. Harding (2015), and others, noted captures of juvenile steelhead both north and south of Cape Blanco, Oregon in August (Moyle et al., 2017).

Burgner et al. (1992) also noted that, although approximately 1.2M California-origin steelhead were CWT and released between 1980–1988, no California CWT-tagged fish were recovered at sea. However, nine disk-tagged California-origin steelhead were captured in the Gulf of Alaska (Burgner et al., 1992). These authors suggest that California-origin steelhead may have a more westerly (as opposed to northerly) distribution than steelhead originating from more northern river systems. However, Myers et al. (1996) noted that five maturing California-origin steelhead were detected in the Gulf of Alaska, with Myers (2018) stating as many as nine maturing California-origin steelhead were detected in these waters.

Harding et al., (2021) analyzed summer 20102014 salmonid trawl surveys conducted along 16 east-west transect lines with five locations surveyed along each transect; from the northernmost location at Heceta Head, Oregon, south to Pigeon Point (Bodega Bay), California. They found that both juvenile and subadult steelhead catch per unit effort (CPUE) was greatest between Klamath River and the Eel River, and rare south of Cape Mendocino. Both juvenile and subadult steelhead occurred more frequently at offshore stations than Chinook or coho salmon (Harding et al., 2021). Juvenile steelhead were detected most frequently at locations with mean water depths from 55 to 122 m but were relatively absent in the catch at the most nearshore locations (mean depth of 30 m) and furthest offshore locations (mean

depth of 370 m). Subadult steelhead occurred most frequently at the furthest offshore locations and were infrequently captured at the most nearshore locations.

After the first month or two, juvenile steelhead move north and west away from the coastline and begin maturing. These older steelhead are difficult to capture as they are non-schooling, surface-oriented fish, with a very broad at-sea distribution. Relatively few older fish have been captured at-sea, though some authors reviewing capture data suggest that California-origin steelhead may be more abundant west, than north, though no comparative abundance studies were found in the literature. More recent pop-up satellite archival tags studies investigating marine occupancy of Alaska-origin kelts have shown that these fish tend to occupy ocean surface habitats directly over the shelf slope, where upwelling likely increases available food resources (Courtney et al., 2022; Seitz & Courtney, 2021).

While migrating and rearing in marine waters, steelhead are generally-surface oriented. Moore and Berejikian (2022) used acoustic tags with depth and temperature sensors to monitor the behavior of 498 steelhead smolts in the presence of a Puget Sound floating bridge. In the absence of the bridge, steelhead smolts were considered "nearly exclusively surface-oriented." Only when encountering the bridge did these fish occasionally dive to avoid the migration barrier and fish predators that congregate there. In a radio and sonic tagging study of the marine migratory behavior of 19 adult steelhead in a British Columbia fjord, Ruggerone et al. (1990) found that these fish spent the majority of time in the top two meters of the water column. In a pop-up satellite archival tag (PSAT) study of 16 steelhead kelts from the Situk River, Alaska, Seitz and Courtney (2021) found that these fish, once exiting this southeast Alaska river and entering the North Pacific Ocean, moved west of the continental slope, typically occurring in the top five meters of the water column, though occasionally diving as deep as 20 m.

Return migration

Northern California steelhead spend from 1 to 4 years rearing in the ocean prior to returning to their natal systems (Moyle et al., 2017). The diversity of having both ocean-maturing and stream-maturing fish within this DPS results in adult entry, at the DPS level, occurring year-round, with return timing tied to both system origin and life history type (Myers, 2018). Summer-run steelhead from this DPS return to estuaries between April and June in the northernmost systems for this DPS, between April and July in the Mad River, and between March and June in the Mattole River (Moyle et al., 2017). In larger rivers (e.g., Mad and Eel Rivers), winter-run adults leave the marine environment and enter estuaries as early as September of October. In smaller systems, enter the estuaries from December to May (Busby et al., 1996).

C.5.2.3.1.3 Population Trends

Overall, the available data for winter-run populations—predominately in the North Coastal, North-Central Coastal, and Central Coastal strata—indicate that all populations are well below viability targets, most being between 5 percent and 15 percent of these goals (National Marine Fisheries Service, 2024a). There is a mix in trends regarding the longer and shorter time series. Most supporting independent populations have shown downward (but non-significant) trends (National Marine Fisheries Service, 2024a).

Summer-run populations continue to be of significant concern. While Middle Fork Eel River population is closer to its 80 percent recovery target, other populations range from as low as 18–26 percent of their recovery target, or there is a lack of data to estimate percent recovery(National Marine Fisheries Service, 2024a). In summary, the available information for winter-run and summer-run populations of Northern California steelhead do not suggest an appreciable increase or decrease in extinction risk since

publication of the last status reviews and viability assessments. Although conservation efforts have reduced some threats facing this DPS, the threats have remained unchanged since the last review (National Marine Fisheries Service, 2024a). Poor ocean conditions, water withdrawals, marijuana cultivation and drought, in particular, have significant negative impacts on Northern California steelhead since the last review. In summary, the best available updated information on the biological status of and threats to Northern California steelhead DPS indicate it continues to remain a threatened species.

C.5.2.3.1.4 Population Threats

Most of the threats to steelhead occur outside the Study Area and include alteration of stream flow patterns and habitat degradation, barriers to fish passage, channel alterations, water quality problems, non-native fishes and plants, and climate change.

In addition, steelhead predators include seabirds, such as terns and cormorants, and marine mammals, such as sea lions and harbor seals (National Marine Fisheries Service, 2010g). Juveniles in freshwater feed mostly on zooplankton (small animals that drift in the water), while adults feed on aquatic and terrestrial insects, molluscs, crustaceans, fish eggs, minnows, and other small fishes, including other trout and salmon depending on whether they are inhabiting streams or the ocean (National Marine Fisheries Service, 2010g).

C.5.2.3.2 California Central Valley DPS

C.5.2.3.2.1 Status and Management

The California Central Valley Steelhead DPS was listed as threatened on March 19, 1998 (63 FR 13347) and their status was updated on January 5, 2006 (71 FR 834). This DPS includes naturally spawned steelhead originating below natural and manmade impassable barriers from the Sacramento and San Joaquin Rivers and their tributaries; excludes such fish originating from San Francisco and San Pablo Bays and their tributaries. In 2020, NMFS issued a final rule (85 FR 81822) adding the Mokelumne River Hatchery Program to this DPS which increased the total number of hatchery programs to three.

Critical Habitat

NMFS designated critical habitat for Central Valley DPS steelhead on September 2, 2005 (70 FR 52488). Critical habitat includes freshwater spawning sites, freshwater rearing sites, freshwater migration corridors, and estuarine areas. The PBFs that characterize these sites include water quality and quantity, natural cover, forage, adequate passage conditions, and floodplain connectivity necessary to support spawning, incubation and larval development, juvenile growth and mobility, and adult survival. Designated critical habitat for the Central Valley DPS steelhead does not overlap spatially with the HCTT Study Area (Figure C-6).

Recovery Goals

See the 2014 Recovery Plan for the California Central Valley Steelhead DPS for complete downlisting/delisting criteria for recovery goals for the species (National Marine Fisheries Service, 2014b). The delisting criteria for this DPS are:

- One population in the Northwestern California Diversity Group at low risk of extinction,
- Two populations in the Basalt and Porous Lava Flow Diversity Group at low risk of extinction,
- Four populations in the Northern Sierra Diversity Group at low risk of extinction,
- Two populations in the Southern Sierra Diversity Group at low risk of extinction, and
- Maintain multiple populations at moderate risk of extinction.

C.5.2.3.2.2 Habitat and Geographic Range

Geographic range of spawning systems for this DPS: Naturally spawned anadromous steelhead originating below natural and manmade impassable barriers from the Sacramento and San Joaquin Rivers and their tributaries; excludes such fish originating from San Francisco and San Pablo Bays and their tributaries. This DPS includes steelhead from three artificial propagation programs: the Coleman National Fish Hatchery Program, the Feather River Fish Hatchery Program, and the Mokelumne River Hatchery Program(79 FR 20802; 85 FR 81822).

Juvenile outmigrants

The remaining populations of California Central Valley steelhead are winter-run fish (Moyle, 2002; National Marine Fisheries Service, 2014e). California Central Valley steelhead fry emerge from the gravel in spring. Scale analysis indicates that 70 percent of juveniles from this DPS reared in freshwater systems for 2 years prior to migrating to the ocean (McEwan, 2001). This DPS, more so than more northern populations of steelhead, appears to have a higher proportion of fish that remain resident, and forego migrating to marine habitats (Crozier et al., 2019). Downstream migration of naturally-spawned juvenile steelhead from this DPS typically occurs from December to May, with a peak outmigration in March, with another small peak in fall (McEwan, 2001). When these fish leave their natal systems and migrate to marine habitats, marine entry occurs to the east of the northernmost portion of the California Study Area (Figure C-6).

Ocean rearing

Natural-spawning steelhead from this DPS are believed to rear in the ocean for 1–2 years, whereas hatchery fish typically spend 1–3 years in the marine environment (Crozier et al., 2019). As steelhead are infrequently captured in the marine environment, DPS-specific marine distribution for steelhead is largely unavailable. Therefore, with the additional DPS-specific finding from one fish in Teo et al. (2013) below, the ocean rearing description for Northern California steelhead would also be applicable for this DPS.

Teo et al. (2013) tagged 14 Coleman National Fish Hatchery kelts (11 females and 3 males) from this DPS with acoustic and archival tags. Tagged fish ranged in size from 17 to 20 in. Of these 14 fish, only one exited estuarine waters and was detected in coastal California waters. From May to August 2008, this fish ranged from as far north as offshore of Eureka and as far south as due west of Big Sur. This fish spent most of the time within 50 NM of the coast, though on a few occasions it was detected beyond 100 NM from shore (Teo et al., 2013).

Return migration

Adult California Central Valley steelhead return through the San Francisco estuary from August through April (Myers, 2018; National Marine Fisheries Service, 2014e) and are detected in their natal streams from late September through early April (Lindley et al., 2006; National Marine Fisheries Service, 2014e).

C.5.2.3.2.3 Population Trends

Continued decline in the ratio between naturally produced juvenile steelhead to hatchery juvenile steelhead in fish monitoring efforts indicates that the wild population abundance is declining (National Marine Fisheries Service, 2016c, 2023e; Williams et al., 2016a). Hatchery releases have remained relatively constant over the past decade, yet the proportion of adipose fin-clipped hatchery smolts to unclipped naturally produced smolts has steadily increased over the past several years. One continuing strength of this DPS is its widespread distribution throughout the Central Valley. While most of the measured populations are small, steelhead can be found in most of the major rivers and streams of the Sacramento River, San Joaquin River, and eastside tributaries including the Mokelumne River and Calaveras River. Although there have been recent restoration efforts in the San Joaquin River tributaries, California Central Valley steelhead populations in the San Joaquin Basin continue to show an overall very low abundance, and fluctuating return rates. The widespread distribution of wild steelhead in the Central Valley provides the spatial structure necessary for the DPS to survive and avoid localized catastrophes. However, most wild California Central Valley populations may lack the resiliency to persist for protracted periods if subjected to additional stressors, particularly widespread stressors such as climate change and drought (National Marine Fisheries Service, 2014d).

The genetic diversity of California Central Valley steelhead has likely been impacted by low population sizes and high numbers of hatchery fish relative to wild fish (Goetz et al., 2024; Huber et al., 2024). The best chance for eventual delisting of this species is expansion of their range, as it was the creation of dams that has removed them from over 80 percent of their original spawning and rearing habitat in the Central Valley. This species has clearly benefited from the removal of Saeltzer Dam on Clear Creek, resulting in one of the strongest steelhead populations in the Central Valley. NMFS concluded that California Central Valley steelhead remain listed as threatened, as the DPS is likely to become endangered within the foreseeable future throughout all or a significant portion of its range (National Marine Fisheries Service, 2016c, 2023e; Williams et al., 2016a).

C.5.2.3.2.4 Population Threats

Population threats are similar across many steelhead populations. Please see the description of these threats described for the Northern California Steelhead DPS.

C.5.2.3.3 Central California Coast DPS

C.5.2.3.3.1 Status and Management

The Central California Coast Steelhead DPS was listed as threatened on August 18, 1997 (62 FR 43937) and their status was reaffirmed on January 5, 2006 (71 FR 834) and updated on April 14, 2014 (79 FR 20802). This DPS includes naturally spawned steelhead originating below natural and manmade impassable barriers from the Russian River to and including Aptos Creek, and all drainages of San Francisco and San Pablo Bays eastward to Chipps Island at the confluence of the Sacramento and San Joaquin Rivers. This DPS also includes steelhead from two artificial propagation programs (79 FR 20802). There are no proposed changes in hatchery programs included in this DPS (81 FR 72759).

Critical Habitat

NMFS designated critical habitat for Central California Coast DPS steelhead on September 2, 2005 (70 FR 52488). Critical habitat includes freshwater spawning sites, freshwater rearing sites, freshwater migration corridors, and estuarine areas. The PBFs that characterize these sites include water quality and quantity, natural cover, forage, adequate passage conditions, and floodplain connectivity necessary to support spawning, incubation and larval development, juvenile growth and mobility, and adult survival. Designated critical habitat for the Central California Coast DPS steelhead does not overlap spatially with the HCTT Study Area (Figure C-6).

Recovery Goals

See the 2016 recovery plan for the Central California Coast Steelhead DPS for complete downlisting/delisting criteria for recovery goals for the species (National Marine Fisheries Service, 2016l). The recovery plan's objectives are to: 1) Reduce the present or threatened destruction, modification, or curtailment of habitat or range; 2) Ameliorate utilization for commercial, recreational, scientific, or educational purposes; 3) Abate disease and predation; 4) Establish the adequacy of existing regulatory mechanisms for protecting CCC steelhead now and into the future (i.e., post-delisting); 5) Address other natural or manmade factors affecting the continued existence of CCC steelhead; and 6) Ensure CCC steelhead status is at a low risk of extinction based on abundance, growth rate, spatial structure and diversity.

C.5.2.3.3.2 Habitat and Geographic Range

Geographic range of spawning systems for this DPS: Naturally spawned anadromous steelhead originating below natural and manmade impassable barriers from the Russian River to and including Aptos Creek, and all drainages of San Francisco and San Pablo Bays eastward to Chipps Island at the confluence of the Sacramento and San Joaquin Rivers. This DPS includes steelhead from two artificial propagation programs: the Don Clausen Fish Hatchery Program and the Kingfisher Flat Hatchery Program (Monterey Bay Salmon and Trout Project) (79 FR 20802).

Juvenile outmigrants

Central California Coast steelhead exhibit a broad range of life history patterns (Moyle et al., 2017). As indicated by Shapovalov and Taft (1954), as many as 32 different combinations of life history patterns from juvenile emergence, residency, and migration to adult spawning and migration occurs within steelhead in this geographic region. However, Central California Coast steelhead life history can be generally grouped into three categories: anadromous, freshwater resident, lagoon-anadromous (Bond, 2006; Moyle et al., 2017). All steelhead populations have the potential to produce both anadromous and freshwater resident fish. However, it's not until reaching the more southern populations of steelhead do they display the third variation to adapt to seasonal migrational barriers. As a result, juvenile steelhead, instead of maturing in marine environments, grow and mature in lower stem lagoons (Bond, 2006). These fish can then return as mature/maturing adults to upstream habitats suitable for spawning.

Following the late-spring spawning of adults, Central California Coast steelhead fry emerge from the gravel 5–7 weeks later. Like many steelhead populations, juveniles from this DPS may rear in freshwater systems for 1–3 years, though approximately 57 percent of Central California Coast steelhead remain in freshwater for two years before migrating downstream to towards the ocean (review within Crozier et al., (2019)). Larger smolts move directly to sea in the spring (Osterback et al., 2018), whereas smaller smolts rear in estuaries for an extended period (Bond, 2006). These "lagoon-anadromous life history" steelhead grow larger in freshwater lagoons and contribute to a larger proportion of adult spawners (Bond, 2006). Peak outmigration for anadromous variants occurs in April and May (Crozier et al., 2019) and peak outmigration for lagoon-anadromous occurs during winter storms (Bond, 2006). When these fish leave their natal systems and migrate to marine habitats, marine entry occurs to the east of the northernmost portion of the California Study Area (Figure C-6).

Ocean rearing

A literature review by Crozier et al. (2019) indicated that approximately 70 percent of spawning adults from this DPS spent 1–2 years maturing in the marine environment. However, as steelhead are infrequently captured in the marine environment, DPS-specific marine distribution for steelhead is largely unavailable. Therefore, with the additional DPS-specific findings from Hayes et al. (Bond et al., 2008; Hayes et al., 2011; Huber et al., 2024; Osterback et al., 2018), below, the ocean rearing description

for Northern California steelhead would also be applicable for this DPS (Bond et al., 2008; Hayes et al., 2011; Huber et al., 2024; Osterback et al., 2018).

From 2003 to 2008, Hayes et al. (2011) tagged and monitored steelhead at the Scott Creek Fish Hatchery with archival tags. Scott Creek is located approximately 60 mi. south of San Francisco. Although not included within the Central California Coast steelhead DPS, these hatchery fish originate from the same geographic area. They tagged a total of 319 steelhead, of these, 69 were attached to adult female steelhead (kelts) with the remaining tags deployed on smolts. To reconstruct at-sea travel range estimates, the authors conducted a literature review and ascertained that, while at sea. Steelhead display a mean swim speed of 15 mi./day, and a maximum of 53 mi./day, resulting in a 40 mi./day estimate for modeling (two standard deviations above the mean distance). Tag return rates were low, less than 1 percent for smolts and 2 percent for steelhead kelts. Only three of these tags indicated outmigration into the ocean; one smolt and two kelts. The archival tags indicated substantial variability. In 2004, one hatchery juvenile and one wild kelt generally occupied waters west of California and southern Oregon. However, the tags attached to a 2004 wild kelt and a 2007 hatchery kelt indicated that these fish occupied the Gulf of Alaska and North Pacific. Ideal sea surface temperature was thought to play a role in the broad marine distribution of steelhead.

Return migration

Steelhead originating from more northern streams within the Central California Coast Steelhead DPS typically return to spawn as age-2+ adults, whereas fish returning to more southern systems (e.g., Russian River) return as age 3+ adults (Moyle et al., 2017). Generally, adult steelhead from this DPS leave the marine environment and migrate upstream from October to May (Busby et al., 1996; Myers, 2018; Osterback et al., 2018), with peak entry occurring between November and February (Moyle et al., 2017), and spawning occurring in late spring.

C.5.2.3.3.3 Population Trends

In the North Coastal and Interior strata, steelhead still appear to occur in the majority of watersheds, though in the Russian River basin, the ratio of hatchery fish to natural origin fish returning to spawn remain largely unknown and continues to be a source of concern (Williams et al., 2016a). New information in the Santa Cruz Mountain stratum indicates that population sizes are perhaps higher than previously thought. However, the downward trend in the Scott Creek population, which has the most robust estimates of abundance, is a source of concern. The status of populations in the two San Francisco Bay diversity strata remains highly uncertain, and it is likely that many populations where historical habitat is now inaccessible due to dams and other passage barriers are at high risk of extinction. In summary, while data availability for this DPS remains poor, there is little new evidence to suggest that the extinction risk for this DPS has changed appreciably in either direction since publication of the last status review in 2010 (Williams et al., 2016a).

C.5.2.3.3.4 Population Threats

Population threats are similar across many steelhead populations. Please see the description of these threats described for the Northern California Steelhead DPS.

C.5.2.3.4 South-Central California Coast DPS

C.5.2.3.4.1 Status and Management

The South-Central California Coast Steelhead DPS was listed as threatened on August 18, 1997 (62 FR 43937) and their status was reaffirmed on June 28, 2005 (70 FR 37160) and updated on April 14, 2014

(79 FR 20802). This DPS includes naturally spawned steelhead originating below natural and manmade impassable barriers from the Pajaro River to (but not including) the Santa Maria River (79 FR 20802). No hatchery programs are currently included as part of this DPS.

Critical Habitat

NMFS designated critical habitat for South-Central California Coast DPS steelhead on September 2, 2005 (70 FR 52488). Critical habitat includes freshwater spawning sites, freshwater rearing sites, freshwater migration corridors, and estuarine areas. The PBFs that characterize these sites include water quality and quantity, natural cover, forage, adequate passage conditions, and floodplain connectivity necessary to support spawning, incubation and larval development, juvenile growth and mobility, and adult survival. Designated critical habitat for the South-Central California Coast DPS steelhead only includes freshwater spawning sites, freshwater rearing sites, freshwater migration corridors, and estuarine areas (70 FR 52488), not marine habitats, so it does not overlap spatially with the HCTT Study Area (Figure C-6).

Recovery Goals

See the 2013 recovery plan for the South-Central California Coast Steelhead DPS (National Marine Fisheries Service, 2013b) for complete down-listing/delisting criteria for recovery goals for the species. The Recovery Plan outlines the following coordinated actions that will be required for an effective steelhead recovery program:

- Prevent steelhead extinction by protecting existing populations and their habitats,
- Maintain current distribution of steelhead and restore distribution to some previously occupied areas,
- Increase abundance of steelhead to viable population levels, including the expression of all life-history forms and strategies,
- Conserve existing genetic diversity and provide opportunities for interchange of genetic material between and within viable populations within the DPS,
- Restore and maintain suitable habitat conditions and characteristics for all life-history strategies, thereby preserving the diversity of life-history strategies that allow for adaptation to a highly variable environment, and
- Conduct necessary research to refine recovery criteria, monitor the status and trends of individual populations, and adaptively modify recovery actions and strategies in response to new information and better understanding of the biology and habitat requirements of the species.

C.5.2.3.4.2 Habitat and Geographic Range

Geographic range of spawning systems for this DPS: Naturally spawned anadromous steelhead originating below natural and manmade impassable barriers from the Pajaro River to (but not including) the Santa Maria River (79 FR 20802).

As described for Central California Coast steelhead, South-Central California Coast and Southern California steelhead have also evolved to have anadromous, freshwater resident, lagoon-anadromous forms to ensure annual spawning occurs, even in the presence of downstream barriers to migration. To maintain occupancy within suitable habitat conditions, the two southernmost steelhead DPS's display greater range movement within and between freshwater habitats within a given system (Moyle et al., 2017). The proportion of these fish that leave the freshwater system and mature within the marine environment is unknown.

Juvenile outmigrants

South-Central California Coast steelhead fry emerge from the gravel from late spring through early summer. Like many other steelhead, juveniles from this DPS may rear in freshwater and estuarine habitats for 1–3 years. Juveniles migrate from freshwater habitat to estuaries in spring and summer. However, within the San Luis Obispo creek watershed, Spina et al. (2005) found that in observing three years of trap data that the peak downstream migration of steelhead smolts from this DPS occurred in April, with no smolts captured after May. As with other southern steelhead populations, due to low flows, outmigrating smolts from this DPS can get locked behind sandbars that delay their migration into marine waters. As a result, these fish could have their outmigration delayed by weeks or months (Moyle et al., 2017). When these fish leave their natal systems and migrate to marine habitats, marine entry occurs to the east of the California Study Area (Figure C-6).

Ocean rearing

As with other more southern populations of steelhead, ocean migration and rearing of South-Central California Coast steelhead is poorly understood. South-Central California Coast steelhead likely rear in the marine environment for two to four years (Moyle et al., 2017). Although fish from California have been detected as far north as the Gulf of Alaska (Burgner et al., 1992), it is likely that when adults have returned to their natal estuaries to find that they are blocked due to low stream flows, these fish remain relatively close to their natal systems in coastal California waters waiting for the barrier to be breached.

Return migration

In low water years where there are physical barriers to entering the estuaries (e.g., sandbars), returning South Central California Coast steelhead adults may delay their entry by weeks to a year (Moyle et al., 2017). Moyle et al. (2017) indicated that adults from this DPS can enter estuaries between January and May, before continuing their migration upstream to spawn. In a review, Myers (2018) indicated that adults begin entering the San Lorenzo River as early as November, where adults typically don't begin entering the Carmel River until January.

C.5.2.3.4.3 Population Trends

Following the completion of their most recent status review, NMFS (2023b) determined that, based on the best available information, including the new viability assessment, the current South-Central California Coast DPS recovery priority number remains the same as it was prior to this review (3C). The systemic anthropogenic threats identified at the time of the initial listing have remained essentially unchanged, though there has been significant progress in removing fish passage barriers in a number of the smaller and mid-sized watersheds. Threats to the South-Central California Coast DPS posed by environmental variability resulting from projected climate change are likely to exacerbate the factors affecting the continued existence of the DPS.

C.5.2.3.4.4 Population Threats

Population threats are similar across many steelhead populations. Please see the description of these threats described for the Northern California Steelhead DPS.

C.5.2.3.5 Southern California DPS

C.5.2.3.5.1 Status and Management

The Southern California Steelhead DPS was listed as threatened on August 18, 1997 (62 FR 43937) and their status was reaffirmed on June 28, 2005 (70 FR 37160) and updated on April 14, 2014 (79 FR 20802). This DPS includes naturally spawned steelhead originating below natural and manmade impassable barriers from the Santa Maria River to the U.S.-Mexico Border (79 FR 20802). No hatchery programs are currently included as part of this DPS.

Critical Habitat

NMFS designated critical habitat for Southern California DPS steelhead on September 2, 2005 (70 FR 52488). Critical habitat includes freshwater spawning sites, freshwater rearing sites, freshwater migration corridors, and estuarine areas. The PBFs that characterize these sites include water quality and quantity, natural cover, forage, adequate passage conditions, and floodplain connectivity necessary to support spawning, incubation and larval development, juvenile growth and mobility, and adult survival. Designated critical habitat for the Southern California DPS steelhead only includes freshwater spawning sites, freshwater rearing sites, freshwater migration corridors, and estuarine areas (70 FR 52488), not marine habitats, so it does not overlap spatially with the HCTT Study Area (Figure C-6).

Recovery Goals

See the 2012 recovery plan for the Southern California Steelhead DPS (National Marine Fisheries Service, 2012f) for complete down-listing/delisting criteria for recovery goals for the species. The Recovery Plan outlines the following coordinated actions that will be required for an effective steelhead recovery program:

- Prevent steelhead extinction by protecting existing populations and their habitats,
- Maintain current distribution of steelhead and restore distribution to some previously occupied areas,
- Increase abundance of steelhead to viable population levels, including the expression of all life history forms and strategies,
- Conserve existing genetic diversity and provide opportunities for interchange of genetic material between and within viable populations, and
- Maintain and restore suitable habitat conditions and characteristics to support all lifehistory stages of viable populations.
- Refine and demonstrate attainment of recovery criteria through research and monitoring.

C.5.2.3.5.2 Habitat and Geographic Range

Geographic range of spawning systems for this DPS: Naturally spawned anadromous steelhead originating below natural and manmade impassable barriers from the Santa Maria River to the Tijuana River at U.S.-Mexico Border (79 FR 20802).

Juvenile outmigrants

The highly variable environmental conditions where Southern California steelhead occur requires fish from this DPS to be highly adaptable to poor conditions and display multiple life history patterns. Like the two steelhead DPS's in closest proximity to the north, Southern California steelhead display anadromous, freshwater resident, lagoon-anadromous life history strategies. Habitat occupancy and

migration within streams at the southern extent of this species' range are dependent on winter rains bringing increased flows and lower temperatures. Like populations to the north, it's likely that lagoonanadromous steelhead represent a larger proportion of the spawning fish than do the anadromous steelhead in this DPS (Moyle et al., 2017).

Due to warmer conditions in southern habitats, Southern California steelhead eggs hatch more quickly than for steelhead further north. Juvenile steelhead can remain in freshwater systems for one to three years before migrating to the ocean. Growth rates are accelerated for juvenile steelhead within some southern systems. For example, Dagit et al. (Dagit et al., 2019; Huber et al., 2024) found that some freshwater systems produce large steelhead smolts by age-1 and age-2. Due to a combination of high growth rate and relatively poor freshwater conditions, those fish within this DPS that display anadromy may enter the marine environment at a younger age than other steelhead populations (Moyle et al., 2017). When these fish leave their natal systems and migrate to marine habitats, marine entry occurs to the east of PMSR, near Camp Roberts (Figure C-6).

Ocean rearing

Though ocean migration and rearing of Southern California steelhead is poorly understood, juveniles from this DPS are believed to outmigrate as age-1 or age-2 smolts. Age at outmigration is dependent on sufficient stream flows to navigate past physical barriers to fish migration, or to human assistance past these barriers (Stillwater Sciences, 2024). Fish from California have been detected as far north as the Gulf of Alaska (Burgner et al., 1992). Age at maturation for this DPS may be broader than for other DPS's. Although Southern California steelhead are thought to mature as age-2 to age-4 fish (Crozier et al., 2019), some of the returning fish may be age-5 and age-6 fish. This may be due, in part, to annual barriers to upstream migration, with ocean-rearing fish from this DPS spending an extended period in the marine environment waiting for natal stream barriers to be breached.

Return migration

Very little is known about mature adult steelhead from the Southern California Steelhead DPS. Only 177 adult steelhead from this DPS were documented over a 25-year period (Dagit et al., 2020). Adults appear to have a patchy coastal distribution that is tied to hydrologic conditions of their natal streams (Dagit et al., 2020). There is a high degree of interannual variability in observed presence, with adult detections ranging from as few as one fish to as many as 49 (annual average of five fish per year) (Dagit et al., 2020). Provided flows are sufficient to reduce or eliminate migration barriers, adult Southern California steelhead begin leaving the marine environment and entering their natal streams from September to November (Myers, 2018) to begin spawning from January through May, with peak spawning occurring from February through April (Crozier et al., 2019; Moyle et al., 2017).

C.5.2.3.5.3 Population Trends

Following the completion of their most recent status review, NMFS (National Marine Fisheries Service, 2023c) determined that, based on the best available information, including the new viability assessment, the current Southern California DPS recovery priority number remains the same as it was prior to this review (1C). The extended drought and genetic data documenting the high level of introgression and extirpation of native steelhead stocks in the southern portion of the DPS has elevated the threats level to the already endangered populations; the drought, and the lack of comprehensive monitoring, has also limited the ability to fully assess the status of individual populations and the DPS as whole. The systemic anthropogenic threats identified at the time of the initial listing have remained essentially unchanged over the past five years, though there has been significant progress in removing fish passage

barriers in several the smaller and mid-sized watersheds. Threats to the Southern California Steelhead DPS posed by environmental variability resulting from projected climate change are likely to exacerbate the factors affecting the continued existence of the DPS.

Steelhead stocks have declined substantially from their historic numbers and many now are threatened with extinction. Native lineages have been nearly extirpated from the southern region of the native range, with only a few relict populations persisting in the headwaters of the San Gabriel, Santa Ana, and San Luis Rey rivers (National Marine Fisheries Service, 2016s). Abadia-Cardoso et al. (2016) and Jacobson et al (2014) documented that the majority of steelhead sampled between southern California watersheds and Mexico were genetically related to hatchery rainbow trout. This may indicate either replacement of native steelhead or hybridization with native steelhead in southern California.

Most of the steelhead DPS, including the Southern California Coast DPS, have low abundances relative to historical levels, and there is widespread occurrence of hatchery fish in naturally spawning populations (Goetz et al., 2024; Good et al., 2005; Huber et al., 2024; National Marine Fisheries Service, 2010g, 2012c). NMFS has reported population sizes from individual DPSs, but because of these units occur together while at sea, it is difficult to estimate the marine population numbers.

C.5.2.3.5.4 Population Threats

Population threats are similar across many steelhead populations. Please see the description of these threats described for the Northern California Steelhead DPS.

C.5.2.4 Green Sturgeon (Acipenser medirostris)

C.5.2.4.1 Status and Management

NMFS has identified two DPS of green sturgeon; northern and southern (Israel et al. 2009). Effective June 6, 2006, NMFS determined that the Southern DPS of green sturgeon warranted listing as a threatened species under the ESA (71 FR 17757). Green sturgeon have been observed in large concentrations in the summer and autumn within coastal bays and estuaries along the west coast of the US, including the Columbia River estuary, Willapa Bay, Grays Harbor, San Francisco Bay and Monterey Bay (Huff et al. 2012; Lindley et al. 2011; Lindley et al. 2008; Moser and Lindley 2007).

Critical Habitat

NMFS designated critical habitat for this DPS on October 9, 2009 (74 FR 52300). Critical habitat includes coastal U.S. marine waters within 60 fathoms (360 ft.) depth from Monterey Bay, California north to Cape Flattery, Washington, to its U.S. boundary. Approximately 25 mi. due west of San Francisco Bay, a small portion of the northern study area boundary overlaps with designated green sturgeon critical habitat (Figure C-7). Critical habitat also includes several rivers and estuaries along the U.S. West Coast.

For coastal marine areas, the physical or biological features of critical habitat designated for green sturgeon include food resources, migratory corridors, and water quality. Corresponding species life history events include subadult growth and development, movement between estuarine and marine areas, and migration between marine areas, as well as adult sexual maturation, growth and development, movement, movements between estuarine and marine areas, migration between marine areas, and migration between stuarine and marine areas, migration between marine areas, and marine areas, migration between marine areas, and marine areas, migration between marine areas, and spawning migration (74 FR 52300).

Recovery Goals

See the 2018 Recovery Plan for the de-listing criteria crucial for the recovery of Southern DPS of green sturgeon (National Marine Fisheries Service, 2018b). The criteria for recovery are listed below:

- Abundance. The adult Southern DPS of green sturgeon census population remains at or above 3,000 for 3 generations (this equates to a yearly running average of at least 813 spawners for approximately 66 years). In addition, the effective population size must be at least 500 individuals in any given year and each annual spawning run must be comprised of a combined total, from all spawning locations, of at least 500 adult fish in any given year.
- Distribution. The Southern DPS of green sturgeon spawn successfully in at least two rivers within their historical range. Successful spawning will be determined by the annual presence of larvae for at least 20 years.
- Productivity. A net positive trend in juvenile and subadult abundance is observed over the course of at least 20 years.
- The population is characterized by a broad distribution of size classes representing multiple cohorts that are stable over the long term (20 years or more).
- Diversity. There is no net loss of Southern DPS green sturgeon diversity from current levels.
- Operation guidelines and/or fish screens are applied to water diversions in mainstem Sacramento, Feather, and Yuba rivers or San Francisco Bay Delta Estuary such that early life stage entrainment is below a level that limits juvenile recruitment.
- Threat-Based Recovery Criteria:
 - Access to spawning habitat is improved through barrier removal or modification in the Sacramento, Feather, and/or Yuba rivers such that successful spawning occurs annually in at least two rivers. Successful spawning will be determined by the annual presence of larvae for at least 20 years.
 - 2. Volitional passage is provided for adult green sturgeon through the Yolo and Sutter bypasses.
 - 3. Water temperature and flows are provided in spawning habitat such that juvenile recruitment is documented annually. Recruitment is determined by the annual presence of age-0 juveniles in the lower Sacramento River or San Francisco Bay Delta Estuary. Flow and temperature guidelines have been derived from analysis of inter-annual spawning and recruitment success and are informing this criterion.
 - 4. Adult contaminant levels are below levels that are identified as limiting population maintenance and growth.
 - 5. Take of adults and subadults through poaching and state, federal, and tribal fisheries is minimal and does not limit population persistence and growth.



Figure C-7: Designated Critical Habitat for the Southern DPS of Green Sturgeon in the Action Area

C.5.2.4.2 Habitat and Geographic Range

Offshore portions of the northernmost portion of the California Study Area overlaps with the marine distribution of the southern DPS of green sturgeon. Subadult green sturgeon leave their Californian natal rivers and disperse widely along continental shelf waters of the west coast, typically north and shoreward of the 110 m contour (Erickson & Hightower, 2007; Moyle, 2002; National Marine Fisheries Service, 2005). Sub-adult and mature Southern DPS green sturgeon are known to exit the estuary of their natal watershed (San Francisco Bay-Delta) and enter the marine environment during late fall, migrate north along the Pacific coast within a relatively a narrow depth corridor within the 110 m contour of the continental shelf, typically occupying depths of 40-70 m (Erickson & Hightower, 2007; National Marine Fisheries Service, 2005; Payne et al., 2015). These fish then move into Oregon and Washington bays and estuaries again from mid-summer through early fall (Heironimus et al., 2022, 2023; Heironimus et al., 2024; Israel et al., 2009; Moser & Lindley, 2007). Huff et al. (2011) found that upon initially exiting the bays and estuaries again in mid-September, green sturgeon remained at relatively shallow depths of just more than 20 m. By mid-October these fish moved to deeper habitats ranging from 50–60 m in depth. Huff et al. (2011) found that no tags reported from waters greater than 115 m depth. Though not typical since green sturgeon are naturally a demersal species, green sturgeon occasionally make rapid vertical ascents to near the surface (Erickson & Hightower, 2007).

While Huff et al. (2011) found that green sturgeon along the Siletz Reef near Lincoln City, Oregon, appeared to prefer marine areas with high seafloor complexity and boulder presence, Payne et al. (2015) found that that green sturgeon further south near the Umpqua River (Reedsport, Oregon) were associated with flat, soft bottom habitats that lack high relief bottoms. Information regarding their preference for areas of high seafloor complexity and prey selection in coastal waters (benthic prey) indicate green sturgeon reside and migrate along the seafloor while in coastal waters. Neither of these studies provided information on the prevalence of the southern DPS to the northern DPS.

Huff et al. (2012) estimated the distribution of green sturgeon by modeling species-environment relationships using oceanographic and migration behavior covariates with maximum entropy modeling of species geographic distributions. The models predicted that green sturgeon presence would vary somewhat throughout the species range across seasons, with a modeled predictive range extending from Baja California, Mexico, to the Bering Sea. However, the predictive concentration of green sturgeon was modeled to occur from approximately 41 to 51.5° N and in the vicinity of San Francisco and Monterey Bays from 36 to 37° N latitude. Trawl and fisheries observer data, as well as tagging studies prior to and following this publication, support the author's prediction that green sturgeon are primarily concentrated in the coastal waters of Washington, Oregon, and Vancouver Island (Huff et al., 2012).

In general, Huff et al. (2011) suggest that green sturgeon generally occur at low densities within the Pacific coastal marine environment, with northern habitats occupied more readily than southern habitats. Within northern regions where green sturgeon are more frequently observed, Heironimus et al. (2022, 2023; 2024) found that in June and July, subadult and adult green sturgeon become more prevalent in the coastal waters near Washington estuaries, apparently staging until estuary water quality is ideal.

The coastal distribution of green sturgeon in California waters is less understood than their occupancy in more northern waters. Miller et al. (Miller et al., 2020a) placed acoustic receivers within the San Francisco estuary and immediately north of the estuary at Point Reyes to detect acoustically tagged sturgeon, but their report did not indicate that any receivers were placed south of the estuary. The Point

Reyes receivers indicated small numbers of fish moving into and out of the estuary, but whether they moved north or south along the California coastline is unknown. As noted above, the distribution model developed by Huff et al. (Huff et al., 2012) indicated that the entire coastline of California could be suitable for green sturgeon, with the Monterey Bay area being suggested as an area with a higher probability of occurrence. However, with the supplement to Huff et al. (2012), the authors reviewed green sturgeon bycatch in limited entry trawl and California halibut fisheries in 2002–2010 from Washington, Oregon, and California. Although far more fishing effort occurred in Oregon and Washington than in California, of the 269 green sturgeon that occurred as bycatch in 55,711 commercial sets, none occurred south of Santa Cruz.

Over a two-year study period, Lindley et al. (Lindley et al., 2008) acoustically tagged more than 200 green sturgeon and monitored their detection using acoustic receivers from southeast Alaska to Monterey Bay. Unfortunately, the receivers in Monterey Bay were only deployed for 5 ½ months during the study (March–July 2005), but any potential differentiation between northern and southern DPS fish was not included. The Monterey Bay receivers detected very small numbers of green sturgeon from March–May 2005. Based on the limited number of studies investigating green sturgeon habitat occupancy in coastal California waters, it is estimated that green sturgeon likely occur in very low numbers south of the San Francisco estuary, relative to waters north of the estuary. There is insufficient data to estimate whether green sturgeon might occur more frequently in any given season along the California coastline.

C.5.2.4.3 Population Trends

The recovery criteria requires that the adult Southern DPS green sturgeon population remain at or above 3,000 for 3 generations. This equates to a yearly running average of at least 813 spawners for approximately 66 years (National Marine Fisheries Service, 2021b). However, in the most recent census, Mora et al. (2018) estimated the total population of Southern DPS green sturgeon at 17,548 individuals, with an estimated 2,106 adults, therefore notably below the recovery criteria.

C.5.2.4.4 Population Threats

Threats to the green sturgeon species that contribute to their risk of extinction include the loss of spawning habitat; concentration of spawning into a single spawning river; entrainment or impingement by water project operations, dredging, the Yolo Bypass migration barrier, power plant operations, or other in-water activities; bycatch of green sturgeon in other fisheries; and poor water quality conditions. The main factor in the decline of the Southern DPS of green sturgeon is the reduction of the spawning area to a limited section of the Sacramento River. Other threats to the DPS include insufficient freshwater flow rates in spawning areas; contaminants (e.g., pesticides); bycatch of green sturgeon in other fisheries; potential poaching (for caviar); entrainment by water projects; influence of non-native species; small population size; and elevated water temperatures (National Marine Fisheries Service, 2021b).

Larval and juvenile green sturgeon are likely eaten by other species present in freshwater spawning and rearing areas. Adult green sturgeon have few known predators, although some observations suggest predation by some shark species and marine mammals may occur (Emmett et al., 1991; Huff et al., 2011).

C.5.2.5 Eulachon (*Thaleichthys pacificus*)

C.5.2.5.1 Status and Management

The Southern DPS of Pacific Eulachon was listed as threatened under the ESA on March 18, 2010 (75 FR 13012. This listing includes all subpopulations of eulachon within the states of Washington, Oregon, and California and extended from the Skeena River in British Columbia south to the Mad River in Northern California.

Critical Habitat

Critical habitat for the Southern DPS was designated on October 20, 2011 (76 FR 65324). The southern DPS of Pacific eulachon has 16 specific designated areas as critical habitat within the states of California, Oregon, and Washington. The designated areas are a combination of freshwater creeks and rivers and their associated estuaries, comprising approximately 335 mi. (539 km) of habitat (76 FR 65324). Designated critical habitat for the Southern DPS of Pacific Eulachon does not overlap spatially with the HCTT Study Area.

Recovery Goals

See (National Marine Fisheries Service, 2017) for complete down listing/delisting criteria for the Southern DPS of eulachon. The goal of this recovery plan is to: 1) Increase the abundance and productivity of eulachon; 2) Protect and enhance the genetic, life history, and spatial diversity of eulachon throughout its geographical range; and 3) Reduce existing threats to warrant delisting of the species. To accomplish these goals, the Eulachon Recovery Team identified four recovery objectives:

- Ensure subpopulation viability.
- Conserve spatial structure and temporal distribution patterns.
- Conserve existing genetic and life history diversity and provide opportunities for interchange of genetic material between and within subpopulations.
- Eliminate or sufficiently reduce the severity of threats.

C.5.2.5.2 Habitat and Geographic Range

The Southern DPS of Pacific eulachon may be present in the most northern portions of the California Study Area. Eulachon typically spends three to five years in saltwater before returning to freshwater to spawn. They have been documented to occur from Point Conception, CA to Alaska (Gustafson et al., 2016b). Eulachon are primarily found within the "echo scattering layer" of the coastal continental shelf in near-benthic habitats of open marine waters (Gustafson et al., 2016b). Eulachon appear to live near the ocean bottom, or on the continental shelf at depths most commonly of 20–200 m, though they may occur as deep as 500 m (Wilson et al., 2006). Gustafson (2016b) found that the average depth of occurrence is between 137 and 147 m, with minimum depths of 59–79 m and maximum depths of 322–466 m.

C.5.2.5.3 Population Trends

Although eulachon spawn in the lower reaches of freshwater rivers and streams, they are primarily a marine fish, spending over 95 percent of their lives in ocean waters (California Department of Fish & Game, 2010; Gustafson et al., 2010; Gustafson et al., 2016a). The main spawning population in California has historically occurred in the Klamath River with smaller runs in the Mad River and Redwood Creek (California Department of Fish & Game, 2010). This spawning population represented the southernmost population of the species. In January 2006, a mature male eulachon was caught in a juvenile salmonid

monitoring rotary screw trap operation at Knights Landing in the Upper Sacramento River, indicating that this species is not locally extirpated; however, abundances are extremely low (California Department of Fish & Game, 2010).

C.5.2.5.4 Population Threats

Limited new information has become available regarding the threats to eulachon since the 2016 5-year review (National Marine Fisheries Service, 2022a). High to moderate threats to eulachon include climate change impacts on ocean conditions, dams /water diversions, eulachon by-catch, climate change impacts on freshwater habitat, predation, water quality, and destruction, modification or curtailment of eulachon habitat or range (National Marine Fisheries Service, 2022a).

Predators of adult Pacific eulachon include fish-eating birds, sturgeon, salmonids, Pacific halibut, and marine mammals (Hart, 1973).

C.5.2.6 Oceanic Whitetip Shark (Carcharhinus longimanus)

C.5.2.6.1 Status and Management

The oceanic whitetip shark was listed as threatened on January 30, 2018 (83 FR 4153). A comprehensive status review of the oceanic whitetip shark based on the best scientific and commercial information available was completed in 2016 (Young et al., 2016a). Young and Carlson (2020) summarized the biology and conservation information of the oceanic whitetip shark, identified information gaps, and discussed future directions for recovery of this species. In 2023, NMFS published a draft recovery plan which provides detailed information on the oceanic whitetip shark's biology, ecology, status and threats, and conservation efforts, as well as a description of site-specific management actions necessary for the conservation and survival of the species and objective, measurable criteria that, when met, will allow the species to be removed from the endangered and threatened species list (National Marine Fisheries Service, 2023d).

Critical Habitat

In 2020, NMFS concluded that critical habitat is not determinable because sufficient information is not currently available to assess the impacts of designation or regarding physical and biological features essential to the conservation of this species (85 FR 12898).

Recovery Goals

(National Marine Fisheries Service, 2024e)See (National Marine Fisheries Service, 2017, 2024e) for complete down listing/delisting criteria for the oceanic whitetip shark. The goal of this recovery plan is to increase oceanic whitetip shark viability across its range, such that the species can achieve recovery and be removed from the List of Endangered and Threatened Wildlife under the ESA (i.e., delisted). To accomplish this goal, the Recovery Team identified three recovery objectives:

- Ensure the oceanic whitetip shark maintains resiliency and geographic representation, and is a functional component of the ecosystem, by increasing overall abundance to achieve viable populations in all ocean basins.
- Increase oceanic whitetip shark resiliency by managing or eliminating significant anthropogenic threats.
- Ensure the continued viability of the oceanic whitetip shark through development and effective implementation of regulatory mechanisms for the long-term protection of the species.

C.5.2.6.2 Habitat and Geographic Range

Oceanic whitetip sharks are found worldwide in warm tropical and subtropical waters between the 30° N and 35° S latitude near the surface of the water column (Young et al., 2016a). Oceanic whitetips occur throughout the Central Pacific, including the Hawaiian Islands south to Samoa Islands and in the eastern Pacific from Southern California to Peru, including the Gulf of California. This species has a clear preference for open ocean waters, with abundances decreasing with greater proximity to continental shelves. In terms of California fish fauna, Allen and Cross (2006) categorized oceanic white tip sharks as holoepipelagic and individuals would be found mostly far from shore. Preferring warm waters near or over 20°C (68°F), and offshore areas, the oceanic whitetip shark is known to undertake seasonal movements to higher latitudes in the summer (National Oceanic and Atmospheric Administration, 2016e) and may regularly survey extreme environments (deep depths, low temperatures) as a foraging strategy (Young et al., 2016a).

Oceanic whitetip sharks could occur in deep open ocean areas in the California Current Large Marine Ecosystem. They are known to occur in Baja California and may be found in surface waters off the continental shelf (Baum et al., 2015). Oceanic whitetip sharks would be expected offshore of Hawaii, but only in pelagic waters off the continental shelf in the far western part of southern California.

C.5.2.6.3 Population Trends

While the current population size is unknown, the best available information indicates the oceanic whitetip shark has experienced significant declines in abundance throughout its range over at least the last several decades due to overutilization in commercial fisheries resulting in excessive fishing mortality (National Marine Fisheries Service, 2023d).

C.5.2.6.4 Population Threats

Threats include pelagic longline and drift net fisheries bycatch, targeted fisheries (for the shark fin trade), and destruction or modification of its habitat and range (Baum et al., 2015; Defenders of Wildlife, 2015b). Legal and illegal fishing activities have caused significant population declines for the oceanic whitetip shark. It is caught as bycatch in tuna and swordfish longlines throughout its range. Habitat degradation has occurred due to pollutants in the environment that bioaccumulate and biomagnify to high levels in their bodies due to their high position in the food chain, long life, and large size (Defenders of Wildlife, 2015b).

As an apex species in the tropical open ocean waters, the oceanic whitetip shark has few natural threats.

C.5.2.7 Scalloped Hammerhead Shark (Sphyrna lewini)

C.5.2.7.1 Status and Management

On July 3, 2014, four of six identified DPS of scalloped hammerhead sharks were listed as endangered or threatened (79 FR 38214). The Eastern Pacific DPS of the scalloped hammerhead population, which includes the west coast of the U.S. and the southern part of the California Study Area, is listed as endangered under the ESA. The central Pacific DPS, which includes the Hawaiian archipelago and the Hawaii Study Area, was not warranted for listing. The scalloped hammerhead shark has undergone substantial declines throughout its range (Baum et al., 2003b). There is some evidence of population increases in some areas of the southeast U.S., such as the Gulf of Mexico (Ward-Paige et al., 2012), but because many catch records do not differentiate between the hammerhead species, or shark species in general, population estimates and commercial or recreational fishing landing data are unavailable in the

Study Area. Most of the abundance data is from the Gulf of California, where it is estimated that the scalloped hammerhead population has been decreasing by 6 percent per year (INP, 2006).

Critical Habitat

In 2015, NMFS concluded that that there are no marine areas within the jurisdiction of the United States that meet the definition of critical habitat for the Eastern Pacific DPS of scalloped hammerhead shark (80 FR 71774). In addition, NMFS found that there are no identifiable physical or biological features that are essential to the conservation of the scalloped hammerhead DPSs (80 FR 71774).

Recovery Goals

There is currently no Recovery Plan for scalloped hammerhead sharks.

C.5.2.7.2 Habitat and Geographic Range

The scalloped hammerhead shark is a coastal and semi-oceanic species distributed in temperate and tropical waters (Froese & Pauly, 2016a). Distribution in the eastern Pacific Ocean extends from the coast of southern California (U.S.), including the Gulf of California, to Ecuador and possibly Peru (Compagno, 1984) and off Hawaii in the central Pacific ocean. A genetic marker study suggests that females remain close to coastal habitats, while males disperse across larger open ocean areas (Daly-Engel et al., 2012).

Juveniles rear in coastal nursery areas in the southern California portion of the Study Area (Duncan & Holland, 2006), but rarely inhabit the open ocean (Kohler & Turner, 2001). Sub adults and adults occur over shelves and adjacent deep waters close to shore and entering bays and estuaries (Compagno, 1984). In the California Current Large Marine Ecosystem, records of the presence of scalloped hammerhead sharks in this area are very rare. Sighting and landings in the Study Area are documented to have occurred in San Diego Bay in 1981, 1996, and 1997 (Shane, 2001). Results of a long-term telemetry study (2009–2020) by Hutchinson et al. (2023) found that adult males and juveniles tagged in Kaneohe Bay (Oahu) exhibit fairly restricted movements throughout the Hawaiian Archipelago, and mature males specifically exhibit strong seasonal site fidelity to Kaneohe Bay.

C.5.2.7.3 Population Trends

The scalloped hammerhead shark has undergone substantial declines throughout its range (Baum et al., 2003a). There is some evidence of population increases in some areas of the southeast (Ward-Paige et al., 2012), but because many catch records do not differentiate between the hammerhead species, or shark species in general, population estimates and commercial or recreational fishing landing data are unavailable in the Study Area.

Specific information for the Eastern Pacific DPS of scalloped hammerhead shark is unavailable as only data for overall shark population estimates are available. In its 2014 status review, NMFS used two models to estimate the overall population of scalloped hammerhead sharks to range from approximately 142,000 to 169,000 individuals in 1981 and between 24,000 and 28,000 individuals in 2005 (Miller et al., 2014). Although there are no population estimates specifically for the Eastern Pacific DPS in Southern California, estimates of historical (~3,600 to 12,000 years ago) effective population sizes for the entire eastern Pacific region range from 34,995 to 43,551. However, Nance et al. (2011) reported that the current effective population size of the Eastern Pacific DPS is significantly smaller (1–3 orders of magnitude) than the historical effective population size. In general, however, the species has higher occurrence in the eastern tropical Pacific south of Southern California (Musick & Fowler, 2007). In 2019,

NMFS announced its intent to conduct a 5-year review for the four DPSs of the scalloped hammerhead shark (84 FR 46938), however this review has not yet been completed.

Historically, three species of hammerhead sharks have been reported in California waters, although all are noted as uncommon species: *Sphyrna zygaena* (smooth hammerhead shark), *S. tiburo* (bonnethead shark), and *S. lewini* (scalloped hammerhead shark) (Shane, 2001). All three species have similar eastern Pacific distributions with smooth hammerhead shark being the more frequent of the uncommon species in California waters (Allen et al., 2006).

With a lack of population data for the Southern California area and likely limited occurrence due to very warm water preference, fisheries data is one method for assessing frequency of occurrence. Even though these types of data are often biased, fishery direct catch and bycatch data are often the most reliable source of information on the presence of transient, infrequent marine species such as the Eastern Pacific DPS of scalloped hammerhead shark.

Fusaro and Anderson (1980), Seigel (1985), and Shane (2001) report on known documented scalloped hammerhead shark catches in Southern California:

- First documented catch of a scalloped hammerhead in Southern California was for a single shark caught 1 mi. (2 km) off Santa Barbara in 1977 (Fusaro & Anderson, 1980)
- Three catches were recorded from Los Angeles County in 1984, with one shark reported as a juvenile (Seigel, 1985)
- 19 juvenile sharks (9 females/10 males) were caught by commercial gillnet and scientific research gillnets in south San Diego Bay from 1996 to 1997 (Shane, 2001)¹

The San Diego Bay scalloped hammerhead shark catches were associated with the unusually strong 1997–1998 El Niño event (National Weather Service Climate Prediction Center 2014a). Shane (2001) reported monthly mean surface sea water temperature off La Jolla from 1926 to 1994 as ranging from 14–19°C with temperatures during the 1997–1998 El Niño being elevated 3–4°C higher than normal. Long term maximum coastal sea water temperatures off San Diego typically average around 21°C (70–71°F) (National Weather Service Climate Prediction Center 2014b).

C.5.2.7.4 Population Threats

The primary threat to the scalloped hammerhead shark is direct take, especially by the foreign commercial shark fin fishery (Miller et al., 2014; National Marine Fisheries Service, 2011d). Scalloped hammerheads are a principal component of the total shark bycatch in the swordfish and tuna longline fishery and are particularly susceptible to overfishing and bycatch in gillnet fisheries because of schooling habits (Food and Agriculture Organization of the United Nations, 2013). Longline mortality for this species is estimated between 91 and 94 percent (National Marine Fisheries Service, 2011d).

Scalloped hammerhead sharks have few predators and few natural threats. However, because the this species is found over broad geographic ranges, large-scale impacts such as global climate change that affect ocean temperatures, currents, and potentially food chain dynamics, most likely to pose the greatest natural threat to this species (Miller et al., 2014).

¹ The highly estuarine south San Diego Bay area was also influenced by a thermal plume from seawater discharge by a regional power plant. The power plant and discharge pipe was decommissioned and demolished in February 2013.

C.5.2.8 Giant Manta Ray (*Manta birostris*)

C.5.2.8.1 Status and Management

The giant manta ray was listed as a threatened species under the ESA by NMFS on January 12, 2018 (83 FR 2916). NMFS also found that that critical habitat for the giant manta ray is not determinable due to the lack of sufficient data to perform the required analyses.

Critical Habitat

In 2019, NMFS determined that a designation of critical habitat was not prudent because there are no identifiable physical or biological features that are essential to the conservation of the giant manta ray within areas under U.S. jurisdiction (84 FR 66652).

Recovery Goals

There is currently no Recovery Plan for giant manta rays.

C.5.2.8.2 Habitat and Geographic Range

Giant manta rays are visitors to productive coastlines with regular upwelling, including oceanic island shores, and offshore pinnacles and seamounts. They utilize sandy bottom habitat and seagrass beds, as well as shallow reefs, and the ocean surface both inshore and offshore. The species ranges globally and is distributed in tropical, subtropical, and temperate waters. Typically they seasonally migrate more than 1,000 km (621.4 mi.), however not likely across ocean basins (National Oceanic and Atmospheric Administration, 2016d).

Although giant manta rays are found throughout the Hawaiian Islands, due to their typically more oceanic distribution (Stewart et al., 2016a), they are far less abundant in the coastal waters of the islands than reef mantas, *Manta alfredi* (Kashiwagi et al., 2011). In a genetic connectivity study, Whitney et al., (Whitney et al., 2023) found that manta rays in the Hawaiian archipelago have small, genetically-isolated resident island populations, suggesting that female manta rays are strongly philopatric (remain near a particular area) and do not migrate between island groups. Southern California is the northern edge of the giant manta ray's distribution in the California Current Large Marine Ecosystem (Defenders of Wildlife, 2015a).

C.5.2.8.3 Population Trends

No stock assessments exist for the giant manta ray. Most estimates of subpopulations are based on anecdotal observations by divers and fishermen, with current populations throughout its range estimated between 100 and 1,500 individuals (Miller & Klimovich, 2016). In general, giant manta ray populations have declined, except in areas where they are specifically protected, such as the Hawaiian Islands (National Oceanic and Atmospheric Administration, 2016d). Giant manta rays reach maturity at age 10 and have one pup every two to three years (National Oceanic and Atmospheric Administration, 2016d).

C.5.2.8.4 Population Threats

Threats to giant manta rays include fisheries and bycatch, and destruction or modification of habitat. The international market highly values the gill plates of the giant manta ray for use in traditional medicines. They also trade their cartilage and skins and consume the manta ray meat or use it for local bait. Bycatch occurs in purse seine, gillnet, and trawl fisheries as well (National Oceanic and Atmospheric Administration, 2016d). Other potential threats include degradation of coral reefs, interaction with marine debris, marine pollution, and boat strikes (Food and Agriculture Organization of the United Nations, 2013).

Threats to giant manta rays include disease and predation. Because of their large size, mantas have few natural predators and only large sharks such as tiger sharks and some hammerhead species are thought to be capable of preying on adult mantas (Manta Trust, 2017).

C.5.3 Species Not Listed under the Endangered Species Act

C.5.3.1 Jawless Fishes-Hagfishes (Order Myxiniformes) and Lampreys (Order Petromyzontiformes)

Hagfishes and lamprey are primitive, cartilaginous, vertebrates with very limited external features often associated with fishes, such as fins and scales (Helfman et al., 2009). Both groups inhabit marine water column and soft bottom seafloor habitats in depths greater than 30 m and below 13°C in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems.

Hagfish reproduction and early development has not been observed, and captive breeding has been unsuccessful (Powell et al., 2005). Females lay leathery eggs on the seafloor and when the eggs hatch, they are essentially miniature adults. Hagfishes prey on dying fishes or feed on dead fishes. Some hagfishes have commercial fishery importance as their external "skin" is used for making "eel leather" goods.

Lampreys are anadromous and larvae are buried in the soft bottoms of river backwaters (Moyle & Cech, 2004). Juvenile lamprey filter feed on algae and detritus. Adults are parasitic and use their oral disc mouth to attach to other fishes and feed on their blood (Moyle & Cech, 2004; Nelson et al., 2004). Hagfishes and lampreys have no known predators.

C.5.3.2 Ground Sharks (Orders Carcharhiniformes), Mackerel Sharks (Order Lamniformes), Carpet Sharks (Order Orectolobiformes), and Bullhead Sharks (Order Heterodontiformes)

Ground sharks and allies (bull, dusky, hammerheads, oceanic whitetip, and tiger) are cartilaginous fishes with two dorsal fins, an anal fin, five gill slits, and eyes with nictitating membranes. Reproduction includes internal fertilization with the young born fully developed. These sharks are highly migratory. They are found in the water column and bottom/seafloor habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems and open ocean areas. These sharks are associated with hard and soft bottoms, nearshore and open ocean surface waters, and deep-sea habitats.

Mackerel sharks and allies (great white, makos, and porbeagle) are cartilaginous fishes with a large first dorsal fin that is high, erect, and angular or somewhat rounded, anal fin with a keel, and a mouth extending behind the eyes. Reproduction includes internal fertilization with young being produced by means of eggs that are hatched within the body of the female. They are found in the water column and bottom/seafloor habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems and open ocean areas. These sharks are associated with nearshore and open ocean surface water habitats. Ground and Mackerel Sharks are efficient predators on large fishes, cephalopods, and marine mammals. Some species are targeted for commercial and recreational purposes.

Carpet sharks and allies are a diverse group inhabiting coral and rocky reefs in the order Orectolobiformes. This group includes whale sharks, which are the largest shark in the group and are one of three filter feeding sharks. Many of the carpet sharks, such as whale shark, are also highly migratory. Carpet sharks all share certain characteristics, including their mouth being completely in front of the eyes, both dorsal fins without spines, five pairs of gill slits, and an anal fin being present. Nurse sharks are also in this group and are usually yellowish-tan to dark brown, average around 8–9 ft. long, and can weigh over 200 pounds. They are nocturnal, scouting the sea bottom for prey such as crustaceans, molluscs, and stingrays. They spend most of the day resting on sandy bottom or in caves or reef crevices. Whale sharks are another member of the carpet sharks group and are the largest shark in the world, growing to a length of over 40 ft.

Bullhead sharks and allies (horn shark) are cartilaginous fishes with two dorsal fins, an anal fin, five gill slits, and eyes without nictitating membranes. Reproduction includes internal fertilization with egg cases laid in crevices. They are found in the bottom/seafloor habitat in the California Current Large Marine Ecosystems and are associated with soft bottoms habitat.

C.5.3.3 Frilled and Cow Sharks (Order Hexanchiformes), Dogfish Sharks (Order Squaliformes), and Angel Sharks (Order Squatiniformes)

Frill and cow sharks (sevengill, sixgill) are cartilaginous fishes, generally characterized by lacking traits such as an anal fin and nictitating membrane; they do possess six to seven gill slits, compared to five gill slits found in all other sharks. Reproduction includes internal fertilization with young being produced by means of eggs that are hatched within the body of the female. They are associated with deep-sea habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems (Froese & Pauly, 2016b; Moyle & Cech, 2004).

Dogfish sharks are cartilaginous fishes with two dorsal fins spines and a caudal fin that's divided into two lobes: a larger dorsal lobe and a smaller ventral lobe. Reproduction includes internal fertilization with young emerging from eggs that are hatched within the body of the female. They are associated with soft bottom and deep-sea habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems (Froese & Pauly, 2016b; Moyle & Cech, 2004).

Angel sharks (e.g., Pacific angel shark) are cartilaginous fishes with flat, batoid-like body, two small spineless dorsal fins behind pelvic fins, and anal fin absent. Reproduction includes internal fertilization with young emerging from eggs that are hatched within the body of the female. They are associated with soft bottom habitat in the California Current Large Marine Ecosystem (Froese & Pauly, 2016b; Moyle & Cech, 2004).

C.5.3.4 Stingrays and Allies (Order Myliobatiformes), Sawfishes (Order Pristiformes), Skates and Guitarfishes (Order Rajiformes), and Electric Rays (Order Torpediniformes)

Stingrays and allies (eagle ray, manta) are cartilaginous fishes, distinguished by flattened bodies, enlarged pectoral fins that are fused to the head and gill slits that are placed on their ventral surfaces. Reproduction includes internal fertilization with the young born fully developed. They are associated with reefs, nearshore open ocean, inland waters, and deep-sea water column habitat in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems (Froese & Pauly, 2016b; Moyle & Cech, 2004).

Skates and guitarfishes are cartilaginous fishes, distinguished by flattened bodies, two reduced dorsal fins, and a reduced caudal fin. Reproduction includes internal fertilization and deposition of egg sacks. They are associated with soft bottom habitat in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems (Froese & Pauly, 2016b; Moyle & Cech, 2004).

Electric rays are cartilaginous fishes, distinguished by flattened bodies, two well-developed dorsal fins and caudal fin. Two large kidney shaped organs in a disc on either side of the electric ray's head distinguish it from others, as these organs are able to produce strong electric shock at will (Madl & Yip, 2000). Reproduction includes internal fertilization with young being produced by means of eggs that are hatched within the body of the female. Only one species, the Pacific electric ray (*Torpedo californica*), has been recorded in the Study Area.

C.5.3.5 Ratfishes (Order Chimaeriformes)

Ratfishes (chimera, rabbitfish, and ratfish) are cartilaginous fishes, with smooth skin largely covered by placoid scales, and their color can range from black to brownish gray. Reproduction includes internal fertilization and deposition of egg capsules. Fishes in this group are associated with soft bottom and deep-sea habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems (Froese & Pauly, 2016b).

C.5.3.6 Herrings (Order Clupeiformes)

Herring and allies (anchovies, herrings, sardines, and shad) are bony fishes with a silvery body with the lateral line and fin spines absent, and usually scutes along ventral profile. They are found only in the marine environment in the water column and in seafloor habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems. Herring, menhaden, sardine, and anchovy species are well-known as valuable targets of commercial fisheries. Herring account for a large portion of the total worldwide fish catch (Food and Agriculture Organization of the United Nations, 2005, 2009). Herrings and allies are broadcast spawners. They are known to form schools to help conserve energy and minimize predation (Brehmer et al., 2007), which may facilitate some level of communication during predator avoidance (Marras et al., 2012). They feed on decaying organic matter and plankton while swimming in the water column (Moyle & Cech, 2004). Herring and allies support marine food webs as a forage fish and preyed upon by fish, birds, and marine mammals.

C.5.3.7 Tarpons (Orders Elopiformes and Albuliformes)

Tarpons and allies (bonefishes, halosaurs, Hawaiian ladyfish, and machete) are bony fishes with the body encased in silvery scales, a large mouth, a single dorsal fin (most), and a somewhat tapered tail with fin spines absent. They are associated with riverine, estuarine and marine environments on the surface, water column, and seafloor/bottom habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems. Tarpon and allies are important game species but are not considered edible. Tarpons and allies are broadcast spawners. Fertilized eggs float in the water column until hatching into a leptocephalous larva (ribbon-like, with no resemblance to the adult). During the change from larvae to juvenile, the body shrinks in length. Juveniles prey upon plankton and marine invertebrates, while adults feed on mid-water fishes. Tarpon and allies are nocturnal ambush predators (Wainwright & Richard, 1995) who prey on bottom-dwelling invertebrates and small fishes. Tarpons and allies are preyed upon by larger fishes, birds, and marine mammals.

C.5.3.8 Eels (Anguilliformes, Notacanthiformes, and Saccopharyngiformes)

Eels (conger, cutthroat, duckbill, false moray, morays, sawtooth, short-tailed, spiny, gulpers, and pelican eels) are bony fishes with a very elongate body, usually scaleless with pelvic fins, and without fin spines. They are associated with riverine, estuarine and marine environments in the water column, and seafloor/bottom habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems. Eels and allies have little fishery importance. Some species are broadcast spawners, and fertilized eggs float in the water column until hatching into a leptocephalous larva. Juveniles prey upon plankton and marine invertebrates, while adults feed on small fishes. Depending on the species and its habitat, eels can be diurnal or nocturnal ambush predators and prey on bottom-dwelling invertebrates and small fishes. Eels are preyed upon mostly by larger fishes.

C.5.3.9 Argentines and Allies (Order Argentiniformes)

Argentines and allies (argentines, barreleyes, deep-sea smelts, slickheads, and tubeshoulders) are bony fishes with typically silvery, elongate bodies, adipose fin and extremely large mouths sometimes present, and pelvic fins and spines sometimes absent. They are found only in the marine environment in the water column, and seafloor habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems. Argentines and allies have little fishery importance. Argentines and allies vary in their reproduction strategy. Some deep-sea species are capable of bioluminescence and release scents that may help to attract mates. Argentines are broadcast spawners and fertilized eggs float in the water column until hatching. Argentines and allies likely have few predators, but may be preyed upon by larger fishes.

C.5.3.10 Bristlemouths (Order Stomiiformes) and Allies

Bristlemouths and allies (dragonfishes, fangjaws, hatchfishes, and lightfishes) are bony fishes with photophores and adipose fin present and chin barbels sometimes present. Bristlemouths and hatchetfishes are small in size and the most abundant fishes in many parts of the world's oceans. They are capable of eating large and small prey items and are known to engage in prey-related vertical migration patterns. Other species in this order are largely piscivorous (Moyle & Cech, 2004).

C.5.3.11 Greeneyes and Allies (Order Aulopiformes)

Greeneyes and allies (barracudinas, daggertooth, lizardfishes, pearleyes, and waryfishes) are bony fishes with an upper protrusible jaw, an adipose fin and forked tail usually present with fin spines absent. Most greeneyes and allies are small (less than 50 cm) predators capable of devouring a wide range of species, including other fishes nearly their same size and pelagic invertebrates. Fishes in this order are preyed upon by salmon, tunas, and swordfishes. Reproduction is usually external, and includes the ability to change sex (Froese & Pauly, 2016b).

C.5.3.12 Lanternfishes and Allies (Order Myctophiformes)

Lanternfishes and allies (headlight, lampfishes, and lancetfishes) are bony fishes that are usually smallsized, with an adipose fin, forked tail and photophores usually present. Lanternfishes can occur closer to the surface at night (10–100 m) and deeper during the day (300 to 1,200 m) (Froese & Pauly, 2016b), where they may become prey for marine mammals. These fishes often are an important part of the deep scattering layer (Moyle & Cech, 2004). Lanternfishes prey upon copepods and krill (Tyler & Pearcy, 1975).

C.5.3.13 Hakes and Allies (Order Gadiformes)

Hakes and allies (cods, codlings, grenadiers, and whiptails) are bony fishes with long dorsal and anal fins, no true spines in fins, although spinous rays present in dorsal fin of most species, and chin barbels are often present. Hakes and allies account for approximately half of the global commercial landings (Food and Agriculture Organization of the United Nations, 2005). Prey items for fishes in this group include small crustaceans during juvenile phases and larger crustaceans, squid and fishes as adults. Predators include striped bass, sharks, and cetaceans (Froese & Pauly, 2016b).

C.5.3.14 Brotulas and Allies (Order Ophidiiformes)

Brotulas and allies (cusk-eels) are bony fishes with pelvic absent or far forward and filamentous, dorsal and anal fins joined to caudal fin, and spines absent. These fishes exhibit a variety of reproductive strategies including external fertilization and giving live birth. Prey items for fishes in this group include

small crustaceans during juvenile phases and larger crustaceans, squid and fishes as adults. Predators include striped bass, sharks, and cetaceans (Froese & Pauly, 2016b).

C.5.3.15 Toadfishes and Allies (Order Batrachoidiformes)

Toadfishes and allies (midshipman) are bony fishes with compressed bodies, large, depressed head and mouth usually with tentacles, and two dorsal fins with the first with spines. These fishes are known to build nests (Moyle & Cech, 2004).

C.5.3.16 Anglerfishes and Allies (Order Lophiiformes)

Anglerfishes and allies (footballfishes, frogfishes, goosefishes, and sea devils) are bony fishes with globulose bodies, a spine on the first dorsal fin and the pelvic fins usually absent. Anglerfish attract potential prey using their first dorsal fin (illicium) as a lure (Yasugi & Hori, 2016). Fishes in these orders are found occasionally on the surface, but most frequently in the water column and seafloor habitats. Additional adaptations include large mouths, sharp teeth, and sensitive lateral line (sensory) systems (Haedrich, 1996; Koslow, 1996; Marshall, 1996; Rex & Etter, 1998; Warrant & Locket, 2004). These fishes are mostly generalist feeders. Reproduction is not well studied, but sexes are separate and some exhibit parasitism (Moyle & Cech, 2004). Fishes in this group generally have no fishery importance.

C.5.3.17 Flyingfishes (Order Beloniformes)

Flyingfishes (halfbeaks, needlefishes, and sauries) are bony fishes with jaws extended into a beak; pelvic fins very large wing-like; spines absent. These fishes are associated with reefs, submerged aquatic vegetation, and open ocean habitat in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems and open ocean areas (Froese & Pauly, 2016b).

C.5.3.18 Killifish (Order Cyprinodontiformes)

Killifishes such as the California killifish (*Fundulus parvipinnis*) is bony fish with a protrusible upper jaw, fin spines rarely present, and a single dorsal fin. Killifishes are found in the water column of rivers and estuaries in the California Current Large Marine Ecosystem.

C.5.3.19 Silversides (Order Atheriniformes)

Silversides (grunion, jacksmelt, and topsmelt) are bony fishes with a silvery stripe on their sides, high pectoral fins, a dorsal fin, and a pelvic fin with a spine. These fishes are found on the surface and in the water column in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems.

C.5.3.20 Opahs and Allies (Order Lampriformes)

Opahs and allies (crestfishes, oarfishes, ribbonfishes, tapertails, and tube-eyes) are bony fishes with an upper protrusible jaw, and pelvic fins located forward on body, below, or just behind insertion of pectoral fins. Toadfishes (midshipman) have compressed bodies; large, depressed head and mouth usually with tentacles; and two dorsal fins, the first with spines. Fishes in this group exhibit a variety of reproductive strategies including external fertilization and parasitism. Prey items for fishes in this group include crustaceans, squid, and fishes. These fishes are found in the water column and seafloor habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems and open ocean areas.

C.5.3.21 Squirrelfishes and allies (Order Beryciformes)

Squirrelfishes and allies (bigscales, fangtooths, pricklefishes, slimeheads, and whalefishes) are bony fishes with round bodies and one dorsal fin often set far back, with pelvic fins absent and fin spines often present. Squirrelfishes (family Holocentridae) are the largest and most widely distributed family in

the order, with over 60 species found throughout tropical and subtropical marine habitats (Moyle & Cech, 2004). Most species in this group occupy shallow nearshore reef and rocky areas where they hide during the day and come out at night to feed on zooplankton in the water column.

C.5.3.22 Dories and Allies (Order Zeitformes)

Dories and allies (boarfishes, oreos, and tinselfishes) are bony fishes that have deeply compressed bodies, protrusible jaws, spines in dorsal fin, and pelvic fin spines sometimes present. There are three species reported in the Study Area (Froese & Pauly, 2016b). These fishes are only found in marine habitats, and most are deep-sea species. Fishes in this order typically have large heads with distensible jaws that allow them to capture larger-sized prey, including fishes and crustaceans.

C.5.3.23 Pipefishes and Allies (Orders Syngnathiformes)

Pipefishes and allies (cornetfish, seahorses, and snipefishes) are bony fishes that exhibit unique body shapes with a tube-like snout, small mouth, and scales that are often modified bony plates. These fishes are associated with hard and soft bottom, submerged aquatic vegetation, reefs, and deep-sea habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems (Froese & Pauly, 2016b; Paxton & Eshmeyer, 1998). Some pipefishes and allies exhibit a high level of parental care by brooding pouches (male seahorses), which results in relatively few young being produced (Helfman et al., 2009). Most fishes in this group are diurnal ambush predators and prey on zooplankton, marine invertebrates, and small fishes. Pipefishes and allies are preyed upon by larger fishes and birds.

C.5.3.24 Sticklebacks (Order Gasterosteiformes)

Sticklebacks are small fishes comprised of only seven species that live in freshwater, saltwater, or brackish water (Helfman et al., 2009; Moyle & Cech, 2004). Species in this group are easily recognized by the presence of three to 16 isolated spines on their back in front of the dorsal fin, large eyes, and small upturned mouths. Most species in this group possess a row of bony plates on each side. Some sticklebacks display parental care through nest building. Fishes in this group are found in littoral marine waters and freshwater habitats in the Study Area.

C.5.3.25 Scorpionfishes (Order Scorpaeniformes)

Scorpionfishes and allies (poachers, rockfishes, snailfishes, and sculpins) are bony fishes with usually strong spines on head and dorsal fin, cheeks with bony struts, and rounded pectoral fins. These fishes are associated with hard and soft bottom, reefs, and deep-sea habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems and open ocean areas (Froese & Pauly, 2016b; Paxton & Eshmeyer, 1998). Some scorpionfishes have commercial and recreation fishery importance (Moyle & Cech, 2004). Reproduction methods vary widely between species and include external fertilization and egg deposition (sculpins) and internal fertilization and bearing live young (rockfishes). Most fishes in this group are diurnal ambush predators and prey on bottom-dwelling invertebrates and small fishes. Scorpionfishes are allies are preyed upon by larger fishes, birds, and marine mammals.

C.5.3.26 Mullets (Order Mugiliformes)

Mullets (blue spot, flathead grey, kanga, striped) are bony fishes with a streamline body, forked tail, hard angled mouth, large scales, high pectoral fins, and pelvic fins with one spine. Striped mullet is an important commercial fishery (Froese & Pauly, 2016b). These fishes are associated with soft bottom, reefs, and nearshore open ocean habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems (Froese & Pauly, 2016b; Moyle & Cech, 2004). Mullet are catadromous; they spawn in saltwater but spend most of their lives in freshwater environments. Mullet farming is also an ancient
Hawaiian tradition that pre-dates European contact with the islands (Costa-Pierce, 2012). Fishponds in ancient Hawaii were developed in upland areas to cultivate taro and simultaneously grow a limited range of euryhaline and freshwater fish, such as mullet.

C.5.3.27 Order Perciformes

Perciforms are the largest order of vertebrates, with over 7,800 species. They are extremely diverse, but most species are adapted for life as predators in the shallow or surface waters of the ocean. Some of the characteristics include fin spines present, dorsal fins either double or made up of two distinct parts with the lead spiny, adipose fin absent, pelvic fins thoracic or jugular in position or absent, pectoral fins on side of body, ctenoid scales, and closed swim bladder. Nearly half of all species belong to four families: gobies, wrasses, seabasses, or blennies(Moyle & Cech, 2004). Fish groupings in this section generally follow the classification in Nelson (2016).

C.5.3.27.1 Perches and Allies

Perches and allies (angelfishes, cardinal fishes, damselfishes, drums, grunts, jacks, remoras, sea basses, snappers, striped bass, and surfperches) are bony fishes with deep to moderately elongate bodies, one to two dorsal fins, with large mouth and eyes and thoracic pelvic fins. The Deep 7 (six species of snapper and one grouper) are the most culturally important and highly valued of the deep-water bottomfish species in Hawaii. Perches and allies are associated with hard and soft bottom, reefs, submerged aquatic vegetation, open ocean, and deep-sea habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems and open ocean areas (Froese & Pauly, 2016b; Moyle & Cech, 2004).

C.5.3.27.2 Wrasses and Allies

Wrasses and allies (hogfishes, parrotfishes, wrasses, and damselfishes) are bony fishes with a compressed body, large scales, well-developed teeth, and usually colorful coloring. Some wrasses and allies have recreational fishery and aquarium trade importance. Most of these fishes are associated with depths less than 30 m hard and soft bottom and reef habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems (Froese & Pauly, 2016b; Moyle & Cech, 2004). Wrasses and allies can change sex, usually female-to-male, and exhibit broadcast spawning; the fertilized eggs float in the water column or attach to substrate until hatching into larvae. Most are diurnal opportunistic predators (Wainwright & Richard, 1995). Prey items include zooplankton, invertebrates, and small fishes. Predators of wrasses and allies include larger fishes and marine mammals.

C.5.3.27.3 Eelpouts and Allies

Eelpouts and allies (gunnels, ocean pout, pricklebacks, and wolfeels) are bony fishes with an eel-like body, long dorsal and anal fins, and pelvic fins usually absent. These fishes are associated with soft bottom and deep-sea habitats in the California Current Large Marine Ecosystem (Froese & Pauly, 2016b; Moyle & Cech, 2004). Eelpouts have been found to occur near deep-sea vents in the Atlantic Ocean's Mid-Atlantic Ridge (National Geographic, 2016) and in deep water areas off Oahu and the Northern Hawaiian Islands (Yeh, 2008).

C.5.3.27.4 Stargazers

Stargazers are bony fishes with an elongated body and eyes on top of their head and big oblique mouths and are associated with soft bottom and deep-sea habitats in the California Current Large Marine Ecosystem (Froese & Pauly, 2016b). This group of fishes ambush their prey from the sand.

C.5.3.27.5 Blennies, Gobies, and Allies

Blennies, gobies, and allies (blackeye goby, cheekspot goby, mussel blenny) are bony fishes with an eel-like to sculpin-like body, and pelvic fins reduced or fused. They are associated with hard and soft bottoms, reefs, and deep-sea habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems (Froese & Pauly, 2016b).

C.5.3.27.6 Surgeonfishes

Surgeonfish (blue tang, moorish idol) are bony fishes with bodies that are deeply compressed laterally, small mouth, small scales, and pelvic fins with spines. They are associated with reef habitats in the Insular Pacific-Hawaiian Large Marine Ecosystem (Froese & Pauly, 2016b). These fishes scrape algae from coral reefs with small, elongated mouths. These grazers provide an important function to the reef system by controlling the growth of algae on the reef (Goatley & Bellwood, 2009).

C.5.3.27.7 Tunas and Allies

The tuna and allies (barracudas, billfishes, swordfishes, and tunas) have a large mouth, keels usually present, pelvic fins often absent or reduced, and are fast swimmers. These fishes are associated with reefs, nearshore and offshore open ocean habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems (Froese & Pauly, 2016b; Moyle & Cech, 2004). Most species have commercial and recreational importance. Tuna and allies are voracious open ocean predators (Estrada et al., 2003). They exhibit broadcast spawning and fertilized eggs float in the water column until hatching into larvae. Many feed nocturnally (Goatley & Bellwood, 2009) and in low-light conditions of twilight (Rickel & Genin, 2005). Many species in this group make large-scale migrations that allow for feeding in highly productive areas, which vary by season (Pitcher, 1995). Prey items include zooplankton for larvae and juvenile stages, while fishes and squid are consumed by subadults and adults. Predators of tuna and allies include other tuna species, billfishes, toothed whales, and some open ocean shark species. The Pacific bluefin tuna is a candidate species for listing under ESA.

C.5.3.27.8 Butterfishes

Butterfishes (ariommas, driftfishes, and medusafishes) are bony fishes with a blunt and thick snout, teeth small, and a maxilla mostly covered by bone. They are associated with soft bottom and deep-sea habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems (Froese & Pauly, 2016b). Butterfishes form large schools over the continental shelf, except during winter months when it may descend to deeper waters. Juveniles are associated with jellies and floating vegetation. Adults feed mainly on jellies, squids, and crustaceans. Some species of butterfishes are also commercially harvested (Froese & Pauly, 2016b).

C.5.3.28 Flatfishes (Order Pleuronectiformes)

Flatfish (flounders, halibut, sand dabs, soles, and tonguefish) are bony fishes with a flattened body and eyes on one side of body. These fishes occur on soft bottom habitat in inland waters, as well as in deep-sea habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems, and are an important part of commercial fisheries in the Study Area. The California halibut (*Paralichthys californicus*) is a representative of this group and is a recreationally fished species. Flatfishes are broadcast spawners. They are ambush predators, and prey on other fishes and bottom-dwelling invertebrates. Some species in this group have been affected by overfishing (Drazen & Seibel, 2007; Froese & Pauly, 2010).

C.5.3.29 Pufferfishes (Order Tetraodontiformes)

Pufferfishes (boxfishes, filefishes, ocean sunfishes and triggerfishes) are bony fishes with thick or rough skin, sometimes with spines or scaly plates, pelvic fins absent or reduced, and a small mouth with strong teeth coalesced into a biting plate. They are associated with hard and soft bottom, reef, submerged aquatic vegetation, nearshore and offshore open-ocean, and deep-sea habitats in the California Current and Insular Pacific-Hawaiian Large Marine Ecosystems. Pufferfishes are broadcast spawners. Predators vary by species, but due to spiny and rough exterior of this group, it is likely few are successful. Prey vary by species, but includes jellies, crustaceans, detritus, molluscs, and other bottom dwelling marine invertebrates (Froese & Pauly, 2016b).

C.6 Marine Mammals

C.6.1 General Background

Marine mammals are a diverse group of approximately 132 species (Committee on Taxonomy, 2022). Four main types of marine mammals are recognized worldwide: cetaceans (whales, dolphins, and porpoises), pinnipeds (seals, sea lions, and walruses), sirenians (manatees, dugongs, and sea cows), and other marine carnivores (sea otters and polar bears) (Jefferson et al., 2008; Rice, 1998). However, only 45 species are known to occur in the Study Area, and these include only species of cetaceans, seals and sea lions, and the southern sea otter.

Cetaceans can be divided into two smaller groups, odontocetes (i.e., toothed whales, dolphins, and porpoises) and mysticetes (i.e., baleen whales), based on their feeding strategy and anatomy. The different feeding strategies affect their distribution and occurrence patterns (Goldbogen et al., 2015). Odontocetes use teeth to capture and consume prey. Baleen whales use a fibrous structure called a baleen formed along the upper jaw and made of keratin, a type of protein similar to that found in human fingernails, which enables the whales to filter or extract prey from the water. Baleen whales are batch feeders that use baleen to engulf, suck, or skim large numbers of small prey, such as small schooling fishes, shrimp, or tiny animals called zooplankton from the water or out of ocean floor sediments (Heithaus & Dill, 2008).

Most pinnipeds can be divided into two families: phocids (true seals) and the otariids (fur seals and sea lions). Pinnipeds forage at sea on variety of prey, but unlike cetaceans, pinnipeds also spend time on land, or haul-out, for a variety of reasons including breeding, pupping, resting, and predator avoidance (Jefferson et al., 2015; Rice, 1998).

All marine mammals in the U.S. waters are protected under the Marine Mammal Protection Act (MMPA), while select species also receive additional protection under the ESA. Within the framework of the MMPA, a marine mammal "stock" is defined as "a group of marine mammals of the same species or smaller taxon (subspecies) in a common spatial arrangement that interbreed when mature" (16 U.S.C. section 1362). Per NMFS guidance, "for purposes of management under the MMPA, a stock is recognized as being a management unit that identifies a demographically independent biological population" (National Marine Fisheries Service, 2016o). However, in practice, recognized management stocks may fall short of this ideal because of a lack of information or, in some cases, stocks may even include multiple species in a management unit.

The ESA provides for listing species, subspecies, or DPSs of species, all of which are referred to as "species" under the ESA. The Interagency Policy Regarding the Recognition of Distinct Vertebrate Population Segments under the ESA (61 *FR* 4722, February 7, 1996) defines a DPS as, "any subspecies of

fish or wildlife or plants, and any DPS of any species of vertebrate fish or wildlife which interbreeds when mature." If a population meets the criteria to be identified as a DPS, it is eligible for listing under the ESA as a separate species (National Marine Fisheries Service, 2016o). However, MMPA stocks do not necessarily coincide with DPS under the ESA (81 *FR* 62660–62320, September 8, 2016).

For a comprehensive summary of the general biology and ecology of marine mammals beyond the scope of this section, see Rice (1998), Twiss and Reeves (1999), Hoelzel (2002), Berta et al. (2006), Jefferson et al. (2015), and Perrin et al. (2009b). Additional species profiles and information on the biology, life history, distribution, and conservation of marine mammals can also be found through the following organizations:

- NMFS Office of Protected Resources (includes species distribution maps)
- Ocean Biogeographic Information System-Spatial Ecological Analysis of Megavertebrate Populations (known as OBIS-SEAMAP) species profiles
- National Oceanic Atmospheric Administration (NOAA) Cetacean Density and Distribution Mapping Working Group
- International Whaling Commission
- International Union for Conservation of Nature, Cetacean Specialist Group
- Marine Mammal Commission
- Society for Marine Mammalogy

C.6.1.1 Group Size

Many species of marine mammals, particularly odontocetes, are highly social animals that spend much of their lives in groups called "pods." The sizes and structures of these pods are dynamic and, based on the species, can range from several to several thousand individuals. Similarly, aggregations of mysticete whales may form during particular breeding or foraging seasons, although they do not persist through time as a social unit. Marine mammals that live or travel in groups are more likely to be detected by observers, and group size characteristics are incorporated into the acoustic effects modeling to represent a more realistic patchy distribution of species density. The behavior exhibited by many species of aggregating into pods is also important for the purposes of mitigation and monitoring, since animals that occur in larger groups have an increased probability of being detected. Information on species group size was reviewed and updated as part of updating density estimates for the Study Area.

C.6.1.2 Habitat Use

Marine mammals occur in every marine environment in the Study Area, from coastal and inshore waters to the open ocean. Their distributions are influenced by multiple factors, but primarily migration driven by breeding behaviors and prey distribution. Major ocean currents, bottom relief, water temperature, water depth, and salinity, can all affect prey distribution and are therefore often factors in understanding marine mammal distributions. The continuous movement of water from the ocean bottom to the surface in persistent upwelling zones around the world creates nutrient-rich, highly productive environments for marine mammal prey and are areas where marine mammal densities are typically higher (Jefferson et al., 2015; U.S. Department of the Navy, 2024). While these factors generally affect the distribution of most marine mammal species, their degree of influence varies by species.

For most cetaceans the distribution, abundance, and quality of prey largely determine where cetaceans occur at any specific time (Heithaus & Dill, 2008). Most of the baleen whales are migratory, but many of the toothed whales do not migrate in the strictest sense. Instead, they undergo seasonal dispersal or shifts in density distribution and occupy habitats preferable for feeding, breeding, and other important

behaviors. Pinnipeds occur mostly in coastal habitats close to haulouts and forage over the continental shelf; however, some species disperse widely into the open ocean during the non-breeding, foraging season and may not haul out until returning to island or coastal breeding colonies.

In 2011, the Cetacean Density and Distribution Mapping Working Group identified and categorized areas of importance for cetaceans for reproduction, feeding, migration behaviors and areas in which small or resident populations are concentrated. Areas identified through this process were termed Biologically Important Areas (BIAs) (Ferguson et al., 2015; Van Parijs, 2015). The BIAs located in the Main Hawaiian Islands have since been reviewed and revised based on new data and information collected since the original BIAs were defined on how species use these areas (Kratofil et al., 2023). Similar revisions and additions to the original BIAs located off California were also identified (Calambokidis et al., 2024).

The BIAs were not meant to define exclusionary zones or serve as sanctuaries or marine protected areas and have no direct or immediate regulatory consequences. The identification of BIAs is intended to be a "living" process based on the best available science at the time (Ferguson et al., 2015; Harrison et al., 2023). As new empirical data are gathered, BIAs can be redefined to more closely correspond to the data describing a species' habitat use. Changes in habitat use may indicate that a previously defined BIA is no longer important to the essential life function for which it was defined, or may show that a broader expanse of habitat is used by the species for an essential behavior and that the BIA should be larger than previously defined. Also, a BIA may shift as a species' migratory routes change in response to environmental changes (e.g., warming sea surface temperatures).

The initial BIA delineations were published in March 2015, and included BIAs in Hawaii and off the U.S. West Coast (Aquatic Mammals, 2015a, 2015b; Baird et al., 2015b; Calambokidis et al., 2015c; Ferguson et al., 2015). In Hawaii, 21 BIAs for 12 cetacean species were identified. These included 20 small resident population areas and 1 non-contiguous humpback whale reproductive area (Baird et al., 2015b). In 2023, Kratofil et al. (2023) presented revisions to BIAs in Hawaii based on the implementation of a standardized scoring system. Each new and existing BIA was scored based on four criteria: Intensity of Use, Data Support, Importance, and Spatiotemporal Variability (Harrison et al., 2023). Using the scoring system and a hierarchical approach to identify core use areas within a broader area, 35 BIAs were identified in Hawaii for 12 cetacean species; these included 33 small resident BIAs for 11 odontocetes and 2 reproductive BIAs for humpback whales in the Main Hawaiian Islands (Kratofil et al., 2023). Hierarchical BIAs were defined for 9 of the 12 species yielding between one and three child BIAs for each of the 9 parent BIAs, depending on the species. Ten non-hierarchical BIAs were defined for six species. Table 4 in Kratofil et al. (2023) summarizes the characteristics and scores for each BIA. BIAs in the Hawaii Study Area are depicted in the descriptions of habitat and geographic range below for those species with BIAs defined in the Hawaiian Islands.

Twenty eight BIAs were identified for four species off the U.S. West Coast in 2015 (Calambokidis et al., 2015c), with five of those areas located within or overlapping the California portion of the 2018 HSTT Study Area. The BIAs included four feeding areas for blue whales and a migration area for gray whales (Calambokidis et al., 2015c). NMFS recently updated the BIAs for cetaceans on the U.S West Coast using the standardized scoring system described above for the BIAs in Hawaii (Calambokidis et al., 2024). BIAs were identified for two additional species, fin whales and Southern Resident killer whales, that were not delineated in the original effort. With the exception of the BIAs for harbor porpoise, which did not change, the BIAs for all other species included larger overall areas (parent BIAs), and smaller core use areas (child BIAs). BIAs in the California Study Area are depicted in the descriptions of habitat and geographic range below for those species with BIAs defined in the West Coast region.

It is important to note that BIAs are not a complete list of areas where species engage in important behavioral activities, do not represent a species' range or comprehensive habitat, and likely represent only a fraction of a species' overall distribution and habitat use (Ferguson et al., 2015).

C.6.1.3 Dive Behavior

Most marine mammals spend a considerable portion of their lives underwater while traveling or foraging. Some species of marine mammals have developed specialized adaptations to allow them to make deep dives lasting over an hour, primarily to forage for deep-water prey such as squid. Other species spend the majority of their lives closer to the surface and make relatively shallow, short duration dives. The diving behavior of a particular species or individual has implications for an observer's ability to detect them for purposes of mitigation and monitoring. In addition, their relative distribution through the water column is an important consideration when conducting acoustic exposure and direct strike analyses. Information and data on diving behavior for each marine mammal species were compiled and summarized in a technical report (U.S. Department of the Navy, 2017b) that provides estimates of time at depth based on available research. The dive data compiled in this technical report were incorporated into the Navy acoustic effects modeling.

C.6.1.4 Hearing and Vocalization

Refer to Appendix D (Acoustic and Explosive Impacts Supporting Information) for a summary and details regarding the hearing and vocalization of marine mammals.

C.6.1.5 General Threats

The growth and productivity of marine mammal populations, stocks, and individuals can be negatively affected by various natural factors and human activities. Direct effects, such as those resulting from disease or activities such as hunting and whale watching, can combine with indirect effects, such as a reduction in prey availability resulting from a large-scale change in the environment (e.g., an El Niño event) or lowered reproductive success of individuals, to impact populations. Nelms et al. (2021) provide a general discussion of current and emerging threats faced by marine mammals and approaches to conservation. General threats to marine mammal populations are summarized for each species in the population threats sections below. A more detailed discussion of general threats to marine mammals was provided in the 2018 HSTT and 2022 PMSR EIS/OEISs. New research published since 2022 on threats to marine mammals is consistent with information in the 2018 HSTT and 2022 PMSR EIS/OEISs and does not change the qualitative assessment of general threats on marine mammals described in those two EIS/OEISs. Therefore, with two exceptions, no updates to the descriptions of general threats provided in the 2018 HSTT EIS/OEIS are made in this section. The two exceptions are for threats from vessel strike and climate change. Information on vessel strikes as a general threat to marine mammals is relevant to the Proposed Action given the potential for vessel strikes from Navy vessels in the Study Area, and updates on climate change are relevant because of the potential for large-scale impacts on most marine mammal species and their distributions and the comprehensive new research published since the 2018 HSTT EIS/OEIS (Frankel et al., 2022; Gulland et al., 2022; Nelms et al., 2021; Sanderson & Alexander, 2020; Santora et al., 2020).

C.6.1.5.1 Vessel Strike

Vessel strikes are a growing issue for most large marine mammals. Although mortality may be a more significant concern for ESA-listed species, especially those that occupy areas with high levels of vessel traffic, the likelihood of encounter is greater for non-listed species with higher abundances (Currie et al., 2017a; Van der Hoop et al., 2013; Van der Hoop et al., 2015).

The reasons that whales are struck by vessels are likely several fold, including vessels approaching at high speeds making avoidance difficult, acoustic shadowing of an approaching vessel (i.e., the vessel body interferes with sound from the propulsion unit propagating forward) reducing alert time, and an increase in the number of vessels over the years transiting the oceans (Winkler et al., 2020). An animal at the surface could be struck directly by a vessel, a surfacing animal could hit the bottom of a vessel, or an animal just below the surface could be cut by a vessel's propeller. The severity of injuries typically depends on the size and speed of the vessel (Knowlton & Kraus, 2001; Laist et al., 2001; Vanderlaan & Taggart, 2007). Species that spend more time at or near the surface are at greater risk.

An examination of all known ship strikes from all shipping sources (civilian and military) indicates vessel speed is a principal factor in whether a strike results in death (Jensen & Silber, 2003; Knowlton & Kraus, 2001; Laist et al., 2001; Vanderlaan & Taggart, 2007(Rockwood et al., 2021; Winkler et al., 2020). In assessing records in which vessel speed was known, Laist et al., (2001) found a direct relationship between the occurrence of a whale strike and the speed of the vessel involved in the collision. The authors concluded that most deaths occurred when a vessel was traveling more than 13 knots. Jensen and Silber (2003) detailed 292 records of known or probable ship strikes of all large whale species from 1975 to 2002. Of these, vessel speed at the time of collision was reported for 58 cases. Of these cases, 39 (or 67 percent) resulted in serious injury or death. Operating speeds of vessels that struck various species of large whales ranged from 2 to 51 knots. The majority (79 percent) of these strikes occurred at speeds of 13 knots or greater. The average speed that resulted in serious injury or death was 18.6 knots. Pace and Silber (2005) found that the probability of death or serious injury increased rapidly with increasing vessel speed. Specifically, the predicted probability of serious injury or death increased from 45 percent to 75 percent as vessel speed increased from 10 to 14 knots and exceeded 90 percent at 17 knots. Higher speeds during collisions result in greater force of impact, but higher speeds also appear to increase the chance of severe injuries or death by pulling whales toward the vessel. Computer simulation modeling showed that hydrodynamic forces pulling whales toward the vessel hull increase with increasing speed (Clyne & Kennedy, 1999; Knowlton et al., 1995; Silber et al., 2010).

C.6.1.5.2 Climate Change

The global climate is warming and is having impacts on some populations of marine mammals (Garcia-Aguilar et al., 2018; Jefferson & Schulman-Janiger, 2018; National Oceanic and Atmospheric Administration, 2015c, 2018a; Peterson et al., 2006; Salvadeo et al., 2010; Shirasago-Germán et al., 2015; Silber et al., 2017; Simmonds & Eliott, 2009; Tulloch et al., 2018). Climate change can affect marine mammal species directly by causing shifts in distribution to match physiological tolerance under changing environmental conditions (Doney et al., 2012; National Marine Fisheries Service, 2018c; Peterson et al., 2006; Silber et al., 2017), which may or may not result in net habitat loss (some can experience habitat gains). Climate change can also affect marine mammals indirectly via impacts on prey, changing prey distributions and locations, and changes in water temperature (Giorli & Au, 2017; National Marine Fisheries Service, 2020a; Peterson et al., 2006; Rockwood et al., 2020; Santora et al., 2020). Sanford et al. (2019) have noted that severe marine heatwaves in California in 2014–2016 triggered marine mammal mortality events, harmful algal blooms, and declines in subtidal kelp beds. According to the Office of National Marine Sanctuaries (2019), climate drivers are currently the most concerning aspect of a decline in water quality and ecosystem health for giant kelp, mussels, and deep-sea corals across the Southern California Bight.

Changes in prey can impact marine mammal foraging success, which in turn affects reproduction success and survival. Starting in January 2013, an elevated number of strandings of California sea lion pups were

observed in five Southern California counties. Additional California counties experiencing elevated California sea lion strandings include Santa Barbara County, Ventura County, Los Angeles County, and Orange County. This unusual number of strandings, continuing into 2016, were declared an Unusual Mortality Event (UME) by NMFS (National Oceanic and Atmospheric Administration, 2017a, 2018a). Although this UME was still considered as "ongoing" through 2017, the number of strandings recorded in 2017 were at or below average (National Oceanic and Atmospheric Administration, 2017a). This is the sixth UME involving California sea lions that has occurred in California since 1991. For this 2013–2015 event, NMFS biologists indicated that warmer ocean temperatures have shifted the location of prey species that are no longer adjacent to the rookeries, which thereby impacted the female sea lions' ability to find food and supply milk to their pups (National Oceanic and Atmospheric Administration, 2017a). As a result, this confluence of natural events causes the pups to be undernourished, and many are subsequently found stranded dead or emaciated due to starvation. In 2015, an UME was declared for Guadalupe fur seals along the entire California coast because of an eight-fold increase over the average historical number of strandings (approximately 12 per year) (National Marine Fisheries Service, 2019a; National Oceanic and Atmospheric Administration, 2018a). This event continued into 2017, although the number of animals involved declined in 2017; in April 2017 an additional seven Guadalupe fur seals stranded associated with this UME, with these latest strandings still being investigated. The initial assumption was that the cause for the increase in strandings was a change in the prey base due to warming conditions, but to date there has been no subsequent cause or other information in that regard provided by NMFS (National Oceanic and Atmospheric Administration, 2015c, 2018a). In a similar occurrence for gray whales and since January 2019, an elevated number of gray whale strandings has occurred along the west coast of North America from Mexico through Alaska resulting in NMFS declaring a UME for this species (National Marine Fisheries Service, 2019b; National Oceanic and Atmospheric Administration, 2020). This is similar to a previous UME for gray whales that occurred in 1999–2000.

Likely also due to changing prey distributions, data tagging efforts in July 2016 focusing on blue and fin whales had to be shifted north to central California waters when the majority of blue, fin, and humpback whales encountered in southern California waters were found to be too thin or otherwise in poor body condition to allow for them to be tagged (Oregon State University, 2017). In central California waters, the researchers identified good numbers of blue, fin, and humpback whales in better condition and indicative of a good feeding area that was likely to be sustained that season (Oregon State University, 2017).

Harmful algal blooms may become more prevalent in warmer ocean temperatures with increased salinity levels such that blooms will begin earlier, last longer, and cover a larger geographical range (Edwards, 2013; Moore et al., 2008). Warming ocean waters have been linked to the spread of harmful algal blooms into the North Pacific where waters had previously been too cold for most of these algae to thrive. The spread of the algae and associated blooms has led to mortality in marine mammals in locations where algae-caused biotoxicity had not been previously known (Lefebvre et al., 2016).

Climate change may indirectly influence marine mammals through changes in human behavior, such as increased shipping and oil and gas extraction, which benefit from sea ice loss (Alter et al., 2010). Ultimately impacts from global climate change may result in an intensification of current and ongoing threats to marine mammals (Edwards, 2013). In addition, the ability of marine mammals to alter behaviors may serve as a buffer against measurable climate change—induced impacts and could delay or mask any adverse effects until critical thresholds are reached (Baker et al., 2016b).

Marine mammals are influenced by climate-related phenomena, including storms and other extreme weather patterns such as the 2015–2016 El Niño in the ocean off the U.S. West Coast (see for example, Santora et al. (2020). Generally, not much is known about how large storms and other weather patterns affect marine mammals, other than that mass strandings (when two or more marine mammals become beached or stuck in shallow water) sometimes coincide with hurricanes, typhoons, and other tropical storms (Bradshaw et al., 2006; Marsh, 1989; Rosel & Watts, 2008) or other oceanographic conditions. There have also been correlations in time and space between strandings and the occurrence of earthquakes. However, there has been no scientific investigation demonstrating evidence for or against a relationship between earthquakes and the occurrence of marine mammal strandings. Indirect impacts may include altered water chemistry in estuaries (low DO or increased nutrient loading), causing massive fish kills (Burkholder et al., 2004) and thereby changing prey distribution and availability for cetaceans (Stevens et al., 2006). Human responses to extreme weather events may indirectly affect behavior and reproductive rates of marine mammals. For example, Miller et al. (2010) reported an increase in reproductive rates in bottlenose dolphins in the Mississippi Sound after Hurricane Katrina, presumably resulting from an increase in fish abundance due to a reduction in fisheries landings, a decrease in recreational and commercial boat activities (National Marine Fisheries Service, 2007c), and an increase in the number of reproductively active females available during the breeding seasons following the storm. Smith et al. (2013) supplemented the findings from this study and documented a marked increase in foraging activity in newly identified foraging areas that were observed during the two-year study period after the storm.

Habitat deterioration and loss is a major factor for almost all coastal and inshore species of marine mammals, with effects ranging from depleting a habitat's prey base and the complete loss of habitat (Ayres et al., 2012; Kemp, 1996; Pine et al., 2016; Rolland et al., 2012; Smith et al., 2009; Veirs et al., 2015; Williams et al., 2014a). Many researchers predict that if oceanic temperatures continue to rise with an associated effect on marine habitat and prey availability, then either changes in foraging or life history strategies, including poleward shifts in many marine mammal species distributions, should be anticipated (Alter et al., 2010; Fleming et al., 2016; Ramp et al., 2015; Salvadeo et al., 2015; Silber et al., 2017; Sydeman & Allen, 1999). Poloczanska et al. (2016) analyzed climate change impact data that integrated multiple climate influenced changes in ocean conditions (e.g., temperature, acidification, DO, and rainfall) to assess anticipated changes to a number of key ocean fauna across representative areas. In relation to the Study Area, Poloczanska et al. (2016) included the California Current Ecosystem in their assessment. Their results predict a northward expansion in the distribution of zooplankton, fish, and squid, all of which are prey for many marine mammal species. Examples from the 2018 NMFS California Current Ecosystem survey consistent with that hypothesis were notable northern shifts in the summer/fall distribution and abundance of short-beaked common dolphins and blue whales from their 1996 to 2014 multi-year average in response to changing ocean conditions (Becker et al., 2020).

Concerns over climate change modifying the U.S. West Coast upwelling patterns, increasing levels of hypoxia, and ocean acidification have generated targeted research and monitoring efforts at selected "Sentinel Sites" (Lott et al., 2011); the Channel Islands National Marine Sanctuary is one of these monitored sites. There remains scientific uncertainty about how or if such changes will affect marine mammals and their prey, but acidification of the ocean could potentially impact the mobility, growth, and reproduction of calcium carbonate-forming organisms such as crustaceans and plankton, which are the direct prey of some marine mammals, as well as an important part of the overall food chain in the ocean, and can alter the propagation of sound underwater (Lynch et al., 2018; Rossi et al., 2016).

C.6.2 Endangered Species Act-Listed Species

There are 11 marine mammal species and applicable stocks or DPSs listed under the ESA that occur within in the Study Area.

C.6.2.1 Blue Whale (Balaenoptera musculus)

C.6.2.1.1 Status and Management

The world's population of blue whales can be separated into five subspecies, based on geographic location and some morphological differences (National Marine Fisheries Service, 2020c). In the HCTT Study Area the subspecies *Balaenoptera musculus* is present. In the North Pacific, NMFS divided *B. musculus* into two stocks, the Eastern North Pacific and Central North Pacific stocks (Carretta et al., 2023b). Both stocks of blue whales are listed as endangered under the ESA.

Recovery Goals

In response to the current threats facing the species, in 1998 NMFS developed goals to recover blue whale populations. The November 2020 Revised Recovery Plan (National Marine Fisheries Service, 2020c) for the blue whale provides the complete down-listing/delisting criteria to accomplish the recovery goal. The goal of the Revised Recovery Plan is to promote recovery of blue whales to a level at which it becomes appropriate to downlist the species from endangered to threatened status, and ultimately to delist, or remove the species from the list of Endangered and Threatened Wildlife and Plants, under the provisions of the ESA. The plan outlines the recovery actions to accomplish this goal as follows:

- Coordinate federal and international measures to maintain international regulation of whaling for blue whales.
- Determine blue whale taxonomy, population structure, occurrence, distribution, and range.
- Estimate population size and monitor trends in abundance.
- Identify, characterize, protect, and monitor habitat important to blue whale populations.
- Investigate human-caused potential threats and, should they be determined to be limiting blue whale recovery, take steps to minimize their occurrence and severity.
- Maximize efforts to acquire scientific information from dead, stranded, and entangled or entrapped blue whales.

C.6.2.1.2 Habitat and Geographic Range

Blue whales inhabit all oceans and typically occur near the coast, over the continental shelf, though they are also found in oceanic waters having been sighted, acoustically recorded, and satellite tagged in the eastern tropical Pacific (Ferguson, 2005; Stafford et al., 2004).

Blue whales from the Central North Pacific stock are found in the Hawaii portion of the Study Area, but the sighting frequency is low and the peak abundance is seasonal, generally occurring in the winter (Bradford et al., 2013). During three systematic ship surveys of the Hawaiian Islands EEZ in 2002, 2010, and 2017 (all in summer and fall), there was only one blue whale sighting in 2010 (Bradford et al., 2021). Whales feeding along the Aleutian Islands and in the Gulf of Alaska likely migrate to Hawaii in winter (Stafford et al., 2001). In the winter of 2014–2015 (December to January), passive acoustic detections of blue whales were recorded intermittently over the 3-week period of the survey (Klinck et al., 2015).

The Eastern North Pacific Stock of blue whales includes animals found in the eastern north Pacific from the northern Gulf of Alaska to the eastern tropical Pacific (Carretta et al., 2023b). Based on habitat

models derived from line-transect survey data collected between 1991 and 2018 off the U.S. west coast, relatively high densities of blue whales are predicted off southern California during the summer and fall (Barlow et al., 2009b; Becker et al., 2010; Becker et al., 2016; Forney et al., 2012). Data from year-round surveys conducted off southern California from 2004 to 2013 show that the majority of blue whales were sighted in summer (62 sightings) and fall (9 sightings), with only single sightings in winter and spring (Campbell et al., 2015). In the Southern California Bight in summer and fall, the highest densities of blue whales occurred along the 200 m isobath in waters with high surface chlorophyll concentrations (Redfern et al., 2013). Campbell et al. (2015) documented blue whale sightings along both the southern California shelf, and over deep ocean water (>2,000 m).

This species has also frequently been heard on passive acoustic recording devices in the southern portion of the California Study Area (Širović et al., 2015a). Based on approximately 3 million detections in the waters of the Southern California Bight between 2006 and 2012, Širović et al. (2015a) found that blue whale vocalizations were more common at coastal sites and near the northern Channel Islands and generally heard between June and January with a peak in September. There was large variation among blue whales tagged in the southern portion of the California Study Area with the distance to shore ranging from less than 1 km and up to 884.8 km and blue whale movement along the Pacific coastline extending south to just 7.4°N latitude (just north of the equator and north to 50°N latitude just off British Colombia, Canada (Mate et al., 2015a). Data from a number of years and sources (Calambokidis & Barlow, 2013; Calambokidis et al., 2009a; Douglas et al., 2014b; Irvine et al., 2014; Mate et al., 2016a) consistently indicate large interannual variability in blue whale presence in small specific areas. Annual density predictions based on a habitat model also showed localized interannual variability in blue whale distribution patterns between 1996 and 2018 (Becker et al., 2020).

Abrahms et al. (2019) documented higher blue whale occurrence north of the SOCAL Range Complex and with critical areas located along shipping routes within the Santa Barbara Channel that provide access to the Ports of Los Angeles and Long Beach. Szesciorka et al. (2020) investigated the timing of blue whale migrations in association with environmental conditions and prey concentrations off southern California over a 10-year period. Their findings showed that blue whales were arriving up to one month earlier off southern California at the end of the study than they had been 10 years prior. However, the whales did not depart any earlier, leading to longer residency times in the Southern California Bight. Based on acoustic call detections, blue whales arrived in May and depart in November, remaining at the feeding grounds an average of 8.4 months. Blue whales demonstrated a flexible response to prey availability on an interannual basis based strongly on sea surface temperatures which are also correlated with krill biomass.

Szesciorka et al. (2019) analyzed passive acoustic detections and satellite tagging data to show that blue whales appeared to have little or no behavioral responses to close vessel passages. This is similar to lack of blue whale response to vessel traffic reported by McKenna et al. (2015). Palacios et al. (2019) showed how blue whale foraging behavior was influenced by modeled oceanographic variables likely associated with concentrating krill prey. The northward movement of blue whale foraging during marine heatwaves was also noted. Calambokidis et al. (2019) documented differences in blue whale day-night behaviors with more blue whale transit movements at night and at shallower depths.

BIAs were redefined for blue whale feeding behavior off the U.S. West coast by Calambokidis et al. (2024) and incorporated tagging and additional line-transect survey data not previously considered (Calambokidis et al., 2015c). The parent BIAs encompass 173,000 km² equivalent to 21 percent of the

U.S. West Coast EEZ and include coastal, shelf beak, and offshore waters (Figure C-8). The child BIA is 30 percent of the parent BIAs but still larger than the previous blue whale feeding BIAs defined in 2015.

C.6.2.1.3 Population Trends

Widespread whaling over the last century is believed to have decreased the global blue whale population to approximately 1 percent of its pre-whaling population size (Branch, 2007; Monnahan, 2013; Monnahan et al., 2014; Rocha et al., 2014; Širović et al., 2004). Off the Pacific Coast of North America, there was a documented increase in the blue whale population size between 1979–80 and 1991 (Barlow, 1994a) and between 1991 and 1996 (Barlow, 1997). Based on subsequent line-transect surveys conducted off the Pacific Coast between 2001 and 2005, the abundance estimates of blue whales appeared to decline in those waters over the survey period (Barlow & Forney, 2007). However, this apparent decline was likely due to variability in the distribution patterns of blue whales off the coast of North America rather than a true population decline (Barlow, 2010; Calambokidis et al., 2009a). Calambokidis et al. (2009a) suggested that when feeding conditions off California are not optimal, blue whales may move to other regions to feed, including waters farther north. A comparison of survey data from the 1990s to 2008 indicates that there has been a northward shift in blue whale distribution within waters off California, Oregon, and Washington (Barlow, 2010; Širović et al., 2015b). Consistent with the earlier suggested variability in the distribution patterns, Carretta et al. (2013) report that blue whales from the U.S. west coast have been increasingly found feeding to the north and south of the U.S. west coast during summer and fall. A mark-recapture study reported by Calambokidis et al. (2009b) indicated, "a significant upward trend in abundance of blue whales" at a rate of increase just under 3 percent per year for the U.S. west coast blue whale population (Calambokidis & Barlow, 2013).

Recent information suggests that the population in the HCTT Study Area may have recovered and has been at a stable level following the cessation of commercial whaling in 1971 despite the impacts of ship strikes, interactions with fishing gear, and increased levels of ambient sound in the Pacific Ocean (Campbell et al., 2015; Carretta et al., 2015; Monnahan, 2013; Monnahan et al., 2015; Monnahan et al., 2014; Širović et al., 2015b). Based on a relative comparison of past sightings, dating as far back as the 1950s, with survey results from 2012, Smultea and Jefferson (2014) ranked blue whales as the sixthmost frequently sighted species in the Southern California Bight, noting that, "[t]his represents a clear relative increase from historical records." Sixth (out of 16 species) is the highest rank for blue whales, which were ranked 12th based on 1981 survey results. Despite the evidence of a potential increase in the population size of blue whales off the U.S. west coast, a formal trend analysis has not been conducted so the current trend is unknown (Carretta et al., 2023b).



Figure C-8: Blue Whale Feeding BIAs in the California Study Area

C.6.2.1.4 Population Threats

Blue whales are susceptible to vessel strikes and entanglement in fishing gear. The most recent NMFS data from 2017 through 2021 reported 3 cases of blue whale injury or mortality attributed to vessel strikes off the U.S. West Coast (Carretta et al., 2023a). There has been approximately 14 recorded vessel strikes resulting in injury or mortality to blue whales in the region since 2007.

Furthermore, blue whales have been observed entangled in pot and trap fisheries, as well as unidentified fishing debris. Data from 2017 through 2021 indicate that that the mean annual entanglement rate of blue whales along the U.S. West Coast is 0.61 whales annually (Carretta et al., 2023a). Data specific to the California Dungeness crab pot fishery from the same 5-year period indicate that the average interaction that resulted in mortality or serious injury was 0.15 blue whales annually (Carretta et al., 2023a). Other anthropogenic threats to blue whales include pollution exposure, increased noise (e.g., vessel noise), and ingestion or other interactions with marine debris (National Marine Fisheries Service, 2016k).

Climate change has also increasingly become a threat to marine mammals, including baleen whales. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021). Its effects on oceanographic conditions that drive the distribution of planktonic prey are a potential threat to blue whale populations (Palacios et al., 2019; Szesciorka et al., 2020).

C.6.2.2 Fin Whale (Balaenoptera physalus)

C.6.2.2.1 Status and Management

The fin whale is listed as endangered under the ESA and depleted under the MMPA. In the North Pacific, NMFS recognizes three fin whale stocks: (1) a Northeast Pacific stock in Alaska; (2) a California, Oregon, and Washington stock; and (3) a Hawaii stock (Carretta et al., 2023b; Young, 2023). Although some fin whales migrate seasonally (Falcone et al., 2011; Mate et al., 2016b; Mate et al., 2015c), NMFS does not recognize fin whales from the Northeast Pacific stock as occurring in either Hawaii or off California.

Recovery Goals

In response to the threats facing the species, NMFS developed goals to recover fin whale populations. The 2010 Final Recovery Plan (National Marine Fisheries Service, 2010b) for the fin whale provides complete downlisting/delisting criteria for both of the following recovery objectives 1) Achieve sufficient and viable population in all ocean basins, and 2) Ensure significant threats are addressed. To accomplish these objectives, the plan outlines the recovery actions as follows:

- Coordinate state, federal, and international actions to implement recovery actions and maintain international regulation of whaling for fin whales.
- Determine population discreteness and population structure of fin whales.
- Develop and apply methods to estimate population size and monitor trends in abundance.
- Conduct risk analyses.
- Identify, characterize, protect, and monitor habitat important to fin whale populations in U.S. waters and elsewhere.
- Investigate causes and reduce the frequency and severity of human-caused injury and mortality.
- Determine and minimize any detrimental effects of anthropogenic noise in the oceans.

- Maximize efforts to acquire scientific information from dead, stranded, and entangled or entrapped fin whales.
- Develop post-delisting monitoring plan.

C.6.2.2.2 Habitat and Geographic Range

The fin whale is found in all the world's oceans and is the second largest species of whale (Jefferson et al., 2015). Fin whales prefer temperate and polar waters and are scarcely seen in warm, tropical waters (Reeves et al., 2002).

Fin whales are found in Hawaiian waters, but this species is not commonly detected in this portion of the Study Area (Carretta et al., 2023b). There was a total of nine fin whale sightings during systematic line-transect surveys of the Hawaiian Islands EEZ in 2002, 2010, and 2017 (Bradford et al., 2021). These data allowed for the derivation of an updated design-based abundance estimate for the Hawaiian Islands fin whale stock of 203 whales; however, the uncertainty associated with this estimate was quite high, resulting in a 95 percent confidence interval of 40 to 1,028 animals (Bradford et al., 2021). Based on sighting data and acoustic recordings, fin whales are likely to occur in Hawaiian waters mainly in fall and winter (Barlow et al., 2006; Barlow et al., 2008, Barlow, 2004 #2610; Klinck et al., 2015). In summer, fin whales are likely absent from Hawaiian waters, and during three separate line-transect surveys of waters within the Hawaiian Islands EEZ during summer and fall, fin whales were only seen during the fall months (Barlow, 2006; Bradford et al., 2017). Fin whales were not detected during the summer months of any year from 2011 to 2017 from passive acoustic recordings on an array of 14 hydrophones at the U.S. Navy Pacific Missile Range Facility (PMRF) off Kauai, Hawaii (Guazzo et al., 2021; Helble et al., 2020).

Fin whales calls have frequently been recorded in waters within the California portion of the Study Area (Barlow & Forney, 2007; Campbell et al., 2015; Jefferson et al., 2014; Mate et al., 2016b, 2017; Mizroch et al., 2009; Širović et al., 2016; Širović et al., 2004; Širović et al., 2015b; Smultea & Jefferson, 2014). As demonstrated by satellite tags and discovery tags², fin whales make long-range movements along the entire U.S. west coast (Falcone et al., 2011; Mate et al., 2015c; Mizroch et al., 2009). However, photo-identification studies of fin whales off the U.S. west coast suggest that not all fin whales undergo long seasonal migrations, but instead make short seasonal trips in spring and fall (Falcone et al., 2011; Falcone & Schorr, 2011).

The movements of six fin whales with satellite tags were shown to be highly variable, ranging from less than 1 to over 200 km from the California coast and as far north as the Oregon border and as far south as the central Baja California Peninsula, Mexico (Mate et al., 2015c). Fin whales frequently congregate in areas with high primary productivity, often in upwelling zones, which may indicate high concentrations of prey. Fin whales are known to be highly adaptable to varying habitat and tend to following prey, which frequently aggregates off the continental shelf (Azzellino et al., 2008; Panigada et al., 2008).

Based on predictive habitat-based density models derived from line-transect survey data collected between 1991 and 2018 off the U.S. west coast, relatively high densities of fin whales are predicted off southern California during the summer and fall with fewer occurring in winter and spring (Barlow et al., 2009a; Becker et al., 2020; Becker et al., 2012a; Becker et al., 2022a; Calambokidis et al., 2024; Forney et al., 2012). Aggregations of fin whales are present year-round in southern and central California

² As a means of data collection starting in the 1930s, discovery tags having a serial number and return address were shot into the blubber of the whale by scientists and if that whale was later harvested by the whaling industry and the tag "discovered" during flensing, it could be sent back to the researchers providing data on the movement of individual whales.

(Campbell et al., 2015; Douglas et al., 2014b; Forney & Barlow, 1998a; Forney et al., 1995; Jefferson et al., 2014), although their distribution shows seasonal shifts. Sightings from year-round surveys off southern California from 2004 to 2013 show fin whales farther offshore in summer and fall and closer to shore in winter and spring (Campbell et al., 2015; Douglas et al., 2014b).

During the first phase of BIA development, the best available science was not sufficient to define BIAs for fin whale behavior off California (Calambokidis et al., 2015b). A combination of sightings, satellite tagging data, and habitat-based distribution models has since enabled researchers to define fin whale feeding BIAs along the west coast (Calambokidis et al., 2024). The parent BIA encompasses 315,000 km² and 38 percent of the U.S. West Coast EEZ and is the largest BIA designated off the West Coast (Figure C-9). The child BIA is 49 percent of the parent BIA (approximately 154,350 km²), which is still a large area that does not effectively identify important core feeding areas within the child BIA. Additional distribution data are needed to more precisely delineate key feeding areas (Calambokidis et al., 2024).

A fin whale reproductive BIA was considered off Hawaii but was not developed due to a lack occurrence and distribution data, particularly in winter when the whales are most likely to occur in Hawaiian waters (Kratofil et al., 2023).

C.6.2.2.3 Population Trends

No data are available on the current population trends for fin whales in Hawaii (Carretta et al., 2023b). The available abundance estimates for the Hawaii stock of fin whales are based on sighting data collected in summer and fall (Bradford et al., 2021), when fin whales are not likely present in large numbers. Further, as noted previously the uncertainty associated with these abundance estimates is quite high (i.e., CVs close to 1.0), thus prohibiting a robust assessment of trends.

For waters off California, Moore and Barlow (2011) predicted continued increases in fin whale abundance into the present decade, and suggested that fin whale densities are reaching "current ecosystem limits." Based on a comparison of sighting records from the 1950s to 2012, Smultea and Jefferson (2014) also showed an increase in the relative abundance of fin whales inhabiting the Study Area. Širović et al. (2015b) used passive acoustic monitoring of fin whale calls to estimate the spatial and seasonal distribution of fin whales in the Southern California Bight. An increase in the number of calls detected between 2006 and 2012 suggested that the population of fin whales off the U.S. west coast has been increasing. Based on 18 aerial surveys conducted between 2008 and 2013, fin whales were one of the most common large whales sighted in the Study Area (Jefferson et al., 2014). These findings all indicate the abundance of the California/Oregon/Washington stock has been increasing for decades and that a recovery of the stock dates back to the 1970s and 1980s (Barlow, 1994b). However, there is strong evidence that fin whale abundance increased in the California Current between 1991 and 2018 based on estimates from three methods, analysis of line transect survey data (Barlow, 2016), habitatbased species distribution models (Becker et al., 2020), and a Bayesian population trend analysis (Nadeem et al., 2016). Furthermore, the trend analysis reported by Nadeem et al. (2016) estimated that mean annual abundance of fin whales increased 7.5 percent annually from 1991 to 2014.

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Figure C-9: Fin Whale Feeding BIAs in the California Study Area

C.6.2.2.4 Population Threats

Fin whales are susceptible to both ship strikes and entanglement in fishing gear. The most recent NMFS data from 2017 through 2021 indicate that 8 ship strikes of fin whales along the U.S. West Coast resulted in mortality (Carretta et al., 2023a). There are likely several other unobserved vessel strikes that resulted in serious injury or mortality due to some species not stranding or not appearing to be visibly injured during the time of impact (Carretta et al., 2024).

In the HSTT Study Area, for the 10-year period from 2007 to 2016, there were two Navy ship strikes with large whales and both involved fin whales off southern California and occurred in 2009. In 2021, there were three ship strikes involving large whales, which may have been fin whales due to the offshore location and time of the strikes. Additionally, an Australian Navy vessel was positioning to participate in a U.S. Navy-led exercise in Southern California and struck 2 fin whales during a single incident in 2021. As a result, the Navy has reinitiated the HSTT biological opinion to request additional takes of large whales for the remaining years of the MMPA permit (i.e., mid-2023 through the end of 2025).

The most recent data from 2017 through 2021 indicate that there were two recorded entanglements of the California/Oregon/Washington stock of fin whales in unidentified fisheries, and two entanglements involving unidentified whale species (Carretta et al., 2023a). As a result, mean annual rate of entanglement of fin whales in fisheries along the U.S. West Coast is 0.41 whales annually.

Climate change has increasingly become a threat to marine mammals, including baleen whales. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.2.3 Gray Whale (Eschrichtius robustus; Western North Pacific Stock)

C.6.2.3.1 Status and Management

NMFS recognizes two stocks of gray whales in the North Pacific: the Eastern North Pacific stock and the Western North Pacific stock (Weller et al., 2013). Both stocks could be present in the California portion of the Study Area during their northward and southward migrations (Mate et al., 2015b; Sumich & Show, 2011). The Western subpopulation has previously been known as the Korean-Okhotsk population (Carretta et al., 2023b). This stock is critically endangered, shows no apparent signs of recovery, and should be very rare in the California Study Area given their low abundance. The two stocks are genetically distinguished but the population may be changing due to evolving migratory patterns of both stocks (Carretta et al., 2023b).

Recovery Goals

Recovery goals have not been established for the Western North Pacific stock of gray whales.

C.6.2.3.2 Habitat and Geographic Range

Gray whales are not expected to occur regularly in the Hawaii Study Area or in the transit corridor. There were two sightings of what appeared to be a juvenile gray whale off the island of Hawaii in February 2022, but this is the first recorded sighting of this species in the central Tropical Pacific and it is considered very unusual (Baird et al., 2022).

Earlier sighting data suggested that the western gray whale population had a limited range extending between the Sea of Okhotsk, off the coast of Sakhalin Island (Russia), and the South China Sea (Weller et al., 2002). However, subsequent long-term studies of tagged whales, improved photographic

identification, and genetic studies have since indicated that the coastal waters of eastern Russia, the Korean Peninsula, and Japan are a segment of the Western North Pacific stock's migration route, and that "Sakhalin" whales have been detected along the North American coast from British Columbia, Canada as far south as the Baja California Peninsula, Mexico (Mate et al., 2015b; Muir et al., 2016; Weller et al., 2013; Weller et al., 2002; Weller et al., 2012a; Weller et al., 2012b). A total of 43 whales initially photographed and identified in summer feeding grounds off Sakhalin Island were later identified in breeding areas off Mexico, representing 14 percent of the Sakhalin gray whale sub-population (Carretta et al., 2023b). The migratory route taken by these gray whales would have led them through nearshore waters of the HCTT Study Area. The vast majority of gray whales occurring off the West Coast and in the California Study Area are from the larger Eastern North Pacific stock (Carretta et al., 2023b). For purposes of this analysis, the Navy assumed that a very small percentage of gray whales migrating off California could be individuals from the endangered Western North Pacific stock and that the majority would be from the unlisted Eastern North Pacific stock.

C.6.2.3.3 Population Trends

Based on photo identification data collected off Sakhalin and Kamchatka in 2016, the Western North Pacific stock of gray whales was estimated at 290 whales, and given the combined Sakhalin and Kamchatka populations, there was an approximate 2 to 5 percent annual increase between 2005 and 2016 (Cooke, 2018). There have been 18 western gray whales identified in waters far enough south to have passed through the HCTT Study Area (National Marine Fisheries Service, 2014f). In a comparison of Western North Pacific and Eastern North Pacific gray whale photo ID catalogs, 12 Western North Pacific whales identified off Russia have been identified along the U.S. west coast, with an approximately equal number of both sexes (Weller et al., 2012b).

C.6.2.3.4 Population Threats

Gray whales have historically been harvested by subsistence hunters in Alaska and Russia. The International Whaling Commission sets catch limits on the annual subsistence harvest for these areas. For example, the Chukotka indigenous hunters (located on the Chukchi Peninsula) took a total of 127 gray whales in 2013 (Ilyashenko & Zharikov, 2014). In 2010, a gray whale discovered dead onshore in Humboldt, California had two embedded harpoons in its flesh; one of these harpoons had 10 m of rope attached (Carretta et al., 2016a).

Gray whales are also susceptible to entanglement in fishing gear and ship strikes, particularly incidental catches in coastal fisheries (Carretta et al., 2021b). Based on photographic data of western gray whales on their feeding ground off Sakhalin Island (Russia), approximately 19 percent of whales in the sample had detectable anthropogenic scarring resulting from fishing gear entanglement (Bradford et al., 2009).

Natural population threats to gray whales include disease, parasites, reduced prey availability, and predator attacks. The gray whale is preyed on particularly by killer whales. Many individuals exhibit attack scars indicating not all attacks are fatal, however fatalities are known. Killer whale predation of gray whales has been documented in California waters off Monterey (PHYSORG, 2017) as well as the targeting of calves during the spring migration into colder northern waters (Jones & Swartz, 2009).

C.6.2.4 Humpback Whale (*Megaptera novaeangliae;* Mexico and Central America Distinct Population Segments)

C.6.2.4.1 Status and Management

NMFS has identified 14 DPSs of humpback whales worldwide, with 4 DPSs occurring in the North Pacific (Carretta et al., 2023b). Humpback whales that occur seasonally in the HCTT Study Area are from three of the four DPSs identified by low-latitude wintering habitats: Hawaii DPS, Mexico DPS, and Central America DPS (Bettridge et al., 2015a; Carretta et al., 2023b; National Marine Fisheries Service, 2016q; Young, 2023). The three previously defined stocks of North Pacific humpback whales did not align with the DPS structure, so NMFS reevaluated the stock structure to incorporate both the locations of foraging and overwintering areas and population demographics. As a result, NMFS defined five stocks in the North Pacific:

- 1. Central America/Southern Mexico-California-Oregon-Washington stock
- 2. Mainland Mexico-California-Oregon-Washington stock
- 3. Mexico-North Pacific stock
- 4. Hawaii stock
- 5. Western North Pacific stock

Humpback whales from the first four stocks listed above occur seasonally in the HCTT Study Area; humpbacks from the Western North Pacific stock do not occur in the Study Area. Humpback whales wintering in Hawaii are identified as the Hawaii DPS and comprise the Hawaii stock. Humpback whales from the Hawaii DPS/stock forage across the North Pacific (Figure C-10). Humpback whales from the Mexico DPS migrate to summer foraging habitat from California northward along the U.S. West Coast, Canada, Alaska, into the Bering Sea, and off the coast of Russia and are divided into the Mexico-North Pacific stock and the Mainland Mexico-California-Oregon-Washington stock. Humpback whales from the Central America DPS forage is waters off California and the Pacific Northwest and make up the Central America/Southern Mexico-California-Oregon-Washington stock (Carretta et al., 2023b). For additional information on the revised stock and DPS structure and population dynamics refer to Martien et al. (2023), Wade (2021), Martien et al. (2021) and Martien et al. (2019).

Humpback whales in the Hawaii DPS are not listed under the ESA, because the population is believed to have fully recovered to its pre-whaling abundance (Barlow et al., 2011; Bettridge et al., 2015a; Muto et al., 2017; National Marine Fisheries Service, 2016j; Wade et al., 2016). Humpback whales from the Mexico DPS are listed as threatened and those from the Central America DPS are listed as endangered under the ESA (National Marine Fisheries Service, 2016j).







AI/BS = Aleutian Islands/Bering Sea, GoA = Gulf of Alaska, SEAK/NBC = Southeast Alaska/Northern British Columbia, WA/SBC = Washington/Southern British Columbia, CA/OR = California Oregon. Source: Carretta et al. (2023b)

Figure C-10: Humpback Whale Stocks and DPSs Defined in the North Pacific. Whales From the Hawaii, Mexico, and Central America DPSs Occur Seasonally in the Study Area.

Critical Habitat

NMFS designated critical habitat for the Mexico and Central America DPSs of humpback whale on April 21, 2021 (86 FR 21082). The wintering areas for the Mexico DPS are the waters and islands off Mexico, and, for the Central America DPS, wintering areas are waters from southern Mexico and south along the coast of Central America (Calambokidis et al., 2008). Critical habitat for both DPSs extends beyond the Study Area but includes the California Current Ecosystem, which overlaps with nearshore potions of the Study Area but does not include all of the Southern California Bight (Figure C-11). The critical habitat is defined by water depth, with the nearshore limit set at 15 m, 30 m, or 50 m and the offshore limit at 2,000 m, 3,000 m, or 3,700 m for different segments along the California coastline. Prey species (primarily euphausiids and small schooling fishes) were identified by NMFS as the essential feature of the designated critical habitat.

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Figure C-11: Humpback Whale Critical Habitat in the HCTT Study Area

Recovery Goals

In response to the threats facing the species, NMFS developed goals to recover humpback whale populations. The 1991 Final Recovery Plan (National Marine Fisheries Service, 1991) for the humpback whale provides the complete down listing/delisting criteria for each of the four following recovery goals (these apply to the Mexico DPS and the Central America DPS of humpback whale):

- 1. Maintain and enhance habitats used by humpback whales currently or historically.
- 2. Identify and reduce direct human-related injury and mortality.
- 3. Measure and monitor key population parameters.
- 4. Improve administration and coordination of recovery program for humpback whales.

C.6.2.4.2 Habitat and Geographic Range

Humpback whales are distributed worldwide in all major oceans and most seas (Bettridge et al., 2015a; National Marine Fisheries Service, 2016j). They typically are found during the summer in high-latitude feeding grounds, including Alaska and British Colombia, and during the winter migrate to breeding areas off Hawaii, Mexico, Central America, and Okinawa where breeding and calving occurs. As a result, humpback migrations are complex and cover great distances (Bettridge et al., 2015a; Calambokidis et al., 2009b; Calambokidis et al., 2008). Whales migrating from Hawaii to summer feeding habitat in the Gulf of Alaska will cover 2,600 NM over several weeks. Mate et al. (1998), used satellite tags to track three migrating whales using independent routes to Alaskan waters, and the fastest averaged 93 NM per day. At that rate, the whale would have reached waters off the coast of Alaska in about 39 days.

Off the U.S. west coast, humpback whales are more abundant in shelf and slope waters (<2,000 m deep), and are often associated with areas of high productivity (Becker et al., 2020; Becker et al., 2010; Becker et al., 2012b; Becker et al., 2014; Forney et al., 2012; Redfern et al., 2013). While most humpback whale sightings are in nearshore and continental shelf waters, humpback whales frequently travel through deep oceanic waters during migration (Calambokidis et al., 2001; Clapham, 2000; Clapham & Mattila, 1990; Mate et al., 1997). Humpback whales migrating from breeding grounds in Central America to feeding grounds at higher latitudes may cross the SOCAL portion of the HCTT Study Area including the Transit Corridor located farther offshore. While most humpback whales migrate, data from surveys conducted between 2004 and 2013 show that humpback whales occur year-round off southern California (Campbell et al., 2015). Peak occurrence during migration occurs in the California Study Area from December through June (Calambokidis et al., 2015a). During late summer, more humpback whales are sighted north of the Channel Islands, and limited occurrence is expected south of the northern Channel Islands (San Miguel, Santa Rosa, Santa Cruz) (Carretta et al., 2010). Based on aerial survey data collected between 2008 and 2012 in the California Study Area, Smultea and Jefferson (2014) determined that humpback whales ranked eighth in relative occurrence and concluded that this species has clearly increased their representation in the Navy's SOCAL Range Complex over the last several decades.

Two BIAs (parent and core) for humpback whale feeding behavior have been identified in the California Study Area (Figure C-12) (Calambokidis et al., 2024). The BIAs are only in effect from March through November when foraging humpback whales are expected to be present.

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Figure C-12: Humpback Whale Feeding BIAs in the California Study Area

C.6.2.4.3 Population Trends

Humpback whale abundance off the U.S. west coast has appeared to increase at a rate of approximately 8 percent per year since 1989 (Calambokidis & Barlow, 2020). However, since multiple humpback whale stocks occur in these waters, this overall trend cannot be assumed for each of the individual stocks. Based on capture-recapture analyses of photographic identification data collected between 2019 and 2021, there appears to be an annual growth rate of 1.6 percent for the Central America/Southern Mexico – CA/OR/WA stock of humpback whales (Curtis et al., 2022). Stock-specific trend data are not available for the Mainland Mexico – CA/OR/WA stock of humpback of humpback whales (Carretta et al., 2023b). Since some of the individuals from the Mexico-North Pacific stock of humpback whales feed in Alaska, and there have been recent declines in the numbers of humpback whale in these feeding grounds, it is unknown if there is an increasing or decreasing population trend for this stock (Young, 2023).

C.6.2.4.4 Population Threats

Humpback whales are susceptible to entanglement in fishing gear and ship strikes. Pot and trap fishery entanglements are the most-common source of injury to humpback whales along the U.S. west coast (Carretta et al., 2022). Between 2015 through 2019, there have been 81 observations of humpback whale interactions with pot and trap fisheries (Carretta et al., 2022). Of these interactions, serious injuries and mortalities were calculated as 51.75 humpback whales during this time period (Carretta et al., 2022). From 2015 to 2019, there was 79 humpback whale interactions with gillnet and unidentified fisheries (Carretta et al., 2022). Gillnet related serious injuries and mortalities totaled to 54.75 for this time period (Carretta et al., 2022). Humpback whales have also been reported seriously injured and killed from entanglement in fishing gear while in their Alaskan feeding grounds (Helker et al., 2017). Humpback whales from Mexico and Central America have been identified feeding in Alaska (Bettridge et al., 2015b; Calambokidis et al., 2008). Some proportion of these entanglements could be to be whales from the Central America DPS. An overall minimum estimate of mortality and serious injury due to fisheries in Alaska is 14 humpback whales annually (Muto et al., 2017).

Available data from NMFS indicate that there have been 14 reports of humpback whales struck by ships from 2016 through 2020, totaling to 2.6 humpback whale serious injuries or mortalities per year (Carretta et al., 2022). The mean vessel collision mortality and serious injury rate in Alaska is 4.3 humpback whales annually (Muto et al., 2017).

Humpback whales are also potentially affected by underwater noise, jet skis and similar fast waterborne tourist-related traffic, and pollutants (Muto et al., 2017).

C.6.2.5 Sei Whale (Balaenoptera borealis)

C.6.2.5.1 Status and Management

The sei whale is listed as endangered under the ESA and as depleted under the MMPA, but there is no designated critical habitat for this species. Sei whales in Hawaii are assigned to the Hawaii stock. Along the U.S. west coast, the Eastern North Pacific stock is recognized within the U.S. EEZ including the California Study Area (Carretta et al., 2023b).

Recovery Goals

In response to the threats facing the species, NMFS developed goals to recover sei whale populations. The 2011 Final Sei Whale Recovery Plan (National Marine Fisheries Service, 2011a) provides the complete downlisting/delisting criteria for both of the following objectives, 1) Achieve sufficient and viable populations in all ocean basins, and 2) Ensure significant threats are addressed. The plan outlines the following recovery actions to accomplish these objectives:

- Coordinate state, federal, and international actions to implement recovery actions and maintain international regulation of whaling for sei whales.
- Develop and apply methods to collect sei whale data.
- Support existing studies to investigate population discreteness and population structure of sei whales using genetic analyses.
- Continue to collect data on "unknown" threats to sei whales.
- Maximize efforts to acquire scientific information from dead, stranded, and entangled sei whales.
- Estimate population size and monitor trends in abundance.
- Initiate new studies to determine population discreteness and population structure of sei whales.

C.6.2.5.2 Habitat and Geographic Range

Sei whales have a worldwide distribution and are found primarily in cold temperate to subpolar latitudes. During the winter, sei whales are found in warm tropical waters like Hawaii. Sei whales are also encountered during the summer off California and the North America coast from approximately the latitude of the Mexican border to as far north as Vancouver Island, Canada (Horwood, 2009; Masaki, 1976, 1977; Smultea et al., 2010). Although sei whales have been observed south of 20° N in the winter (Fulling et al., 2011; Horwood, 2009; Horwood, 1987), they are considered absent or at very low densities in most equatorial areas. Sei whales are typically found in the open ocean and are rarely observed near the coast (Horwood, 2008). Whaling data provide some evidence of differential migration patterns by reproductive class, with females arriving at and departing from feeding areas earlier than males (Horwood, 1987; Perry et al., 1999). Although there appears to be some seasonal movement between higher latitude summer feeding areas and lower latitude winter calving areas, these movements are not as extensive as those of many other baleen whale species (Jefferson et al., 2015).

Sei whales are not commonly detected in waters of the Hawaiian Islands. Sei whales were not sighted during aerial surveys conducted within 25 NM of the main Hawaiian Islands from 1993 to 1998 (Mobley et al., 2000). The first verified sei whale sighting was made during a NMFS survey of the Hawaiian Island EEZ in 2002 (Barlow, 2006). A subsequent sighting that included subadults made nearshore of the main Hawaiian Islands occurred in 2007 and was cited as evidence suggesting that the area north of the main Hawaiian Islands may be part of a reproductive area for North Pacific sei whales (Smultea et al., 2010). On March 18, 2011 off Maui, the Hawaiian Islands Entanglement Response Network found a subadult sei whale entangled in rope and fishing gear (Bradford & Lyman, 2015c; National Marine Fisheries Service, 2011c). An attempt to disentangle the whale was unsuccessful although a telemetry buoy attached to the entangled gear was reported to be tracking the whale over 21 days as it moved north and over 250 NM from the Hawaiian Islands. During three systematic ship surveys of the Hawaiian Islands EEZ between 2002 and 2017, there were a total of eight sei whale sightings, allowing for the derivation of an updated design-based abundance estimate for the Hawaiian Islands fin whale stock of 401 (CV = 0.84) whales (Bradford et al., 2021). In the summer, sei whales are likely absent from low productivity tropical waters (Jefferson et al., 2015), and during two separate line-transect surveys of the Hawaiian Islands EEZ during summer and fall, sei whales were only seen during the fall months (Barlow, 2006; Bradford et al., 2017).

Sei whales are distributed in offshore waters in the California Study Area (Carretta et al., 2023b). A total of 25 sei whale sightings were made during systematic ship surveys conducted off the U.S. west coast in summer and fall between 1991 and 2014 (Barlow, 2016), and an additional 4 sightings were made during a 2018 survey (Henry et al., 2020). Sei whales were not seen in the Southern California Study Area (or the larger Southern California Bight) during 15 aerial surveys conducted from 2008 through 2012 (Smultea et al., 2014) or during any systematic ship surveys conducted by NMFS (Barlow, 2010, 2016).

Sei whales are likely present in the Transit Corridor portion of the Study Area, and are seen at least as far south as 20° N into the North Pacific Gyre (Horwood, 2009; Horwood, 1987).

C.6.2.5.3 Population Trends

No data are available on current population trends for the Hawaii stock of sei whales in the HCTT Study Area (Carretta et al., 2023b). There has not been a formal trend analysis conducted for the Eastern North Pacific stock of sei whales, but design-based abundance estimates made from 1991 to 2014 show an increasing population trend for sei whales off the U.S. West Coast, with the 2014 estimate being the highest to date (Barlow, 2016). This increase could be due in part to this population's recovery from commercial whaling, or may also represent distribution shifts in these waters (Carretta et al., 2023b).

C.6.2.5.4 Population Threats

Sei whales off the U.S. West Coast are most likely to interact with the California swordfish drift gillnet fishery; however, there were not any observed entanglements in monitored fishing sets from 1990 through 2021 (Carretta, 2022a; Carretta et al., 2023a). Additionally, data from 2012 through 2016 indicate that there has only been one documented vessel strike of this species off the U.S. West Coast (Carretta et al., 2018; Carretta et al., 2023b). Most recent NMFS data from 2017 through 2021 indicate that there were no documented vessel strikes of sei whales during the five-year period (Carretta et al., 2023a).

Climate change has increasingly become a threat to marine mammals, including baleen whales. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.2.6 Sperm Whale (Physeter macrocephalus)

C.6.2.6.1 Status and Management

The sperm whale has been listed as endangered since 1970 under the precursor to the ESA (National Marine Fisheries Service, 2009b), and is depleted under the MMPA, but there is no designated critical habitat for this species in the North Pacific. Sperm whales are divided into three stocks in the Pacific; two (Hawaii and California/Oregon/Washington) occur within the Study Area (Carretta et al., 2023b). Based on genetic analyses, Mesnick et al. (2011) found that sperm whales in the California Current are demographically independent from animals in Hawaii and the eastern tropical Pacific.

Recovery Goals

In response to the threats facing the species, NMFS developed goals to recover sperm whale populations. The 2010 Final Sperm Whale Recovery Plan (National Marine Fisheries Service, 2010c) provides the complete downlisting/delisting criteria. The two main objectives for sperm whale recovery

are to 1) achieve sufficient and viable populations in all ocean basins, and 2) ensure significant threats are addressed. The plan outlines the following recovery actions to accomplish these objectives:

- Coordinate state, federal, and international actions to implement recovery actions and maintain international regulation of whaling for sperm whales.
- Develop and apply methods to estimate population size and monitor trends in
- abundance.
- Determine population discreteness and population structure of sperm whales.
- Conduct Risk Analyses.
- Identify, characterize, protect, and monitor habitat important to sperm whale populations in U.S. waters and elsewhere.
- Investigate causes of and reduce the frequency and severity of human-caused injury and mortality.
- Determine and minimize any detrimental effects of anthropogenic noise in the oceans.
- Maximize efforts to acquire scientific information from dead, stranded, and entangled sperm whales.
- Develop post-delisting monitoring plan.

C.6.2.6.2 Habitat and Geographic Range

The sperm whale is one of the most widely distributed cetacean species and occurs throughout the entire Study Area. Primarily, this species is typically found in the temperate and tropical waters of the Pacific (Rice, 1989), with a secondary range that includes areas at latitudes higher than 50 degrees in the North Pacific (Jefferson et al., 2015; Whitehead, 2009; Whitehead et al., 2008; Whitehead & Weilgart, 2000). This species appears to have a preference for deep waters (Baird et al., 2013c; Jefferson et al., 2015). Typically, sperm whale concentrations correlate with areas of high productivity. These areas are generally near drop offs and areas with strong currents and steep topography (Gannier & Praca, 2007; Jefferson et al., 2015).

Sperm whales are somewhat migratory. General shifts occur during summer months for feeding and breeding, while in some tropical areas, sperm whales appear to be largely resident (Rice, 1989; Whitehead, 2003, 2009; Whitehead et al., 2008). Pods of females with calves remain on breeding grounds throughout the year, between 40° N and 45° N (Rice, 1989; Whitehead, 2003), while males migrate between low-latitude breeding areas and higher-latitude feeding grounds (Pierce et al., 2007). In the northern hemisphere, "bachelor" groups (males typically 15 to 21 years old and bulls [males] not taking part in reproduction) generally leave warm waters at the beginning of summer and migrate to feeding grounds that may extend as far north as the perimeter of the arctic zone. In fall and winter, most return south, although some may remain in the colder northern waters during most of the year (Pierce et al., 2007). Sperm whales occur in Hawaii waters year-round and are one of the more abundant large whales found in that region (Baird et al., 2003b; Barlow, 2006; Bradford et al., 2017; Mobley et al., 2000). A total of 109 sperm whale sightings were made during three summer/fall systematic shipboard surveys of waters within the U.S. EEZ of the Hawaiian Islands (Barlow, 2006; Bradford et al., 2021). Based on predictive habitat-based density models derived from line-transect survey data collected between 1997 and 2012 within the central North Pacific, relatively high densities of sperm whales were predicted within the U.S. EEZ of the Hawaiian Islands during the summer and fall, particularly in the northwest (Forney et al., 2015). Habitat-based density models derived from line-transect survey data collected between 2002 and 2017 within the U.S. EEZ of the Hawaiian Islands also predicted highest

sperm whale densities in the northwest portion of the study area (Becker et al., 2021). Predictions from seasonal habitat-based density models derived from line-transect survey data collected between 2000 and 2020 within the offshore waters of the Main Hawaiian Islands indicated that sperm whale abundance estimates in winter were almost double that of non-winter, although the difference was not found to be statistically significant (Becker et al., 2022a).

Sperm whales are found year-round in California waters, but their abundance is temporally variable, most likely due to the availability of prey species (Barlow, 1995; Barlow & Forney, 2007; Forney & Barlow, 1993; Smultea & Jefferson, 2014). Their distribution is typically associated with waters over the continental shelf break, over the continental slope, and into deeper waters (Carretta et al., 2017b; Rice, 1989; Whitehead, 2003; Whitehead et al., 2008). Based on habitat models derived from line-transect survey data collected between 1991 and 2018 off the U.S. west coast, sperm whales show a strong preference for deep waters (Barlow et al., 2009b; Becker et al., 2020; Becker et al., 2012a; Becker et al., 2010; Forney et al., 2012). During quarterly ship surveys conducted off southern California between 2004 and 2008, there were a total of 20 sperm whale sightings, the majority (12) occurring in summer in waters greater than 2,000 m deep (Douglas et al., 2014b). Only one sperm whale group was observed during 18 aerial surveys conducted in the Southern California Bight from 2008 through 2012 (Smultea et al., 2014).

C.6.2.6.3 Population Trends

Current data are not sufficient to assess a population trend for the Hawaii stock of sperm whales (Carretta et al., 2023b).

Moore and Barlow (2014) used a Bayesian hierarchical approach to examine sperm whale population abundance and trends based on line-transect surveys conducted off the U.S. west coast from 1991 to 2008. Although an estimate of trends was not conclusive, they found that the abundance of adult male sperm whales has increased (Moore & Barlow, 2014). Moore and Barlow (2017b) updated their sperm whale assessment using new data from a NMFS 2014 U.S. west coast survey. While they reported little evidence of increasing trends in overall sperm whale abundance, the new analysis supports prior evidence for an increasing number of sperm whales that occur in small groups (presumed to be adult or near-adult males). However, given high uncertainty associated with the estimated growth rates of this population, a definite trend could not be confirmed (Moore & Barlow, 2017a).

C.6.2.6.4 Population Threats

Sperm whales are susceptible to entanglement in fishing gear and ship strikes. Off the U.S. West Coast, the sperm whales are most likely to interact with the thresher shark/swordfish drift gillnet fishery (Beeson, 1998; Carretta et al., 2019a; Carretta et al., 2019b). Based on California swordfish drift gillnet fishery observer data from 1990 through 2021, NMFS has estimated that the overall probability of a bycatch event resulting in mortality or serious injury to sperm whales from this fishery in 2017 through 2021 was 0.32 whales annually (Carretta, 2022a). Additionally, most recent NMFS data from the same 5-year period indicate that one sperm whale was recorded entangled in unidentified fishing gear (Carretta et al., 2023a). As a result, the annual mean serious injury and mortality of sperm whales resulting from interactions with California drift gillnet fisheries from 2017 through 2021 is 0.52 whales annually. Bradford and Lyman (2015b) recorded one observed interaction between a sperm whale and longline fishing in Hawaiian waters.

Although vessel strikes are considered a potential population threat to sperm whales, most recent data from 2017 through 2021 indicate that there were no observed sperm whale vessel strike deaths on the U.S. West Coast (Carretta et al., 2023a; Carretta et al., 2023b).

Climate change has increasingly become a threat to marine mammals, including sperm whales. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.2.7 False Killer Whale (*Pseudorca crassidens*; Main Hawaiian Islands Insular stock)

C.6.2.7.1 Status and Management

NMFS currently recognizes three stocks of false killer whale in Hawaiian waters: the Hawaii pelagic stock, the Northwestern Hawaiian Islands stock, and the Main Hawaiian Islands insular stock (Bradford et al., 2015; Carretta et al., 2015; Carretta et al., 2023b; Forney et al., 2010; National Oceanic and Atmospheric Administration, 2012; Oleson et al., 2010a). All stocks of false killer whale are protected under the MMPA. The Hawaii Pelagic stock and the Northwestern Hawaiian Islands stock of false killer whales are not listed as threatened or endangered under the ESA. The Main Hawaiian Islands insular stock is listed as endangered under the ESA as a DPS (National Oceanic and Atmospheric Administration, 2012).

Critical Habitat

In July 2016, a complaint was filed in the U.S. District Court for the District of Columbia (Case 1:16-cv-01442; Filed 07/13/16) by the Natural Resources Defense Council against NMFS claiming that NMFS "failed to timely designate" critical habitat for Main Hawaiian Islands insular false killer whales. On July 24 2018, NOAA Fisheries published a final rule to designate critical habitat for the main Hawaiian Islands insular false killer whale DPS by designating waters from the 45 m depth contour to the 3,200 m depth contour around the main Hawaiian Islands from Niihau east to Hawaii (83 FR 35062, July 24, 2018) (Figure C-13). The critical habitat is described by the following four characteristics or essential features, which enable the whales to forage, communicate, and move freely around and among the waters surrounding the main Hawaiian Islands.

- 1. Adequate space for movement and use within shelf and slope habitat
- 2. Prey species of sufficient quantity, quality, and availability to support individual growth, reproduction, and development, as well as overall population growth
- 3. Waters free of pollutants of a type and amount harmful to main Hawaiian Islands insular false killer whales
- 4. Sound levels that would not significantly impair false killer whales' use or occupancy.



Figure C-13: Critical Habitat for MHI Insular False Killer Whale in the HCTT Study Area

Recovery Goals

In response to the threats facing the species, NMFS developed goals to recover the Main Hawaiian Islands Insular False Killer Whale DPS. The 2021 Final Main Hawaiian Islands Insular False Killer Whale Recovery Plan (National Marine Fisheries Service, 2021a) provides the complete downlisting/delisting criteria. The recovery goal is subdivided into discrete component objectives that, collectively, describe the conditions necessary to achieve recovery. NMFS (2021) identified seven recovery objectives for the Main Hawaiian Islands Insular False Killer Whale that address demographic concerns and threats abatement. The plan then outlines specific recovery actions to accomplish these objectives. The seven objectives are as follows:

- Ensure productivity and social connectedness of the Main Hawaiian Islands Insular False Killer Whale (trend, abundance, and social clusters) have met or exceeded target levels.
- Address threats from fisheries including incidental take and competition for prey.
- Address threats from environmental contaminants and biotoxins.
- Address threats from anthropogenic noise.
- Better understand the effects of climate change and manage accordingly.
- Ensure that regulatory mechanisms, including state and federal management and post-delisting monitoring, are in place prior to delisting.
- Ensure secondary threats and synergies among threats are not limiting recovery of the population.

The species is not typically expected to be present in the California Study Area, and false killer whales are not included by NMFS as a managed species in California waters (Carretta et al., 2017b; Carretta et al., 2023b). Strandings and sightings of false killer whales have been recorded in Southern California and north, but these have generally been considered extralimital. During the unusually warm oceanographic conditions in 2014, whale watching boats photographed false killer whales in Southern California waters, but there were none sighted during the SWFSC systematic survey that year (Barlow, 2016). False killer whales do occur in waters off the Baja California Peninsula, Mexico within the California Study Area (Hamilton et al., 2009).

C.6.2.7.2 Habitat and Geographic Range

This species is known to occur in deep oceanic waters off Hawaii, and elsewhere in the Pacific. False killer whales have been detected in acoustic surveys and are commonly observed in the eastern tropical Pacific, including waters off the Baja California Peninsula, Mexico within the Study Area (Carretta et al., 2015; Carretta et al., 2023b; Miyashita et al., 1996; Oswald et al., 2003; Wade & Gerrodette, 1993; Wang et al., 2001). False killer whale are also regularly found within Hawaiian waters and have been reported in groups of up to 100 over a wide range of depths and distance from shore (Baird et al., 2003b; Baird et al., 2013a; Bradford et al., 2018; Bradford et al., 2014; Bradford et al., 2015; Oleson et al., 2013; Shallenberger, 1981).

The ranges and stock boundary descriptions for false killer whales in the Hawaiian Islands are complex and overlapping. For example, all three stocks are known to overlap in the vicinity of Kauai and Niihau, which is where the Navy's underwater instrumented range has been in use since the 1980s. All significant information regarding the range of the three stocks was presented in Bradford et al. (2015), and later updated for the pelagic stock (Bradford et al., 2020). A summary of the data used to delineate the stock boundaries, and the research supporting those data are provided in the Final 2022 Pacific Stock Assessment Report (Carretta et al., 2023b) that is synthesized in the next few paragraphs for the stocks in the Hawaiian Islands.

The Main Hawaiian Islands insular stock is considered resident to the main Hawaiian Islands consisting of Kauai, Oahu, Molokai, Lanai, Kahoolawe, Maui, and Hawaii, although they have been satellite tracked as far as 115 km from the main Hawaiian Islands (Bradford et al., 2020; Bradford et al., 2012; Bradford et al., 2015; Carretta et al., 2015; Forney et al., 2010; National Oceanic and Atmospheric Administration, 2012; Oleson et al., 2010a). The Main Hawaiian Islands insular stock boundary is a 72 km radius extending around the main Hawaiian Islands, with the offshore extent of the radii connected on the leeward sides of Hawaii Island and Niihau to encompass the offshore movements of Main Hawaiian Islands insular stock animals within that region.

False killer whales in the Northwestern Hawaiian Islands stock have been seen as far as 93 km from the Northwestern Hawaiian Islands and near shore around Kauai and Oahu (Baird et al., 2012; Bradford et al., 2015). The Northwestern Hawaiian Islands stock boundary is defined by a 93 km radius around Kauai, Niihau, and the Northwestern Hawaiian Islands, with the boundary around the Northwestern Hawaiian Islands at the eastern end to encompass animal movements observed outside the 93 km radius.

Given new telemetry data that indicated that pelagic stock animals occurred within 5.6 km of the main Hawaiian Islands and throughout the Northwestern Hawaiian Islands, the previous inner pelagic stock boundary at 11 km from shore around each of the main Hawaiian Islands was removed (Bradford et al., 2020). The pelagic stock now has no inner or outer boundary within the Hawaiian Islands EEZ. There is now an overlap zone between the entirety of the Main Hawaiian Islands insular stock area and the pelagic stock area. There is also now an overlap zone between the entirety of the Northwestern Hawaiian Islands stock area and the pelagic stock area. All three stock boundaries overlap out to the Main Hawaiian Islands insular stock boundary between Kauai and Niihau and the Northwestern Hawaiian Islands stock boundary between Kauai and Oahu (Carretta et al., 2023b).

Two year-round Small and Resident Population BIAs (a parent and a child BIA) have been delineated in the main Hawaiian Islands for the insular stock of false killer whales (Kratofil et al., 2023) (Figure C-14). The BIAs were updated from the original BIAs published by Baird et al. (2015d) based on additional analysis of photo-identification, satellite tracking, and genetic studies. The parent BIA encompasses 94,217 km² and the child BIA encompasses 7,775 km², the latter representing the core high-use areas in the Main Hawaiian Islands (Kratofil et al., 2023). In addition, a year-round non-hierarchical Small and Resident Population BIA was delineated for the Northwestern Hawaiian Islands and encompasses 138,001 km² (Kratofil et al., 2023) (Figure C-14).



Figure C-14: False Killer Whale Small and Resident BIAs in the Hawaii Study Area

As noted previously, false killer whales are not usually expected to be present in the California Study Area. Older records document only a handful of sightings from areas such as Monterey Bay, Santa Catalina, and the Channel Islands (Baird, 2009a; Jefferson et al., 2008; Miller & Scheffer, 1986). False killer whales were not detected during the 15 aerial surveys conducted in the Southern California Range Complex from 2008 through 2012 (Smultea & Jefferson, 2014). A nearshore marine mammal survey off San Diego Bay in March 2014 detected a false killer whale pod that was assumed to be the same pod that had been seen 6 days before off Dana Point (Graham & Saunders, 2015). Two years later in April– March 2016, a whale watch vessel out of Dana Point again sighted a pod of false killer whales in the same area (Ritchie, 2016). This species normally prefers warmer tropical waters found outside of southern California and the presence of this species to the north of its usual habitat was likely due to the warmer than normal water temperatures associated with a known El Niño event. Such documented strandings and sightings of false killer whales in California waters have thus been considered extralimital. False killer whales do occur in warmer waters off the Baja California Peninsula, Mexico within the California Study Area (Hamilton et al., 2009).

C.6.2.7.3 Population Trends

Reeves et al. (2009) suggested that the Main Hawaiian Islands Insular stock of false killer whales declined between 1989 and 2009. A review of sighting rates of false killer whales from aerial surveys conducted around the main Hawaiian Islands between 1994 and 2004 also indicated a decline in this population (Baird, 2009b). A Status Review of the Main Hawaiian Islands Insular stock of false killer whales was consistent with these earlier studies, indicating that the population had declined at a rate of 9 percent per year since 1989, although alternative models showed a lower rate of decline (Oleson et al., 2010b). (Baird, 2009a; Baird et al., 2015f; Bradford & Forney, 2016, 2017; Carretta et al., 2017b; Carretta et al., 2023b; Cascadia Research Collective, 2010; Oleson et al., 2010b; Reeves et al., 2009; West, 2016)Population Threats

(Cascadia Research Collective, 2010) In Hawaiian waters, false killer whales are particularly susceptible to fishery interactions and entanglements (Baird et al., 2015f; Bradford & Forney, 2016). A historic decline in the Main Hawaiian Islands insular population has been the result of various non-Navy factors that include the small population size of this stock and incidental take by commercial fisheries (Bradford & Forney, 2016; Oleson et al., 2010b; Reeves et al., 2009). There were four strandings of Main Hawaiian Island Insular false killer whales in the Hawaiian Islands in the 7-year period between the start of 2010 and the end of 2016 (West, 2016). Two of these stranded animals had fishing gear (fishhooks, leaders, line) found within the stomach contents examined during necropsy (West, 2016). Most recent data from 2017 through 2021 indicates that there were no entanglements or hooks of false killer whales in the shallow-set longline fishery; however, there were 54 reported entanglements or hooks of this species in the deep-set longline fishery during the same time period (Carretta et al., 2023b). Of the deep-set longline fishery interactions, 18 were encountered in the outside of the Hawaii EEZ, where 14 were considered seriously injured and 2 were found dead. Of the remaining 36 encounters in the Hawaii EEZ, 23 whales were considered seriously injured and 5 were found dead (Bradford, 2018a; Bradford, 2018b; Bradford, 2021; Bradford et al., 2017; Bradford et al., 2021; Carretta et al., 2023b; McCracken, 2019).

Because false killer whales feed on large prey at the top of the food chain (e.g., squid, tunas) they may also be impacted by competition with fisheries (Cascadia Research Collective, 2010).

Like many marine mammals, false killer whales also accumulate high levels of toxins in their blubber over the course of their long lives, but the consequence of that bioaccumulation remains unknown.
Climate change has increasingly become a threat to marine mammals. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.2.8 Killer Whale (Orcinus orca ater; Eastern North Pacific Southern Resident stock)

Different geographic forms of killer whale are distinguished by distinct social and foraging behaviors and other ecological traits. In the North Pacific, these recognizable geographic forms are variously known as "residents," "transients," and "offshore" ecotypes (Hoelzel et al., 2007; Morin et al., 2024). Recently, new analyses suggest that species status may be warranted for two of the different eastern North Pacific ecotypes, the Bigg's or transient killer whales and the resident killer whales, including the Eastern North Pacific Southern Resident stock (Morin et al., 2024). However, the proposal before the Society for Marine Mammalogy Committee on Taxonomy failed to receive the 2/3 majority needed to pass, so killer whales will remain as a single species, but Bigg's and resident killer whales will now be recognized as separate subspecies. *Orcinus orca rectipinnus* and *Orcinus orca ater*, respectively. In the HCTT Study Area, both the transient and offshore ecotypes are known to occur, and Southern Resident killer whales may seasonally occur along the northern portion of the California Study area north of Monterey Bay (Hanson et al., 2018);National Marine Fisheries Service, 2021 #15025;Millman, 2019 #3115}.

C.6.2.8.1 Status and Management

Eight killer whale stocks are recognized within the North Pacific U.S. EEZ, with only the Hawaiian stock occurring in Hawaii and three stocks occurring in the California Study Area consisting of the West Coast Transient stock, the Eastern North Pacific Offshore stock, and the Eastern North Pacific Southern Resident stock (Carretta et al., 2023b). Three separate pods comprise the Southern Resident stock, identified as the J, K, and L pods (Ford et al., 2000). Killer whales are protected under the MMPA and the Southern Resident killer whale stock or DPS is listed as endangered under the ESA listed. The other two stocks are not listed under the ESA.

Critical Habitat

NMFS designated critical habitat for the Southern Resident killer whale DPS on November 29, 2006, in the inland waters of Washington State (71 FR 69054) and revised the designation to expand critical habitat into offshore waters of Washington, Oregon, and California on August 2, 2021 (86 FR 41668). The critical habitat along the West Coast that extends into the Study Area is defined as marine waters between the 6.1 and 200 m depth contours (86 FR 41668). As shown in Figure C-15, critical habitat occurs within a small, nearshore portion of the northern portion of the California Study Area and shoreward of the PMSR to just south of Monterey.

The essential features defining critical habitat for the Southern Resident killer whale are: (1) Water quality to support growth and development; (2) Prey species of sufficient quantity, quality, and availability to support individual growth, reproduction, and development, as well as overall population growth; and (3) Passage conditions to allow for migration, resting, and foraging. Calambokidis et al. (2024) defined a small and resident BIA (parent and core) off the U.S. West Coast extending from Washington State south to Point Sur, California. Only the parent BIA is located within or adjacent to the Study Area (Figure C-16); the core BIA is north of the Study Area off the coast of Washington State. The BIA is the same spatial extend as the designated critical habitat for Southern Resident killer whales.

Hawaii-California Training and Testing Draft EIS/OEIS



Figure C-15: Critical Habitat for Southern Resident Killer Whale in the California Study Area

Hawaii-California Training and Testing Draft EIS/OEIS



Figure C-16: Southern Resident Killer Whale Small and Resident BIA in the California Study Area

Recovery Goals

In response to the threats facing the species, NMFS developed goals to recover the Southern Resident killer whale. The 2008 Southern Resident Killer Whale Recovery Plan (National Marine Fisheries Service, 2008) provides the complete downlisting/delisting criteria. The recovery action outline includes the following management measures and research and monitoring actions:

- Protect the Southern Resident killer whale population from factors that may be contributing to its decline or reducing its ability to recover.
- Protect Southern Resident killer whales from additional threats that may cause disturbance, injury, or mortality, or impact habitat.
- Develop public information and education programs.
- Respond to killer whales that are stranded, sick, injured, isolated, pose a threat to the public, or exhibit nuisance behaviors.
- Transboundary and interagency coordination and cooperation.
- Monitor status and trends of the Southern Resident killer whale population.
- Conduct research to facilitate and enhance recovery efforts for Southern Resident killer whales.

C.6.2.8.2 Habitat and Geographic Range

Killer whales are found in all marine habitats from the coastal zone (including most bays and inshore channels) to deep oceanic basins and from equatorial regions to the polar pack ice zones of both hemispheres. Although killer whales are also found in tropical waters and the open ocean, they are most numerous in coastal waters and at higher latitudes (Dahlheim & Heyning, 1999). Forney and Wade (2006) found that killer whale densities increased by 1–2 orders of magnitude from the tropics to the poles.

All three ecotypes of killer whale are known to occur along the west coast of North America, from the entire Alaskan coast, in British Columbia and Washington inland waterways, and along the outer coasts of Washington, Oregon, and California, but the endangered resident ecotype's range typically does not extend south of Monterey California (Calambokidis & Barlow, 2004; Carretta et al., 2017b; Dahlheim et al., 2008; Ford & Ellis, 1999; Forney et al., 1995; Hanson et al., 2018).

Southern Resident killer whales have seasonal shifts in distribution from the inland waters of the Salish Sea and Puget Sound in Washington and British Columbia to locations that can be up to hundreds of miles from Washington waters both north (as far as Southeast Alaska) or south as far as central California (Carretta et al., 2023b; National Marine Fisheries Service, 2021c). Of the three pods, the K and L pods appear to have a more extensive and seasonally variable offshore coastal distribution, with rare sightings as far south as Monterey Bay and central California in recent years; and the L pod has been observed in in Chatham Strait, Southeast Alaska (Hanson et al., 2017; National Marine Fisheries Service, 2021c).

To better predict the pattern of distribution of the endangered Southern Resident killer whales off the Washington, Oregon, and Northern California coasts, researchers integrated visual sightings, location data obtained between 2012 and 2016 from satellite-tagged Southern Resident killer whales, and acoustic detections from underwater hydrophones obtained from 6 to 13 recorders deployed from 2011 to 2015 off the Washington, Oregon, and California coast (Hanson et al., 2018; U.S. Department of the Navy, 2018). Along the Pacific coast, the distribution of satellite-tag locations confirms that Southern

Resident killer whales generally inhabit nearshore waters over the continental shelf in waters less than 200 m deep and typically within 34 km from shore (Hanson et al., 2017). Over multiple years the data revealed that the killer whales spent the greatest amount of time near the mouth of the Columbia River and off Westport, Washington, north of the California Study Area (Hanson et al., 2018; Hanson et al., 2017; U.S. Department of the Navy, 2018). Based on the Hanson et al. (2018) analyses, members of the K and L pods may occur within the northern coastal portion of the HCTT study area from January to May.

Their seasonal range and preference for nearshore habitat reduces the likelihood that Southern Resident killer whales would occur in the Study Area, and, furthermore, that their occurrence would be limited to the easternmost portion of the northern portion of the California Study Area and inshore of the PMSR in winter and early spring.

C.6.2.8.3 Population Trends

Based on the Draft 2023 U.S. Pacific Marine Mammal Stock Assessment Report (Carretta et al., 2024), the most recent estimate of the total population of Southern Resident killer whales based on data collected from 1 July 2021 through 1 July 2022 was 73 whales. In 1995, abundance of the stock peaked at 99 and has declined an average of 1 percent per year (Carretta et al., 2023b). Further declines are predicted if the population remains genetically isolated (Kardos et al., In Press).

C.6.2.8.4 Population Threats

The reduced availability of salmon, specifically Chinook salmon, their preferred prey, is considered one of the main threats to the southern resident killer whales (Couture et al., 2022). Many salmon populations that were once abundant historically have declined to the point where they have been listed as endangered or threatened with extinction (see Section 3.6, Fishes). The reduced availability of salmon has been linked to overfishing, poor artificial propagation practices, and degradation of freshwater and estuarine habitats through urbanization, dam building, and forestry, agricultural, and mining practices (Hilborn et al., 2012; National Marine Fisheries Service, 2008, 2016t; National Oceanic and Atmospheric Administration Fisheries, 2014; Office of the Washington Governor, 2018).

Since the 1970s commercial shipping, whale watching, ferry operations, and recreational boat traffic in Puget Sound and the coastal islands of southern British Columbia when southern residents occur most frequently has increased (Bassett et al., 2012; Bassett et al., 2010; Erbe, 2002; Holt et al., 2017; Holt et al., 2011; Williams et al., 2014b; Williams et al., 2019). In addition to the disturbance associated with the presence of vessels, the noise associated with vessel traffic affects the acoustic ecology of Southern Resident killer whales, which would affect their social ecology. Foote et al. (2004) compared recordings of Southern Resident killer whales that were made in the presence or absence of boat noise in Puget Sound during three time periods between 1977 and 2003. The authors determined that the duration of primary calls in the presence of boats had increased by about 15 percent during the last of the three time periods (2001–2003). Holt et al. (2008) reported that Southern Resident killer whales in Haro Strait off the San Juan Islands in Puget Sound increased the amplitude of their social calls in the face of increased levels of background noise. Although the costs of these vocal adjustments remains unknown, Foote et al. (2004) suggested that the amount of boat noise may have reached a threshold above which the killer whales need to increase the duration of their vocalization to overcome masking effects.

Exposure to contaminants may also harm killer whales. The presence of high levels of persistent organic pollutants, such as PCB, DDT, and flame-retardants, has been documented in southern resident killer whales (Krahn et al., 2007). Although the consequences of these pollutants on the fitness of individual killer whales and the population itself remain unknown, in other species these pollutants have been

reported to suppress immune responses (Wright et al., 2007), impair reproduction, and exacerbate the energetic consequences of physiological stress responses when they interact with other compounds in an animal's tissues (Wright et al., 2007). Because of their long-life span, position at the top of the food chain, and their blubber stores, killer whales would be capable of accumulating high concentrations of contaminants.

Although Southern Resident killer whales are also susceptible to interactions with fisheries, there has only been one recorded entanglement of this species in 1977. Most recent data indicate that there were no recorded entanglements of Southern Resident killer whales in California gillnet fisheries from 2017 through 2021(Carretta et al., 2023a).

Climate change has increasingly become a threat to marine mammals, including killer whales. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.2.9 Hawaiian Monk Seal (Neomonachus schauinslandi)

C.6.2.9.1 Status and Management

The Hawaiian monk seal was listed as endangered under the ESA in 1976 (National Marine Fisheries Service, 1976) and is listed as depleted under the MMPA. The species is considered a high priority for recovery, based on the high magnitude of threats, the high recovery potential, and the potential for economic conflicts while implementing recovery actions (National Marine Fisheries Service, 2007b, 2011b, 2016p). The approximate area encompassed by the northwestern Hawaiian Islands was designated as the Papahanaumokuakea National Marine Monument in 2006, in part to protect the habitat of the Hawaiian monk seal. Hawaiian monk seals are managed as a single stock. There are six main reproductive subpopulations at: French Frigate Shoals, Laysan Island, Lisianski Island, Pearl and Hermes Reef, Midway Island, and Kure Atoll in the northwestern Hawaiian Islands.

Critical Habitat

Critical habitat for Hawaiian monk seals was designated August 21, 2015 (National Oceanic and Atmospheric Administration, 2015a) (Figure C-17). The essential features of the critical habitat were identified as: (1) adjacent terrestrial and aquatic areas with characteristics preferred by monk seals for pupping and nursing; (2) shallow, sheltered aquatic areas adjacent to coastal locations preferred by monk seals for pupping and nursing; (3) marine areas from 0 to 500 m in depth preferred by juvenile and adult monk seals for foraging; (4) areas with low levels of anthropogenic disturbance; (5) marine areas with adequate prey quantity and quality; and (6) significant areas used by monk seals for hauling out, resting, or molting (National Oceanic and Atmospheric Administration, 2015a).



Figure C-17: Critical Habitat for Hawaiian Monk Seal in the HCTT Study Area

Recovery Goals

A recovery plan for the Hawaiian monk seal was completed in 1983 and was revised in 2007 (National Marine Fisheries Service, 2007b, 2011b, 2016p). The 2007 Hawaiian Monk Seal Recovery Plan for the complete downlisting/delisting criteria. The recovery action outline includes the following fourteen short-term and long-term actions:

- Investigate and mitigate factors affecting food limitation.
- Prevent entanglements of monk seals.
- Reduce shark predation on monk seals.
- Minimize exposure and spread of infectious disease.
- Conserve Hawaiian monk seal habitat.
- Reduce Hawaiian monk seal interactions with fisheries.
- Reduce male aggression toward pups/immature seals and adult females.
- Reduce the likelihood and impact of human disturbance.
- Investigate and develop response to biotoxin impacts.
- Reduce impacts from compromised and grounded vessels.
- Reduce the impact of contaminants.
- Continue population monitoring and research.
- Create a Main Hawaiian Islands Hawaiian Monk Seal Management Plan.
- Implement the Recovery Program for the Hawaiian monk seal.

C.6.2.9.2 Habitat and Geographic Range

Hawaiian monk seals occur in the main Hawaiian Islands and Northwestern Hawaiian Islands, but sightings have been reported at Johnston Atoll, Wake Island, and Palmyra Atoll (south of the Hawaiian Island chain; (Carretta et al., 2010; Gilmartin & Forcada, 2009; Jefferson et al., 2015; National Marine Fisheries Service, 2009a, 2010d). The six main breeding sites are in the northwestern Hawaiian Islands: Kure Atoll, Midway Islands, Pearl and Hermes Reef, Lisianski Island, Laysan Island, and French Frigate Shoals. Smaller breeding sites are on Necker Island and Nihoa Island, and monk seals have been observed at Gardner Pinnacles and Maro Reef.

There is a small breeding population of monk seals found throughout the main Hawaiian Islands. Births have been documented on most major islands and most commonly on Kauai and Niihau (Gilmartin & Forcada, 2009; National Marine Fisheries Service, 2007b, 2010d). Hawaiian monk seals give birth throughout the year, but peak pupping season is typically spring through summer. Monk seals prefer sandy, protected beaches for pupping (National Marine Fisheries Service, 2024g). Based on one study, on average, 10 to 15 percent of the monk seals migrate among the northwestern Hawaiian Islands and the main Hawaiian Islands (Carretta et al., 2010). Another source suggests that approximately 35 percent of the main Hawaiian Island seals travel between islands throughout the year (Littnan, 2011). Greater than expected movement between sites within the main Hawaiian Islands and the northwestern Hawaiian Islands (Johanos et al., 2014), has allowed for genetic conductivity between Hawaiian monk seal subpopulations (Schultz et al., 2011).

When hauled out, Hawaiian monk seals seem to prefer beaches of sand, coral rubble, and rocky terraces (Baker et al., 2006; Jefferson et al., 2015). Consistent with ten previous detections of monk seals at Kaula Island, in 2012 there were three individual monk seals that were observed hauled out on the rock ledge on the northwest side of the island (Richie et al., 2012). Aerial surveys of Kaula Island from April

2013 through March 2016 continued to document monk seals routinely hauled out on the rocky ledges at the edge of the island, numbering between five and 11 monk seals seen on each of the six surveys (Normandeau Associates & APEM, 2013a, 2013b, 2014, 2015a, 2015b, 2016).

In the Main Hawaiian Islands, monk seals are generally solitary and have no established rookeries unlike pinnipeds in Southern California. Hawaiian monk seals do, however, routinely haul out for molting and pupping in locations including at the Navy's PMRF, Pearl Harbor, and other military lands. When foraging, monk seals spend most of their time in nearshore, shallow marine habitats, but can rapidly cover large areas in search of food and may travel hundreds of miles in a few days (D'Amico, 2013; Littnan, 2011; Stewart et al., 2006; Wilson et al., 2012).

From 1996 to 2002 and in an effort to better understand the range of foraging monk seals, Stewart et al. (2006) used satellite-linked radio transmitters to document the movements of 147 Hawaiian monk seals from all six northwestern Hawaiian Islands breeding colonies. Foraging patterns were complex and varied among colonies by season, age and sex, but in general monk seals were found to forage extensively within the atoll barrier reefs and on the leeward slopes of reefs and islands at all colony sites. They also ranged away from these sites along the Hawaiian Islands submarine ridge to most nearby seamounts and submerged reefs and banks (Stewart et al., 2006).

Between February 2010 and July 2011, 12 data tags on monk seals in the main Hawaiian Islands were successfully deployed, retrieved, and analyzed (D'Amico, 2013; Littnan, 2011; Stewart et al., 2006; Wilson et al., 2012). The average foraging trip was approximately 30 km in distance, almost 19 hours in duration, and most seals remained within the 600 m depth contour. Although most trips were less than 50 km, two seals made at least one long pelagic foraging trip during the deployment period (Littnan, 2011). An adult male tagged on Oahu traveled over 3,000 km on a trip which lasted 36 days and a sub-adult female tagged on Kauai traveled 300 km on a trip that lasted almost 4 days. Approximately 54 percent of the seals made regular trips between two or more of the islands, while the remainder showed fidelity to one island (Littnan, 2011).

Hawaiian monk seals are not present in the California Study Area.

C.6.2.9.3 Population Trends

Population dynamics at the different locations in the northwestern Hawaiian Islands and the main Hawaiian Islands have varied considerably (Antonelis et al., 2006).

The smaller subpopulation in the Main Hawaiian Islands has been increasing in recent years, whereas the larger population in the northwestern Hawaiian Island was thought to have been in a long-term decline (Antonelis et al., 2006; Baker et al., 2016c; Baker et al., 2011; Baker & Johanos, 2004). However, a new approach was developed to estimate the abundance range-wide and for individual island-specific subpopulations (Baker et al., 2016c). The new approach incorporates multiple methods of estimating site-specific abundances (e.g., direct counts, counts corrected for seals at sea, capture-recapture) and combines the results into a model (Harting et al., 2017). The Monte Carlo-style model was employed to overcome inconsistent field survey data, which, due to the difficulty of surveying numerous remote islands simultaneously, are collected years apart and often using differing, non-standardized methods. Based on the most recent counts and modeling results, the range-wide abundance is estimated at 1,437 monk seals (Carretta et al., 2022). Of particular importance is that the model also indicted the monk seal population increased at a rate of 2 percent per year from 2013 to 2019, countering previous trend analyses indicating the population was in decline (Carretta et al., 2022; Robinson et al., 2022).

C.6.2.9.4 Population Threats

Monk seals are susceptible to fishery and marine debris entanglements at rates higher than most other pinnipeds (Carretta et al., 2023b; Henderson, 2001). Records collected in the main Hawaiian Islands show at least 140 seal hooking and entanglement incidents from 1976 to 2014 (National Marine Fisheries Service, 2016p). In 2021, 29 Hawaiian monk seal hookings were observed, with two hookings resulting in serious injury (Carretta et al., 2024; Mercer, 2023). Monk seals have also been observed entangled in nearshore fishing gillnets, which has resulted in injury and mortality.

There have been several hundred documented cases of marine debris entanglement of monk seals, 10 of which have resulted in mortality (Carretta et al., 2023b; Henderson, 2001; Henderson, 2019; Mercer, 2021). In the northwestern Hawaiian Islands, derelict fishing gear has been identified as a top threat to the monk seal (Donohue & Foley, 2007), while in the main Hawaiian Islands, high risks are associated with health hazards from exposure to pollutants and infectious disease agents associated with terrestrial animals. The Hawaiian Monk Seal Research Program reported that in Hawaii since 2001, there have been at least 8 deaths of Hawaiian Monk Seal Research Program, 2015; Rogers, 2016). In 2015, the Hawaiian Islands (Hawaiian Monk Seal Research Program to protect Hawaiian monk seals from morbillivirus because of the threat it poses given that monk seals do not otherwise carry antibodies to the virus (National Oceanic and Atmospheric Administration, 2015d).

Natural population threats to Hawaiian monk seals include disease, parasites, reduced prey availability, and predator attacks, particularly by both killer whales and sharks. Shark predation is one of the major sources of mortality for this species especially in the northwestern Hawaiian Islands. Galapagos sharks are a major source of juvenile mortality in the northwestern Hawaiian Islands, with most predation occurring in the French Frigate Shoals (Antonelis et al., 2006; Gilmartin & Forcada, 2009). Another species-specific threat includes aggressive male monk seals that have been documented to injure and sometimes kill females and pups (National Marine Fisheries Service, 2010e, 2010f).

Climate change has increasingly become a threat to marine mammals, including pinnipeds. Since monk seals rely on coastal habitats for survival, monk seals may be affected by future sea level rise and loss of habitat as predicted by global climate models. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.2.10 Guadalupe Fur Seal (Arctocephalus townsendi)

C.6.2.10.1 Status and Management

The Guadalupe fur seal is listed as threatened under the ESA and depleted under the MMPA. Critical habitat for the Guadalupe fur seal has not been designated, and the only areas likely to meet the requirements as critical habitat are outside of U.S. jurisdiction (National Oceanic and Atmospheric Administration, 1985). All fur seals alive today are recent descendants from one breeding colony at Isla Guadalupe and Isla San Benito off Mexico and are considered a single stock (Carretta et al., 2017b; Pablo-Rodriguez et al., 2015).

C.6.2.10.2 Habitat and Geographic Range

Guadalupe fur seals are not found in the Hawaii Study Area.

On shore, Guadalupe fur seals are typically found hauled out along coastlines with abundant large rocks, often at the base of large cliffs. They are also known to inhabit caves, which provide protection and cooler temperatures, especially during the warm summer breeding season (Belcher & Lee, 2002). Adult males, juveniles, and nonbreeding females may remain at sea for much of the year (Reeves et al., 1992). Several observations suggest that this species travels alone or in small groups of fewer than five individuals (Belcher & Lee, 2002; Seagars, 1984).

Navy funded tagging studies tracking Guadalupe fur seal movements from Guadalupe Island north along the U.S. West Coast show that non-pups (adults and juveniles of both sexes) occur in highest concentrations in offshore waters near the Patten Escarpment or at approximately the 2,000 m depth contour and in the SOCAL Range Complex and PMSR (Norris, 2019; Norris, 2022; Norris & Elorriaga-Verplancken, 2020). Pups, however, migrate closer to shore than non-pups and are known to migrate farther north into waters off Oregon, Washington, and British Columbia. Based on the tagging results and unpublished data, a "core range" and a broader "geographic range" representing Guadalupe fur seal distribution was defined along the West Coast (Norris, 2022). Detailed information on the distribution of this species in the Study Area is provided in the *U.S. Navy Marine Species Density Database Phase IV for the Hawaii-California Training and Testing Study Area* technical report (U.S. Department of the Navy, 2024).

C.6.2.10.3 Population Trends

Guadalupe fur seals were once plentiful off the coasts of California and Mexico, ranging from the Gulf of the Farallones near San Francisco, to the Revillagigedo Islands, Mexico (Aurioles-Gamboa et al., 1999). However, over-harvesting in the 19th century led them to the brink of extinction. With implementation of protective measures in the 20th century by both the U.S. and Mexico, the population began to slowly recover and expand into its historical range extending from central Mexico to waters off Washington State (Aurioles-Gamboa et al., 2010; D'Agnese et al., 2020; Melin & DeLong, 1999; Norris & Elorriaga-Verplancken, 2020; Stewart, 1981; Stewart et al., 1993b). An unpublished abundance of 43,360 Guadalupe fur seals based on pup counts was provided by Norris (2022) as the mean of two separately derived abundance estimates of 37,940 and 48,780 fur seals. Current and ongoing studies indicate that the population is continuing to increase.

C.6.2.10.4 Population Threats

Most recent data indicates that there was a total of 13 reported serious injuries and/or deaths of Guadalupe fur seals along the U.S. west coast from 2013 to 2017 due to human-related causes (primarily marine debris entanglement)(Carretta et al., 2023b). In 2015 an UME was declared for Guadalupe fur seal. 80 strandings of Guadalupe fur seals, which were approximately eight times higher than the historical average, occurred along the entire coast of California, consisted of mostly weaned pups and juveniles in the one-to-two-year age-range, and included animals in distress but alive as well as dead individuals. Findings from the majority of these stranded Guadalupe fur seals were that they were malnourished and had secondary bacterial and parasitic infections (National Marine Fisheries Service, 2015a). It is likely that a shift in the prey may have resulted in these young animals being unable to obtain adequate food due to anomalously persistent warm ocean conditions (Bond et al., 2015).

Climate change has increasingly become a threat to marine mammals, including baleen whales. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.2.11 Southern Sea Otter (Enhydra lutris neris)

C.6.2.11.1 Status and Management

The southern sea otter is listed as threatened under the ESA and depleted under the MMPA. The southern sea otter is managed by the USFWS, and critical habitat has not been designated for this species. Southern sea otters are not found in the Hawaii Study Area. Between 1987 and 1990, the USFWS managed a program to translocate southern sea otters from the mainland to SNI to ensure the population would survive a catastrophic event, such as an oil spill, off the mainland coast (U.S. Fish and Wildlife Service, 2012a). The program would also help to reestablish a population on an island where they historically occurred and promote the recovery of the species (Bodkin, 2015). A total of 140 sea otters were moved to SNI, but by 1993, fewer than 15 survived. The USFWS declared the translocation program a failure in 2012 and ended the program, but despite that, the population has continued to grow (Yee et al., 2023).

The NDAA for Fiscal Year 2016 included provisions directing the Secretary of the Navy to establish Southern Sea Otter Military Readiness Areas at SNI and SCI. Within these Military Readiness Areas, the 2016 NDAA established that the ESA sections 4 and 9 and MMPA sections 101 and 102 do not apply to the incidental taking of any southern sea otter during military readiness activities. Any sea otter within the Military Readiness Areas is to be treated for the purposes of section 7 of the ESA as a member of a species that is proposed to be listed as endangered or threatened under the ESA.

As an additional component of the management of the species, the 2016 NDAA required that the Navy conducts monitoring and research within the Military Readiness Areas to determine the effects of military readiness activities on the growth or decline of the southern sea otter population and on the nearshore ecosystem. The monitoring and research were designed in consultation with the USFWS, and reports to Congress are required periodically. The first of these reports was completed in 2017 (U.S. Department of the Navy, 2017a; U.S. Department of the Navy et al., 2016). Subsequent follow-on reports have been provided every three years thereafter, and findings from these reports will continue to be reviewed by the Navy and USFWS to ensure the plan continues to adequately monitor interactions between military readiness activities and the sea otter population.

C.6.2.11.1.1 Special Status of San Nicholas Island population

Shortly after their discovery by 18th century European explorers, fur traders hunted sea otters across the north Pacific. By the turn of the 20th century, sea otters were nearly extinct. Southern sea otters are descendants of a small remnant colony that survived along the central California coast. In 1986, the USFWS sought to enhance recovery of the species through translocation of southern sea otters from the central coast of California to SNI. Inconsistencies between the ESA and MMPA led the USFWS to seek congressional authorization for the Southern Sea Otter Translocation Program, and President Reagan signed Public Law 99-625 into law on November 7, 1986. The law authorized the USFWS to establish an experimental population of sea otters and provided provisions for a sea otter management zone and specific exemptions from the ESA for Department of Defense activities. Between 1987 and 1990, the USFWS moved 140 sea otters to SNI. By 1993, fewer than 15 sea otters remained at the island. Many animals swam back to the central coast; some were captured and returned to the central coast after swimming into the designated sea otter management zone, and some died due to being moved (U.S. Fish and Wildlife Service, 2012a). The USFWS eventually declared the translocation program a failure and removed regulations governing the program (77 FR 75266, December 19, 2012).

Since declaring the translocation a failure, the sea otter colony has increased significantly with more than 100 animals routinely observed at SNI. At the start of the translocation program, the USFWS had committed to removing sea otters from SNI if the translocation program was ever declared a failure. They instead determined that it would be in the best interest of southern sea otter recovery to leave them at the island. The USFWS acknowledged that the Navy was given an exemption from ESA for sea otters on SNI but stated in their final rule (77 FR 75266) that there was no exemption from the MMPA for Navy activities. Clarification of Department of Defense ESA and MMPA responsibilities for sea otters in Southern California was provided by Congress in the National Defense Authorization Act for Fiscal Year 2016, which included provisions directing the Secretary of the Navy to establish Southern Sea Otter Military Readiness Areas at SNI and San Clemente Island (Figure 3.7 7). Within these Military Readiness Areas, the 2016 NDAA established that the ESA sections 4 and 9 and MMPA sections 101 and 102 do not apply to the incidental taking of any southern sea otter during Navy testing and training activities. Any sea otter within the Areas is to be treated for the purposes of section 7 of the ESA as a member of a species that is proposed to be listed as endangered or threatened under the ESA.

As an additional component of the management of the species, the 2016 NDAA requires that the Navy conduct monitoring and research within the Southern Sea Otter Military Readiness Areas (Figure C-18) to determine the effects of military readiness activities on the growth or decline of the southern sea otter population and on the nearshore ecosystem. The monitoring and research are designed in consultation with the USFWS, and reports to Congress are required periodically. The first of these reports was completed in 2017 (U.S. Department of the Navy, 2017a; U.S. Department of the Navy et al., 2016). Subsequent follow-on reports are to be provided every three years thereafter, and findings from these reports will continue to be reviewed by the Navy and USFWS to ensure the plan continues to adequately monitor interactions between military readiness activities and the sea otter population.





C.6.2.11.2 Habitat and Geographic Range

The distribution of the southern sea otter is currently limited to nearshore waters off the coast of central California, ranging from Pigeon Point in the north to south of Point Conception, and off SNI (Hatfield et al., 2016; Hatfield et al., 2019; Tinker et al., 2017). Sea otter distribution is typically defined by habitat features, frequently water depth and distance from shore, which are linked to the otter's dive depth limitations or preferences when foraging (Bodkin et al., 2004; Thometz et al., 2016; Tinker et al., 2017; Tinker et al., 2021). The primary foraging depth range for the southern sea otter is between 2 and 35 m (Tinker et al., 2006), depths found only closer to shore in the Study Area. Surveys conducted in 2019 along the central California mainland extended from shore to the 60 m depth contour (Hatfield et al., 2019) and surveys off SNI from 2017 through 2020 extended out to the 30 m depth contour (Yee et al., 2020). Kelp canopy has also been shown to be a strong indicator of sea otter occurrence in California waters (Lafferty & Tinker, 2014; Yee et al., 2020).

Sea otters are occasionally be present in deeper waters when moving between areas or in attempts to establish new habitat (Burn & Doroff, 2005). Although uncommon, sea otters have been known to transit between SNI and the mainland coast, likely in search of new habitat (Hatfield, 2005).

The sea otter population off SNI is subject to different habitat conditions and stressors than those inhabiting the central California coastline (Tinker et al., 2007). Navy management and restricted access to the area has had a beneficial effect on the otters. The abundance of sea otter prey at San Nicolas exceeds that at the central California coastline by as much as three orders of magnitude (Tinker et al., 2007). As a result of greater prey availability, sea otters on SNI have double the average food intake rate, spend only half as much time foraging, and have better body conditions than sea otter occurring along the central California coastline (Tinker et al., 2007).

Detailed information on the distribution of this species in the Study Area is provided in the U.S. Navy Marine Species Density Database Phase IV for the Hawaii-California Training and Testing Study Area technical report (U.S. Department of the Navy, 2024).

C.6.2.11.3 Population Trends

U.S. Fish and Wildlife Service (2021b) reported an abundance of 99 sea otters in waters around SNI. From 2020 to 2023, Yee et al. (2023) measured a 10 percent annual increase in the population on SNI and estimated an abundance around the island of 146 otters, as of April 2023.

C.6.2.11.4 Population Threats

Sea otters are preyed upon by sharks, particularly white shark, which are likely the greatest threat to population growth off California (Carretta et al., 2022; Tinker et al., 2017; U.S. Fish and Wildlife Service, 2021b). Miller et al. (2020c) found that in Southern sea otters that were subjected to necropsy between 1998 and 2012 (n=560), the most prominent cause of death was infectious disease. The toxoplasmosis parasite (often attributed to feral cat feces in urban area storm run-off) impacts sea otters along the U.S. West Coast (Simeone et al., 2015), and the emergence of a nematode parasite in southern sea otters-associated with hepatitis has also been reported (Miller et al., 2020b). Heart disease associated with the inadvertent consumption domoic acid that accumulates in prey (specifically crabs and clams) has been revealed as a potential threat to population growth, because the risk was shown to be more pronounced in younger adults in their prime compared with older otters. Having a greater effect on adults in their prime reproductive years has long-term consequences for the recovery of the species, particularly with warmer ocean temperatures giving rise to more frequent and longer-lasting harmful algal blooms, which are linked to elevated concentrations of domoic acid in the marine environment (Moriarty et al., 2021; Wells et al., 2015).

C.6.3 Species Not Listed under the Endangered Species Act

C.6.3.1 Bryde's Whale (Balaenoptera edeni)

C.6.3.1.1 Status and Management

Bryde's whale is protected under the MMPA and is not listed under the ESA. NMFS recognizes two stocks of Bryde's whales in the U.S. Pacific, the Eastern Tropical Pacific stock (whales found east of 150° W, including the Gulf of California and waters off California) and the Hawaii stock (Carretta et al., 2023b). Bryde's whales in Hawaii or Southern California are considered to belong to their respective separate stocks, with the transition at 150° W longitude as defined by NMFS.

C.6.3.1.2 Habitat and Geographic Range

Bryde's whales occur primarily in offshore oceanic waters of the north Pacific (Barlow, 2006; Bradford et al., 2017), with a consistent lower density region near the Main Hawaiian Islands (Becker et al., 2021). They typically do not move poleward of 40° in either hemisphere and tend to occur primarily in tropical

and subtropical zones, where water temperatures are relatively warm (Jefferson et al., 2015). Data suggest that winter and summer grounds partially overlap in the central north Pacific (Murase et al., 2015; Ohizumi, 2002; Ohizumi et al., 2002). Long migrations are not typical of Bryde's whales, although limited shifts in distribution toward and away from the equator, in winter and summer, have been observed (Best, 1996; Cummings, 1985).

A total of 48 Bryde's whale sightings were made during three systematic shipboard surveys of the Hawaiian Islands EEZ in 2002, 2010, and 2017, although the number of sightings varied substantially between years, with a low of 2 sightings in 2017 and a high of 32 sightings in 2010 (Bradford et al., 2021). Based on predictive habitat-based density models derived from these line-transect survey data, there was also great annual variability in the distribution patterns of Bryde's whales within the Hawaiian Islands EEZ (Becker et al., 2021). The substantial annual variability in both sighting numbers and distribution patterns likely reflects a fluctuating distribution of the whales relative to habitat or prey within a broader geographic region of the central North Pacific (Becker et al., 2022b). Based on linetransect survey data collected between 1997 and 2012 in the central North Pacific, relatively high densities of Bryde's whales are predicted within the U.S. EEZ of the Hawaiian Islands during the summer and fall (Forney et al., 2015). Given that the majority of survey data have been collected during summer and fall, less is known about the abundance and distribution of Bryde's whales within waters of the Hawaiian Islands EEZ in winter and spring. A sighting of a single Bryde's whale was made during a systematic survey of waters within the Main Hawaiian Islands in February of 2009 (Oleson et al., 2009), suggesting that this species is present during the winter months. Acoustic monitoring data collected using the Navy's instrumented training range hydrophones off the north coast of Kauai from August through October of 2014 also suggest that this species may be present year-round in Hawaii (Martin et al., 2017).

Bryde's whales were previously only occasionally sighted in the waters off SOCAL (Carretta et al., 2010; Smultea, 2012; Smultea et al., 2011), but sightings and acoustic monitoring indicates that the presence of the species is no longer considered anomalous (Carretta et al., 2017b; Debich et al., 2015b; Kerosky et al., 2012; Smultea et al., 2012; Smultea & Jefferson, 2014; Smultea et al., 2010). During aerial surveys conducted year-round between 2008 and 2013 off the Southern California coast, Bryde's whales were sighted on two occasions (Jefferson et al., 2014). These were the first sightings in this area since 1991 when a Bryde's whale was sighted within 300 NM of the California coast (Barlow, 1995). There was also an off-effort Bryde's whale sighting in waters off California during a 2014 systematic ship survey (Barlow, 2016). The peak in recorded Bryde's whale vocalizations has varied but generally occurs between late July and November in the southern portion of the California Study Area (Debich et al., 2015a; Debich et al., 2015b; Kerosky et al., 2012).

C.6.3.1.3 Population Trends

Little is known of population status and trends for most Bryde's whale populations, and there are no trend data for Bryde's whale abundance in the eastern tropical Pacific (Carretta et al., 2023b). Based on acoustic data there appeared to be in increase in the number of Bryde's whales within the Southern California Bight between 2000 and 2010 (Kerosky et al., 2012); however, during four systematic ship surveys of these waters in 2005, 2008, 2014, and 2018, there was only one verified off-effort Bryde's whale sighting in 2014 (Barlow, 2016).

C.6.3.1.4 Population Threats

Bryde's whales are susceptible to interactions with fisheries, entanglement in fishing gear, and vessel strikes. Off the U.S. West Coast, the California gillnet fishery is the only fishery likely to interact with this species in the region. However, monitoring data from 2001 through 2013 indicate that there have been no entanglements of Bryde's whales during this time period (Carretta et al., 2023b).

In Hawaii, Bryde's whales are most likely threatened by the deep-set longline fishery and the shallow-set longline fishery. The most recent monitoring data from 2017 through 2021 indicate that there were no Bryde's whales observed hooked or entangled in these fisheries (Bradford, 2018a; Bradford, 2018b; Bradford et al., 2017; Carretta et al., 2023b; McCracken, 2019). Although there have been zero recorded entanglements, there is the potential for injury and mortality of Bryde's whales from fisheries interactions to go unobserved (Carretta et al., 2023b). Additionally, there was one documented vessel strike of an individual belonging to the Eastern Tropical Pacific Stock near Washington in 2010 (Carretta et al., 2023b).

Climate change has increasingly become a threat to marine mammals, including baleen whales. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.2 Humpback Whale (*Megaptera novaeangliae:* Hawaii Distinct Population Segment)

C.6.3.2.1 Status and Management

NMFS has identified 14 DPSs of humpback whales worldwide, with 4 DPSs occurring in the North Pacific (Carretta et al., 2023b). Humpback whales that occur seasonally in the HCTT Study Area are from three of the four DPSs identified by low-latitude wintering habitats: Hawaii DPS, Mexico DPS, and Central America DPS (Bettridge et al., 2015a; Carretta et al., 2023b; National Marine Fisheries Service, 2016q; Young, 2023). The three previously defined stocks of North Pacific humpback whales did not align with the DPS structure, so NMFS reevaluated the stock structure to incorporate both the locations of foraging and overwintering areas and population demographics. As a result, NMFS defined five stocks in the North Pacific:

- Central America/Southern Mexico-California-Oregon-Washington stock
- Mainland Mexico-California-Oregon-Washington stock
- Mexico-North Pacific stock
- Hawaii stock
- Western North Pacific stock

Humpback whales from the first four stocks listed above occur seasonally in the HCTT Study Area; humpbacks from the Western North Pacific stock do not occur in the Study Area. Humpback whales wintering in Hawaii are identified as the Hawaii DPS and comprise the Hawaii stock. Humpback whales from the Hawaii DPS/stock forage across the North Pacific (Figure C-10). Humpback whales from the Mexico DPS migrate to summer foraging habitat from California northward along the U.S. West Coast, Canada, Alaska, into the Bering Sea, and off the coast of Russia and are divided into the Mexico-North Pacific stock and the Mainland Mexico-California-Oregon-Washington stock. Humpback whales from the Central America DPS forage is waters off California and the Pacific Northwest and make up the Central America/Southern Mexico-California-Oregon-Washington stock (Carretta et al., 2023b). For additional information on the revised stock and DPS structure and population dynamics refer to Martien et al. (2023), Wade (2021), Martien et al. (2021) and Martien et al. (2019).

Humpback whales in the Hawaii DPS are not listed under the ESA, because the population is believed to have fully recovered to its pre-whaling abundance (Barlow et al., 2011; Bettridge et al., 2015a; Muto et al., 2017; National Marine Fisheries Service, 2016j; Wade et al., 2016). Humpback whales from the Mexico DPS are listed as threatened and those from the Central America DPS are listed as endangered under the ESA (National Marine Fisheries Service, 2016j).

C.6.3.2.2 Habitat and Geographic Range

Humpback whales are distributed worldwide in all major oceans and most seas (Bettridge et al., 2015a; National Marine Fisheries Service, 2016j). They typically are found during the summer in high-latitude feeding grounds, including Alaska and British Colombia, and during the winter migrate to breeding areas off Hawaii, Mexico, Central America, and Okinawa where breeding and calving occurs. As a result, humpback migrations are complex and cover great distances (Bettridge et al., 2015a; Calambokidis et al., 2009b; Calambokidis et al., 2008). Whales migrating from Hawaii to summer feeding habitat in the Gulf of Alaska will cover 2,600 NM over several weeks. Mate et al. (1998), used satellite tags to track three migrating whales using independent routes to Alaskan waters, and the fastest averaged 93 NM per day. At that rate, the whale would have reached waters off the coast of Alaska in about 39 days.

Hawaii Study Area

Humpback whales that breed in Hawaii generally migrate to northern British Columbia and southeast Alaska to feed (Bettridge et al., 2015a; Calambokidis et al., 2008). Animals breeding in Hawaii have also been "matched" (i.e., identified as the same individual using photo-identification methods) to humpbacks feeding in the Gulf of Alaska, the Aleutian Islands, and Bering Sea (Calambokidis et al., 2008). In all these feeding areas, humpback whales from Hawaii must cross paths with humpback whales migrating from Mexico and Central America (Figure C-10). In addition, based on the identification of individual whales, there is evidence that some humpback whales (most likely males) move between winter breeding areas in Hawaii and Mexico (Forestall and Urban-Ramirez 2007) and Hawaii and Japan (Salden et al. 1999).

In the Hawaii portion of their range, peak densities are from February through March, although the breeding season typically spans December through April (Baird et al., 2015d; Mobley et al., 1999; Mobley et al., 2001b; Norris et al., 1999). New survey data collected in offshore waters of the Main Hawaiian Islands in 2020 supported the development of the first habitat-based density model for humpback whale for the Hawaiian Islands EEZ (Becker et al., 2022b). This model provided further evidence that peak numbers of humpback whales occur within these waters from approximately 19 February through 22 March. Acoustic recordings near the northwestern Hawaiian Islands indicate that humpback whales were present in that portion of the HCTT Study Area from early December through early June (Lammers et al. 2011). It is not yet known if this represents a previously undocumented breeding stock or if the whales occurring at the northwestern Hawaiian Islands are part of the same population that winters near the Main Hawaiian Islands (Bettridge et al., 2015a). Acoustic recordings over multiple years (including 2016) using the PMRF hydrophones have demonstrated a seasonal presence of humpback whales off Kauai from November to May (Martin et al., 2016; Martin et al., 2017). The majority of humpback whales in Hawaii during the breeding season have been detected within the 200 m isobath (Mobley, 2005; Mobley et al., 2015; Mobley & Pacini, 2013; Mobley et al., 2001b). This presence may include very nearshore and inland water areas (Richie et al., 2016).

From December 2013 to January 2014, a passive acoustic recording device onboard an unmanned glider moving in the deep ocean approximately 100–300 km south of Oahu recorded humpback whale songs during all recording periods (Klinck et al., 2015). While the acoustic data do not provide an indication for how far away the animals are from the recorder, they would have definitely been offshore as opposed to nearshore shallow water areas previously documented as their preferred habitat. Mate et al. (2019), reported on the movements of 24 humpback whales tagged off Maui. While in Hawaiian waters the whales mainly remained in the Maui Nui region and Penguin Banks with a few whales venturing to Middle Bank in the Papahānaumokuākea Marine National Monument. Twelve tags were still transmitting when the whales began their northward migration to foraging habitat, and three of those whales were tracked to waters off British Columbia, Canada. The trajectories of other tracks indicated that several whales were headed towards the Gulf of Alaska and the Aleutian Islands.

There have been six locations identified in the main Hawaiian Islands as a single reproductive area for humpback whales (Baird et al. 2015). The greatest densities of humpback whales (including calves) have been in the four-island region consisting of Maui, Molokai, Kahoolawe, and Lanai, as well as Penguin Bank (Mobley et al., 2001b) and around Kauai (Mobley, 2005). A March 2007 pilot survey across the Northwestern Hawaiian Islands documented the existence of extensive wintering habitat used by humpback whales in the Northwestern Hawaiian Islands (Johnston et al., 2007). Two humpback whale reproductive BIAs (a parent and a child BIA) have been delineated in the main Hawaiian Islands during the overwintering breeding season (Kratofil et al., 2023)(Figure C-19). The BIAs were updated from the original BIAs (Baird et al., 2015d) based on satellite tag data collected from 1995 to 2019. The parent BIA encompasses 23,042 km² and the child BIA encompasses 6,679 km², including what are likely the most important reproductive areas for humpback whales in the Main Hawaiian Islands (Kratofil et al., 2023). The BIAs are in effect from December through May.



Figure C-19: Humpback Whale Reproductive BIAs in the Hawaii Study Area

Humpback whales migrating from breeding grounds in Hawaii to feeding grounds at higher latitudes may cross eastern portions of the HCTT Study Area Transit Corridor. Whales tagged off Maui, Kauai, and the island of Hawaii in 2018 spent a limited amount of time in the Hawaii Range Complex, with just 15 percent of tagged whales occurring within W-188A and 14 percent in W-188B (Mate et al., 2018). A higher proportion of whales tagged off Kauai entered Navy training areas; however, this may be a function of tagging location bias given Kauai's closer proximity to Navy training areas. No whales tagged off the island of Hawaii entered Navy training areas.

C.6.3.2.3 Population Trends

Until recently, there was evidence that the population of humpback whales in the Hawaiian Islands had been increasing since the early 1980s and had reached numbers greater than some pre-whaling abundance estimates (Barlow et al., 2011; Wade et al., 2016). Various abundance estimates for humpback whales in Hawaii also provided evidence of an increasing trend, with the annual estimated rate of increase varying from approximately 5 percent to 10 percent per year (Young, 2023). More recently however, declines in the numbers of humpback whales in the feeding areas in Alaska have raised some uncertainty regarding the current trend of the Hawaii stock (Young, 2023).

C.6.3.2.4 Population Threats

Humpback whales are susceptible to entanglement in fishing gear and ship strikes. Pot and trap fishery entanglements are the most-common source of injury to humpback whales along the U.S. west coast (Carretta et al., 2022). Between 2015 through 2019, there have been 81 observations of humpback whale interactions with pot and trap fisheries (Carretta et al., 2022). Of these interactions, serious injuries and mortalities were calculated as 51.75 humpback whales during this time period (Carretta et al., 2022). From 2015 to 2019, there was 79 humpback whale interactions with gillnet and unidentified fisheries (Carretta et al., 2022). Gillnet related serious injuries and mortalities totaled to 54.75 for this time period (Carretta et al., 2022).

Available data from NMFS indicate that there have been 14 reports of humpback whales struck by ships from 2016 through 2020, totaling to 2.6 humpback whale serious injuries or mortalities per year (Carretta et al., 2022).

Humpback whales are also potentially affected by underwater noise, jet skis and similar fast waterborne tourist-related traffic, and pollutants (Muto et al., 2017).

C.6.3.3 Common Minke Whale (Balaenoptera acutorostrata)

C.6.3.3.1 Status and Management

The common minke whale is protected under the MMPA and is not listed under the ESA. NMFS has designated three stocks of minke whale in the U.S. North Pacific: (1) the Hawaii stock, (2) the California/Oregon/Washington stock, and (3) the Alaska stock (Carretta et al., 2023b). Minke whales in Hawaii or California are considered to belong to their respective separate stocks.

C.6.3.3.2 Habitat and Geographic Range

The common minke whale's range is known to include the open ocean, coastal waters, and extends from subarctic to arctic waters (Jefferson et al., 2015; Kuker et al., 2005). The migration paths of some populations of minke whales include travel between low-latitude breeding grounds in the winter to high-latitude feeding grounds in the summer (Jefferson et al., 2015), although in some areas there appears to be resident populations (Dorsey et al., 1990).

Common minke whales previously were considered a rare species in Hawaiian waters due to limited sightings and detections (Barlow, 2006; Carretta et al., 2017b; Klinck et al., 2015; Lammers et al., 2015). However, during a 2002 survey around the Hawaiian Islands, minke whales were confirmed as the source of the mysterious "boing" sound of the north Pacific Ocean, specifically offshore of Kauai and closer in, near the PMRF, Barking Sands region (Barlow et al., 2004; Rankin & Barlow, 2005). This information subsequently allowed for acoustic detections of minke whales, although they remain rarely observed during visual surveys and its now widely accepted that their cryptic surfacing behavior is the reason for the low sighting rates (Barlow, 2006; Bradford et al., 2013; Bradford et al., 2017; Lammers et al., 2015; Rankin et al., 2007). In the summer, minke whales are likely absent from low-productivity tropical waters (Jefferson et al., 2015; Perrin et al., 2009a), and based on acoustic data, it is likely that in summer they have migrated north out of Hawaiian waters to feed (Martin et al., 2022). During three separate line-transect surveys of the Hawaii EEZ during summer and fall, minke whales were only seen and/or acoustically detected during the fall months (Barlow, 2006; Bradford et al., 2017; Bradford et al., 2021). Research involving passive acoustic detection now suggests minke whales are somewhat common in Hawaii in the winter(Klinck et al., 2015; Rankin & Barlow, 2005; Rankin et al., 2007; U.S. Department of the Navy, 2011). Acoustic recordings over multiple years using the PMRF hydrophones have demonstrated a seasonal presence of minke whales off Kauai from November to May (Martin et al., 2017).

Common minke whales occur year-round off California (Forney & Barlow, 1998b; Forney et al., 1995), mainly in nearshore areas (Barlow & Forney, 2007; Becker et al., 2020; Hamilton et al., 2009; Smultea & Jefferson, 2014), and "resident" minke whales off the U.S. West Coast appear behaviorally distinct from migratory whales that occur further north (Dorsey et al., 1990{Carretta, 2023 #14843)}. During year-round aerial surveys conducted in the SOCAL Range Complex from 2008 through 2013, minke whales were sighted 19 times (Jefferson et al., 2014). Sighting data collected during 9 systematic ship surveys between 1991 and 2018 off the U.S. West Coast provided sufficient sample sizes to develop the first habitat-based density model for minke whale in this study area (Becker et al., 2020). Consistent with previous observations, the model predicted greatest numbers of minke whales in nearshore areas over the continental shelf, with relatively low variability in annual distribution patterns.

C.6.3.3.3 Population Trends

There are no data on population trends for common minke whales in the Hawaiian stock (Carretta et al., 2023b). Based on abundance estimates from design- and model-based estimates derived from line-transect ship survey data collected between 1991 and 2018 off the U.S. West Coast (Barlow, 2016; Becker et al., 2020), there are no apparent trends in the population size of the California/Oregon/Washington stock of common minke whales.

C.6.3.3.4 Population Threats

Common minke whales are susceptible to entanglement in fishing gear and vessel strikes. Off California, minke whales interact with coastal set gillnets and offshore set gillnets. From 2017 through 2021, the estimated bycatch of this species in the California swordfish drift gillnet fishery was 0.02 minke whales annually based on modeling using recorded entanglement interactions from 1990 through 2021 (Carretta et al., 2024; Carretta, 2022a). Additionally, there were two recorded interactions of minke whales with other fisheries off California from the same 5-year period. One of the two interactions was with an unidentified fishery, resulting in serious injury, while the other was with the Dungeness crab pot fishery in San Diego and did not result in serious injury (Carretta et al., 2023a). In Hawaii, common minke whales are threatened by the deep-set longline fishery and the shallow-set longline fishery. The most

recent monitoring data from 2014 through 2018 indicate that there have been no observed entanglements or hookings of this species in these fisheries (Bradford, 2018a; Bradford, 2018b; Bradford, 2021; Bradford et al., 2017; Carretta et al., 2023b; McCracken, 2019). There were no reported vessel strikes of minke whales from 2017 through 2021 off the U.S. West Coast; however, strikes of this species are more likely to go undetected (Carretta et al., 2023a).

Most recent data from 2017 through 2021 indicate that there was one recorded mortality of a minke whale from the California/Oregon/Washington stock from a shooting, likely attributed to fisheries interactions (Carretta et al., 2023a).

Climate change, along with other anthropogenic threats, has increasingly become a threat to marine mammals, including baleen whales. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.4 Gray Whale (Eschrichtius robustus; Eastern North Pacific Stock)

C.6.3.4.1 Status and Management

NMFS recognizes two stocks of gray whales in the North Pacific: the Eastern North Pacific stock and the Western North Pacific stock (Weller et al., 2013). Both stocks could be present in the California portion of the Study Area during their northward and southward migrations (Mate et al., 2015b; Sumich & Show, 2011). The Western subpopulation has previously been known as the Korean-Okhotsk population (Carretta et al., 2023b). This stock is critically endangered, shows no apparent signs of recovery, and should be very rare in the California Study Area given their low abundance.

The Eastern North Pacific stock (also known as the California-Chukchi population) has recovered from whaling exploitation and was removed from listing under the ESA in 1994 (Swartz et al., 2006). An UME for the eastern North Pacific stock declared by NMFS in 2019 was closed in March 2024, but it lasted from December 17, 2018, to – November 9, 2023, and resulted in hundreds of gray whale deaths in the eastern North Pacific leading to a 40 percent decline in the population (National Marine Fisheries Service, 2024d). The two stocks are genetically distinguished but the population may be changing due to evolving migratory patterns of both stocks (Carretta et al., 2023b).

C.6.3.4.2 Habitat and Geographic Range

Gray whales are not expected to occur regularly in the Hawaii Study Area or in the transit corridor. There were two sightings of what appeared to be a juvenile gray whale off the island of Hawaii in February 2022, but this is the first recorded sighting of this species in the central Tropical Pacific and it is considered very unusual (Baird et al., 2022).

The vast majority of gray whales occurring off the West Coast and in the California Study Area are from the larger Eastern North Pacific stock (Carretta et al., 2023b). Whales from the eastern subpopulation are found in the Chukchi, Beaufort, and Bering seas in summer and fall foraging seasons; however, a small number feed along the coast between Kodiak Island, Alaska and northern California during that time (Calambokidis et al., 2017; Gosho et al., 2011). This group of whales was designated as the Pacific Coast Feeding Group by the International Whaling Commission and for purposes of abundance estimation was defined as gray whales feeding between northern California and northern British Columbia, Canada from June through November (Carretta et al., 2023b).

Gray whales are known to make one of the longest annual migrations of any mammal, 15,000–20,000 km roundtrip (Jefferson et al., 2015; Jones & Swartz, 2009). Eastern North Pacific gray whales begin their migration from breeding areas off Mexico and along the coast of North America in late fall through early spring to reach foraging areas by summer (Carretta et al., 2023b; Urbán et al., 2021; Weller et al., 2012a) and would only be present in the California Study Area while during northbound and southbound migrations. A year-long (2013–2014) survey effort in the nearshore waters off San Diego encountered gray whales in January, February, and in the April-June timeframe (Graham & Saunders, 2015). For purposes of this analysis, the Action Proponents assumed that a very small percentage of gray whales migrating off California could be individuals from the endangered Western North Pacific stock and that the majority would be from the unlisted Eastern North Pacific stock.

The timing of the October-July gray whale migrations that pass through the California Study Area can be loosely categorized into three phases (Calambokidis et al., 2015b; Jones & Swartz, 2009; Mate et al., 2013; Mate et al., 2015b; Mate & Urban-Ramirez, 2003; Rugh et al., 2008; Rugh et al., 2005; Urbán et al., 2021). Calambokidis et al. (2015b) noted these migration phases are not distinct; the timing for a phase may vary based on environmental variables, and that a migration phase typically begins with a rapid increase in migrating whales, followed by moderate numbers over a period of weeks, and then slowly tapering off. A southward migration from summer feeding areas includes all age classes as they migrate primarily to the nearshore waters and lagoons of Baja California, Mexico. During this southward migration from October through March, the whales generally are within 10 km of the coast (Calambokidis et al., 2015b) although there are documented exceptions where migrating gray whales have bypassed the coast by crossing sections of the open ocean (Mate et al., 2015b; Mate & Urban-Ramirez, 2003). In the California Study Area, migrating gray whales may deviate farther from the mainland as some are routinely seen near the Channel Islands and to the west of SCI (Sumich & Show, 2011).

(Calambokidis et al., 2015c) delineated four migratory BIAs off the U.S. West Coast for the Eastern North Pacific stock of gray whales. The four areas were defined by season as well as age and sex classes to capture the variation in migratory behavior of the species. Calambokidis et al. (2024) modified the BIA delineations by incorporating new data and historical sightings, focusing on regional differences in migratory behavior, considering that the Phase B northbound migration used by mother-calf pairs should also be treated as a reproductive BIA, and applying the new parent-child hierarchy. Four migratory BIAs were created (Figure C-20):

- West Coast to Gulf of Alaska (parent) June November
- Southbound (child) November February
- Northbound Phase A (child) January May
- Northbound Phase B (child) March May

The parent migratory BIA was revised from the original southbound BIA defined by Calambokidis et al. (2015c) and extended north to connect with the Gulf of Alaska migratory BIA (Wild et al., 2023). The revised BIA is also referred to as the transboundary migratory BIA. The southbound (child) BIA is for all age and sex classes and extends 10 km from shore off California (and broadens to 15 km off Oregon and 30 km off Washington). The Northbound Phase A (child) BIA, primarily for adults and juveniles, extends 8 km from shore off California, and broadens to 15 km off Oregon and 20 km off Washington. The Northbound Phase B (child) BIA is primarily for mother-calf pairs and extends 5 km from shore north of the Southern California Bight and fall entirely within the Northbound Phase A (child) BIA.

Calambokidis et al. (2024) noted that two satellite-tagged Western North Pacific gray whales were documented using migratory corridors off the U.S. West Coast; however, the data used to delineate the BIAs were almost entirely from gray whales in the Eastern North Pacific stock.

In addition to the migratory BIAs, a reproductive BIA was delineated to coincide with the Northbound Phase B (child) migratory BIA for mother-calf pairs (Figure C-20) and a feeding BIA (Figure C-21), which is located north of the Study Area, off the coast of the Pacific Northwest.



Figure C-20: Gray Whale Migratory BIAs in the California Study Area

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Figure C-21: Gray Whale Reproductive BIA in the California Study Area

Based on the identified migratory seasons, gray whales should occur off the California coast for most of the year with the exception of the July – October timeframe (Calambokidis et al., 2024; Calambokidis et al., 2015b).

C.6.3.4.3 Population Trends

The Eastern North Pacific stock of gray whales is estimated to be 26,960 with 243 whales in the Pacific Coast Feeding Group (Carretta et al., 2023b). Despite the UME from 2019 – 2024, the eastern population is expected to recover based on historical responses to similar events (e.g., 1999 – 2000 event). The Western North Pacific subpopulation of gray whale was once considered extinct but now small numbers are known to exist (Carretta et al., 2017b; Cooke et al., 2015; International Union for Conservation of Nature, 2011; International Whaling Commission, 2014; Mate et al., 2015b; Weller et al., 2013). There are no current population trend data available at this time (Carretta et al., 2017b), however, previous data on population growth indicated a positive growth of roughly 2.5 to 3.2 percent per year (National Marine Fisheries Service, 2014f).

C.6.3.4.4 Population Threats

Gray whales have historically been harvested by subsistence hunters in Alaska and Russia. The International Whaling Commission sets catch limits on the annual subsistence harvest for these areas. For example, the Chukotka indigenous hunters (located on the Chukchi Peninsula) took a total of 127 gray whales in 2013 (Ilyashenko & Zharikov, 2014). In 2010, a gray whale discovered dead onshore in Humboldt, California had two embedded harpoons in its flesh; one of these harpoons had 10 m of rope attached (Carretta et al., 2016a).

Gray whales are also susceptible to entanglement in fishing gear and ship strikes, particularly incidental catches in coastal fisheries (Carretta et al., 2021b). Based on photographic data of western gray whales on their feeding ground off Sakhalin Island (Russia), approximately 19 percent of whales in the sample had detectable anthropogenic scarring resulting from fishing gear entanglement (Bradford et al., 2009).

Natural population threats to gray whales include disease, parasites, reduced prey availability, and predator attacks. The gray whale is preyed on particularly by killer whales. Many individuals exhibit attack scars indicating not all attacks are fatal, however fatalities are known. Killer whale predation of gray whales has been documented in California waters off Monterey (PHYSORG, 2017) as well as the targeting of calves during the spring migration into colder northern waters (Jones & Swartz, 2009).

C.6.3.5 Dwarf Sperm Whale (Kogia sima)

There are two species of *Kogia*: the pygmy sperm whale (discussed in Section C.6.3.6) and the dwarf sperm whale, which had previously been considered to be the same species. Dwarf and pygmy sperm whales are difficult to distinguish from one another at sea, and many misidentifications have been made. Sightings of either species are often categorized as the genus *Kogia* (Jefferson et al., 2015).

C.6.3.5.1 Status and Management

The dwarf sperm whale is protected under the MMPA and is not listed under the ESA. Dwarf sperm whales within the Pacific U.S. EEZ are divided into two separate stocks: (1) the Hawaiian stock and (2) the California, Oregon, and Washington stock (Carretta et al., 2023b).

C.6.3.5.2 Habitat and Geographic Range

Dwarf sperm whales tend to occur largely in offshore waters (Jefferson et al., 2015), although they may be relatively coastal in some areas with deep waters nearshore (MacLeod et al., 2004). Although the

dwarf sperm whale appears to prefer more tropical waters than the pygmy sperm whale, the exact habitat preferences of the species are not well understood.

There were a total of six pygmy sperm whale sightings during systematic ship surveys within the Hawaiian Islands EEZ in 2002, 2010, and 2017, and none of the sightings were in waters within 140 km of the Main Hawaiian Islands (Bradford et al., 2021). During small boat surveys between 2002 and 2012 in the main Hawaiian Islands, this species was the fifth most frequently encountered species of odontocete in waters shallower than 1,000 m with a strong peak in the sighting rate where depths are between 500 and 1,000 m (Baird et al., 2013b; Oleson et al., 2013). Dwarf sperm whales have been seen near Niihau, Kauai, Oahu, Lanai, and Hawaii. Photo-identification of individuals off Hawaii Island since 2003 has provided evidence of long-term site fidelity, with a third of identified individuals being seen in more than one year, and therefore suggesting the existence of an island-resident population (Baird et al., 2013).

Along the U.S. Pacific coast, no reported sightings of this species have been confirmed as dwarf sperm whales and it is likely that most *Kogia* species off California are pygmy sperm whale (*Kogia breviceps*) (Carretta et al., 2023b). There were no *Kogia* detected during 15 aerial surveys conducted in the SOCAL Range Complex from 2008 through 2012 (Smultea et al., 2014). This may be somewhat due to their pelagic distribution, cryptic behavior (i.e., "hidden" because they are not very active at the surface and do not have a conspicuous blow), and physical similarity to the pygmy sperm whale (Jefferson et al., 2008; McAlpine, 2009). However, the presence of dwarf sperm whales off the coast of California has been demonstrated by at least five dwarf sperm whale strandings in California between 1967 and 2000 (Carretta et al., 2010).

BIAs were redefined for a year-round Small and Resident Population area for dwarf sperm whales off the west coast of the Island of Hawaii by (Kratofil et al., 2023), and incorporated additional sighting data not available when the original BIA was defined (Baird et al., 2015c). The parent BIA is 1,341 km² in size and encompasses all sighting locations in waters less than 2,000 m (Figure C-22). The child BIA represents an area of intensified use relative to the entire range of this island-associated population and encompasses 457 km².

C.6.3.5.3 Population Trends

In the Hawaiian Islands, there are no data available for assessing a population trend (Carretta et al., 2023b).

There is no information available to estimate the population size of dwarf sperm whales off the U.S. west coast. There are no known sighting records of this species despite many vessel surveys along the west coast, and sightings of unidentified *Kogia* species are likely to be pygmy sperm whales (Carretta et al., 2023b). Due to the lack of data, there is no way of estimating an abundance trend.

C.6.3.5.4 Population Threats

Dwarf sperm whales are threatened by the deep-set longline fishery and the shallow-set longline fishery in Hawaii. The most recent monitoring data from 2014 through 2018 indicate that there has been one probable entanglement of this species in the deep-set longline fishery and none observed in the shallow-set longline fishery (Bradford, 2018a; Bradford, 2018b; Bradford, 2021; Bradford et al., 2017; Carretta et al., 2023b; McCracken, 2019). Off the U.S. West Coast, dwarf sperms whales would be most likely to interact with the California swordfish gillnet fishery; however, there are no observed entanglements of this species from 1990 through 2014 (Carretta et al., 2019a; Carretta, 2023).



Figure C-22: Dwarf Sperm Whale Small and Resident BIAs in the Hawaii Study Area

C.6.3.6 Pygmy Sperm Whale (Kogia breviceps)

There are two species of *Kogia*: the pygmy sperm whale (*Kogia breviceps*) and the dwarf sperm whale (*Kogia sima*; discussed in Section C.6.3.5). Dwarf and pygmy sperm whales are difficult to detect and distinguish from one another at sea, and many misidentifications have been made. Sightings of either species are often categorized as the genus *Kogia* (Jefferson et al., 2015).

C.6.3.6.1 Status and Management

The pygmy sperm whale is protected under the MMPA but is not listed under the ESA. Pygmy sperm whales are divided into two discrete stocks: (1) the Hawaiian stock and (2) the California, Oregon, and Washington stock (Carretta et al., 2023b).

C.6.3.6.2 Habitat and Geographic Range

Pygmy sperm whales occur in tropical to temperate waters of all oceans, generally in deep oceanic waters beyond the continental shelf (Jefferson et al., 2015). The pygmy sperm whale frequents more temperate habitats than the dwarf sperm whale, which is more of a tropical species. Movement patterns for the pygmy sperm whale are poorly understood, and available data are insufficient to identify any seasonal patterns in the distribution of pygmy sperm whales in the HCTT Study Area.

Sightings of pygmy sperm whales are rarely reported in Hawaii (Baird et al., 2013c; Oleson et al., 2013). There were a total of five pygmy sperm whale sightings during systematic ship surveys within the Hawaiian Islands EEZ in 2002, 2010, and 2017, and none of the sightings were in waters of the Main Hawaiian Islands (Bradford et al., 2021). During small boat surveys between 2000 and 2012 in the Main Hawaiian Islands, this species was observed, but less commonly than the dwarf sperm whale (Baird, 2005; Baird et al., 2003b; Baird et al., 2013c; Barlow et al., 2004; Oleson et al., 2013). Pygmy sperm whales are one of the more commonly stranded species in the Hawaiian Islands, and this frequency of strandings indicates that the species is likely more common than sightings suggest (Maldini et al., 2005).

The majority of field sightings of *Kogia* off the U.S. west coast are likely to have been pygmy sperm whales, but the limited number of confirmed sightings cannot be used to produce a reliable population estimate (Carretta et al., 2023b). *Kogia* species are thus treated as a genus in this region by scientists who have published species density estimates for this study area. Several studies have suggested that this species generally occurs beyond the continental shelf edge (Bloodworth & Odell, 2008; MacLeod et al., 2004) and all confirmed pygmy sperm whale sightings off the U.S. west coast have been well offshore (Barlow, 2016; Hamilton et al., 2009). For California, a total of six pygmy sperm whale sightings have been made in offshore waters along the U.S. west coast during systematic surveys conducted between 1991 and 2014 (Barlow, 2016; Hamilton et al., 2009). There were no *Kogia* detected during 15 aerial surveys conducted in the SOCAL Range Complex from 2008 through 2012 (Smultea & Jefferson, 2014).

C.6.3.6.3 Population Trends

There are no data available for an analysis of population trends for pygmy sperm whales in the Pacific (Carretta et al., 2023b).

C.6.3.6.4 Population Threats

Pygmy sperm whales are susceptible to interactions with fisheries and entanglement in fishing gear. Off California, pygmy sperm whales have been observed entangled in coastal set gillnets and offshore set gillnets in waters. The California swordfish gillnet fishery is the fishery most likely to interact with this

species in the region; however, monitoring data from indicate that there have been no entanglements of pygmy sperm whales in the fishery in the most recent monitoring period (Carretta et al., 2017a; Carretta et al., 2023b). Additionally, there is one recorded pygmy sperm whale death in 2002 due to a shooting that was likely from an interaction with a net fishery (Carretta et al., 2023b).

Off Hawaii, pygmy sperm whales are threatened by the deep-set longline fishery and the shallow-set longline fishery. The most recent monitoring data from 2014 through 2018 indicate that there has been one observed entanglement of this species in the deep-set longline fishery, which resulted in serious injury (Bradford, 2018a; Bradford, 2018b; Bradford, 2021; Bradford et al., 2017; Carretta et al., 2023b; McCracken, 2019).

Anthropogenic noise such as sonar may result in unknown levels of injury or mortality to pygmy sperm whales and other species (Carretta et al., 2023b). In 1988, a mass stranding including 2 pygmy sperm whales occurred near the Canary Islands (Carretta, 2023; D'Amico, 2009). In 2005, there was an UME off the U.S. East Coast that resulted in a mass stranding of 2 dwarf sperm whales, 33 short-finned pilot whales, and a minke whale (Hohn et al., 2006). These strandings may be associated with military sonar use that occurred in theses area during the time of the strandings; however, a definitive association has not been confirmed (Hohn et al., 2006).

Climate change has increasingly become a threat to marine mammals. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.7 Killer Whale (*Orcinus orca;* Hawaii, Eastern North Pacific Offshore stocks, and *Orcinus orca rectipinnus*; Eastern North Pacific/West Coast Transient stocks)

Different geographic forms of killer whale are distinguished by distinct social and foraging behaviors and other ecological traits. In the North Pacific, these recognizable geographic forms are variously known as "residents," "transients," and "offshore" ecotypes (Hoelzel et al., 2007; Morin et al., 2024). Recently, new analyses suggest that species status may be warranted for two of the different eastern North Pacific ecotypes, the Bigg's or transient killer whales and the resident killer whales, including the Eastern North Pacific Southern Resident stock (Morin et al., 2024). However, the proposal before the Society for Marine Mammalogy Committee on Taxonomy failed to receive the 2/3 majority needed to pass, so killer whales will remain as a single species, but Bigg's and resident killer whales will now be recognized as separate subspecies. *Orcinus orca rectipinnus* and *Orcinus orca ater*, respectively. In the HCTT Study Area, both the transient and offshore ecotypes are known to occur, and Southern Resident killer whales may seasonally occur along the northern portion of the California Study Area north of Monterey Bay (Hanson et al., 2018);National Marine Fisheries Service, 2021 #15025;Millman, 2019 #3115}.

C.6.3.7.1 Status and Management

Eight killer whale stocks are recognized within the North Pacific U.S. EEZ, with only the Hawaiian stock occurring in Hawaii and three stocks occurring in the California Study Area consisting of the West Coast Transient stock, the Eastern North Pacific Offshore stock, and the Eastern North Pacific Southern Resident stock (Carretta et al., 2023b). Three separate pods comprise the Southern Resident stock, identified as the J, K, and L pods (Ford et al., 2000). Killer whales are protected under the MMPA and the Southern Resident killer whale stock or DPS is listed as endangered under the ESA. The other two stocks are not listed under the ESA.

C.6.3.7.2 Habitat and Geographic Range

Killer whales are found in all marine habitats from the coastal zone (including most bays and inshore channels) to deep oceanic basins and from equatorial regions to the polar pack ice zones of both hemispheres. Although killer whales are also found in tropical waters and the open ocean, they are most numerous in coastal waters and at higher latitudes (Dahlheim & Heyning, 1999). Forney and Wade (2006) found that killer whale densities increased by 1–2 orders of magnitude from the tropics to the poles.

Although killer whales apparently prefer cooler waters, they have been observed in Hawaiian waters (Baird et al., 2013c; Barlow, 2006; Mobley et al., 2001a; Shallenberger, 1981). There are also documented strandings for this species from the Hawaiian Islands (Maldini et al., 2005). Sightings are extremely infrequent in Hawaiian waters, and typically occur during winter, suggesting those sighted in Hawaii are seasonal migrants to Hawaii (Baird et al., 2003a; Baird et al., 2013c; Mobley et al., 2001a). During three separate systematic ship surveys of the Hawaiian EEZ in summer and fall, there were two killer whale sightings in 2002 a single sighting in 2010, and a single sighting in 2017, with the average group size ranging from 4.7 to 7.4 animals (Barlow, 2006; Bradford et al., 2017; Bradford et al., 2021). Baird (2006) documented 21 killer whale sightings within the Hawaiian EEZ, primarily around the main Hawaiian Islands during relatively nearshore small boat surveys. In the period from 2000 to 2012, there were two sightings with each pod consisting of four killer whales (Baird et al., 2013b). A single adult female was also sighted off Kauai in July 2011 (Cascadia Research Collective, 2012). A pod of killer whales was observed off the southwest coast of the island of Hawaii in May 2013 (Pacific Fishery Management Council, 2014).

All three ecotypes of killer whale are known to occur along the west coast of North America, from the entire Alaskan coast, in British Columbia and Washington inland waterways, and along the outer coasts of Washington, Oregon, and California, but the endangered resident ecotype's range typically does not extend south of Monterey California (Calambokidis & Barlow, 2004; Carretta et al., 2017b; Dahlheim et al., 2008; Ford & Ellis, 1999; Forney et al., 1995; Hanson et al., 2018). In the southern portion of the California Study Area, only the transient and offshore ecotypes may be present (Carretta et al., 2023b). During seven systematic ship surveys of waters off the U.S. west coast between 1991 and 2014, there were 37 killer whale sightings, only five of which were off southern California (Barlow, 2016). An additional 10 killer whale sightings were made on a more recent survey in 2018, and except for a single sighting off Point Conception (34.4°N), all the sightings were made well north of the HCTT Study Area (Henry et al., 2020). Based on two sightings from 15 aerial surveys conducted in the SOCAL Range Complex from 2008 through 2012, killer whales were ranked 12th in occurrence as compared to other cetaceans (Jefferson et al., 2014; Smultea et al., 2014).

C.6.3.7.3 Population Trends

No data are available on current population trends for the Hawaiian stock of killer whales (Carretta et al., 2023b). The Eastern North Pacific stock is considered to be stable based on an estimated 98 percent survival rate and positive annual recruitment (Ford et al., 2014).

The population of West Coast Transient stock of killer whales grew rapidly from the mid-1970s to the mid-1990s coinciding with an increase in harbor seal abundance, their primary prey. Since 1990s, growth slowed, but continued to increase. However, no reliable estimate of population trend is available for the stock (Young, 2023).

C.6.3.7.4 Population Threats

The Hawaii stock of killer whales is susceptible to interactions with the deep-set longline fishery and the shallow-set longline fishery. However, the most recent monitoring data from 2014 through 2018 indicate that there have been no observed entanglements or hookings of killer whales in these fisheries (Bradford, 2018a; Bradford, 2018b; Bradford et al., 2017; Carretta et al., 2023b; McCracken, 2019). Additionally, there have been no documented anthropogenic-caused injuries or mortalities of the Eastern North Pacific offshore stock of killer whale; however, this stock, like other killer whale stocks, is likely susceptible to interactions with fisheries and vessel strikes (Carretta et al., 2023b).

Exposure to contaminants may also harm killer whales. The presence of high levels of persistent organic pollutants, such as PCB, DDT, and flame-retardants, has been documented in southern resident killer whales (Krahn et al., 2007). Although the consequences of these pollutants on the fitness of individual killer whales and the population itself remain unknown, in other species these pollutants have been reported to suppress immune responses (Wright et al., 2007), impair reproduction, and exacerbate the energetic consequences of physiological stress responses when they interact with other compounds in an animal's tissues (Wright et al., 2007). Because of their long-life span, position at the top of the food chain, and their blubber stores, killer whales would be capable of accumulating high concentrations of contaminants.

Climate change has increasingly become a threat to marine mammals, including killer whales. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.8 False Killer Whale (*Pseudorca crassidens;* the Hawaii pelagic stock and the Northwestern Hawaiian Islands stock)

NMFS currently recognizes three stocks of false killer whale in Hawaiian waters: the Hawaii pelagic stock, the Northwestern Hawaiian Islands stock, and the Main Hawaiian Islands insular stock (Bradford et al., 2015; Carretta et al., 2015; Carretta et al., 2023b; Forney et al., 2010; National Oceanic and Atmospheric Administration, 2012; Oleson et al., 2010a). All stocks of false killer whale are protected under the MMPA. The Hawaii Pelagic stock and the Northwestern Hawaiian Islands stock of false killer whales are not listed as threatened or endangered under the ESA. The Main Hawaiian Islands insular stock is listed as endangered under the ESA as a DPS (National Oceanic and Atmospheric Administration, 2012).

The species is not typically expected to be present in the California Study Area, and false killer whales are not included by NMFS as a managed species in California waters (Carretta et al., 2017b; Carretta et al., 2023b). Strandings and sightings of false killer whales have been recorded in Southern California and north, but these have generally been considered extralimital. During the unusually warm oceanographic conditions in 2014, whale watching boats photographed false killer whales in Southern California waters, but there were none sighted during the SWFSC systematic survey that year (Barlow, 2016). False killer whales do occur in waters off the Baja California Peninsula, Mexico within the HCTT Study Area (Hamilton et al., 2009).

C.6.3.8.1 Habitat and Geographic Range

This species is known to occur in deep oceanic waters off Hawaii, and elsewhere in the Pacific. False killer whales have been detected in acoustic surveys and are commonly observed in the eastern tropical Pacific, including waters off the Baja California Peninsula, Mexico within the Study Area (Carretta et al.,

2015; Carretta et al., 2023b; Miyashita et al., 1996; Oswald et al., 2003; Wade & Gerrodette, 1993; Wang et al., 2001). False killer whale are also regularly found within Hawaiian waters and have been reported in groups of up to 100 over a wide range of depths and distance from shore (Baird et al., 2003b; Baird et al., 2013a; Bradford et al., 2018; Bradford et al., 2014; Bradford et al., 2015; Oleson et al., 2013; Shallenberger, 1981).

The ranges and stock boundary descriptions for false killer whales in the Hawaiian Islands are complex and overlapping. For example, all three stocks are known to overlap in the vicinity of Kauai and Niihau, which is where the Navy's underwater instrumented range has been in use since the 1980s. All significant information regarding the range of the three stocks was presented in Bradford et al. (2015), and later updated for the pelagic stock (Bradford et al., 2020). A summary of the data used to delineate the stock boundaries, and the research supporting those data are provided in the Final 2022 Pacific Stock Assessment Report (Carretta et al., 2023b) that is synthesized in the next few paragraphs for the stocks in the Hawaiian Islands.

The Main Hawaiian Islands insular stock is considered resident to the main Hawaiian Islands consisting of Kauai, Oahu, Molokai, Lanai, Kahoolawe, Maui, and Hawaii, although they have been satellite tracked as far as 115 km from the main Hawaiian Islands (Bradford et al., 2020; Bradford et al., 2012; Bradford et al., 2015; Carretta et al., 2015; Forney et al., 2010; National Oceanic and Atmospheric Administration, 2012; Oleson et al., 2010a). The Main Hawaiian Islands insular stock boundary is a 72 km radius extending around the main Hawaiian Islands, with the offshore extent of the radii connected on the leeward sides of Hawaii Island and Niihau to encompass the offshore movements of Main Hawaiian Islands insular stock animals within that region.

False killer whales in the Northwestern Hawaiian Islands stock have been seen as far as 93 km from the Northwestern Hawaiian Islands and near shore around Kauai and Oahu (Baird et al., 2012; Bradford et al., 2015). The Northwestern Hawaiian Islands stock boundary is defined by a 93 km radius around Kauai, Niihau, and the Northwestern Hawaiian Islands, with the boundary around the Northwestern Hawaiian Islands at the eastern end to encompass animal movements observed outside the 93 km radius.

Given new telemetry data that indicated that pelagic stock animals occurred within 5.6 km of the main Hawaiian Islands and throughout the Northwestern Hawaiian Islands, the previous inner pelagic stock boundary at 11 km from shore around each of the main Hawaiian Islands was removed (Bradford et al., 2020). The pelagic stock now has no inner or outer boundary within the Hawaiian Islands EEZ. There is now an overlap zone between the entirety of the Main Hawaiian Islands insular stock area and the pelagic stock area. There is also now an overlap zone between the entirety of the Northwestern Hawaiian Islands stock area and the pelagic stock area. All three stock boundaries overlap out to the Main Hawaiian Islands insular stock boundary between Kauai and Niihau and the Northwestern Hawaiian Islands stock boundary between Kauai and Oahu (Carretta et al., 2023b).

As noted previously, false killer whales are not usually expected to be present in the California Study Area. Older records document only a handful of sightings from areas such as Monterey Bay, Santa Catalina, and the Channel Islands (Baird, 2009a; Jefferson et al., 2008; Miller & Scheffer, 1986). False killer whales were not detected during the 15 aerial surveys conducted in the SOCAL Range Complex from 2008 through 2012 (Smultea & Jefferson, 2014). A nearshore marine mammal survey off San Diego Bay in March 2014 detected a false killer whale pod that was assumed to be the same pod that had been seen 6 days before off Dana Point (Graham & Saunders, 2015). Two years later in April–March 2016, a whale watch vessel out of Dana Point again sighted a pod of false killer whales in the same area (Ritchie, 2016). This species normally prefers warmer tropical waters found outside of southern California and the presence of this species to the north of its usual habitat was likely due to the warmer than normal water temperatures associated with a known El Niño event. Such documented strandings and sightings of false killer whales in California waters have thus been considered extralimital. False killer whales do occur in warmer waters off the Baja California Peninsula, Mexico within the HCTT Study Area (Hamilton et al., 2009).

C.6.3.8.2 Population Trends

No data are available for the derivation of population trends for either the Hawaii Pelagic stock or the Northwestern Hawaiian Islands stock of false killer whales in Hawaii (Carretta et al., 2023b).

C.6.3.8.3 Population Threats

Because false killer whales feed on large prey at the top of the food chain (e.g., squid, tunas) they may be impacted by competition with fisheries (Cascadia Research Collective, 2010). In Hawaiian waters, false killer whales are particularly susceptible to fishery interactions and entanglements (Baird et al., 2015f; Bradford & Forney, 2016). Most recent data from 2017 through 2021 indicates that there were no entanglements or hooks of false killer whales in the shallow-set longline fishery; however, there were 54 reported entanglements or hooks of this species in the deep-set longline fishery during the same time period (Carretta et al., 2023b). Of the deep-set longline fishery interactions, 18 were encountered in the outside of the Hawaii EEZ, where 14 were considered seriously injured and 2 were found dead. Of the remaining 36 encounters in the Hawaii EEZ, 23 whales were considered seriously injured and 5 were found dead (Bradford, 2018a; Bradford, 2018b; Bradford, 2021; Bradford et al., 2017; Bradford et al., 2021; Carretta et al., 2023b; McCracken, 2019).

Like many marine mammals, false killer whales also accumulate high levels of toxins in their blubber over the course of their long lives, but the consequence of that bioaccumulation remains unknown.

Climate change has increasingly become a threat to marine mammals. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.9 Pygmy Killer Whale (Feresa attenuata)

C.6.3.9.1 Status and Management

The pygmy killer whale is protected under the MMPA and is not listed under the ESA. For the MMPA stock assessment reports, there is a single Pacific management stock including animals found within the U.S. EEZ of the Hawaiian Islands and the adjacent high seas (Carretta et al., 2023b).

C.6.3.9.2 Habitat and Geographic Range

The pygmy killer whale is generally an open ocean deepwater species (Davis et al., 2000; McSweeney et al., 2009; Oleson et al., 2013; Würsig et al., 2000). Movement patterns for this species are poorly understood. During a NMFS 2014 systematic ship survey off the U.S. west coast, when there were unusually warm water conditions, a group of 27 pygmy killer whales was sighted in offshore waters of southern California (Barlow, 2016). Given that there is a remote likelihood for this species to occur regularly off the U.S. west coast, the 2022 Pacific Stock Assessment report does not include pygmy killer whales as a managed stock in California waters (Carretta et al., 2023b).
This species' range in the open ocean generally extends to the southern regions of the North Pacific Gyre and the southern portions of the North Pacific Transition Zone. Many sightings have occurred from cetacean surveys of the eastern tropical Pacific (Au & Perryman, 1985; Barlow & Gisiner, 2006; Wade & Gerrodette, 1993). This species is also known to be present in the western Pacific (Wang & Yang, 2006). Its range is generally considered to be south of 40° N and continuous across the Pacific (Donahue & Perryman, 2008; Jefferson et al., 2008). There was a total of 11 sightings of pygmy killer whales during three systematic ship surveys of the Hawaiian Islands EEZ in 2002 (3 sightings), 2010 (5 sightings), and 2017 (3 sightings), with average group size ranging from 14.6 to 25.7 animals (Bradford et al., 2021).

A year-round Small and Resident Population area has been identified for pygmy killer whales off the Island of Hawaii (Baird et al., 2015a). The delineated area extends along the coast of Hawaii Island from northwest of Kawaihae to South Point and along the southeast coast of the island, as determined by locations from two satellite-tagged individuals, photo-identification data, extensive vessel-based survey data, and expert judgment (Baird et al., 2015a). Two year-round, non-hierarchical Small and Resident Population BIAs have been delineated in the main Hawaiian Islands for pygmy killer whales (Kratofil et al., 2023) (Figure C-23). The BIAs were updated from the original BIAs (Baird et al., 2015d) based on additional analyses. One BIA encompasses 7,416 km² of waters surrounding Oahu and Maui Nui, and the second BIA encompasses 5,201 km² around the Island of Hawaii (Kratofil et al., 2023).

C.6.3.9.3 Population Trends

Abundance estimates for pygmy killer whales have broad and overlapping confidence intervals, thus precluding a robust assessment of population trends (Carretta et al., 2023b).

C.6.3.9.4 Population Threats

Pygmy killer whales are susceptible to interactions with fisheries, particularly the deep-set longline fishery and the shallow-set longline fishery. However, the most recent monitoring data from 2014 through 2018 indicate that there have been no observed entanglements or hookings of pygmy killer whales in these fisheries (Bradford, 2018a; Bradford, 2018b; Bradford et al., 2017; Carretta et al., 2023b; McCracken, 2019). Off the U.S. West Coast, the California swordfish drift gillnet fishery is the fishery most likely to interact with this species in the region. However, monitoring data from 1999 through 2014 indicate that there have been no entanglements of this species in the fishery during this time period (Bradford & Forney, 2017).

Anthropogenic noise such as sonar may result in unknown levels of injury or mortality to pygmy killer whales (Carretta et al., 2023b; Wang & Yang, 2006). In 2005, two pygmy killer whale strandings occurred near Taiwan, which could possibly be associated with the use of sonar during military training exercises that were occurring in the area (Wang & Yang, 2006).

Climate change has increasingly become a threat to marine mammals. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).



Figure C-23: Pygmy Killer Whale Small and Resident BIA in the Hawaii Study Area

C.6.3.10 Short-finned Pilot Whale (Globicephala macrorhynchus)

C.6.3.10.1 Status and Management

Short-finned pilot whales are protected under the MMPA and are not listed under the ESA. For MMPA stock assessment reports, short-finned pilot whales within the Pacific U.S. EEZ are divided into two discrete stocks: (1) the Hawaiian stock; and (2) the California, Oregon and Washington stock (Carretta et al., 2023b).

C.6.3.10.2 Habitat and Geographic Range

The short-finned pilot whale is widely distributed throughout most tropical and warm temperate waters of the world and occurs in waters over the continental shelf break, in slope waters, and in areas of high topographic relief (Baird et al., 2013b; Olson, 2009). While pilot whales are typically distributed along the continental shelf break, movements over the continental shelf are commonly observed in the northeastern U.S. (Payne & Heinemann, 1993) and close to shore at oceanic islands like Hawaii, where the shelf is narrow and deeper waters are found nearby (Baird, 2013; Gannier, 2000; Mignucci-Giannoni, 1998). Short-finned pilot whales are not considered a migratory species, although seasonal shifts in abundance have been noted in some portions of the species' range. A number of studies in different regions suggest that the distribution and seasonal inshore/offshore movements of pilot whales coincide closely with the abundance of squid, their preferred prey (Bernard & Reilly, 1999; Hui, 1985; Payne & Heinemann, 1993).

Short-finned pilot whales in the Hawaiian Islands were the most commonly encountered species of odontocete during near-shore surveys in depths over 2,000 m and were one of the most common species encountered during the NMFS 2002 (25 sightings), 2010 (36 sightings), and 2017 (35 sightings) systematic ship surveys of the Hawaiian EEZ (Baird et al., 2013b; Barlow, 2006; Bradford et al., 2013; Bradford et al., 2021; Oleson et al., 2013). Small boat surveys from 2003 through 2007 photo-identified 250 individuals seen in more than one year, suggesting site fidelity (Abecassis et al., 2015; Mahaffy et al., 2015; Oleson et al., 2013). Habitat-based models developed from systematic ship survey data collected in the central North Pacific show some of the highest short-finned pilot whale densities around the Hawaiian Islands (Becker et al., 2012b; Forney et al., 2015). Sighting data from systematic ship surveys conducted within waters of the Hawaiian Islands EEZ from 2000 to 2020 supported the development of an updated habitat-based density model for short-finned pilot whale and confirmed the strong island association indicated from the previous models (Becker et al., 2022a).

A year-round Small and Resident Population parent BIA and three child BIAs have been delineated for short-finned pilot whales in waters of the Main Hawaiian Islands (Kratofil et al., 2023) (Figure C-24). The BIAs were updated from the original BIA (Baird et al., 2015d) based on additional analyses. The parent BIA encompasses 58,999 km² of waters surrounding all of the Main Hawaiian Islands. The child BIAs encompass three communities representing core habitat in the Main Hawaiian Islands: a western community (4,040 km²), a central community (2,427 km²), and an eastern community (2,658 km²) that encompass waters mainly on the leeward sides of Kauai, Oahu. Lanai, and the Island of Hawaii (Kratofil et al., 2023) (Figure C-24).



Figure C-24: Short-Finned Pilot Whale Small and Resident BIAs in the Hawaii Study Area

Short-finned pilot whale distribution off Southern California changed dramatically after El Niño in 1982–1983, when squid did not spawn as usual in the area, and pilot whales virtually disappeared from the area for 9 years (Shane, 1995). There have been nine short-finned pilot whale sightings during seven systematic ship surveys conducted by NMFS off California, Oregon, and Washington between 1991 and 2014, with three of these off southern California (Barlow, 2016; Barlow & Forney, 2007). During a NMFS 2018 survey of waters off the U.S. west coast and the Baja California Peninsula, Mexico, there was one short-finned pilot whale sightings during 16 ship surveys conducted in the Southern California Bight between 2004 and 2008 (Douglas et al., 2014b). Short-finned pilot whales were not sighted during 18 aerial surveys conducted in the Southern California Bight between 2008 and 2013 (Jefferson et al., 2014). A group of approximately 50 individuals was encountered off San Diego in May 2015 and included an individual photo identified previously off Ensenada, Mexico (Kendall-Bar et al., 2016).

C.6.3.10.3 Population Trends

For Hawaiian waters, the available data preclude an assessment of population trends for short-finned pilot whales (Carretta et al., 2023b).

Pilot whales appeared to have returned to California waters as evidenced by an increase in sighting records, as well as incidental fishery bycatches (Barlow, 2016; Barlow & Forney, 2007; Douglas et al., 2014a). Because these changes likely reflect a change in distribution based on a changing environment rather than a change in the population, there can be no assessment of the current population trend for short-finned pilot whales in California (Carretta et al., 2023b).

C.6.3.10.4 Population Threats

Short-finned pilot whales are susceptible to entanglement in fishing gear and marine debris. The most recent monitoring data from 2010 through 2014 indicate that the estimate of mortality and serious injury for this species in the California drift gillnet fishery is 6 individuals, or 1.2 whales annually off the U.S. West Coast. Short-finned pilot whales were also historically observed entangled in the Southern California squid purse seine fishery; however, interactions are now less common due to the decline of the presence of this species in the region.

In Hawaii, short-finned pilot whales are threatened by the deep-set longline fishery and the shallow-set longline fishery. The most recent monitoring data from 2017 through 2021 indicate that there have been no observed entanglements or hookings of this species in the shallow-set longline fishery; however, there was one recorded entanglement of a short-finned pilot whale in the deep-set longline fishery, which resulted in serious injury (Bradford, 2018a; Bradford, 2018b; Bradford, 2021; Bradford et al., 2017; Bradford et al., 2021; Carretta et al., 2023b; McCracken, 2019). Additionally, several stranded short-finned pilot whales have been found off Hawaii with large amounts of marine debris from fisheries, such as fishing nets and fishing lines in their stomachs (Carretta et al., 2023b).

Anthropogenic noise such as sonar may result in unknown levels of injury or mortality to short-finned pilot whales (Carretta et al., 2023b). In 2005, there was an UME off the U.S. East Coast that resulted in a stranding of 33 short-finned pilot whales and a minke whale (Hohn et al., 2006). These strandings may be associated with military sonar use that occurred in theses area during the time of the strandings; however, a definitive association has not been confirmed (Hohn et al., 2006).

Climate change has increasingly become a threat to marine mammals, including toothed whales. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in

competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.11 Melon-headed Whale (Peponocephala electra)

C.6.3.11.1 Status and Management

The melon-headed whale is protected under the MMPA and is not listed under the ESA. For the MMPA stock assessment reports, there are two Pacific management stocks within the Hawaiian Islands EEZ based on photo-identification, social network analysis, movement data, and genetics (Oleson et al., 2013). These stock are (1) the Kohala Resident stock, which includes melon-headed whales off the Kohala and west coast of Hawaii Island in waters less than 2,500 m deep; and (2) the Hawaiian Islands stock, which includes melon-headed whales inhabiting waters throughout the U.S. EEZ of the Hawaiian Islands (Aschettino et al., 2012; Baird et al., 2015d; Carretta et al., 2017b; Carretta et al., 2023b; Oleson et al., 2013).

C.6.3.11.2 Habitat and Geographic Range

Melon-headed whales are found worldwide in tropical and subtropical waters but movement patterns for this species are poorly understood. They have occasionally been reported at higher latitudes, but these movements are considered to be beyond their normal range, because the records indicate these movements occurred during incursions of warm water currents (Jefferson et al., 2015; Perryman, 2008; Perryman et al., 1994). In the north Pacific, occurrence of this species is well known in deep waters off many areas, including the Hawaii Study Area (Aschettino et al., 2012; Au & Perryman, 1985; Ferguson, 2005; Perrin, 1976; Wang et al., 2001).

The melon-headed whale is regularly found within Hawaiian waters (Baird et al., 2010; Baird et al., 2015e; Baird et al., 2003a; Baird et al., 2003b; Mobley et al., 2000; Shallenberger, 1981). Large groups are seen regularly, especially off the Waianae coast of Oahu, the north Kohala coast of Hawaii, and the leeward coast of Lanai (Baird, 2006; Oleson et al., 2013; Shallenberger, 1981). There was a total of nine sightings of melon-headed whales during three systematic ship surveys of the Hawaiian Islands EEZ in 2002 (one sighting), 2010 (one sighting), and 2017 (seven sightings) (Bradford et al., 2021). The single sightings in 2002 and 2010 included groups of 89 (Baird, 2006) and 153 melon-headed whales (Bradford et al., 2013), respectively, and the mean group size in 2017 was 187.9 animals (Bradford et al., 2021).

Brownell et al. (2009) found that melon-headed whales near oceanic islands rest near shore during the day, and feed in deeper waters at night. Melon-headed whales are known to enter shallow water areas on occasion although these are generally characterized as animals being "out of habitat" and/or "mass strandings"; a few hundred did so at Hanalei Bay, Kauai and Sasanhaya Bay, Rota (Mariana Islands) on July 4, 2004 (Jefferson et al., 2006), and similar numbers did so in the Philippines entering Manila Bay in Feb 2009 and the bay at Odiongan, Romblon in March of 2009 (Aragones et al., 2010). In surveys around the main Hawaiian Islands, melon-headed whales showed no clear pattern in depth use (Baird et al., 2013b).

A year-round, non-hierarchical Small and Resident Population BIA has been delineated for melonheaded whales off the Island of Hawaii (Kratofil et al., 2023) (Figure C-25). The BIA was updated from the original BIA (Baird et al., 2015d) based on additional analyses and encompasses 3,816 km² off the northwest coast of the Island of Hawaii (Kratofil et al., 2023). During ship-based bird surveys in the eastern tropical Pacific, melon-headed whales were observed from the U.S.-Mexico border south to Peru, typically associated with pelagic sea birds while foraging (Pitman & Ballance, 1992). The species is not expected to be present in the California Study Area.



Figure C-25: Melon-Headed Whale Small and Resident BIA in the Hawaii Study Area

C.6.3.11.3 Population Trends

Population data are currently insufficient to identify trends for the Kohala resident stock of melonheaded whales (Carretta et al., 2023b). Current abundance estimates for the Hawaiian Islands stock of melon-headed whales have broad and overlapping confidence intervals, and thus preclude a robust trend analysis. In addition, given the typically large group sizes observed in the field, the addition of a single sighting in a given year can have a substantial effect on the resulting abundance estimate, making it even more challenging to conduct a robust trend assessment (Carretta et al., 2023b).

C.6.3.11.4 Population Threats

In Hawaii, melon-headed whales are threatened by the deep-set longline fishery and the shallow-set longline fishery. The most recent monitoring data from 2014 through 2018 indicate that there have been no observed entanglements or hookings of this species in these fisheries (Bradford, 2018a; Bradford, 2018b; Bradford et al., 2017; Carretta et al., 2023b; McCracken, 2019). Additionally, there are no reported interactions of melon-headed whales and nearshore fisheries in Hawaii; however, nearshore fisheries are not monitored for protected species bycatch.

Anthropogenic noise such as sonar may result in unknown levels of injury or mortality to melon headed whales (Carretta et al., 2023b; Celi et al., 2013; Hohn et al., 2006). In 2004, a mass stranding of 150–200 melon-headed whales occurred in Kauai during the same timeframe as a multi-national military exercise using sonar (Hohn et al., 2006). The use of sonar in this instance is considered to be a plausible cause of this stranding event.

Climate change has increasingly become a threat to marine mammals. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.12 Long-beaked Common Dolphin (Delphinus delphis bairdii)

C.6.3.12.1 Status and Management

The Society for Marine Mammalogy's Committee on Taxonomy and NMFS currently recognize all common dolphins as a single species, *D. delphis*. Long-and short-beaked common dolphins are still recognized as separate subspecies, *D. delphis bairdii* and *D. delphis delphis*, respectively. In the future it is possible that they will again be recognized as separate species, but additional taxonomic analyses are required.

This species is protected under the MMPA and is not listed under the ESA. For the MMPA stock assessment reports, there is a single Pacific management stock for those animals found within the U.S. EEZ off the U.S. west coast, which is called the California stock (Carretta et al., 2023b).

C.6.3.12.2 Habitat and Geographic Range

Long-beaked common dolphins are not present in the Hawaii Study Area.

The long-beaked common dolphin appears to be restricted to waters relatively close to shore (Jefferson & Van Waerebeek, 2002; Perrin, 2008a), apparently preferring shallower and warmer water than the short-beaked common dolphin (Becker et al., 2016; Becker et al., 2022a; Gerrodette & Eguchi, 2011; Perrin, 2008a). Off California and Baja California, Mexico, long-beaked common dolphins are commonly found within 50 NM of the coast (Becker et al., 2022a; Carretta et al., 2011; Gerrodette & Eguchi, 2011). This species is found off Southern California year-round, but it may be more abundant there during the

warm-water months (May to October) (Barlow & Forney, 2007; Bearzi, 2005b; Douglas et al., 2014b; Henderson et al., 2014; Heyning & Perrin, 1994). Stranding data, sighting records, and habitat-based density models suggest that this species' abundance fluctuates seasonally and from year to year off California (Becker et al., 2020; Carretta et al., 2011; Douglas et al., 2014b; Henderson et al., 2014). Southern California waters represent the northern limit to this species' range and the seasonal and inter-annual changes in abundance off California are assumed to reflect the shifts in the movements of animals between U.S. and Mexican waters (Becker et al., 2022a).

C.6.3.12.3 Population Trends

There appears to be an increasing trend in the abundance of long-beaked common dolphin in California waters over the last 30 years based on both design- and model-based analyses, but a robust trend analysis has not yet been conducted (Barlow, 2016; Becker et al., 2020; Carretta et al., 2017b; Carretta et al., 2023b).

C.6.3.12.4 Population Threats

Long-beaked common dolphins are susceptible to entanglement in fishing gear. Most recent monitoring data from 2015 through 2019 indicate that the estimate of human-caused mortality or serious injury of this species in the California drift gillnet fishery is 1.7 individuals annually (Carretta, 2021). Additionally, stranding data along the U.S. West Coast during 2015 through 2019 yields a minimum estimate of 84 fishery-related mortalities of long-beaked common dolphins (Carretta, 2023). Mortalities from hook and line fisheries during the same time period are estimated as 3.2 individuals annually (Carretta, 2023).

Climate change has increasingly become a threat to marine mammals, including dolphins. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021). There have been reports dating to 2007 of long-beaked common dolphin mortalities due to domoic acid toxicity, which is likely related to ocean acidification and increased CO₂ levels.

C.6.3.13 Short-beaked Common Dolphin (Delphinus delphis delphis)

C.6.3.13.1 Status and Management

The Society for Marine Mammalogy's Committee on Taxonomy and NMFS currently recognize all common dolphins as a single species, *D. delphis*. Long-and short-beaked common dolphins are still recognized as separate subspecies, *D. delphis bairdii* and *D. delphis delphis*, respectively. In the future it is possible that they will again be recognized as separate species, but additional taxonomic analyses are required.

This species is protected under the MMPA and is not listed under the ESA. For the MMPA stock assessment reports, there is a single Pacific management stock for those animals found within the U.S. EEZ off the U.S. west coast, which is called the California, Oregon, and Washington stock (Carretta et al., 2023b).

C.6.3.13.2 Habitat and Geographic Range

Short-beaked common dolphins are not present in the Hawaii Study Area.

Historically along the U.S. west coast, short-beaked common dolphins were sighted primarily south of Point Conception (Dohl et al., 1983), but now they are commonly encountered as far north as 42°N (Hamilton et al., 2009), and occasionally as far north as 48°N (Forney, 2007). Seasonal distribution shifts

are pronounced, with a significant southerly shift south of Point Arguello in the winter (Becker et al., 2014; Campbell et al., 2014; Forney & Barlow, 1998b; Henderson et al., 2014). Short-beaked common dolphins are a warm temperate to tropical species, and based on habitat models developed using linetransect survey data collected off the U.S. west coast from 1991 to 2018, densities are greatest when waters are warmest (Barlow et al., 2009b; Becker et al., 2010; Becker et al., 2016; Becker et al., 2014; Becker et al., 2018; Forney & Barlow, 1998b; Forney et al., 2012). The distribution of short-beaked common dolphins off the U.S. west coast exhibits substantial seasonal and annual variability due to changes in oceanographic conditions, often resulting in shifts both north-south and inshore-offshore (Barlow et al., 2009b; Becker et al., 2020; Becker et al., 2016; Becker et al., 2014; Becker et al., 2018; Becker et al., 2017; Forney & Barlow, 1998b; Forney et al., 2012; Henderson et al., 2014). Short-beaked common dolphin abundance off California has increased dramatically since the late 1970s, along with a smaller decrease in abundance in the eastern tropical Pacific, suggesting a large-scale northward shift in the distribution of this species in the eastern North Pacific (Carretta et al., 2017b; Forney & Barlow, 1998b; Forney et al., 1995). The trend for an increase in the population off California appears to be continuing given current data from the most recent 2014 and 2018 NMFS surveys (Barlow, 2016; Becker et al., 2020).

Short-beaked common dolphins are found in the California Study Area throughout the year, distributed between the coast and at least 345 mi. from shore (Barlow, 2016; Barlow & Forney, 2007; Forney & Barlow, 1998b). Based on multiple line-transect studies conducted by NMFS, the short-beaked common dolphin is the most abundant cetacean species with a widespread distribution off southern California (Barlow, 2016; Barlow & Forney, 2007; Becker et al., 2020; Becker et al., 2017; Campbell et al., 2014; Carretta et al., 2011; Douglas et al., 2014b; Forney et al., 1995). From 2004 to 2008 during ship surveys conducted quarterly off southern California, short-beaked common dolphins were encountered year-round, with highest encounters during the summer (Douglas et al., 2014b). From 2008 to 2013 during 18 aerial surveys conducted in the Southern California Bight, short-beaked common dolphins were the most-frequently observed species (Jefferson et al., 2014).

C.6.3.13.3 Population Trends

Based on an analysis of sighting data collected during quarterly surveys off southern California from 2004 to 2013, short-beaked common dolphins showed annual variations in density, but there was no significant trend evident during the period of this study (Campbell et al., 2014). However, Barlow (2016) noted a nearly monotonic increase in the abundance of short-beaked common dolphins from 1991 to 2014 off the U.S. west coast. Predictions from habitat-based density models indicate a similar increase in short-beaked dolphin abundance off the U.S. west coast from 1996 to 2018, with the most current (2018) abundance estimate of 1,056,308 dolphins (CV = 0.207) (Barlow, 2016; Becker et al., 2020; Carretta et al., 2023b). However, the increase in short-beaked dolphin abundance could be due to a northward movement of animals from waters off Mexico and a future trend analysis is required to better assess potential population trends (Barlow, 2016; Becker et al., 2022a).

C.6.3.13.4 Population Threats

Short-beaked common dolphins are susceptible to entanglement in fishing gear. Most recent monitoring data from 2015 through 2019 indicate that the estimate of human-caused mortality or serious injury of this species in the California drift gillnet fishery is an average of 26.7 individuals annually (Carretta, 2021). Additionally, the estimated mean annual bycatch of short-beaked common dolphins in the set gillnet fisheries was 16 individuals, or 3.8 individuals annually, from 2015 through 2019 (Carretta, 2023).

Similar to long-beaked common dolphins, they are also susceptible to mortalities or injuries from hook and line fisheries (Carretta, 2023).

Climate change has increasingly become a threat to marine mammals, including dolphins. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.14 Common Bottlenose Dolphin (*Tursiops truncatus*)

C.6.3.14.1 Status and Management

The common bottlenose dolphin is protected under the MMPA and is not listed under the ESA. For the MMPA stock assessment reports, bottlenose dolphins within the Pacific U.S. EEZ are divided into seven stocks: (1) Kauai and Niihau, (2) Oahu, (3) Maui Nui, (4) Hawaii Island, (5) the Hawaii Pelagic stock, (6) California Coastal stock, and (7) the California, Oregon and Washington Offshore stock (Carretta et al., 2024).

C.6.3.14.2 Habitat and Geographic Range

Common bottlenose dolphins typically are found in coastal and continental shelf waters of tropical and temperate regions of the world (Jefferson et al., 2008; Wells et al., 2009). Common bottlenose dolphins occur throughout the Hawaiian Islands, and they are typically observed throughout the main islands and from the Island of Hawaii to Kure Atoll (Baird et al., 2013c; Shallenberger, 1981). In the Hawaiian Islands, this species is found in both shallow coastal waters and deep offshore waters (Baird et al., 2003b; Barlow et al., 2008; Bradford et al., 2013; Mobley et al., 2000). The offshore variety is typically larger than the inshore. Photo-identification and genetics indicate the presence of island associated populations of bottlenose dolphins in the Hawaiian Islands (Martien et al., 2012). During three systematic surveys of the Hawaiian Islands EEZ in 2002, 2010, and 2017, there were a total of 38 sightings of bottlenose dolphins, of which 27 groups were identified as members of the Hawaii pelagic stock and the rest identified as members of one of the four island-associated stocks (Bradford et al., 2021). Habitat-based models developed from systematic ship survey data collected in the central North Pacific show some of the highest common bottlenose dolphin densities around the Hawaiian Islands (Becker et al., 2012b; Forney et al., 2015). More recently, habitat-based density models were developed using systematic survey data collected within waters of the Hawaiian Islands EEZ from 2000 to 2020 using only those common bottlenose dolphin sightings identified as members of the Hawaii pelagic stock (Becker et al., 2022a). Model predictions showed a strong island association for the pelagic stock, with highest densities occurring near all the islands within the EEZ.

Five year-round Small and Resident Population BIAs (a parent BIA, three child BIAs, and one nonhierarchical BIA) have been delineated in the main Hawaiian Islands for the populations of common bottlenose dolphins (Kratofil et al., 2023) (Figure C-26). The BIAs were updated from the original BIAs (Baird et al., 2015d) based on additional analyses. The parent BIA encompasses 36,634 km² of waters surrounding Niihau to the west and extending east to surround the island of Maui. The child BIAs encompass 2,772 km² around Kauai/Niihau, 8,487 km² around Oahu, and 10,622 km² around Maui Nui. In addition, a year-round non-hierarchical Small and Resident Population BIA was delineated and encompasses 8,299 km² around the Island of Hawaii (Kratofil et al., 2023) (Figure C-26).

Common bottlenose dolphins are known to occur year-round in both coastal and offshore waters of Monterey Bay, Santa Monica Bay, San Diego Bay, and SCI, California (Bearzi, 2005a, 2005b; Bearzi et al., 2009b; Carretta et al., 2000; Henkel & Harvey, 2008). In the California Study Area, they are routinely encountered in San Diego Bay in transit to the waters off Coronado where they feed (Graham & Saunders, 2015).

During surveys off California, offshore common bottlenose dolphins were generally found at distances greater than 1.9 mi. from the coast and throughout the waters of Southern California (Barlow, 2016; Barlow & Forney, 2007; Bearzi et al., 2009b; Hamilton et al., 2009). Sighting records off California and Baja California suggest a continuous distribution of offshore common bottlenose dolphins in these regions (Mangels & Gerrodette, 1994). Based on habitat models derived from line-transect survey data collected between 1991 and 2009 off the U.S. west coast, offshore common bottlenose dolphins exhibit a disjunctive longitudinal distribution, suggesting that there may be two separate populations in this area, although additional genetic data are required for confirmation (Becker et al., 2016). This pattern was also apparent in the density predictions from more recent models that included additional survey data collected in 2014 and 2018 (Becker et al., 2020).

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Figure C-26: Common Bottlenose Dolphin Small and Resident BIAs in the Hawaii Study Area

California coastal bottlenose dolphins are found within about 0.6 NM of the shore, generally from Point Conception to as far south as San Quintin, Mexico (Carretta et al., 1998; Defran & Weller, 1999; Hwang et al., 2014). Coastal common bottlenose dolphins also have been consistently sighted off central California and as far north as San Francisco since the 1982–83 El Niño, when they apparently traveled further north tracking prey due to the northern extent of warmer waters and continued using those more northern waters after that El Niño had ended (Hwang et al., 2014). Off Southern California, animals are found within 500 m of the shoreline 99 percent of the time and within 250 m of the shoreline 90 percent of the time (Hanson & Defran, 1993; Hwang et al., 2014). The dolphins in the nearshore waters of San Diego, California differ somewhat from other coastal populations of this species in distribution, site fidelity, and school size (Bearzi, 2005a, 2005b; Carretta et al., 2017b; Defran et al., 2015; Defran & Weller, 1999). Photo identification analyses suggest that there may be two separate stocks of coastal bottlenose dolphins that exhibit limited integration, a California Coastal stock and a Northern Baja California stock (Defran et al. 2015), but this is not yet reflected in the Pacific Stock Assessment Report (Carretta et al., 2023b). The results from relatively contemporaneous surveys at Ensenada, San Diego, Santa Monica Bay, and Santa Barbara between 1996 and 2001 provided samples of the speed and distances individual coastal bottlenose dolphins routinely traveled (Hwang et al., 2014). The minimum travel speed observed was 53 km per day and the maximum was 95 km per day; and the total distances traveled between points was between 104 km and 965 km (Hwang et al., 2014).

C.6.3.14.3 Population Trends

For the Hawaii Pelagic stock, the available abundance estimates have broad and overlapping confidence intervals, thus precluding an assessment of population trends (Carretta et al., 2017b; Carretta et al., 2023b). For the four island-associated insular stocks (Kauai and Niihau, Oahu, Maui Nui, and Hawaii Island), there is currently insufficient information to assess population trends for these stocks (Carretta et al., 2023b).

For the California Study Area, the California Coastal stock population size has remained stable from 1987 to 2005, but more recent abundance estimates suggest the population may be increasing (Carretta et al., 2017b; Carretta et al., 2023b; Dudzik et al., 2006; Weller et al., 2016). For the California, Oregon and Washington Offshore stock, an apparent trend is not evident from either design- or model-based abundance estimates, but a robust trend analysis has not been conducted for the population (Barlow, 2016; Becker et al., 2020; Carretta et al., 2017b; Carretta et al., 2023b).

C.6.3.14.4 Population Threats

Common bottlenose dolphins are susceptible to interactions with fisheries and entanglements in fishing gear. Off the U.S. West Coast, bottlenose dolphins have been observed entangled in both coastal and offshore fisheries. The minimal annual takes for this species across commercial fisheries are estimated as 1.6 dolphins per year (Carretta, 2023).

In Hawaii, common bottlenose dolphins are threatened by the deep-set longline fishery and the shallowset longline fishery. The most recent monitoring data from 2017 through 2021 indicate that there have 1 observed entanglement or hooking of this species in the shallow-set longline fishery and 6 taken in the deep-set longline fishery (Bradford, 2018a; Bradford, 2018b; Bradford et al., 2017; Carretta et al., 2023b; McCracken, 2019). During the same five-year period, there was observed shooting of a bottlenose dolphin, likely attributed to fisheries interactions as well. There are no estimates of mortality or serious injury of this species in Hawaii nearshore gillnet or hook and line fisheries because nearshore fisheries are not monitored for protected species bycatch (Bradford & Lyman, 2018; Carretta, 2023). However, in areas where gillnet fishing is allowed, fishermen are often required to frequently check their nets for bycatch (Carretta et al., 2024). Although these fisheries are not monitored, there have been observations of bottlenose dolphins with serious injuries from hooks likely from nearshore fisheries (Carretta et al., 2024).

Furthermore, this species is known to steal bait and catches off commercial fishing lines in Hawaii, which may cause serious injury. Photo observations of bottle nose dolphins in the Maui Nui region revealed that approximately 27 percent of well-marked, adult individuals had scarring likely attributed to hookings and interactions with fishing gear (Carretta et al., 2024; Machernis et al., 2021).

Climate change has increasingly become a threat to marine mammals, including dolphins. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.15 Pantropical Spotted Dolphin (Stenella attenuata)

C.6.3.15.1 Status and Management

The species is protected under the MMPA and is not listed under the ESA. For the MMPA stock assessment reports, the species has been divided into four stocks based on genetics and the frequency of sightings in pelagic waters around Hawaii (Courbis et al., 2014; Oleson et al., 2013). The four management stocks within the Hawaiian Islands EEZ are (1) the Oahu stock, which includes spotted dolphins within 20 km of Oahu; (2) the Maui Nui stock, which includes spotted dolphins within 20 km of the island group formed by Maui, Molokai, Lanai, and Kahoolawe and their adjacent waters; (3) the Hawaii Island stock, which includes spotted dolphins found within 65 km from Hawaii Island; and (4) the Hawaii Pelagic stock, which includes spotted dolphins inhabiting the waters throughout the Hawaiian Islands EEZ, outside of the insular stock areas (Carretta et al., 2024).

C.6.3.15.2 Habitat and Geographic Range

The pantropical spotted dolphin is distributed in offshore tropical and subtropical waters of the Pacific, Atlantic, and Indian Oceans between about 40° N and 40° S (Baldwin et al., 1999; Perrin, 2008b). The species is much more abundant in the lower latitudes of its range. It is found mostly in deeper offshore waters but does approach the coast in some areas (Jefferson et al., 2008; Perrin, 2001).

Based on sightings during small boat surveys from 2000 to 2012 in the main Hawaiian Islands, pantropical spotted dolphins were the most abundant species of cetacean, although they were frequently observed leaping out of the water which likely increased their detectability (Baird et al., 2013c). This species was also one of the most abundant based on analyses of line-transect data collected in the Hawaiian EEZ in 2002, 2010, and 2017, with a total of 39 sightings during the three surveys (Barlow, 2006; Bradford et al., 2013; Bradford et al., 2021). Known habitat preferences and sighting data indicate the primary occurrence for the pantropical spotted dolphin in Hawaiian waters is shallow coastal waters to depths of 5,000 m, although the peak sighting rates occur in depths from 1,500 to 3,500 m (Baird et al., 2013d; Bradford et al., 2013; Oleson et al., 2013). Habitat-based models developed from systematic ship survey data collected in the central North Pacific show relatively high pantropical spotted dolphin densities around the Hawaiian Islands, particularly around the Main Hawaiian Islands (Becker et al., 2012a; Forney et al., 2015). More recently, sighting data from systematic ship surveys conducted in waters of the Hawaiian Islands EEZ from 2000 to 2020 allowed for the development of separate habitat models for the pelagic and combined insular stocks of pantropical spotted dolphins (Becker et al., 2022a). Consistent with past observations (Baird et al., 2013d; Bradford et al., 2013;

Oleson et al., 2013), the model for the combined insular stocks showed peak abundance in depths from 1,500 to 3,500 m. The habitat model for the pelagic stock predicted low to mid-range density estimates for offshore waters of the Hawaiian Islands EEZ, with highest densities near all the islands, but particularly around the Main Hawaiian Islands (Becker et al., 2022a).

A year-round Small and Resident Population parent BIA and three child BIAs have been delineated in the main Hawaiian Islands for the populations of Pantropical spotted dolphins (Kratofil et al., 2023) (Figure C-27). The BIAs were updated from the original BIAs (Baird et al., 2015d) based on additional analyses. The parent BIA encompasses 57,711 km² of waters surrounding Oahu, Maui Nui, and the Island of Hawaii. The child BIAs encompass 12,952 km² around Oahu, 6,743 km² around Maui Nui, and 10,768 km² around the Island of Hawaii (Kratofil et al., 2023).

Pantropical spotted dolphins are not present in the California Study Area, but they do occur in waters off the Baja California Peninsula, Mexico (Hamilton et al., 2009). Dolphins occurring in Mexican waters are considered part of an Eastern Tropical Pacific population that occurs in high numbers in tropical oceanic waters north of the equator and near the coast off Central America (Forney et al., 2012; Wade & Gerrodette, 1993).

C.6.3.15.3 Population Trends

No data are available on current population trends for any of the insular stocks of pantropical spotted dolphins in Hawaii (Carretta et al., 2023b). Abundance estimates for the pelagic stock have broad and overlapping confidence intervals, thus precluding a robust assessment of population trends.

C.6.3.15.4 Population Threats

Common bottlenose dolphins are susceptible to interactions with fisheries and entanglements in fishing gear. Off the U.S. West Coast, bottlenose dolphins have been observed entangled in both coastal and offshore fisheries. The minimal annual takes for this species across commercial fisheries are estimated as 1.6 dolphins per year (Carretta, 2023).

In Hawaii, common bottlenose dolphins are threatened by the deep-set longline fishery and the shallowset longline fishery. The most recent monitoring data from 2017 through 2021 indicate that there have 1 observed entanglement or hooking of this species in the shallow-set longline fishery and 6 taken in the deep-set longline fishery (Bradford, 2018a; Bradford, 2018b; Bradford et al., 2017; Carretta et al., 2023b; McCracken, 2019). During the same five-year period, there was observed shooting of a bottlenose dolphin, likely attributed to fisheries interactions as well. There are no estimates of mortality or serious injury of this species in Hawaii nearshore gillnet or hook and line fisheries because nearshore fisheries are not monitored for protected species bycatch (Bradford & Lyman, 2018; Carretta, 2023). However, in areas where gillnet fishing is allowed, fishermen are often required to frequently check their nets for bycatch (Carretta et al., 2024). Although these fisheries are not monitored, there have been observations of bottlenose dolphins with serious injuries from hooks likely from nearshore fisheries (Carretta et al., 2024).



Figure C-27: Pantropical Spotted Dolphin Small and Resident BIAs in the Hawaii Study Area

Furthermore, this species is known to steal bait and catches off commercial fishing lines in Hawaii, which may cause serious injury. Photo observations of bottle nose dolphins in the Maui Nui region revealed that approximately 27 percent of well-marked, adult individuals had scarring likely attributed to hookings and interactions with fishing gear (Carretta et al., 2024; Machernis et al., 2021).

Climate change has increasingly become a threat to marine mammals, including dolphins. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.16 Striped Dolphin (Stenella coeruleoalba)

C.6.3.16.1 Status and Management

This species is protected under the MMPA and is not listed under the ESA. In the eastern north Pacific, NMFS identifies two striped dolphin management stocks within the U.S. EEZ: the Hawaiian stock and the California, Oregon, and Washington stock (Carretta et al., 2023b).

C.6.3.16.2 Habitat and Geographic Range

Although primarily a warm-water species, the range of the striped dolphin extends higher into temperate regions than those of any other species in the genus *Stenella (Jefferson et al., 2015)*. Striped dolphins are generally restricted to oceanic regions and are seen close to shore only where deep water approaches the coast. In some areas (e.g., the eastern tropical Pacific), they are mostly associated with convergence zones and regions of upwelling (Au & Perryman, 1985; Reilly, 1990). The northern limits are the Sea of Japan, Hokkaido, Washington State, and along roughly 40° N across the western and central Pacific (Reeves et al., 2002). In the eastern tropical Pacific, striped dolphins inhabit areas with large seasonal changes in surface temperature and thermocline depth, as well as seasonal upwelling (Au & Perryman, 1985; Reilly, 1990). In some areas, this species appears to avoid waters with sea temperatures less than 68°F (20°C) (Van Waerebeek et al., 1998).

The striped dolphin regularly occurs around the Hawaiian Islands. During three systematic ship surveys of waters within the Hawaiian Islands EEZ in summer/fall of 2002, 2010, and 2017, there was a total of 45 sightings of striped dolphin, with the yearly mean group sizes ranging from 36.3 to 54.9 animals (Bradford et al., 2021). Resulting density estimates from these surveys suggest that they are one of the most abundant species in the Hawaiian EEZ. Based on sighting records, this species occurs primarily seaward of the 1,000 m depth contour. Striped dolphins are occasionally sighted closer to shore in Hawaii, so an area of secondary occurrence is expected from a depth range of 100 to 1,000 m. Occurrence patterns are assumed to be the same throughout the year (Mobley et al., 2000). Habitat-based density models developed from systematic ship survey data collected in the central North Pacific show more uniform striped dolphin densities throughout the Hawaiian EEZ, consistent with this species' known occurrence in deep waters (Becker et al., 2012b; Forney et al., 2015). More recently, sighting data from systematic ship surveys conducted within waters of the Hawaiian Islands EEZ from 2000 to 2020 supported the development of an updated habitat-based density model for striped dolphin and confirmed this species apparent preference for deep waters (Becker et al., 2022a).

Based on sighting records, striped dolphins appear to have a continuous distribution in offshore waters from California to Mexico (Mangels & Gerrodette, 1994). The striped dolphin also occurs far offshore, in waters affected by the warm Davidson Current as it flows northward (Archer, 2009; Jefferson et al., 2008). During ship surveys conducted off the U.S. west coast in the summer and fall from 1991 to 2018, striped dolphins were sighted primarily from 100 to 300 NM offshore of the California coast (Barlow,

2016; Barlow & Forney, 2007; Becker et al., 2020). Striped dolphin encounters increase in deep, relatively warmer waters off the U.S. west coast (Becker et al., 2020; Becker et al., 2012a; Becker et al., 2016; Henderson et al., 2014), and their abudance generally decreases north of about 42°N (Barlow et al., 2009b; Becker et al., 2012a; Becker et al., 2016; Forney et al., 2012). There were only three striped dolphin encounters during 16 ship surveys off southern California from 2004 to 2008 (Douglas et al., 2014b) and they were not detected during 15 aerial surveys conducted in the Southern California Range Complex from 2008 through 2012 (Smultea & Jefferson, 2014).

Striped dolphins are a warm temperate to tropical species, and based on design- and model-based abundance estimates derived from line-transect survey data collected off the U.S. west coast from 1991 to 2018, densities are greatest when waters are warmest (Barlow, 2016; Becker et al., 2020; Becker et al., 2018). The distribution of striped dolphins off the U.S. west coast exhibits substantial annual variability due to changes in oceanographic conditions, often resulting in distribution shifts in and out of U.S. waters (Barlow, 2016; Barlow & Forney, 2007; Becker et al., 2022a). During the anomalously warm water year in 2014, striped dolphin abundance off the U.S. west coast increased dramatically, with striped dolphins seen as far north as 44° N (Barlow, 2016; Becker et al., 2020; Becker et al., 2018).

C.6.3.16.3 Population Trends

For the Hawaiian stock of striped dolphin, current abundance data preclude the assessment of population trends (Carretta et al., 2023b).

For the California, Oregon, and Washington stock of striped dolphins, because there is high annual variability in their distribution and abundance, no long-term trends have been identified (Carretta et al., 2023b).

C.6.3.16.4 Population Threats

Striped dolphins are susceptible to interactions with fisheries and entanglement in fishing gear. Recent monitoring data from 2015 through 2019 indicate that there were no recorded human-caused mortality or serious injury of this species in the California drift gillnet fishery (Carretta et al., 2023a). However, when factoring in a co-efficient of variation for non-detected strandings, the stranding data along the U.S. West Coast during 2015 through 2019 yields a minimum estimate of 20 fishery-related mortalities of striped dolphins (Carretta, 2021; Carretta, 2023; Carretta et al., 2016b).

In Hawaii, striped dolphins are threatened by the deep-set longline fishery and the shallow-set longline fishery. The most recent monitoring data from 2017 through 2021 indicate that there was one entanglement of this species in the shallow-set longline fishery, and none in the deep-set longline fishery (Bradford, 2018a; Bradford, 2018b; Bradford et al., 2017; Carretta et al., 2023b; McCracken, 2019). Additionally, there are no estimates of mortality or serious injury of this species in Hawaii nearshore gillnet or hook and line fisheries; however, nearshore fisheries are not monitored for protected species bycatch and there have been anecdotal observations of this species interacting with these fisheries (Carretta, 2023).

Climate change has increasingly become a threat to marine mammals, including dolphins. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.17 Spinner Dolphin (Stenella longirostris)

Four well differentiated geographical forms of spinner dolphins have been described as separate subspecies but only *Stenella longirostris* (Gray's spinner dolphin) is present in the HCTT Study Area.

C.6.3.17.1 Status and Management

The spinner dolphin is protected under the MMPA and the species is not listed under the ESA. The eastern spinner dolphin (*Stenella longirostris orientalis*) is listed as depleted under the MMPA. Hawaiian spinner dolphins (considered a form of Gray's or pantropical spinner dolphin, *Stenella longirostris longirostris*) are considered as separate stocks from those involved in the tuna purse-seine fishery in the eastern tropical Pacific (Dizon et al., 1994). Under the MMPA, there are six stocks found within the U.S. EEZ of the Hawaiian Islands: (1) Hawaii Island, (2) Oahu/4-Islands, (3) Kauai/Niihau, (4) Pearl & Hermes Reef, (5) Kure/Midway, and (6) Hawaii Pelagic, including animals found both within the Hawaiian Islands EEZ (outside of island-associated boundaries) and in adjacent international waters (Carretta et al., 2023b).

C.6.3.17.2 Habitat and Geographic Range

Spinner dolphins occur in both oceanic and coastal environments and seasonal movement patterns for this species have not been documented. Spinner dolphins are pantropical, ranging through oceanic tropical and subtropical zones in both hemispheres (Jefferson et al., 2015). Based on an analysis of individual spinner dolphin movements in Hawaii, no spinner dolphins from the island associated stocks have been found farther than 10 NM from shore and few individuals move long distances (from one main Hawaiian Island to another) (Hill et al., 2011). Open ocean populations, such as the Hawaii Pelagic stock or those animals in the eastern tropical Pacific, often are found in waters with a shallow thermocline (rapid temperature difference with depth) (Au & Perryman, 1985; Perrin, 2008c; Reilly, 1990). The thermocline concentrates open sea organisms in and above it, which spinner dolphins feed on. In the eastern tropical Pacific, spinner dolphins are associated with tropical surface waters typified by extensive stable thermocline ridging and relatively little annual variation in surface temperature (Au & Perryman, 1985; Perrin, 2008c).

In the Hawaiian Islands, spinner dolphins occur along the leeward coasts of all the major islands and around several of the atolls northwest of the main Hawaiian Islands. Spinner dolphins occur year-round throughout the Hawaiian Islands, with primary occurrence from the shore to 4,000 m depth. This considers nearshore resting habitat and offshore feeding areas. Spinner dolphins are expected to occur in shallow water resting areas (about 50 m deep or less) throughout the middle of the day, moving into deep waters offshore during the night to feed (Heenehan et al., 2016; Heenehan et al., 2017; Norris & Dohl, 1980). Some of these resting areas are in proximity to bathymetric features that result in localized concentration of spinner dolphin prey. For example, there is an escarpment off Hawaii Island's Keahole Point that produces a locally enriched area that spinner dolphins exploit during nightly foraging trips from the nearby Makeko Bay (Heenehan et al., 2017; Norris & Dohl, 1980). Primary resting areas are along the west side of Hawaii, including Makako Bay, Honokohau Bay, Kailua Bay, Kealakekua Bay, Honaunau Bay, and Kauhako Bay, and off Kahena on the southeast side of the island (Heenehan et al., 2016; Heenehan et al., 2017; Norris & Dohl, 1980; Ostman-Lind et al., 2004; Tyne et al., 2017; Tyne et al., 2015). Along the Waianae coast of Oahu, Hawaii, spinner dolphins rest along Makua Beach, Kahe Point, and Pokai Bay during the day (Lammers, 2004). Kilauea Bay on Kauai is also a popular resting areas for Hawaiian spinner dolphins (U.S. Department of the Navy, 2006b). Monitoring for the Rim of the Pacific Exercise in 2006 resulted in daily sightings of spinner dolphins within the offshore area of

Kekaha Beach, Kauai, near the PMRF (U.S. Department of the Navy, 2006b). Spinner dolphins have been observed during Navy monitoring surveys at Kaula Island in 2000, 2003, and 2009–2011 (Richie et al., 2012). Although sightings have been recorded around the mouth of Pearl Harbor, Hawaii, spinner dolphin occurrence is rare there (Lammers, 2004; Richie et al., 2016). Occurrence patterns are assumed to be the same throughout the year.

During three systematic ship surveys of waters within the Hawaiian Islands EEZ in summer/fall of 2002, 2010, and 2017, there was a total of 15 sightings of spinner dolphin, the majority from the pelagic stock (Bradford et al., 2021). Habitat-based models developed from systematic ship survey data collected in the central North Pacific show the strong island association of spinner dolphins (Becker et al., 2012b; Forney et al., 2015), consistent with previously documented distribution patterns (Barlow, 2006).

Five year-round, non-hierarchical Small and Resident Population BIAs have been delineated for spinner dolphins in Hawaiian waters (Kratofil et al., 2023) (Figure C-28). The BIAs were based on the current insular stock boundaries and include Kuaihelani/Holaniku (4,841 km²), Manawai (2,094 km²), Kauai/Niihau (7,233 km²), Oahu/Maui Nui (14,651 km²), and the Island of Hawaii (9,477 km²).

Spinner dolphins are not present in the California Study Area.

C.6.3.17.3 Population Trends

For spinner dolphins in Hawaii, differences in survey methodologies or insufficient data have precluded an assessment of any population trend for any of the six identified stocks (Carretta et al., 2023b).

C.6.3.17.4 Population Threats

Spinner dolphins are susceptible to interactions with fisheries and entanglement in fishing gear and marine debris. In Hawaii, the most recent data from 2012 through 2016 indicate that there were 7 recorded spinner dolphins entangled in marine debris or hooked by fishing gear (Bradford, 2018b; Bradford & Lyman, 2015a; Carretta, 2023). Throughout the years, there have been several recorded observations of this species seriously injured by entanglements in fishing equipment.

Spinner dolphins are also threatened by the deep-set longline fishery and the shallow-set longline fishery; however, the monitoring data from 2012 through 2016 indicate that there have been no observed entanglements or hookings of this species in these fisheries (Bradford, 2018b; Bradford & Forney, 2017; Carretta, 2023). There are no reports of interactions of spinner dolphins in nearshore gillnet or hook and line fisheries in Hawaii; however, nearshore fisheries are not monitored for protected species bycatch (Carretta, 2023).

Climate change has increasingly become a threat to marine mammals, including dolphins. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

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Figure C-28: Spinner Dolphin Small and Resident BIA in the Hawaii Study Area

C.6.3.18 Rough-toothed Dolphin (Steno bredanensis)

C.6.3.18.1 Status and Management

This species is protected under the MMPA and is not listed under the ESA. Rough-toothed dolphins are among the most widely distributed species of tropical dolphins, but little information is available regarding population status (Jefferson et al., 2015). There is a single Pacific management stock for rough-toothed dolphins found within the U.S. EEZ of the Hawaiian Islands, but there is no recognized stock of rough-toothed dolphins for the U.S. west coast (Carretta et al., 2023b).

C.6.3.18.2 Habitat and Geographic Range

Rough-toothed dolphins are well known in deep ocean waters off the Hawaiian Islands but are also seen relatively frequently during nearshore surveys (Baird et al., 2015f; Baird et al., 2008; Barlow et al., 2008; Bradford et al., 2013; Carretta et al., 2015; Pitman & Stinchcomb, 2002; Shallenberger, 1981; Webster et al., 2015). During three systematic ship surveys of waters within the Hawaiian Islands EEZ in summer/fall of 2002, 2010, and 2017, there was a total of 67 sightings of rough-toothed dolphin, with yearly mean group size estimates ranging from 15.7 to 25.3 animals (Bradford et al., 2021). Based on density estimates derived from these survey data, rough-toothed dolphin was one of the most abundant species present in the study area in each of the three years. Habitat-based models developed from systematic ship survey data collected in the central North Pacific show the strong island association of roughtoothed dolphins (Becker et al., 2012b; Forney et al., 2015). Sighting data from systematic ship surveys conducted within waters of the Hawaiian Islands EEZ from 2000 to 2020 supported the development of an updated habitat-based density model for rough-toothed dolphin and confirmed the strong island association indicated from the previous models (Becker et al., 2022a). Over a 10-day near-shore survey effort off Kauai in 2014, rough-toothed dolphins were encountered on two occasions and 7 of the 8 individuals photo-identified had been observed in previous years (Baird et al., 2015e). Data from 14 satellite tags deployed off Kauai between 2011–2015 on rough-toothed dolphins indicated a large portion of the core area for those animals overlaps the PMRF range and the channel between Kauai and Niihau (Baird et al., 2015e). The data presented by Baird et al. (2015e) and Webster et al. (2015) are indicative of residency on or near the PMRF range by some of those animals (see also (Baird et al., 2008).

A year-round Small and Resident Population parent BIA and child BIA have been delineated for waters off Kauai, Niihau, and Oahu for rough-toothed dolphins (Kratofil et al., 2023) (Figure C-29). A BIA was not identified for this population in the original BIA effort because there were insufficient data available at that time (Baird et al., 2015d). The parent BIA encompasses 25,083 km² of waters extending from the west coast of Oahu to the northwest and surrounding both Kauai and Niihau. The child BIA encompass 1,098 km² off the west coast of Kauai to capture the core range for this population (Kratofil et al., 2023). In addition, a year-round, non-hierarchical BIA was delineated for rough-toothed dolphins associated with Maui Nui and the Island of Hawaii. This BIA encompasses 15,112 km² of waters from the west coast of the Island of Hawaii, extending north to encompass waters off Maui Nui (Kratofil et al., 2023) (Figure C-28).



Figure C-29: Rough-Toothed Dolphin Small and Resident BIAs in the Hawaii Study Area

The northernmost range of the rough-toothed dolphin includes the southern portion of the California coast (Jefferson et al., 2015) but this is a tropical to subtropical species and there is no recognized stock for the U.S west coast (Carretta et al., 2023b). During systematic ship surveys off the U.S. west coast and the Baja California Peninsula from 1986 to 2005, there were no documented sightings of rough-toothed dolphins north of 25° N (Hamilton et al., 2009). Three strandings were documented for this species in central and Southern California between 1977 and 2002 with pneumonia identified as a cause of death (Zagzebski et al. 2006). This species has not been observed during seven systematic ship surveys from 1991 to 2014 off the U.S. west coast (Barlow, 2016). During 16 quarterly ship surveys off southern California from 2004 to 2008, there was one encounter with a group of 9 rough-toothed dolphins, which was considered an extralimital occurrence (Douglas et al., 2014b).

C.6.3.18.3 Population Trends

Available abundance estimates for the Hawaii stock of rough-toothed dolphins have broad and overlapping confidence intervals, thus precluding a robust assessment of population trends (Carretta et al., 2023b).

C.6.3.18.4 Population Threats

Rough-toothed dolphins are susceptible to interactions with fisheries and entanglement in fishing gear. In Hawaii, rough toothed dolphins are threatened by the deep-set longline fishery and the shallow-set longline fishery. The most recent monitoring data from 2017 through 2021 indicate that there were 8 observed hooking or entanglement of this species in the deep-set longline fishery, and none in the shallow-set fishery (Carretta et al., 2024; Carretta et al., 2023a). Of the 8 recorded observations occurring both within and out of the Hawaii EEZ, 3 rough-toothed dolphins were determined to be seriously injured and 3 interactions resulted in death.

There are no estimates of mortality or serious injury of this species in Hawaii nearshore gillnet or hook and line fisheries because nearshore fisheries are not monitored for protected species bycatch (Bradford & Lyman, 2018; Carretta, 2023). However, there were 52 photographs taken of rough-toothed dolphins that capture evidence of injuries likely resulting from hook and line fisheries in Hawaii (Carretta, 2023; Welch, 2017). There have also been rough-toothed dolphins observed in nearshore areas entangled in unidentified fishing gear.

Climate change has increasingly become a threat to marine mammals, including dolphins. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.19 Pacific White-sided Dolphin (*Lagenorhynchus obliquidens*)

C.6.3.19.1 Status and Management

This species is not listed under the ESA but is protected under the MMPA. Although there is evidence that two forms of Pacific white-sided dolphin occur off the U.S. west coast (a northern and southern stock), due to the difficulty of distinguishing the two stocks in the field, and given an area of apparent overlap off Southern California (Lux et al., 1997), NMFS currently recognizes a single stock, the California, Oregon, and Washington stock for the U.S. west coast (Carretta et al., 2023b).

C.6.3.19.2 Habitat and Geographic Range

Pacific white-sided dolphins are not present in the Hawaii Study Area.

Pacific white-sided dolphins are found in cold temperate waters across the northern rim of the Pacific Ocean as far north as the southern Bering Sea and as far south as the Gulf of California off Mexico (Ferguson, 2005; Jefferson et al., 2015; Leatherwood et al., 1984; Reeves et al., 2002). This species is also known to inhabit inshore regions of southeast Alaska, British Columbia, and Washington, and occurs seasonally off Southern California (Brownell et al., 1999; Forney & Barlow, 1998b). Sighting records and captures in open sea driftnets indicate that this species also occurs in oceanic waters well beyond the shelf and slope (Ferrero & Walker, 1996; Leatherwood et al., 1984).

Off California, Forney and Barlow (1998b) found significant north/south shifts in the seasonal distribution of Pacific white-sided dolphin, with the animals moving north into Oregon and Washington waters during the summer, and showing increased abundance in the Southern California Bight in the winter. There were a total of 121 sightings of Pacific white-sided dolphins during seven systematic ship surveys off the U.S. west coast in summer and fall between 1991 and 2014, with observed group sizes highly variable among the years (Barlow, 2016). During the unusually warm water conditions present in 2014, there were few sightings of Pacific white-sided dolphins off central and southern California (Barlow, 2016). Based on habitat models developed with systematic survey data collected during summer and fall from 1991 to 2018, the abundance of Pacific white-sided dolphin increased in shelf and slope waters and in relatively cooler waters in the study area (Becker et al., 2020). These patterns are consistent with previous habitat modeling efforts using a subset of the same data (Barlow et al., 2009b; Becker et al., 2012b; Becker et al., 2014; Forney et al., 2012). Based on ship survey data collected quarterly from 2004 to 2013, Pacific white-sided dolphins occurred year-round off southern California, but the majority of the sightings were in winter and spring when their distribution was more widespread (Campbell et al., 2014).

C.6.3.19.3 Population Trends

Multiple analyses of sightings and stranding data have indicated a significant decline in abundance over time from the Southern California Bight to the Gulf of California in Mexico (Barlow, 2016; Campbell et al., 2015; Salvadeo et al., 2010; Smultea & Jefferson, 2014). However, abundance estimates derived from both design- and model-based analyses for waters off the U.S. west coast show considerable seasonal and yearly variability (Barlow, 1995, 2016; Becker et al., 2020; Becker et al., 2014; Becker et al., 2018; Forney & Barlow, 1998b; Forney et al., 1995), making it difficult to support a robust trend analysis (Carretta et al., 2023b).

C.6.3.19.4 Population Threats

Pacific white-sided dolphins are threatened by interactions with fisheries, entanglement in fishing gear, and scientific research. The most recent monitoring data from 2015 through 2019 indicate that the estimate of mortality or serious injury of this species in the California drift gillnet fishery is 4.0 individuals annually (Carretta, 2023, 2022b). Additionally, injuries and mortalities of this species have resulted scientific research trails off the U.S. West Coast, specifically for sardines and rockfish. Research from 2015 through 2019 resulted in 14 mortalities and 1 serious injury of this species (Carretta, 2021; Carretta et al., 2023b).

Climate change has increasingly become a threat to marine mammals, including dolphins. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.20 Northern Right Whale Dolphin (Lissodelphis borealis)

C.6.3.20.1 Status and Management

This species it is not listed under the ESA but is protected by the MMPA. The management stock in U.S. waters consists of a single California, Oregon, and Washington stock (Carretta et al., 2023b).

C.6.3.20.2 Habitat and Geographic Range

The northern right whale dolphin occurs in cool-temperate to subarctic waters of the North Pacific Ocean, from the west coast of North America to Japan and Russia. This oceanic species is distributed from approximately 30°N to 50°N, 145°W to 118°E and generally not as far north as the Bering Sea (Jefferson et al., 2015). Occasional movements south of 30°N are associated with unusually cold water temperatures (Jefferson & Lynn, 1994). This species tends to occur along the outer continental shelf and slope, normally in waters colder than 68°F (20°C) (Jefferson & Lynn, 1994). Northern right whale dolphins generally move nearshore only in areas where the continental shelf is narrow or where productivity on the shelf is especially high (Smith et al., 1986).

Northern right whale dolphins are not present in the Hawaii Study Area.

Off California, the northern right whale dolphin is known to occur year-round, but abundance and distribution vary seasonally (Becker et al., 2014; Dohl et al., 1983; Douglas et al., 2014b; Forney & Barlow, 1998b). Northern right whale dolphins are primarily found off California during the colder water months, with distribution shifting northward into Oregon and Washington as water temperatures increase during late spring and summer (Barlow, 1995; Forney & Barlow, 1998b; Forney et al., 1995; Henderson et al., 2014). In the cool water period, the peak abundance of northern right whale dolphins in the California Study Area corresponds closely with the peak abundance of squid (Forney & Barlow, 1998b; Jefferson & Lynn, 1994). Northern right whale dolphins were sighted year-round during 16 ship surveys conducted from 2004 to 2008 off southern California, but the majority of the sightings were in winter and spring (Douglas et al., 2014b). There were a total of 92 sightings of northern right whale dolphin during seven systematic ship surveys off the U.S. west coast in summer and fall between 1991 and 2014, but the majority of these sightings were north of Point Conception (34.4°N), and there were no sightings off California during the unusually warm water conditions present in 2014 (Barlow, 2016)

As noted above, in the warm water periods, the northern right whale dolphin is not as abundant in California waters due to shifting distributions north into Oregon and Washington (Barlow, 1995; Becker et al., 2018; Forney & Barlow, 1998b; Forney et al., 1995). Based on habitat models developed with line-transect survey data collected off the U.S. west coast during summer and fall from 1991 to 2009, Becker et al. (2016) found that encounters of northern right whale dolphin increased in shelf and slope waters, and encounters decreased substantially in waters warmer than approximately 64°F (18°C). Recent habitat models that included additional survey effort collected in 2014 and 2018 confirmed that in the summer and fall, northern right whale dolphins were generally found in the coolest waters off the U.S. west coast (Becker et al., 2020). Northern right whale dolphins also tend to occur further offshore of California during the summer months (Douglas et al., 2014b; Forney & Barlow, 1998b).

C.6.3.20.3 Population Trends

Abundance estimates derived from both design- and model-based analyses show considerable seasonal and yearly variability (Barlow, 1995, 2016; Becker et al., 2020; Becker et al., 2014; Becker et al., 2018; Forney & Barlow, 1998b; Forney et al., 1995), making it difficult to assess trends in abundance (Carretta et al., 2023b). Examination of sighting and stranding data from the 1950s through 2012 suggest that the relative occurrence of northern right whale dolphin in the Southern California Bight has not changed over that period (Smultea & Jefferson, 2014).

C.6.3.20.4 Population Threats

Northern right whale dolphins are susceptible to interactions with fisheries and entanglement in fishing gear. The most recent monitoring data from 2015 through 2019 indicate that the estimate of mortality or serious injury of this species in the California drift gillnet fishery is 0.53 individuals annually (Carretta et al., 2021a).

Climate change has increasingly become a threat to marine mammals, including dolphins. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.21 Fraser's Dolphin (Lagenodelphis hosei)

Since its discovery in 1956, Fraser's dolphin was known only from skeletal specimens until it was once again identified in the early 1970s (Perrin et al., 1973). Although still one of the least-known species of cetaceans, Fraser's dolphin has become much better described as a species in recent years.

C.6.3.21.1 Status and Management

Fraser's dolphin is protected under the MMPA and is not listed under the ESA. For the MMPA stock assessment reports, there is a single Pacific management stock including only animals found within the U.S. EEZ of the Hawaiian Islands (Carretta et al., 2023b).

C.6.3.21.2 Habitat and Geographic Range

In the offshore eastern tropical Pacific, this species is distributed mainly in upwelling modified waters (Aguayo & Sanchez, 1987; Au & Perryman, 1985; Ferguson, 2005; Miyazaki & Wada, 1978; Reilly, 1990).

Fraser's dolphins have been documented within Hawaiian waters with the first published sightings occurring during a 2002 cetacean survey (Barlow, 2006). Fraser's dolphin vocalizations have also been documented in the Hawaiian Islands (Barlow et al., 2008; Barlow et al., 2004). During three systematic surveys of the Hawaiian Islands EEZ in the summer/fall of 2002, 2010, and 2017, there were a total of nine Fraser's dolphin sightings (Bradford et al., 2021). Based on the 2010 survey, Fraser's dolphin was one of the most abundant species within the Hawaiian Islands EEZ, having a notably large mean group size of 283 animals in the four pods observed (Bradford et al., 2013; Bradford et al., 2021). In small boat surveys nearshore around the Hawaiian Islands, Fraser's dolphins have only been seen twice in 10 years (both times off the Kona Coast of Hawaii Island) (Baird et al., 2013b). It is not known whether Fraser's dolphins found in Hawaiian waters are part of the same population that occurs in the eastern tropical Pacific (Carretta et al., 2023b).

Fraser's dolphins are not present in the California Study Area.

C.6.3.21.3 Population Trends

The available abundance estimates for Fraser's dolphins have broad and overlapping confidence intervals, thus precluding a robust assessment of population trends (Carretta et al., 2017b; Carretta et al., 2023b).

C.6.3.21.4 Population Threats

Fraser's dolphins are susceptible to interactions with fisheries and entanglement in fishing gear. In Hawaii, Fraser's dolphins are threatened by the deep-set longline fishery and the shallow-set longline fishery. However, the most recent monitoring data from 2014 through 2018 indicate that there have been no observed entanglements or hookings of this species in these fisheries (Bradford, 2018a; Bradford, 2018b; Bradford et al., 2017; Carretta et al., 2023b; McCracken, 2019).

Climate change has increasingly become a threat to marine mammals, including dolphins. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.22 Risso's Dolphin (Grampus griseus)

C.6.3.22.1 Status and Management

Risso's dolphin is protected under the MMPA and is not listed under the ESA. For the MMPA stock assessment reports, Risso's dolphins within the Pacific U.S. EEZ are divided into two separate stocks: the Hawaiian stock in Hawaiian waters and the California, Oregon and Washington stock that occurs in the California Study Area (Carretta et al., 2023b).

C.6.3.22.2 Habitat and Geographic Range

In the Pacific, Risso's dolphins are found in the waters around the Hawaiian Islands (Bradford et al., 2017) and off the U.S. west coast (Barlow, 2016). Studies have documented that Risso's dolphins are found along the continental slope, over the outer continental shelf (Baumgartner, 1997; Canadas et al., 2002; Cetacean and Turtle Assessment Program, 1982; Davis et al., 1998b; Green et al., 1992; Kruse et al., 1999; Mignucci-Giannoni, 1998), and over submarine canyons (Mussi et al., 2004).

(Bradford et al., 2021) In December–January 2014 using a passive acoustic recording device onboard an unmanned glider south of Oahu, Risso's dolphins were acoustically detected throughout the entire survey except for the southernmost part between Bishop Seamount and McCall Seamount (Klinck et al., 2015). In addition, Risso's dolphins were sighted eight times during Navy monitoring activities within the Hawaii Range Complex between 2005 and 2012 (HDR, 2012). During three systematic ship surveys of waters within the Hawaiian Islands EEZ in summer/fall of 2002, 2010, and 2017, there was a total of 28 sightings of Risso's dolphin, with yearly mean group size estimates ranging from 15.0 to 26.6 animals (Bradford et al., 2021). Most of these sightings were in deep waters. Sighting data from these surveys, as well as additional systematic ship surveys conducted in Hawaiian waters from 2000 to 2020 allowed for the development of a habitat-based density model for Risso's dolphin (Becker et al., 2022b). Model predictions showed highest densities offshore of the islands in approximately 2,500 m to 4,500 m depth, and mid-range densities further offshore.

Risso's dolphin exhibits an apparent seasonal shift in distribution off the U.S. west coast, with movements from California waters north into Oregon and Washington waters in summer (Carretta et al., 2000; Forney & Barlow, 1998b; Green et al., 1992; Soldevilla et al., 2008). During ship surveys conducted quarterly off Southern California from 2004 to 2008, Risso's dolphins were encountered year-round, with highest encounters during the cold-water months (Douglas et al., 2014b), consistent with previously observed seasonal shifts in distribution (Carretta et al., 2000; Forney & Barlow, 1998b; Henderson et al., 2014; Soldevilla, 2008). Off California, they are commonly seen over the slope and in offshore waters (Barlow & Forney, 2007; Forney et al., 1995; Jefferson et al., 2008). This species is frequently observed in the waters surrounding SCI, California (Carretta et al., 2000). Habitat models derived from line-transect survey data collected between 1991 and 2009 off the U.S. west coast show that Risso's dolphins exhibit a disjunctive longitudinal distribution, suggesting that there may be two separate populations in this area, although additional genetic data are required for confirmation (Becker et al., 2016). Habitat models built using additional survey data collected in 2014 and 2018 confirmed this distribution pattern, showing that Risso's dolphin are generally concentrated either along the continental shelf (mainly south of 38° N) or in deep offshore waters, with a distinct longitudinal absence between these two areas (Becker et al., 2020).

C.6.3.22.3 Population Trends

In Hawaii, current abundance data do not support a robust trend analysis for this population (Carretta et al., 2023b).

Based on density estimates derived from aerial survey data collected from 2008 to 2013, the abundance of Risso's dolphin in Southern California waters appears to have increased (Jefferson et al., 2014). Examination of sighting and stranding data from the 1950s through 2012 also indicated an increase in the relative occurrence of this species in the Southern California Bight over this time period (Smultea & Jefferson, 2014). For Risso's dolphins in California, Oregon, and Washington waters, differences in estimated abundance between survey years is most likely due to the inter-annual variability in species distribution rather than a true abundance trend (Barlow, 1995, 2016; Becker et al., 2020; Becker et al., 2014; Becker et al., 2018; Forney & Barlow, 1998b; Forney et al., 1995).

C.6.3.22.4 Population Threats

Risso's dolphins are susceptible to interactions with fisheries and entanglements in fishing gear. Most recent monitoring data for this species from 2010 through 2014 indicate that the estimate of humancaused mortality or serious injury to Risso's dolphins in the California drift gillnet fishery is an average of 1.3 individuals annually (Carretta et al., 2017a; Carretta et al., 2023b). Additionally, stranding data along the U.S. West Coast during 2010 through 2014 yields a minimum estimate of 12 fishery-related mortalities of Risso's dolphins (Carretta et al., 2017a). There are also historical records of this species entangled and seriously injured or killed in ground fisheries and in the Southern California squid purse seine fishery.

In Hawaii, Risso's dolphins are threatened by the deep-set longline fishery and the shallow-set longline fishery. The most recent monitoring data from 2017 through 2021 indicate that there were 4 mortalities or serious injuries of this species in the shallow-set longline fishery, and 4 in the deep-set longline fishery (Bradford, 2018a; Bradford, 2018b; Bradford et al., 2017; Carretta et al., 2023b; McCracken, 2019). Additionally, there are no estimates of mortality or serious injury of this species in Hawaii nearshore gillnet or hook and line fisheries; however, nearshore fisheries are not monitored for protected species bycatch (Carretta et al., 2023b).

Climate change has increasingly become a threat to marine mammals, including dolphins. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.23 Dall's Porpoise (*Phocoenoides dalli*)

C.6.3.23.1 Status and Management

This species is protected under the MMPA and is not listed under the ESA. Dall's porpoise is managed by NMFS in U.S. Pacific waters as two stocks: (1) a California, Oregon, and Washington stock and (2) an Alaskan stock (Carretta et al., 2023b).

C.6.3.23.2 Habitat and Geographic Range

Dall's porpoise is one of the most common odontocete species in north Pacific waters (Calambokidis & Barlow, 2004; Ferrero & Walker, 1999; Houck & Jefferson, 1999; Jefferson, 1991; Jefferson et al., 2008; Williams & Thomas, 2007; Zagzebski et al., 2006). Dall's porpoise is found from northern Baja California, Mexico, north to the northern Bering Sea and south to southern Japan (Jefferson et al., 1993). However, the species is only common between 32° N and 62° N in the eastern North Pacific (Houck & Jefferson, 1999; Morejohn, 1979). It is typically found in waters at temperatures less than 63° F (17° C) with depths of more than 180 m (Houck & Jefferson, 1999; Reeves et al., 2002).

Dall's porpoises are not present in the Hawaii Study Area.

Dall's porpoise distribution off the U.S. west coast is highly variable between years, most likely due to changes in oceanographic conditions (Barlow et al., 2009b; Becker et al., 2010; Becker et al., 2012b; Becker et al., 2018; Forney & Barlow, 1998b; Forney et al., 2012). North-south movements in California, Oregon, and Washington have been observed, with Dall's porpoise shifting their distribution southward during cooler-water periods on both interannual and seasonal time scales (Becker et al., 2014; Becker et al., 2018; Boyd et al., 2017; Forney & Barlow, 1998b). Based on habitat models developed using 1991–2018 survey data collected in waters off the U.S. west coast during summer and fall, Dall's porpoise density increased in shelf and slope waters , and decreased substantially in waters warmer than approximately 63°F (17°C) (Becker et al., 2020). These patterns are consistent with previous habitat modeling efforts using a subset of the same data (Barlow et al., 2009b; Becker et al., 2010; Becker et al., 2016; Becker et al., 2012b; Becker et al., 2014; Forney et al., 2012; Henderson et al., 2014).

During ship surveys conducted quarterly off southern California from 2004 to 2008, Dall's porpoise was encountered year-round, with highest encounters during the cold-water months (Douglas et al., 2014b). There were only five Dall's porpoise sightings during 18 aerial surveys conducted year-round in the SOCAL Range Complex from 2008 to 2013 (Jefferson et al., 2014).

C.6.3.23.3 Population Trends

Because there is high annual variability in the distribution and abundance of Dall's porpoise off the U.S. west coast, no long-term trends have been identified (Carretta et al., 2023b). Examination of sighting and stranding data from the 1950s through 2012 suggest that the relative occurrence of this species in the Southern California Bight has not changed substantially over this time period (Smultea & Jefferson, 2014).

C.6.3.23.4 Population Threats

Dall's porpoises are susceptible to interactions with fisheries and entanglement in fishing gear. The most recent monitoring data from 2015 through 2019 indicate that the estimate of mortality or serious injury of this species in the California drift gillnet fishery is 0.46 individuals annually (Carretta, 2021). Mortalities of Dall's porpoises have historically been recorded from ground fisheries off the U.S. West

Coast; however, data from 2012 through 2016 indicate there were no mortalities of this species in ground fisheries in the region during that time period (Carretta et al., 2023b; Jannot et al., 2018).

Climate change has increasingly become a threat to marine mammals, including porpoises. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.24 Harbor Porpoise (Phocoena phocoena)

C.6.3.24.1 Status and Management

Harbor porpoise is protected under the MMPA and is not listed under the ESA. This species is managed by NMFS in Pacific waters as six separate stocks including: 1) the Morro Bay stock, 2) the Monterey Bay stock, 3) the San Francisco-Russian River stock, 4) the Northern California/Southern Oregon stock, 5) the Northern Oregon/Washington coast stock, and 6) the Inland Washington stock (Carretta et al., 2023b). The southern range limit for this species is considered Point Conception (SAR). Based on published range boundaries (Carretta et al., 2023b), the stocks expected to occur within the California portion of the HCTT Study Area include the Northern California/Southern Oregon stock, the San Francisco-Russian River stock, the Monterey Bay stock, and the Morro Bay stock.

C.6.3.24.2 Habitat and Geographic Range

Harbor porpoises are not present in the Hawaii Study Area.

Harbor porpoise is a cool water species that occurs in cool temperate to subpolar regions of the Northern Hemisphere (Jefferson et al., 2016). In the eastern North Pacific harbor porpoise are found from Alaska south to Point Conception, California, generally in nearshore coastal and inland waters within a mile or two of shore and in waters <200 m deep (Barlow, 1988). Although harbor porpoises exhibit a continuous distribution along the U.S. west coast, significant genetic differences have been identified from multiple regions of California, Oregon, and Washington (Chivers et al., 2007). Genetic differences and density discontinuities identified from aerial surveys led to the identification of the separate harbor porpoise stocks (Carretta et al., 2023b).

Calambokidis et al. (2024) defined two non-hierarchical small and resident BIAs for the Monterey Bay and the Morro Bay stocks of harbor porpoise off California (Figure C-30). The Morro Bay BIA is 4,255 km² in size and the Monterey Bay BIA is 3,455 km² in size; both encompass waters from land to the 200 m isobath within the defined ranges for the respective stocks, and are identical in size to the original BIAs defined in 2015 (Calambokidis et al., 2015c).

C.6.3.24.3 Population Trends

Stratified distance sampling analysis within a Bayesian hierarchical model were recently used to examine trends in harbor porpoise abundance off the California coast (Forney et al., 2020). For the Morro Bay stock, analysis of data collected between 1986 and 2012 indicated that a marked increase in population occurred after 1991, when gillnet bycatch was largely eliminated within this stock's range.

For the Monterey Bay stock, analysis of data collected between 1986 and 2013 showed that during this period the size of this population increased from approximately 1,500 animals to more than 3,500 animals (Forney et al., 2020). Most of the increase occurred after gillnet fisheries were eliminated within this stock's range.

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Figure C-30: Harbor Porpoise Small and Resident BIAs in the California Study Area

For the San Francisco-Russian River stock, analysis of data collected between 1986 and 2017 showed fluctuating population numbers over this period. Following the elimination of gillnets from the range of this stock in 1987, the population increased to a peak of approximately 13,500 animals in 2005 (Forney et al., 2020). Subsequently the size of the population appeared to decrease and level out to approximately 7,000 to 8,000 animals from 2010 to 2017. The apparent decrease after 2005 could be due to a shift in the distribution of animals into San Francisco Bay or could be a result of the large uncertainty in the 2002 to 2007 abundance estimates (Forney et al., 2020).

For the Northern California/Southern Oregon stock, analysis of data collected between 1989 and 2016 within the California portion of this stock's range shows a stable population over this time period, although there is high uncertainty in the abundance estimates (Forney et al., 2020). Since this analysis did not include the southern Oregon portion of this stock's range, a population trend analysis is not available for this stock (Carretta et al., 2023b).

C.6.3.24.4 Population Threats

Harbor porpoises are susceptible to interactions with fisheries and entanglement in fishing gear. Historically, white sea bass and halibut fisheries near Morro Bay and Monterrey Bay attributed to mortalities or serious injuries of this species (Carretta et al., 2023b). However, this fishery was banned from placing gillnets inshore of 110 m in 2002, which limited the interaction of harbor porpoises with this fishery. From 2015 through 2019, there have been no recorded strandings due to fishery interactions for the Morro Bay stock (Carretta et al., 2021a). During the same time period, there was one recorded stranding tied to fisheries for the Monterrey Bay stock (Carretta et al., 2021a).

Coastal gillnets have also been banned throughout the range of the San Francisco-Russian River stock; however, there have been 3 fishery-related strandings of this species from 2015 through 2019. It was determined that net fisheries were responsible for the strandings. From 2017 through 2021, there were no recorded strandings of the Northern California/Southern Oregon stock of harbor porpoises from fishery interactions (Carretta et al., 2023a).

Climate change has increasingly become a threat to marine mammals, including porpoises. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021). The northward expansion of bottlenose dolphins (due to climate change and sea temperature shifts) has increasingly overlapped with the range of the harbor porpoise. As a result, there have been increased instances of dolphin aggressions towards this species, which in turn could result in increased strandings (Gulland et al., 2022).

C.6.3.25 Cuvier's Beaked Whale (Ziphius cavirostris)

C.6.3.25.1 Status and Management

Cuvier's beaked whale is protected under the MMPA and is not listed under the ESA. There are three stocks of Cuvier's beaked whale recognized by NMFS: an Alaska stock, a California/Oregon/Washington stock, and a Hawaii stock (Carretta et al., 2023b). Animals in California or Hawaii are assigned to their respective stock.

C.6.3.25.2 Habitat and Geographic Range

Cuvier's beaked whales have an extensive range that includes all oceans, from the tropics to the polar waters of both hemispheres. Cuvier's beaked whales have been encountered in almost all areas of the

Pacific, including offshore areas of the central and eastern North Pacific, wherever surveys have occurred (Hamilton et al., 2009). Cuvier's beaked whales are generally sighted in waters with a bottom depth greater than 200 m and are frequently recorded in waters with bottom depths greater than 1,000 m (Bradford et al., 2013; Falcone et al., 2009; Jefferson et al., 2015). Acoustic sampling of bathymetrically featureless areas off Southern California detected many beaked whales over an abyssal plain, which counters a common misperception that beaked whales are primarily found over slope waters, in deep basins, or over seamounts (Griffiths & Barlow, 2016).

Cuvier's beaked whales are regularly found in waters surrounding the Hawaiian Islands (Baird et al., 2015d; Baird et al., 2009; Baird et al., 2013b; Barlow, 2006; Baumann-Pickering et al., 2010; Baumann-Pickering et al., 2014; Bradford et al., 2013; Lammers et al., 2015; Mobley, 2004; Oleson et al., 2013; Oleson et al., 2015; Shallenberger, 1981). In Hawaii, Cuvier's beaked whales have been occasionally observed breaching and this along with their large size and visible blows likely increases their detectability (Baird et al., 2013b). There was a total of 40 Cuvier's beaked whale sightings during systematic ship surveys within the Hawaiian Islands EEZ in 2002, 2010, and 2017, and none of the sightings were in waters within 140 km of the Main Hawaiian Islands (Bradford et al., 2021). Sightings have been reported off the Hawaiian Islands of Lanai, Maui, Hawaii, Niihau, and Kauai, providing strong evidence for both insular and offshore populations of Cuvier's beaked whales in waters of the Hawaiian Islands EEZ (Baird et al., 2015; Baird et al., 2009Mobley, 2004 #986; Baird et al., 2013b; Oleson et al., 2015; Shallenberger, 1981).

BIAs were redefined for a year-round Small and Resident Population area for Cuvier's beaked whales in Hawaiian waters (Kratofil et al., 2023). The parent BIA is 37,157 km² in size and the child BIA encompasses 5,400 km² within this region (Figure C-31) The child BIA was defined based on occurrence data that indicate that Cuvier's beaked whales spend the majority of their time between the 2,000 and 3,500 m isobaths off the leeward side of the Island of Hawaii.

Cuvier's beaked whale is the most commonly encountered beaked whale off the west coast of the U.S. (Carretta et al., 2023b). Research involving tagged Cuvier's beaked whales in the SOCAL Range Complex (Falcone & Schorr, 2011, 2012, 2013, 2014; Falcone et al., 2009) has documented movements in excess of hundreds of km. Schorr et al. (2014) reported that 5 out of 8 tagged whales journeyed approximately 250 km from their tag deployment location and one of these 5 made an extra-regional excursion over 450 km to the south to Mexico and back. During nine systematic ship surveys off the U.S. west coast between 1991 and 2018, there were a total of 91 Cuvier's beaked whale sightings, providing sufficient data to develop a habitat-based density model for this species (Fiedler et al., 2023). The model predicted highest numbers of Cuvier's beaked whales in deep, offshore waters of the study area. Repeated sightings of the same individuals have been reported off SCI in Southern California, which indicates some level of site fidelity (Falcone et al., 2009; Schorr et al., 2017). This species has also frequently been heard on passive acoustic recording devices in the southern portion of the California Study Area (Griffiths & Barlow, 2016; Širović et al., 2016). In a test of drifting passive acoustic recorders off California in the fall of 2014, Griffiths and Barlow (2016) reported beaked whale detections over slopes and seamounts, which was not unexpected, and also over deep ocean abyssal plains, which was a novel finding.


Figure C-31: Cuvier's Beaked Whale Small and Resident BIAs in the Hawaii Study Area

C.6.3.25.3 Population Trends

For the Hawaiian Islands, the currently available data precludes evaluation of population trends for Cuvier's beaked whales for the Hawaiian stock (Carretta et al., 2023b). Yearly abundance estimates for the Hawaiian Islands EEZ based on line-transect analyses are highly variable and have very broad confidence intervals, but this is likely due to the substantial variability in encounter rates during the individual survey years rather than a true change in population (Bradford et al., 2021).

A Bayesian trend analysis of systematic survey data collected from 1991 to 2008 suggested a decline in the abundance of beaked whales found in waters off California, Oregon, and Washington (Moore & Barlow, 2013). A more recent analysis that included additional survey data collected in 2014 indicated that the mean annual rate of population decline during this longer period was -3.0 percent per year (Moore & Barlow, 2017a). However, data from this study also indicated that while Cuvier's beaked whales along the entire U.S. west coast appear to have decreased in abundance from high values in 1991–1993, that decline now appears to have leveled off. Further, an acoustic-based estimate of Cuvier's beaked whale abundance in 2016 showed an increase from the previous estimates (Barlow et al., 2021). Unfortunately, this single estimate does not allow for a robust trend assessment given the difference in methodologies, but the greater precision in abundance estimates using acoustic-based methods highlights the potential of using this method for future trend assessments of this population (Barlow et al., 2021).

When considering beaked whales within the California Study Area, multiple studies have indicated that for waters surrounding the Navy training and testing areas in southern California the abundance of beaked whales remains high, including specifically where Navy has been training and testing for decades. Results from passive acoustic monitoring and other research have estimated regional Cuvier's beaked whale densities that were higher than indicated by the NMFS's broad-scale visual surveys for the U.S. west coast (Debich et al., 2015a; Debich et al., 2015b; Falcone & Schorr, 2012, 2014; Hildebrand et al., 2009; Moretti, 2016; Širović et al., 2016; Smultea & Jefferson, 2014). Research also indicates higher than expected residency in the Navy's instrumented Southern California Anti-Submarine Warfare Range in particular (Falcone & Schorr, 2012). Photo identification studies in the SOCAL Range Complex have identified approximately 100 individual Cuvier's beaked whale individuals with 40 percent having been seen in one or more prior years, with re-sightings up to 7 years apart (Falcone & Schorr, 2014). The documented residency by many Cuvier's beaked whales over multiple years indicate that a stable population may exist in that small portion of the stock's overall range (Falcone & Schorr, 2014; Falcone et al., 2009; Schorr et al., 2017). Based on Bayesian mark-recapture estimates of Cuvier's beaked whales in the San Nicolas Basin from photo-identification data collected from 2007 to 2018, an apparent decline of -0.8 percent of individuals per year was estimated (Curtis et al., 2020). However, this study also confirmed long-term site fidelity and high apparent annual survival rates, but the data did not support any definitive conclusions regarding population trends.

C.6.3.25.4 Population Threats

Cuvier's beaked whales are susceptible to interactions with fisheries and entanglements in fishing gear. Off the U.S. West Coast, the California swordfish fishery is the only fishery that has interacted with Cuvier's beaked whales in the region (Carretta et al., 2023b). However, the use of acoustic pingers in the fishery have resulted in no observed entanglements of this species since 1996 (Barlow & Cameron, 2003). Off Hawaii, Cuvier's beaked whales are threatened by the deep-set longline fishery and the shallow-set longline fishery. However, the most recent monitoring data from 2014 through 2018 indicate that there were no mortalities or serious injuries of this species in these fisheries (Bradford, 2018a; Bradford, 2018b; Bradford et al., 2017; Carretta et al., 2023b; McCracken, 2019).

Anthropogenic noise such as sonar could disrupt their foraging behavior and echolocation activities of beaked whales and may result in unknown levels of injury or mortality (Carretta et al., 2023b; Tyack et al., 2011)There have been several stranding events of multiple beaked whale species over the years that may be associated with the use of sonar. It was found that tagged Cuvier's beaked whales demonstrated avoidance behaviors such as prolonged diving and cessation of echolocation clicks during sonar exposure to sonar (DeRuiter et al., 2013). In the Caribbean, monitoring of Blainville's beaked whales through hydrophones also demonstrated avoidance behaviors when exposed to sonar (Tyack et al., 2011). The absence of beaked whales in the California drift gillnet fisheries using pinging technology also provides evidence that this species may have increased sensitivity to anthropogenic noise (Carretta et al., 2023b).

Climate change has increasingly become a threat to marine mammals, including beaked whales. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.26 Baird's Beaked Whale (Berardius bairdii)

C.6.3.26.1 Status and Management

Baird's beaked whale is protected under the MMPA and is not listed under the ESA. Baird's beaked whale stocks are defined for two separate areas within Pacific U.S. waters where they are found: (1) Alaska and (2) California, Oregon, and Washington (Carretta et al., 2023b).

C.6.3.26.2 Habitat and Geographic Range

Baird's beaked whales are not present in the Hawaii Study Area.

Baird's beaked whale occurs mainly in deep waters over the continental slope, near oceanic seamounts, and areas with submarine escarpments, although they may be seen close to shore where deep water approaches the coast (Jefferson et al., 2008; Kasuya, 2009). This species is generally found throughout the colder waters of the North Pacific, ranging from off Baja California, Mexico, to the Aleutian Islands of Alaska (Jefferson et al., 2008; MacLeod & D'Amico, 2006), although they are found mainly north of 28° N in the eastern Pacific (Kasuya & Miyashita, 1997; Reeves et al., 2003).

Along the U.S. west coast, Baird's beaked whales are seen primarily along the continental slope, from late spring to early fall (Carretta et al., 2010; Green et al., 1992; Hamilton et al., 2009). Baird's beaked whales are sighted less frequently and are presumed to be farther offshore during the colder water months of November through April (Carretta et al., 2023b). Based on habitat-based density models developed using 1991–2018 survey data collected off the U.S. west coast during summer and fall (Becker et al., 2020), encounters of Baird's beaked whale increased in waters near the 2,000 m isobath. These patterns are consistent with previous habitat modeling efforts using a subset of the same data (Barlow et al., 2009b; Forney et al., 2012). Yearly density predictions from 1996 to 2018 showed relatively low variability in annual distribution patterns (Becker et al., 2020).

C.6.3.26.3 Population Trends

Bayesian trend analyses indicated that the abundance of Baird's beaked whales off the U.S. west coast has remained stable or increased slightly from 1991 to 2014 (Moore & Barlow, 2017a).

C.6.3.26.4 Population Threats

Baird's beaked whales are susceptible to entanglement in fishing gear and vessel strikes. Off the U.S. West Coast, the California large drift gillnet fishery is the only known fishery that has interacted with beaked whales in the region (Carretta et al., 2023b). However, the use of the use of acoustic pingers in this fishery has resulted in no observed entanglements of any beaked whale species since 1996 (Barlow & Cameron, 2003). Additionally, there was one recorded vessel strike of this species in 2016 that resulted in mortality (Carretta et al., 2021a)

Anthropogenic noise such as sonar could disrupt their foraging behavior and echolocation activities of beaked whales and may result in unknown levels of injury or mortality (Carretta et al., 2023b; Tyack et al., 2011). There have been several stranding events of multiple beaked whale species over the years that may be associated with the use of sonar. It was found that tagged Cuvier's beaked whales demonstrated avoidance behaviors such as prolonged diving and cessation of echolocation clicks during sonar exposure to sonar (DeRuiter et al., 2013). In the Caribbean, monitoring of Blainville's beaked whales through hydrophones also demonstrated avoidance behaviors when exposed to sonar (Tyack et al., 2011). The absence of beaked whales in the California drift gillnet fisheries using pinging technology also provides evidence that this species may have increased sensitivity to anthropogenic noise (Carretta et al., 2023b).

Climate change has increasingly become a threat to marine mammals, including beaked whales. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.27 Blainville's Beaked Whale (Mesoplodon densirostris)

C.6.3.27.1 Status and Management

Blainville's beaked whale is protected under the MMPA and is not listed under the ESA. In Hawaii and based on the number of sightings and genetic analysis of individuals around the Hawaiian Islands, NMFS recognizes a Hawaiian stock of Blainville's beaked whale (Carretta et al., 2023b). Due to the difficulty in distinguishing different *Mesoplodon* species from one another at sea during visual surveys, off the U.S. west coast NMFS designated a single management unit that includes all *Mesoplodon* species known to occur in these waters. This is the case in the California Study Area where six species of *Mesoplodon* beaked whales are represented by a single California/Oregon/Washington stock, including Blainville's beaked whale (Carretta et al., 2023b).

C.6.3.27.2 Habitat and Geographic Range

Blainville's beaked whales are one of the most widely distributed of the distinctive toothed whales within the *Mesoplodon* genus, found in both temperate and tropical waters (Jefferson et al., 2008; MacLeod & Mitchell, 2006). They are found mostly offshore in deeper waters along the California coast, Hawaii, Fiji, Japan, and Taiwan, as well as throughout the eastern tropical Pacific (Leslie et al., 2005; MacLeod & Mitchell, 2006; Mead, 1989).

Blainville's beaked whales are regularly sighted in Hawaiian waters (Baird et al., 2015a; Baird et al., 2003b; Baird et al., 2006; Barlow, 2006; Bradford et al., 2017; McSweeney et al., 2007), and their vocalizations have been routinely detected in acoustic monitoring in the Hawaiian Islands (Henderson et al., 2015; Klinck et al., 2015; Lammers et al., 2015; Manzano-Roth et al., 2016; Manzano-Roth et al., 2013; Rankin & Barlow, 2007). There were a total of 15 Blainville's beaked whale sightings during

systematic ship surveys within the Hawaiian Islands EEZ in 2002, 2010, and 2017, and none of the sightings were in waters within 140 km of the Main Hawaiian Islands (Bradford et al., 2021).

Blainville's beaked whale has been detected off the coast of Oahu, Hawaii for prolonged periods annually, and this species is consistently observed in the same site off the west coast of the Island of Hawaii (Abecassis et al., 2015; Baird et al., 2006; McSweeney et al., 2007). Thirteen Blainville's beaked whales were satellite tagged off Hawaii Island between 2006 and 2012 with data records ranging from 15 to 159 days (Baird et al., 2015a; Baird et al., 2011). One tagged individual ranged from approximately 18 km to 573 km from land and moved a total of over 900 km from the initial tag location in 20 days. Similar data over an 8-day period for an individual tagged off Kauai showed movement on and off the Navy's instrument range at PMRF) three times before transiting to the southwest over a distance of approximately 100 km from the original tag location (Baird et al., 2015e).

BIAs were redefined for a year-round Small and Resident Population area for Blainville's beaked whales off the west coast and North Kohala portion of the Island of Hawaii, extending to the west and north to encompass waters off Maui Nui and Oahu (Kratofil et al., 2023). The parent BIA is 78,714 km² in size and the child BIA encompasses 4,214 km² within this region, representing an area of intensified use off the west coast and North Kohala portion of the Island of Hawaii (Figure C-32).

There are a handful of known records of Blainville's beaked whale from the coast of California and Baja California, Mexico, but the species does not appear to be common in the California portion of the Study Area (Hamilton et al., 2009; Mead, 1989; Pitman et al., 1988). *Mesoplodon* beaked whales were not detected during 15 aerial surveys conducted in the Southern California Range Complex from 2008 through 2012 (Smultea & Jefferson, 2014).

C.6.3.27.3 Population Trends

For the Hawaiian Islands, the currently available data precludes evaluation of population trends for Blainville's beaked whales in the Hawaiian stock (Carretta et al., 2023b). Acoustic monitoring using the Navy range hydrophones off Kauai from 2010 to 2014 suggest a low but stable abundance of *Mesoplodon* beaked whales at that location (Moretti, 2016).

A Bayesian trend analysis of systematic survey data collected from 1991 to 2008 suggested a decline in the abundance of beaked whales found in waters off California, Oregon, and Washington (Moore & Barlow, 2013). However, a more recent study that included data from an additional survey conducted in 2014 indicated that the pattern seen for the U.S. west coast from 1991 to 2014 indicates a reversal in that downward trend, and estimates a 0.87 percent probability of increase during this period (Moore & Barlow, 2017a).

C.6.3.27.4 Population Threats

Blainville's beaked whales are susceptible to fisheries interactions and entanglement in fishing gear. Off the U.S. West Coast, the California large drift gillnet fishery is the only known fishery that has interacted with beaked whales in the region (Carretta et al., 2023b). However, the use of the use of acoustic pingers has resulted in no observed entanglements of any beaked whale species in this fishery since 1996 (Barlow & Cameron, 2003).



Figure C-32: Blainville's Beaked Whale Small and Resident BIAs in the Hawaii Study Area

Off Hawaii, Blainville's beaked whales are threatened by the deep-set longline fishery and the shallowset longline fishery. However, the most recent monitoring data from 2014 through 2018 indicate that there were no mortalities or serious injuries of this species in these fisheries (Bradford, 2018a; Bradford, 2018b; Bradford et al., 2017; Carretta et al., 2023b; McCracken, 2019). Additionally, there are no estimates of mortality or serious injury of this species in Hawaii nearshore gillnet or hook and line fisheries because nearshore fisheries are not monitored for protected species bycatch (Carretta et al., 2023b).

Anthropogenic noise such as sonar could disrupt their foraging behavior and echolocation activities of beaked whales and may result in unknown levels of injury or mortality (Carretta et al., 2023b; Tyack et al., 2011). There have been several stranding events of multiple beaked whale species over the years that may be associated with the use of sonar. It was found that tagged Cuvier's beaked whales demonstrated avoidance behaviors such as prolonged diving and cessation of echolocation clicks during sonar exposure to sonar (DeRuiter et al., 2013). In the Caribbean, monitoring of Blainville's beaked whales through hydrophones also demonstrated avoidance behaviors when exposed to sonar (Tyack et al., 2011). The absence of beaked whales in the California drift gillnet fisheries using pinging technology also provides evidence that this species may have increased sensitivity to anthropogenic noise (Carretta et al., 2023b).

Climate change has increasingly become a threat to marine mammals, including beaked whales. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.28 Longman's Beaked Whale (Indopacetus pacificus)

C.6.3.28.1 Status and Management

Longman's beaked whale is protected under the MMPA and is not listed under the ESA. Only one, the Hawaiian stock, is identified for the Pacific (Carretta et al., 2023b). This stock includes animals found within the Hawaiian Islands EEZ and adjacent high sea waters.

C.6.3.28.2 Habitat and Geographic Range

Longman's beaked whale is found in warm tropical waters, with most sightings occurring in waters with sea surface temperatures warmer than 78 °F (26°C) (Anderson et al., 2006; MacLeod & D'Amico, 2006; MacLeod et al., 2006). Although the full extent of this species' distribution is not fully understood, there have been many recorded sightings at various locations in tropical waters of the Pacific and Indian Oceans (Afsal et al., 2009; Dalebout et al., 2002; Dalebout et al., 2003; Moore, 1972). Sighting records of this species in the Indian Ocean showed that Longman's beaked whales are typically found in waters over deep bathymetric slopes of 200 to 2,000+ m (Anderson et al., 2006). In the Pacific, records of this species indicate presence in the eastern, central, and western Pacific, including waters off the coast of Mexico (Hamilton et al., 2009).

There was a total of 10 Longman's beaked whale sightings during systematic ship surveys within the Hawaiian Islands EEZ in 2002, 2010, and 2017 (Bradford et al., 2021). Observed group sizes during these three surveys were highly variable, ranging from approximately 7 to 99 individuals (Bradford et al., 2017). Longman's beaked whales have also been sighted off Kona (Cascadia Research, 2012) and there have been two known strandings of this species in the main Hawaiian Islands (Maldini et al., 2005; National Marine Fisheries Service, 2015c; West et al., 2012).

Longman's beaked whales are not present in the California Study Area.

C.6.3.28.3 Population Trends

The high uncertainty between the available design-based abundance estimates based on data collected during the 2002, 2010, and 2017 systematic surveys of the Hawaiian Islands EEZ precludes the evaluation of population trends for Longman's beaked whales (Carretta et al., 2023b).

C.6.3.28.4 Population Threats

The Longman's beaked whale is susceptible to fisheries interactions and entanglement in fishing gear. Longman's beaked whales are threatened by the Hawaiian deep-set longline fishery and the shallow-set longline fishery; however, the most recent monitoring data from 2014 through 2018 indicate that there were no mortalities or serious injuries of this species in these fisheries (Bradford, 2018a; Bradford, 2018b; Bradford et al., 2017; Carretta et al., 2023b; McCracken, 2019). Additionally, there are no estimates of mortality or serious injury of this species in Hawaii nearshore gillnet or hook and line fisheries because nearshore fisheries are not monitored for protected species bycatch (Carretta et al., 2023b).

Anthropogenic noise such as sonar could disrupt their foraging behavior and echolocation activities of beaked whales and may result in unknown levels of injury or mortality (Carretta et al., 2023b; Tyack et al., 2011). There have been several stranding events of multiple beaked whale species over the years that may be associated with the use of sonar. It was found that tagged Cuvier's beaked whales demonstrated avoidance behaviors such as prolonged diving and cessation of echolocation clicks during sonar exposure to sonar (DeRuiter et al., 2013). In the Caribbean, monitoring of Blainville's beaked whales through hydrophones also demonstrated avoidance behaviors when exposed to sonar (Tyack et al., 2011). The absence of beaked whales in the California drift gillnet fisheries using pinging technology also provides evidence that this species may have increased sensitivity to anthropogenic noise (Carretta et al., 2023b).

Climate change has increasingly become a threat to marine mammals, including beaked whales. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.29 Mesoplodont Beaked Whales (California, Washington Oregon stock)

C.6.3.29.1 Status and Management

The six species of Mesoplodont beaked whales known to occur off the U.S. west coast include Blainville's beaked whale (*M. densirostris*), Perrin's beaked whale (*M. perrini*), pygmy beaked whale (*M. gingkodens*), and Hubbs' beaked whale (*M. carlhubbsi*). Due to the difficulty in distinguishing the different *Mesoplodon* species from one another at-sea, and thus due to the lack of species-specific abundance estimates, NMFS has combined six *Mesoplodon* species to make up the California, Oregon, and Washington stock of Mesoplodont beaked whales (Carretta et al., 2023b). None of the *Mesoplodon* species are listed under the ESA.

Of the six species included in this stock, Blainville's beaked whale occurs in Hawaiian waters and is addressed as an individual species in Section C.6.3.27. The other five beaked whale species are not expected to regularly occur in Hawaiian waters.

C.6.3.29.2 Habitat and Geographic Range

Worldwide, beaked whales normally inhabit continental slope and deep ocean waters (greater than 200 m) and are only occasionally reported in waters over the continental shelf (Canadas et al., 2002; Ferguson et al., 2006; MacLeod et al., 2006; Pitman, 2008; Waring et al., 2001). During eight systematic ship surveys off the U.S. west coast between 1991 and 2014, there were multiple Mesoplodont beaked whale sightings, although the majority were not identified to species (Carretta et al., 2023b).

Strandings along the U.S. west coast and elsewhere have provided some indication of marine mammal species range. Perrin's beaked whale is known only from five stranded specimens along the California coastline from 1975 to 1997 (Dalebout et al., 2002; MacLeod et al., 2006). These strandings include two at U.S. Marine Corps Base Camp Pendleton (33°15' N, 117°26' W), and one each at Carlsbad, (33°07' N, 117°20' W), Torrey Pines State Reserve (32°55' N, 117°15' W), and Monterey (36°37' N, 121°55' W) (Dalebout et al., 2002; Mead, 1981). Based on stranding data from the Pacific coast of Mexico, the pygmy beaked whale's range is thought to include deep waters off the Pacific coast of North America (Aurioles-Gamboa & Urban-Ramirez, 1993; Jefferson et al., 2008; Urban-Ramirez & Aurioles-Gamboa, 1992). This species was first described in 1991 from stranded specimens from Peru, and since then, strandings have been recorded along the coasts of both North and South America at Mexico, Peru, and Chile (Pitman & Lynn, 2001; Reyes et al., 1991; Sanino et al., 2007). MacLeod et al. (2006) suggested that the pygmy beaked whale occurs in the eastern Pacific from about 30° N to about 30° South (S). The handful of known records of the ginkgo-toothed beaked whale are from strandings, one of which occurred in California (Jefferson et al., 2015; MacLeod & D'Amico, 2006).

Acoustic monitoring has also provided information on the range for some *Mesoplodon* species in the California Study Area. Beaked whales produce species-specific frequency modulated echolocation pulses and acoustic monitoring devices located at seven sites in the Southern California Bight have recorded the presence of sounds identified as Stejneger's beaked whales and recorded other beaked whale-like frequency modulated pulse types that may possibly be produced by Perrin's beaked whale, Hubbs' beaked whale, and pygmy beaked whales (Baumann-Pickering et al., 2014; Baumann-Pickering et al., 2015; Debich et al., 2015a).

C.6.3.29.3 Population Trends

A Bayesian trend analysis of systematic survey data collected from 1991 to 2008 suggested a decline in the abundance of *Mesoplodon* beaked whales found in waters off California, Oregon, and Washington (Moore & Barlow, 2013). However, a more recent analysis that included additional survey data collected in 2014 indicated *Mesoplodon* beaked whales showed markedly higher abundance in 2014, reversing the declining trend from 1991 to 2008 that had been noted in the previous analysis (Moore & Barlow, 2017a). The increase may have been driven by an influx of tropical species of *Mesoplodon* during the unusually warm ocean conditions in 2014, and additional data are needed to better assess long-term population trends for this stock (Moore & Barlow, 2017a).

C.6.3.29.4 Population Threats

Mesoplodont beaked whales are susceptible to interactions with fisheries and entanglement in fishing gear. Off the U.S. West Coast, the California large drift gillnet fishery is the only known fishery that has interacted with beaked whales in the region (Carretta et al., 2023b).

Anthropogenic noise such as sonar could disrupt their foraging behavior and echolocation activities of beaked whales and may result in unknown levels of injury or mortality (Carretta et al., 2023b; Tyack et al., 2011). There have been several stranding events of multiple beaked whale species over the years

that may be associated with the use of sonar. It was found that tagged Cuvier's beaked whales demonstrated avoidance behaviors such as prolonged diving and cessation of echolocation clicks during sonar exposure to sonar (DeRuiter et al., 2013). In the Caribbean, monitoring of Blainville's beaked whales through hydrophones also demonstrated avoidance behaviors when exposed to sonar (Tyack et al., 2011). The absence of beaked whales in the California drift gillnet fisheries using pinging technology also provides evidence that this species may have increased sensitivity to anthropogenic noise (Carretta et al., 2023b).

Climate change has increasingly become a threat to marine mammals, including beaked whales. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.30 California Sea Lion (Zalophus californianus)

C.6.3.30.1 Status and Management

The California sea lion is protected under the MMPA and is not listed under the ESA. The California sea lion is managed by NMFS as a single U.S. Stock (Carretta et al., 2017b).

C.6.3.30.2 Habitat and Geographic Range

California sea lions do not occur in Hawaii.

California sea lions are distributed in the eastern North Pacific from Puerto Vallarta, Mexico, through the Gulf of California and north along the west coast of North America to the Gulf of Alaska (Barlow et al., 2008; Jefferson et al., 2008; Maniscalco et al., 2004). During the summer breeding season, California sea lions congregate near rookery islands and nearby open-water areas. The primary rookeries off the U.S. West Coast are on San Nicolas, San Clemente, San Miguel, and Santa Barbara Islands (Carretta et al., 2023b; Lowry et al., 2021). This species is frequently found hauled out on human-made structures, including on docks, buoys, barges, and rip-rap or other tidal control structures.

California sea lions are the most commonly observed marine mammal in San Diego Bay (Graham & Saunders, 2015; U.S. Department of the Navy, 2015). There are two "bait" barges near the mouth of San Diego Bay that are haulout locations for California sea lions (U.S. Department of the Navy, 2015). During a pier replacement project at Point Loma from October 2014 to April 2015, an average of about 38 sea lions were observed hauled out with an additional 2–3 individuals in the water (U.S. Department of the Navy, 2015).

During the nonbreeding season, late summer through spring, adult and subadult males migrate north along the coast to Washington and into Puget Sound and return south the following spring (Jeffries, 2014; Lowry & Forney, 2005). Females and juveniles also disperse following the breeding season but tend to stay in waters off California to the north and west of the Channel Islands (Lowry & Forney, 2005; Melin & DeLong, 2000; Thomas et al., 2009).

California sea lions from the west coast of the Baja California Peninsula, Mexico, also migrate north and into waters off Southern California during fall and winter (Lowry & Forney, 2005). These sea lions are not part of the U.S. stock but are considered in the analysis of impacts because they are likely to occur in the Study Area.

California sea lions typically forage in waters over the continental shelf and slope; however, they are also known to occur farther offshore in deep, pelagic waters, particularly when prey is scarce (Jefferson et al., 2008; Melin et al., 2008; Urrutia & Dziendzielewski, 2012; Zavala-Gonzalez & Mellink, 2000).

Tagged California sea lions from Monterey Bay and SNI, California, demonstrated that adult males can travel more than 450 km from shore during longer foraging bouts (Weise et al., 2006; Weise et al., 2010); however, rehabilitated females and subadults normally stay mostly within 65 km of the coast (Thomas et al., 2009). Most individuals stay within 50 km of the rookery islands during the breeding season (Melin & DeLong, 2000). Females breeding and pupping on the Channel Islands typically feed over the continental shelf and generally remain within 150 km north and west of the islands (Kuhn & Costa, 2014; Melin & DeLong, 2000; Melin et al., 2008; Melin et al., 2012). Tagging results showed that lactating females foraging along the coast would travel as far north as Monterey Bay and offshore to the 1,000 m depth (Henkel & Harvey, 2008; Kuhn & Costa, 2014; Melin & DeLong, 2000; Melin et al., 2014; Melin & DeLong, 2000; Kuhn & Costa, 2014; Melin & DeLong, 2000; Kuhn & Costa, 2014; Melin & DeLong, 2000; Melin et al., 2008). During the nonbreeding season, most locations of occurrence are over the slope or offshore; during the breeding season, most locations of occurrence are over the slope or offshore; during the breeding season, most locations of occurrence are over the slope or offshore; during the breeding season, most locations of occurrence are over the continental shelf (Melin & DeLong, 2000; Melin et al., 2008). Lowry and Forney (2005) estimated that 47 percent of sea lions would potentially be at-sea during the cold seasons.

Adult females alternate between nursing their pup on shore and foraging at sea, spending approximately 67–77 percent of time at sea (Kuhn & Costa, 2014; Melin & DeLong, 2000).

C.6.3.30.3 Population Trends

The U.S. Stock of California sea lions has an abundance of 257,606 (Carretta et al., 2022; Laake et al., 2018). The abundance estimate is based on a pup count from 2014; however, the mean pup count from 2016 through 2019 reported by Lowry et al. (2021) was nearly the same, suggesting that population growth may be leveling off. Furthermore, Laake et al. (2018) analyzed data from 1987 through 2015 and concluded that the population in 2014 was approaching carrying capacity.

In a comprehensive review of the status of the California sea lion, Hernández-Camacho et al. (2021) estimated the population abundance, including both the U.S. Stock and Mexico breeding population, to be between 327,157 and 334,205 individuals with 80 percent in the U.S. Stock; 14 percent off the Baja California Peninsula, Mexico; and 6 percent in the Gulf of California.

C.6.3.30.4 Population Threats

California sea lions are susceptible to interactions with fisheries and entanglements in fishing gear and marine debris. This species has been known to interact with the trawl, purse seine, and Gillnet fisheries off California. Both commercial and recreational hook and line fisheries have also attributed to injuries and mortalities of this species. From 2012 through 2016, there were 146 recorded mortalities of California sea lions from hook and line fisheries (Carretta et al., 2018; Carretta et al., 2023b).

Other human-caused threats include power plant entrainment, oil exposure, shootings, vessel strikes, dog attacks, and research activities (Carretta et al., 2018; Carretta et al., 2023b). Additionally, under the MMPA, individual California sea lions in the Columbia River have been removed from their environment or euthanized since 2008 due to their predation on the endangered salmon and steelhead fishes in the region (Carretta et al., 2023b).

Anthropogenic noise may also pose a threat to this species, as studies have shown changes in behavioral responses due to noise exposure. Houser et al. (2013) found that when California sea lions were

exposed to sonar, they exhibited responses such as increases in respiration and submergence, lack of participation for food rewarding tasks, and evasive hauling out behaviors (Carretta et al., 2023b).

Climate change has increasingly become a threat to marine mammals, including pinnipeds. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021). Changes in the availability of prey due to changing ocean temperatures has already posed a threat to this species. From 2013 through 2017, an unusually high mortality event of pup and juvenile sea lions was attributed to the lack of availability of sardines (Carretta et al., 2023b). Additionally, there have been reports dating to 1998 of California sea lion mortalities due to domoic acid toxicity. Mortalities from domoic acid exposure could increase as blooms of the Psuedo-nizschia have been increasing in duration and extent partially due to climate change effects (Gulland et al., 2022).

C.6.3.31 Northern Fur Seal (Callorhinus ursinus)

C.6.3.31.1 Status and Management

Two stocks of northern fur seals (*Callorhinus ursinus*) are recognized in U.S. waters: the Eastern Pacific stock and the California stock (Carretta et al., 2023b; Young, 2023). The California stock breeds on San Miguel Island and the Farallon Islands, and the larger Eastern Pacific stock breeds on islands in the Bering Sea. Both stocks are protected under the MMPA, but neither stock is considered depleted or is listed under the ESA (Carretta et al., 2023b; Young, 2023).

C.6.3.31.2 Habitat and Geographic Range

Northern fur seals do not occur in the Hawaii Study Area.

Northern fur seals range from the northern Channel Islands off California, north along the coast of North America to the Bering Sea, and west to Japan (Carretta et al., 2022). They are typically found over the edge of the continental shelf and slope (Gentry, 2009; Sterling & Ream, 2004).

Northern fur seal breeding colonies are present at Adams Cove on San Miguel Island and on Castle Rock, an offshore island 1.1 km northwest of San Miguel Island (Baird & Hanson, 1997; Melin et al., 2012; Pyle et al., 2001; Stewart & Huber, 1993). Northern fur seal can occasionally haulout on SNI during summer (Baird & Hanson, 1997; Melin et al., 2012; Pyle et al., 2001). Animals from the California stock may remain in or near the area throughout the year but generally move to the North Pacific in waters off Washington, Oregon, and northern California to forage (Carretta et al., 2017b; Koski et al., 1998; Melin et al., 2012; Sterling et al., 2014).

Adult female Northern fur seals and juvenile of both sexes from the Eastern Pacific stock migrate along continental margins northern breeding islands from low-latitude winter foraging areas to (Gentry, 2009; Ragen et al., 1995). They leave the breeding islands in November and concentrate around the continental margins of the north Pacific Ocean in January and February, where they have access to vast, predictable food supplies (Gentry, 2009; Ream et al., 2005). Juveniles have been known to conduct trips between 8 and 29 days in duration, ranging from 171 to 680 km (Sterling & Ream, 2004). Adult female fur seals equipped with radio transmitters have been recorded conducting roundtrip foraging trips of up to 740 km (National Marine Fisheries Service, 2007a; Robson et al., 2004).

C.6.3.31.3 Population Trends

The abundance of the Eastern Pacific stock of northern fur seals is estimated to be 626,618 (CV = 0.2) fur seals, and the abundance of the California Stock is estimated at 14,050 fur seals.

C.6.3.31.4 Population Threats

Northern fur seals are likely threatened by interactions with fisheries, entanglement in fishing gear, and research activities. Stranding records off the U.S. West coast from 2009 through 2013 found that fishery-related interactions attributed to 4 mortalities (Carretta et al., 2023b; Carretta et al., 2014). Northern fur seals have also been killed due to research activities, particularly trawling operations. The rate of mortality or serious injury from research activities from 2009 through 2013 is 0.8 individuals annually (Carretta et al., 2023b). Other threats may include entanglement in marine debris, power plant entrainment, and oil exposure.

Climate change has increasingly become a threat to marine mammals, including pinnipeds. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.32 Northern Elephant Seal (Mirounga angustirostris)

C.6.3.32.1 Status and Management

The northern elephant seal is protected under the MMPA and is not listed under the ESA. The northern elephant seal population has recovered dramatically after being reduced to perhaps no more than 10 to 100 animals surviving in Mexico in the 1890s (Carretta et al., 2010; Hoelzel, 1999; Stewart et al., 1994). Movement and some genetic interchange occur among rookeries, but most elephant seals return to the rookeries where they were born to breed and thus may have limited genetic differentiation (Carretta et al., 2010). There are two DPS of northern elephant seals: one that breeds in Baja, Mexico, and a population that breeds in California. NMFS stock assessment report considers northern elephant seals in the Study Area to be from the California Breeding Stock, although elephant seals from Baja Mexico frequently migrate north through the California Study Area (Aurioles-Gamboa & Camacho-Rios, 2007).

C.6.3.32.2 Habitat and Geographic Range

Northern elephant seals are found in both coastal and deep waters of the eastern and central north Pacific. Elephant seals spend more than 80 percent of their annual cycle at sea, making long migrations to offshore foraging areas and feeding intensively to build up the blubber stores required to support them during breeding and molting haulouts (Hindell & Perrin, 2009; Le Boeuf & Laws, 1994; Worthy et al., 1992). Breeding and pupping take place on offshore islands and mainland rookeries (Carretta et al., 2010; Le Boeuf & Laws, 1994). Small colonies of northern elephant seals breed and haul-out on Santa Barbara Island and SCI with large colonies on SNI and San Miguel Island (Stewart et al., 1993a; Stewart et al., 1994). Aerial survey that included all the Channel Islands in July 2015 found the majority (approximately 61 percent) of elephant seals at San Miguel Island, approximately 21 percent at SNI, and 18 percent at Santa Rosa Island (Lowry et al., 2017). Elephant seals use these islands as rookeries from late December to February, and to molt from April to July. Northern elephant seals spend little time nearshore, and migrate through offshore waters four times a year as they travel to and from breeding/pupping and molting areas on various islands and mainland sites along the Mexico and California coasts. With most of their prey found in open oceans, northern elephant seal juveniles and females are often found in deepwater zones while males also engage in benthic foraging and travel as far north as seamounts in the Gulf of Alaska (Le Boeuf et al., 2000; Le Boeuf et al., 1996; Robinson et al., 2012; Simmons et al., 2010; Simmons et al., 2007; Stewart & DeLong, 1995).

There are records of three northern elephant seals being present in the Hawaiian Islands, indicating that movements beyond their normal range do occur, but are very rare. A female, an immature male, and mature male were sighted on Midway Island in the northwestern Hawaiian Islands in 1978 (Tomich, 1986). On January 2, 2002, a juvenile male elephant seal was discovered on Molokai and reported to be the second confirmed sighting in the Main Hawaiian Islands since 2001 (National Marine Fisheries Service, 2006). This same elephant seal was next encountered on January 11, 2002 on the Kona coast of Hawaii at Kawaihae Beach and later at the Kona Village Resort where it was captured and returned to California by NMFS (Fujimori, 2002). These occurrences in the Hawaiian Islands are considered extralimital and northern elephant seals are not expected to be present in Hawaii Study Area.

Northern elephant seals are found in both coastal areas and deeper waters off Southern California (Carretta et al., 2010; Jefferson et al., 2008; Robinson et al., 2012). The foraging range of northern elephant seals extends thousands of km offshore from the breeding range into the central North Pacific Transition Zone well to the north of Hawaii; however, their range is not considered to be continuous across the Pacific (Simmons et al., 2010; Stewart & Huber, 1993). Adult males and females segregate while foraging and migrating (Simmons et al., 2010; Stewart, 1997; Stewart & DeLong, 1995). Adult females mostly range west to about 173° W, between the latitudes of 40° N and 45° N, whereas adult males range farther north into the Gulf of Alaska and along the Aleutian Islands to between 47° N and 58° N (Le Boeuf et al., 2000; Robinson et al., 2012; Stewart & DeLong, 1995; Stewart et al., 1993a). Adults stay offshore during migration, while juveniles are often seen along the coasts of Oregon, Washington, and British Columbia (Le Boeuf et al., 1996; Stewart & Huber, 1993). The most far-ranging individual appeared on Nijima Island off the Pacific coast of Japan in 1989 (Kiyota et al., 1992). This demonstrates the great distances that these animals are capable of covering.

C.6.3.32.3 Population Trends

The population in California continues to increase, but the Mexican stock appears to be stable or slowly decreasing (Carretta et al., 2015; Lowry et al., 2014; Stewart & DeLong, 1994). Some evidence indicates that elephant seals may be expanding their pupping range northward, possibly in response to continued population growth (Hodder et al., 1998). Hodder et al. (1998) noted a possible emerging breeding colony at Shell Island off Cape Arago in southern Oregon. Other northern mainland breeding rookeries include Ano Nuevo, Point Reyes and Cape San Martin (Stewart et al., 1994).

C.6.3.32.4 Population Threats

Northern elephant seals are susceptible to interactions with fisheries and entanglement in fishing gear. The total estimated annual mortalities of this species in commercial fisheries off California is 5.3 individuals annually (Carretta et al., 2021a).

Additionally, the several recorded mortalities or injuries of northern elephant seals have been attributed to shootings, hook and line fisheries, marine debris, dog attacks, vehicle strikes, harassment, oil spills, and vessel strikes (Carretta et al., 2021a) From 2015 through 2019, there were approximately 42 mortalities or serious injuries resulting from the threats listed above (Carretta et al., 2021a).

Climate change has increasingly become a threat to marine mammals, including pinnipeds. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in

competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.33 Harbor Seal (*Phoca vitulina*)

C.6.3.33.1 Status and Management

The harbor seal is protected under the MMPA and is not listed under the ESA. Harbor seals are distributed in temperate to cold water regions in the north Pacific. The Society of Marine Mammalogy's Committee on Taxonomy (2016) has determined that all harbor seals in the north Pacific should be recognized as a single subspecies (*Phoca vitulina richardii*) until the subspecies limits of various populations are better known. There are 17 stocks of harbor seal along the U.S. west coast (Carretta et al., 2017b; Muto & Angliss, 2016); there is a single California stock occurring within the southern portion of the California Study Area.

C.6.3.33.2 Habitat and Geographic Range

The harbor seal is one of the most widely-distributed seals, found in nearly all temperate coastal waters of the northern hemisphere (Jefferson et al., 2008). Harbor seals are generally not present in the open ocean. Harbor seals are not present in the Hawaii Study Area.

Harbor seals, while primarily aquatic, also use the coastal terrestrial environment, where they haul out of the water periodically. Harbor seals are a coastal species, rarely found more than 20 km from shore, and frequently occupy bays, estuaries, and inlets (Baird, 2001). Individual seals have been observed several kilometers upstream in coastal rivers (Baird, 2001). Harbor seals are not considered migratory (Burns, 2008; Jefferson et al., 2008).

Ideal harbor seal habitat includes suitable haulout sites, shelter from high surf during the breeding periods, and sufficient food near haulout sites to sustain the population throughout the year (Bjorge, 2002). Haulout sites vary, but include intertidal and subtidal rock outcrops, sandbars, sandy beaches, estuaries, and even peat banks in salt marshes (Burns, 2008; Gilbert & Guldager, 1998; Prescott, 1982; Schneider & Payne, 1983; Wilson, 1978).

Small numbers of harbor seals are found hauled out on coastal and island sites and forage in the nearshore waters of the SOCAL Range Complex, but are found in only moderate numbers compared to sea lions and elephant seals. In California, approximately 400 to 600 harbor seal haulout sites are widely distributed along the mainland and on offshore islands of the state (Lowry et al., 2008). The harbor seal haulout sites in the San Diego area include mainland beaches and all of the Channel Islands, including Santa Barbara, Santa Catalina, and SNI (Lowry et al., 2008). There were for instance 1,367 harbor seals counted in the Channel Islands during aerial surveys in July 2015 (Lowry et al., 2017). Individuals have also been observed hauled out at La Jolla Cove, and within the channel of San Diego Bay at Ballast Point and Navy Base Point Loma. Monitoring during a pier replacement project in at Point Loma (October 2014–April 2015) encountered a mean number of three harbor seals hauled out and 2.00 to 2.48 per day in the water (U.S. Department of the Navy, 2015). A total of 15 harbor seals were sighted off the coast during 18 aerial surveys conducted between 2008 and 2013 in the southern portion of the California Study Area (Jefferson et al., 2014). There were no harbor seals detected in the 17 days of surveys (between October 2013 and September 2014) nearshore off the Silver Strand Training Complex and San Diego Bay (Graham & Saunders, 2015).

C.6.3.33.3 Population Trends

The most recent (2011) survey of California harbor seal rookeries resulted in the highest recorded pup count since 1975 (Carretta et al., 2015). In the short term, this trend may be affected by the pinniped UME that has been ongoing on the U.S. west coast since 2013.

C.6.3.33.4 Population Threats

Historically, harbor seals were threatened by hunting in the region; however, the population has since made dramatically increased.

Harbor seals are susceptible to interactions with fisheries and entanglement in fishing gear. Off the U.S. West Coast, this species has historically interacted most with the set gillnet fisheries for halibut and sea bass (Carretta et al., 2023a). From 1990 through 1994, mortality estimates ranged from 227 to as much as 1,204 harbor seals in the region; however, these fisheries are no longer observed as frequently as they previously were (Carretta et al., 2023b; Carretta et al., 2014; Julian & Beeson, 1998). They also were often observed entangled in salmon gillnet fisheries in Puget Sound; however, this fishery no longer exists.

There are also recorded observations of harbor seal interactions with tribal fisheries in Washington, mainly tribal gillnet fisheries. The Northwest Indian Fisheries Commission reported a total of 166 serious injuries or mortalities of harbor seals from the Washington inland waters stocks (Carretta et al., 2024). Takes of harbor seals for tribal subsistence purposes are not currently reported.

Other recorded anthropogenic mortalities or injuries of harbor seals have been attributed to shootings, stabbings/wounds, harassment, research, dog attacks, marine debris, fur traps, vehicle collisions, and vessel strikes. From 2017 through 2021, there were approximately 82 mortalities or serious injuries of harbor seals resulting from the threats listed above (Carretta et al., 2023a).

Climate change has increasingly become a threat to marine mammals, including pinnipeds. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.6.3.34 Steller Sea Lion (*Eumetopias jubatus*)

C.6.3.34.1 Status and Management

Information on stocks, status, and abundance is provided in Table 3.7-2 of Section 3.7 (Marine Mammals).

C.6.3.34.2 Habitat and Geographic Range

Steller sea lions range along the North Pacific Rim from northern Japan to California, with centers of abundance and distribution in the Gulf of Alaska and Aleutian Islands. The species is not known to migrate, but many individuals disperse widely outside of the breeding season. NMFS has designated two Steller sea lion stocks in the North Pacific corresponding to two DPSs (Muto et al., 2020). The Eastern U.S. Stock (or DPS) is defined as the population occurring east of 144°W longitude, and the Western U.S. Stock (or DPS) consists of sea lions occurring west of 144°W longitude. Although the distribution of individuals from the two stocks overlaps outside of the breeding season (May–July), Steller sea lions typically return to their natal rookeries and haulouts in each DPS area prior to the breeding season (Fritz et al., 2016; Jemison et al., 2013; Muto et al., 2017; Muto et al., 2018; Muto et al., 2020; National Marine Fisheries Service, 2013a; Raum-Suryan et al., 2004; Sigler et al., 2017).

Only Steller sea lions from the Eastern U.S. Stock are expected to occur in waters off California, with highest levels of occurrence in the northern part of the Study Area and fewer occurring in the Channel Islands and Southern California waters. Important haulouts along the California coastline include Año Nuevo Island and the Farallon Islands in Central California and the Saint George Reef rookery and the Sugarloaf Island rookery at Cape Mendocino in northern California Lowry et al. (2021).

Detailed information on the distribution of this species in the Study Area is provided in the U.S. Navy Marine Species Density Database Phase IV for the Hawaii-California Training and Testing Study Area technical report (U.S. Department of the Navy, 2024).

C.6.3.34.3 Population Trends

Information on population trends is provided in Table 3.7-2 of Section 3.7 (Marine Mammals).

C.6.3.34.4 Population Threats

Stellar sea lions are susceptible to entanglement in fishing gear. In Alaska, stellar sea lions have been documented interacting with the halibut longline fishery, sablefish longline fishery, and the salmon drift gillnet fishery (Delean et al., 2020). Off the U.S. West Coast, this species interacts with several groundfish fisheries, the sablefish hook and line fishery, and the California halibut bottom trawl (Carretta et al., 2023b; Jannot et al., 2018). The total estimated mean mortality or serious injury of this species due to U.S. commercial fisheries from 2013 through 2017 is 24 individuals annually (Carretta et al., 2023b). In Alaska, stellar sea lions are hunted by native populations for subsistence harvests. Available data from 2005 through 2008 and 2012 indicate that approximately 11 individuals were harvested or struck and lost annually (Carretta et al., 2023b; Delean et al., 2020). Stellar sea lions are also hunted in Canada; however, the amount of stellar sea lions harvested is likely minimal.

Other recorded human-caused mortalities or injuries of stellar sea lions have been attributed to recreational fisheries, marine debris, illegal shootings, vessel strikes, and explosives (Carretta et al., 2023b).

Climate change has increasingly become a threat to marine mammals, including pinnipeds. The predicted effects of climate change on marine mammals include habitat loss, shifts in range, changes in competition, changes in prey availability and abundance, altered foraging and reproductive behavior, and increased susceptibility to diseases and harmful algae (Gulland et al., 2022; Nelms et al., 2021).

C.7 Reptiles

C.7.1 General Background

There are two types of marine reptiles analyzed in this EIS/OEIS—sea turtles (including five species of sea turtles, all of which are listed under the ESA) and sea snakes (one species of sea snake that is not currently listed under the ESA).

Sea turtles are highly migratory, long-lived reptiles that occur throughout the open-ocean and coastal regions of the Study Area. Generally, sea turtles are distributed throughout tropical to subtropical latitudes, with some species extending into temperate seasonal foraging grounds. Leatherback sea turtles are partially endothermic, where they can tolerate colder waters relative to other sea turtle species. Leatherback sea turtles are partially endothermic, where they can tolerate range at higher latitudes than other sea turtles, which are generally exothermic and therefore less tolerant of colder waters. In general, sea turtles spend most of their time at sea, with female turtles returning to land to nest. Green sea turtles in

Hawaii, however, will also bask on the shore, particularly on beaches with lower levels of human disturbance. Green sea turtles bask on the shore for purposes of resting, thermoregulation (increasing their temperature by laying in the sun), and predator avoidance. Females also haul out onshore to avoid the advances of males during reproductive season (Spotila, 2004).

Sea snakes, also known as coral reef snakes, form a subfamily of venomous snakes closely related to the cobra and other terrestrial venomous snakes of Australia (Heatwole, 1999). Most species of sea snakes are adapted to a fully aquatic life, with few records on land (Udyawer et al., 2013). Only the yellow-bellied sea snake is thought to occur within the HCTT Study Area. Because of this species' passive drifting ecology, yellow-bellied sea snake sightings are reported in nearshore waters of Hawaii and California where they do not maintain resident breeding populations.

Additional species profiles and information on the biology, life history, species distribution, and conservation of reptile species can also be found on the following organizations:

- NMFS Office of Protected Resources (includes sea turtle species distribution maps),
- USFWS Ecological Services Field Office and Region Offices (for sea turtle nesting habitat and general locations of nesting beaches),
- Ocean Biogeographic Information System-Spatial Ecological Analysis of Megavertebrate Populations (known as OBIS-SEAMAP) species profiles,
- International Union for Conservation of Nature, Marine Turtle Specialist Group, and
- State resource agencies (specifically, Hawaii Division of Land and Natural Resources).

Detailed information about threats to sea turtles and life history information can be found in the ESA listing documentation and their recovery plans (44 *FR* 75074; 52 *FR* 21059; 72 *FR* 13027; (U.S. Fish and Wildlife Service, 1999).

C.7.1.1 Dive Behavior

Sea turtle dive depth and duration varies by species, the age of the animal, the location of the animal, and the activity (e.g., foraging, resting, and migrating). Regional differences in behavior among the same species may also occur. Hochscheid (2014) collected information on generalized dive profiles, with correlations to specific activities, such as bottom resting, bottom feeding, orientation and exploration, pelagic foraging and feeding, mid-water resting, and traveling during migrations. Dive durations are often a function of turtle size, with larger turtles being capable of diving to greater depths and for longer periods (Asada et al., 2022). Fukuoka et al. (2022) noted that olive ridley sea turtles exhibit longer dive times in warmer ocean temperatures. The diving behavior of a particular species or individual has implications for mitigation, monitoring, and developing sound conservation strategies. Figure C-33 presents the ranges of maximum dive depths for each sea turtle species found in the Study Area.



Sources: Hochscheid (2014); Sakamoto et al. (1993); Rice and Balazs (2008); Gitschlag (1996); Salmon et al. (2004).

Figure C-33: Dive Depth and Duration Summaries for Sea Turtle Species

Hochscheid (2014) also collected information on generalized dive profiles, with correlations to specific activities, such as bottom resting, bottom feeding, orientation and exploration, pelagic foraging and feeding, mid-water resting, and traveling during migrations. Generalized dive profiles compiled from 11 different studies by Hochscheid (2014) show eight distinct profiles tied to specific activities (Hochscheid, 2014). These profiles and activities are shown in Figure C-34.

Little is known about yellow-bellied sea snake diving behavior. Yellow-bellied sea snakes likely forage only in pelagic environments, and are believed to forage on the surface to a depth of 10 m (Brischoux et al., 2016; (Goiran et al., 2020). Cook et al. (2015) implanted temperature-depth loggers on three other sea snake species in New Caledonia. Logging 1,850 dives, nearly all dives were less than 30 m deep, with an average dive depth of approximately 11 m. A maximum dive duration was approximately 124 minutes.



Sources: Hochscheid (2014); Rice and Balazs (2008), Sakamoto et al. (1993), Houghton et al. (2003), Fossette et al. (2007), Salmon et al. (2004), Hays et al. (2004); Southwood et al. (1999).

Notes: Profiles A-H, as reported in the literature and compiled by Hochscheid (2014). The depth and time arrows indicate the axis variables, but the figure does not represent true proportions of depths and durations for the various profiles. In other words, the depths can vary greatly, but behavioral activity seems to dictate the shape of the profile. Profiles G and H have only been described for shallow dives (less than 5 m).

Figure C-34: Generalized Dive Profiles and Activities Described for Sea Turtles

C.7.1.2 Hearing and Vocalization

Refer to Appendix D for a summary and details regarding the hearing and vocalization of reptiles.

C.7.1.3 General Threats

C.7.1.3.1 Water Quality

Water quality in sea turtle habitats can be affected by a wide range of activities. The potential for energy exploration and extraction activities to degrade nearshore and off-shore habitats are discussed in Section C.8.1.5.2 (Commercial Industries). Marine debris in sea turtle habitats is discussed in Section C.8.1.5.6 (Marine Debris). Chemical pollution and impacts on water quality is also of great concern, although its effects on reptiles are just starting to be understood in marine organisms (Aguilar de Soto et al., 2008; Jepson et al., 2016; Law et al., 2014; National Marine Fisheries Service, 2011e, 2014b; Ortmann et al., 2012; Peterson et al., 2015). Oil and other chemical spills are a specific type of ocean contamination that can have damaging effects on some sea turtle and other marine reptile species directly through exposure to oil or chemicals and indirectly due to pollutants' impacts on prey and habitat quality. Ingested plastics, discussed in more detail in Section C.8.1.5.6 (Marine Debris), can also release toxins, such as bisphenol-A (commonly known as "BPA") and phthalates, and organisms may absorb heavy metals from the ocean and release those into tissues (Fukuoka et al., 2016; Teuten et al.,

2007). Life stage, geographic location relative to concentrations of pollutants, and feeding preference affects the severity of impacts on reptiles associated with chemical pollution in the marine environment. Exposure to pollutants may reduce turtle immune system responses, making them more susceptible to disease (Spotila, 2004).

Within the Study Area, sea snakes are primarily pelagic, and only occur close to shore in more tropical environments outside of the Study Area. In these locations, sea snakes are likely more susceptible to water quality degradation, which may decrease prey availability.

C.7.1.3.2 Commercial and Recreational Industries

One comprehensive study estimates that worldwide, 447,000 sea turtles are killed each year from bycatch in commercial fisheries around the world (Wallace et al., 2010). Lewison et al. (2014) compared bycatch using three different gear types (longline, gillnet, and trawling nets) for sea turtles, marine mammals, and seabirds. Sea turtles were most susceptible to bycatch, with the Mediterranean and waters off the Atlantic coast of South America as the two fisheries reporting the highest number of sea turtle mortalities (primarily through trawling) (Lewison et al., 2014). In U.S. fisheries, Finkbeiner et al. (2011) estimate that bycatch resulted in 71,000 sea turtle deaths per year prior to effective regulations that protect sea turtles (e.g., regulations adopted since the mid-1990s in different U.S. fisheries for turtle exclusion devices). Current mortality estimates are 94 percent lower (4,600 deaths) than pre-regulation estimates (Finkbeiner et al., 2011). The trend in bycatch reductions continues throughout the Study Area. For example, Eguchi et al. (2018) determined that current restrictions in West Coast fisheries (e.g., time-area closure for West Coast drift gill net fishery) have been effective and suggested that if the fixed time-area closure regulation existed in the 1990s, 18 of 19 observed bycatch events in this fishery could have been avoided (Eguchi et al., 2018).

Large-scale commercial exploitation also contributes to global decline in marine turtle populations. Currently, 42 countries and territories allow direct take of turtles and collectively take in excess of 42,000 turtles per year, the majority of which (greater than 80 percent) are green sea turtles (Humber et al., 2014). Illegal fishing for turtles and nest harvesting also continues to be a major cause of sea turtle mortality, both in countries that allow sea turtle take and in countries that outlaw the practice (Lam et al., 2011; Maison et al., 2010). For example, Humber et al. (2014) estimated that in Mexico 65,000 sea turtles have been illegally harvested since 2000. The authors, however, noted a downward trend of legal and illegal direct takes of sea turtles over the past three decades—citing a greater than 40 percent decline in green sea turtle take since the 1980s, a greater than 60 percent decline in hawksbill and leatherback take, and a greater than 30 percent decline in loggerhead take (Humber et al., 2014).

Boat strike has been identified as one of the important mortality factors in several nearshore turtle habitats worldwide. Precise data are lacking for sea turtle mortalities directly caused by ship strikes; however, live and dead turtles are often found with deep cuts and fractures indicative of collision with a boat hull or propeller (Hazel et al., 2007; Lutcavage & Lutz, 1997). For example, scientists in Hawaii reported that 2.5 percent of green sea turtles found dead on the beaches between 1982 and 2003 had been killed by boat strike (Chaloupka et al., 2008), and in the Canary Islands, 23 percent of stranded sea turtles showed lesions from boat strikes or fishing gear (Oros et al., 2005). Denkinger et al. (2013) reports that boat strikes in the Galapagos Islands were most frequent at foraging sites close to a commercial and tourism port.

Onshore development can lead to nesting habitat loss or habitat degradation. Construction activities can facilitate erosion or inhibit natural sediment deposition to form beaches. Once facilities are operational,

artificial lighting, noise, and other stressors can degrade nesting habitats (National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2011; Seminoff et al., 2015). Two utility-grade offshore wind projects are in the early planning stages for Hawaii (Smith et al., 2015). Projects generating electricity in offshore areas may also use wave generation technologies. While no projects are planned for West Coast states, waters off of Oregon and Washington have the most potential for wave generation, with a targeted installed capacity of 500 megawatts by 2025 (Parkinson et al., 2015). These early individual projects will not likely harm sea turtles or disrupt behaviors because of their northern location, but an increasing trend in offshore energy development may present a cumulative threat to sea turtles in nearshore environments with higher sea turtle concentrations. The anticipated increase in renewable energy development in coastal waters and deeper sites on the continental shelf will require increased vessel traffic, seismic surveys, and possibly pile driving activities for the turbine footings (Pacific Fishery Management Council, 2011), all of which may potentially stress sea turtles and their habitats.

The main threat to sea snakes globally is fisheries bycatch. Milton (2001) determined that the impact is relatively low, with prawn fisheries presenting the highest risk to sea snakes.

C.7.1.3.3 Disease and Parasites

Fibropapillomatosis is a disease of sea turtles that results in the production of tumors, both external and internal, that are considered benign, but may obstruct crucial functions, such as swimming, feeding, sight, and buoyancy, and can lead to death (Balazs, 1986; National Marine Fisheries Service & U.S. Fish and Wildlife Service, 1991; Patrício et al., 2016; Work & Balazs, 2013). The disease was first noticed in 1928, and was not observed again until the 1970s (McCorkle, 2016). The disease shows the highest prevalence among green sea turtles (Patrício et al., 2016), with rapid spread of the disease through the 1980s, becoming an epidemic in both Florida and Hawaii in green sea turtle populations (McCorkle, 2016; Work & Balazs, 2013). By 1995 the concentration of disease in the population reached its climax and has showed a decline in prevalence since (Patrício et al., 2016).

Edmonds et al. (2016) lists 16 parasites known to occur in sea turtles, with the most common and significant (in terms of impacts on health) being blood flukes and flatworms (Watson et al., 2017). Some of the common external parasites found on sea turtles include leeches and a number of different species that reside on the shell called epibiota (Suzuki et al., 2014). Leeches are usually seen around where the flippers attach to the rest of the body. Parasitic isopods (e.g., sea lice) can attach themselves to sea turtle soft tissue on the outside and within the mouth (Júnior et al., 2015).

There is no available information regarding disease of sea snakes and parasites that infect internal organs or external surfaces of sea snakes.

C.7.1.3.4 Invasive Species

Invasive species have been shown to have both harmful and beneficial impacts on sea turtles. Impacts on sea turtles associated with invasive species primarily concern nest predation and prey base (Stokes et al., 2024). Nests and eggs in the Northwestern Hawaiian Islands are at low risk of predation, but eggs deposited on beaches in the main Hawaiian Islands may be consumed by a variety of introduced species (e.g., mongooses, rats, feral dogs and cats, pigs, ants). In foraging grounds, sea turtles have been shown to adapt their foraging preferences for invasive seagrass and algae. Becking et al. (2014) showed green sea turtle foraging behavior shift to consumption of *Halophila stipulacea*, a rapidly spreading seagrass in the Caribbean. In Hawaii, green sea turtles in Kaneohe Bay have modified their diets over several decades to include seven non-native species (*Acanthophora spicifera, Hypnea musciformis, Gracilaria salicornia, Eucheuma denticulatum, Gracilaria tikvahiae, Kappaphycus striatum*, and Kappaphycus

alvarezii), with non-native algae accounting for over 60 percent of sea turtle diet (Russell & Balazs, 2015).

There is no information available on the potential impact of invasive species on sea snakes.

C.7.1.3.5 Climate Change

Sea turtles are particularly susceptible to climate change effects because their life history, physiology, and behavior are extremely sensitive to environmental temperatures (Blechschmidt et al., 2020; Fuentes et al., 2013; Patel et al., 2021; São Miguel et al., 2022). The rate of climate change experienced globally in recent decades may compromise sea turtles' survival. Most notable factors include ocean temperature increases and storm surge affecting nesting beaches. Oceanic temperature increases impact life history characteristics, such as temperature-dependent sex determination, late maturity and migratory abilities of sea turtles (São Miguel et al., 2022). Climate change models predict sea level rise and increased intensity of storms and hurricanes in tropical sea turtle nesting areas (Patino-Martinez et al., 2008). These factors could significantly increase beach inundation and erosion, thus affecting water content of sea turtle nesting beaches and potentially inundating nests (Pike et al., 2015). Climate change may negatively impact turtles in multiple ways and at all life stages. While rising temperatures may initially result in increased female population sizes, the lack of male turtles will likely impact the overall fertility of females in the population (Jensen et al., 2018). For example, breeding male sea turtles show strong natal philopatry (the tendency for animals to return to their birth places to mate) (Roden et al., 2017; Shamblin et al., 2015). With fewer available breeding males, it is unlikely that available males from other locations would interact with females in male-depleted breeding areas (Jensen et al., 2018).

Adaption strategies to protect coastal infrastructure are an anticipated response to rising sea levels. These activities may include shoreline stabilization projects and infrastructure hardening, which could contribute to the loss of nesting habitat. Shoreline stabilization may hold in place beach sediments in a specific location; however, the disruption of onshore currents can reduce the beach replenishment of sediments further away (Boyer et al., 1999; Fish et al., 2008).

Climate change may increase the likelihood of sea snakes moving into locations outside of their normal range. Although recent sightings of sea snakes appear to be correlated with El Niño events, it is reasonable to assume that warming oceanic trends may facilitate range expansion Brischoux et al. (2016).

C.7.1.3.6 Marine Debris

Ingestion of marine debris can cause mortality or injury to sea turtles, with adverse effects resulting from blocking of gastro-intestinal tracts and succumbing to toxicity from harmful chemicals (Sinaei et al., 2021). The United Nations Environment Program estimates that approximately 6.4 million tons of anthropogenic debris enters the marine environment every year (United Nations Environmental Program, 2005). This estimate, however, does not account for cataclysmic events, such as the 2011 Japanese tsunami estimated to have generated 1.5 million tons of floating debris (Murray et al., 2015). Plastic is the primary type of debris found in marine and coastal environments, and plastics are the most common type of marine debris ingested by sea turtles (Schuyler et al., 2014). Sea turtles can mistake debris for prey; one study found 37 percent of dead leatherback sea turtles to have ingested various types of plastic (Mrosovsky et al., 2009), and Narazaki et al. (2013) noted an observation of a loggerhead exhibiting hunting behavior on approach to a plastic bag, possibly mistaking the bag for a jelly fish. Even small amounts of plastic ingestion can cause an obstruction in a sea turtle's digestive track and mortality (Bjorndal, 1997; Bjorndal et al., 1994), and hatchlings are at risk for ingesting small plastic fragments. Ingested plastics can also release toxins, such as BPA and phthalates, or absorb heavy metals from the ocean and release those into tissues (Fukuoka et al., 2016; Teuten et al., 2007). Life stage and feeding preference affects the likelihood of ingestion. Sea turtles living in oceanic or coastal environments and feeding in the open ocean or on the seafloor may encounter different types and densities of debris and may therefore have different probabilities of ingesting debris. In 2014, Schuyler et al. (2014) reviewed 37 studies of debris ingestion by sea turtles, showing that young oceanic sea turtles are more likely to ingest debris (particularly plastic), and that green and loggerhead sea turtles were significantly more likely to ingest debris than other sea turtle species.

Within the Study Area, sea snakes are primarily pelagic, with fish as their primary diet. Further, sea snakes rely on visual cues from fish during hunting activities. With fish as their primary dietary component, mistaking marine debris for a prey item is not likely.

C.7.2 Endangered Species Act-Listed Species

C.7.2.1 Green Turtle (*Chelonia mydas*)

C.7.2.1.1 Status and Management

The green sea turtle was first listed under the ESA in 1978 (43 FR 32800 published July 28, 1978). In 2016, NMFS and USFWS reclassified the species into 11 "DPSs," which maintains federal protections while providing a more tailored approach for managers to address specific threats facing different populations (see 81 FR 20058 published April 6, 2016). The geographic areas that include these DPSs are: (1) North Atlantic Ocean, (2) Mediterranean Sea, (3) South Atlantic Ocean, (4) Southwest Indian Ocean, (5) North Indian Ocean, (6) East Indian Ocean – West Pacific Ocean, (7) Central West Pacific Ocean, (8) Southwest Pacific Ocean, (9) Central South Pacific Ocean, (10) Central North Pacific Ocean, and (11) East Pacific Ocean.

The Central North Pacific DPS is defined as green turtles originating from the Central North Pacific Ocean, including those hatching from nests on the beaches within the Hawaiian Archipelago and those occurring at Johnston Atoll. The Central North Pacific DPS is listed as threatened. The East Pacific DPS, listed as threatened, is defined as green turtles originating from the eastern Pacific Ocean, including those hatching from nests on the beaches in Mexico, Costa Rica, and Ecuador and foraging off the coast of California (88 FR 46376, July 19, 2023). Only the Central North Pacific and East Pacific Ocean DPSs occur within the Study Area. Four regional genetic stocks have been identified for the East Pacific DPS; however, stocks likely mix at foraging areas (81 FR 20058, April 6, 2016).

Critical Habitat

On July 19, 2023, NMFS issued a proposed rule for critical habitat designation (88 FR 46376) containing four essential features, three of which, overlap with the Central North Pacific DPS and East Pacific, and Navy training and testing activities. The reproductive essential feature proposed by NMFS for the Central North Pacific DPS extends "from the MHW to 20 m depth, sufficiently dark and unobstructed nearshore waters adjacent to nesting beaches proposed as critical habitat by USFWS... to allow for the transit, mating, and interesting of reproductive individuals and the transit of post-hatchlings." Navy activities also overlap with the proposed migratory essential feature for the East Pacific DPS, which ranges between Mexico and San Diego Bay "from the MHW line to 10 km offshore, sufficiently unobstructed corridors that allow for unrestricted transit between foraging and nesting areas for reproductive individuals." The proposed benthic foraging/resting essential features for the Central North Pacific DPS and East Pacific DPS also overlap Navy training and testing activities and were proposed "from the MHW to 20 m depth, underwater refugia (rocks, reefs, and troughs) and food resources (i.e.,

seagrasses, macroalgae, and/or invertebrates) of sufficient condition, distribution, diversity, abundance, and density necessary to support survival, development, growth, and/or reproduction" (88 FR 46376 July 19, 2023).

Within the Study Area, NMFS is proposing critical habitat for the green sea turtle within waters under the jurisdiction of JBPHH (Pearl Harbor Naval Defensive Sea Area, Naval Special Warfare training areas at Pearl City Peninsula and Lima Landing, Puuloa Underwater Range, And Barbers Point Underwater Range and Ewa Training Minefield), PMRF, and Navy Training Ranges in Southern California (Silver Strand Training Complex and Coastal San Diego Training Ranges, select areas within San Diego Bay, and Naval Weapons Station Seal Beach).

Recovery Goals

See the 1998 and 1991 recovery plans for the Pacific, East Pacific and Atlantic populations of green sea turtles for complete down-listing/delisting criteria for recovery goals for the species (NMFS and USFWS 1991; NMFS and USFWS 1998b). Broadly, recovery plan goals emphasize the need to protect and manage nesting and marine habitat, protect and manage populations on nesting beaches and in the marine environment, increase public education, and promote international cooperation on sea turtle conservation topics.

C.7.2.1.2 Habitat and Distribution

Green sea turtles are found throughout the world, nesting in 80 countries and living in the coastal areas of 140 countries (National Marine Fisheries Service, 2024f). After emerging from the nest, green sea turtle hatchlings swim to offshore areas where they float passively in major current systems; however, laboratory and modeling studies suggest that dispersal trajectories might also be shaped by active swimming (Putman & Mansfield, 2015). Post-hatchling green sea turtles forage and develop in floating algal mats habitats of the open ocean. At the juvenile stage (estimated at five to six years), they leave the open-ocean habitat and retreat to protected lagoons and open coastal areas that are rich in seagrass or marine algae (Bresette et al., 2006), where they will spend most of their lives (Bjorndal & Bolten, 1988). The optimal developmental habitats for late juveniles and foraging habitats for adults are warm shallow waters (3–5 m), with abundant submerged aquatic vegetation and close to nearshore reefs or rocky areas (Holloway-Adkins, 2006; Seminoff et al., 2003a). Climate change and ocean warming trends may impact the habitat and range of this species over time (Fuentes et al., 2013). These impacts apply to all sea turtle species and are discussed in Section C.8.1.5.5 (Climate Change).

Green sea turtles nest on beaches within the Hawaii Study Area, while they feed and migrate throughout all waters of the Study Area. Green sea turtles likely to occur in the Study Area come from eastern Pacific Ocean and Hawaiian nesting populations. There are very few reports of turtles from southern Pacific Ocean populations occurring in the northern Pacific Ocean (Limpus et al., 2009; Seminoff et al., 2015).

Migratory routes within the open ocean are unknown. The main source of information on distribution in the Study Area comes from catches in U.S. fisheries. About 57 percent of green sea turtles (primarily adults) captured in longline fisheries in the North Pacific Subtropical Gyre and North Pacific Transition Zone come from the Eastern Pacific DPS, while 43 percent are from the North Central Pacific DPS. These findings suggest that green sea turtles found on the high seas of the western and central Pacific Ocean are from these two populations. Though few observations of green sea turtles in the offshore waters along the U.S. Pacific coast have been verified, their occurrence within the nearshore waters from Baja

California to Alaska indicates a presence in waters off of California (Stinson, 1984), including San Diego Bay (Turner-Tomaszewicz & Seminoff, 2012; U.S. Department of the Navy, 2013d).

In Hawaii, green sea turtles enter the reproductive stage upon achieving sizes of 36 in. in carapace length at about 30–35 years of age (Spotila, 2004). Male green sea turtles may mate with females on foraging grounds, along migratory pathways, and off nesting beaches (National Marine Fisheries Service, 2024f). Mating occurs from March to June, and nesting occurs from May to September throughout the Hawaiian Archipelago. In captive green turtles, the average time from mating to nesting is 34.7 days (Wood & Wood, 1980). Green sea turtle clutches may contain 110 eggs (Spotila, 2004). Egg deposition takes place at night prior to sunrise (one reason to limit artificial lighting), but females may begin excavating a nest site as early as 2 hours prior to sunset (Balazs, 1980). During a season, females lay up to nine clutches (mean = 1.8 clutches) with an inter-nesting interval of 11 to 18 days (mean = 13 days) (Balazs et al., 2015). During the internesting interval, males and females regularly occupy neritic waters adjacent to nesting beaches and the undersides of reefs as refugia (Balazs, 1980). Females appear to stay relatively close to shore during the internesting interval; the maximum diving depth recorded during that time was 12.8 m (Balazs, 1980). Nesting trends over the last 40 years have increased approximately 4.8 to 5.4 percent per year (depending on the study) (Balazs et al., 2015; Seminoff et al., 2015).

Green sea turtle distribution is inconsistent and patchy throughout Pearl Harbor, however turtles occur in higher numbers around the entrance channel and within the West Loch channel of the harbor and use "caves" in benthic habitat throughout Pearl Harbor (Teresa, 2021). (Teresa, 2021) In the spring of 2010, two green sea turtles nested at PMRF for the first time in more than a decade. The number of nests observed at this location has increased over the years with six successful nests producing 468 hatchlings (Hanser et al., In Prep.). Green sea turtles are also common at all three landing beaches of U.S. Marine Corps Base Hawaii in Kaneohe Bay, where they forage in the shallow water seagrass beds (Marine Corps Base Hawaii, 2011; Martínez-Abraín, 2008), with successful the first known successful hatching occurring in August 2010 (Marine Corps Base Hawaii, 2011).

The Navy conducts aerial surveys for marine mammals in Hawaii annually as a requirement under the Navy's LOA in compliance with MMPA for at-sea training in the Hawaii Range Complex. Sea turtles are observed and recorded opportunistically while surveying for marine mammals. Turtles can be spotted from a plane or helicopter during surveys. Based on these methods, sea turtle densities were calculated for each island that was surveyed. In 88 FR 46376 (July 19, 2023), NMFS discussed foraging green sea turtle density estimates for each island. The lowest density estimates for those islands was 0.10 green turtles/km at Lana'i (Becker et al., 2019). Therefore, estimates greater than or equal to 0.10 green turtles/km (Becker et al., 2019) constitute high density within the Hawaiian Archipelago. Based on this threshold, high densities of foraging/resting green turtles occur in waters off the Island of Hawai'i (0.27 green turtles/km), Maui (0.24), Moloka'i (0.13), Lana'I (0.10), O'ahu (0.11), and Kaua'i (0.18). Low densities (less than 0.10 green turtles/km) of foraging/resting green turtles occur in waters off Ni'ihau and throughout the PMNM (Becker et al., 2019).

The green sea turtle is not known to nest anywhere on the U.S. West Coast, but ranges widely in nearshore waters as far as British Columbia (National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2007) with high concentrations in the subtropical coastal waters of southern Baja California, Mexico, and Central America (Chaloupka et al., 2004).

In the proposed rule (88 FR 46376, July 19, 2023), NMFS included a summary of research known about green sea turtles within the East Pacific DPS foraging in southern Californian waters, including inside San Diego Bay and outside along the coastal ranges of Silver Strand Training Complex. These areas are known to support a resident population of benthic foraging juvenile and adult green turtles reported by MacDonald et al. (2013). Juveniles comprise the majority of the California population of the East Pacific DPS, which is expected due to recent increases in abundance (Tomaszewicz et al., 2022). Turtles forage on seagrass in the South and Central Bays (MacDonald et al., 2012; MacDonald et al., 2013), which have dense seagrass beds that have expanded to several thousand acres during the past several years; however, the heavily developed jetties on the eastern shores of the central portion of San Diego Bay do not appear to be used, likely attributed to the heavy boat traffic.

Green sea turtles rest after in underwater refugia after foraging. In the winter and in some locations, turtles use refugia during the day, suggesting resting between diurnal foraging activity (Crear et al., 2017; MacDonald et al., 2013). Generally, adults and benthic-foraging juveniles occupy small home ranges that include foraging resources and underwater refugia. For example, green turtles acoustically tracked in San Diego Bay occupied areas of 2.09 to 8.70 km², remaining in one or two core areas more than half the time (MacDonald et al., 2012). Within the action area, Naval Weapons Station Seal Beach is considered one of the most important foraging and resting areas for green turtles in California, given that use of the area is frequent, and many turtles use the areas (National Marine Fisheries Service, 2024f). In 88 FR 46376 (July 19, 2023), NMFS discusses that food resources and refugia are typically found located in adjacent areas of San Diego Bay, and turtles must move between these areas. Refugia are likely to be found nearby the areas noted for sea turtle foraging within San Diego Bay.

In a satellite tracking study involving 25 green turtles within San Diego Bay, juveniles remained within the bay foraging, while four of the five adult turtles that left the bay migrated south to Mexico, and the fifth turtle migrated north to other foraging areas. Three were tracked to nesting beaches within Mexico, with one returning to San Diego Bay after nesting; the fourth turtle was a male that likely migrated to Mexican waters to mate (Eguchi et al., 2020).

The East Pacific DPS of the green sea turtle exhibits moderate levels of green turtle nesting abundance (>20,000 nesting females) occurring in three primary regions, with Mexico having the largest number of nesting females at several sites (13,664 nesting females), followed by the Galápagos, Ecuador (3,603 nesting females), and Costa Rica (2,826 nesting females distributed among 26 nesting sites). As discussed, some green turtles nesting on beaches in Mexico forage in the waters of California, thus requiring migration to complete their life cycle. The foraging population in California is small and has been increasing since the early 2000s, likely as a result of increases in nesting observed at Mexico nesting beaches, which may be attributed to nesting beach protections (National Marine Fisheries Service, 2024f). Twenty-five years of monitoring at the DPS's largest nesting aggregation, Michoacán, Mexico, suggest an increasing trend since the population's low point in the mid-1980s. The broad latitudinal range may provide a benefit to the East Pacific DPS of the green sea turtle in the face of climate change.

In 88 FR 46376 (July 19, 2023), NMFS discussed that reproductive individuals are agile and able to move around minor structures within migratory corridors without using excessive time or energy. However, obstructions may impede their migration in narrow, coastal corridors.

Ocean waters off Southern California and northern Baja California are also designated as areas of occurrence because of the presence of rocky ridges and channels and floating kelp habitats suitable for

green sea turtle foraging and resting (Stinson, 1984); however, these waters are often at temperatures below the thermal preferences of this primarily tropical species and turtles found in these waters are likely transiting.

C.7.2.1.3 Population Trends

The Central North Pacific DPS populations have increased since Federal and State protections were implemented in the mid-1970s (Dentlinger, 2023). The Central North Pacific DPS has seen an estimated 4.8 percent annual increase in nesting activity over the last 40 years (Seminoff et al., 2015). In-water abundance trends appear to also be increasing. A significant increase in catch per unit effort of green sea turtles was seen from 1982 to 1999 during bull-pen fishing conducted at Pala'au, Molokai, with anecdotal indications of increased abundance with more green sea turtle basking activity observed in the main Hawaiian Islands (Balazs & Chaloupka, 2006).

The East Pacific DPS also shows an increasing population trend (Massey et al., 2023; Tomaszewicz et al., 2022). This observed increase may have resulted from the onset of nesting beach protection in 1979—as is suggested by the similarity in timing between the onset of beach conservation and the age to maturity for green sea turtles along Pacific nesting beaches of Mexico (Seminoff et al., 2015).

C.7.2.1.4 Population Threats

In addition to the general threats, damaged seagrass beds and declines in seagrass distribution can reduce foraging habitat for green sea turtles (National Marine Fisheries Service & U.S. Fish and Wildlife Service, 1991; Seminoff et al., 2015; Williams, 1988). Major threats to green sea turtle recovery includes harvesting of eggs and the killing of green turtles for their meat or to shells for the wildlife trafficking trade. Bycatch in commercial and recreational fishing gear, vessel strike, coastal development impacts to nesting habitat, are also threats to green turtle recovery (National Marine Fisheries Service, 2024f). Green sea turtles are susceptible to the disease fibropapillomatosis, which causes tumor-like growths (fibropapillomas) resulting in reduced vision, disorientation, blindness, physical obstruction to swimming and feeding, increased susceptibility to parasites, and increased susceptibility to entanglement (Balazs, 1986; National Marine Fisheries Service & U.S. Fish and Wildlife Service, 1991; Patrício et al., 2016; Work & Balazs, 2013). Some populations (e.g., the Florida population) have begun to show resistance to the disease, but it remains an issue for others, such as Pacific populations, and Hawaii's green sea turtles in particular (Chaloupka et al., 2009; Seminoff et al., 2015). Other factors, such as increased stressors and selection of healthy turtles during illegal poaching activities, may increase susceptibility of turtles (Patrício et al., 2016).

C.7.2.2 Hawksbill Sea Turtle (Eretmochelys imbricata)

C.7.2.2.1 Status and Management

The hawksbill sea turtle is listed as endangered under the ESA (35 FR 8491). While the current listing as a single global population remains valid, data may support separating populations at least by ocean basin under the DPS policy (Seminoff et al., 2015). The most recent status review document was released in 2013 by the NMFS and USFWS (Hill et al., 2017).

There is no critical habitat designated for hawksbill sea turtles in the Study Area.

Recovery Goals

See the 1992 Recovery Plan for the U.S. Caribbean, Atlantic and Gulf of Mexico (NMFS and USFWS 1993) and the 1998 Recovery Plan for the U.S. Pacific populations (NMFS and USFWS 1998c) of hawksbill sea

turtles, for complete down listing/delisting criteria for each of their respective recovery goals. The following items were the top recovery actions identified to support in the recovery plans:

- 1. Identify important nesting beaches.
- 2. Ensure long-term protection and management of important nesting beaches.
- 3. Protect and manage nesting habitat; prevent the degradation of nesting habitat caused by seawalls, revetments, sand bags, other erosion-control measures, jetties and breakwaters.
- 4. Identify important marine habitats; protect and manage populations in marine habitat.
- 5. Protect and manage marine habitat; prevent the degradation or destruction of important [marine] habitats caused by upland and coastal erosion.
- 6. Prevent the degradation of reef habitat caused by sewage and other pollutants.
- 7. Monitor nesting activity on important nesting beaches with standardized index surveys.
- 8. Evaluate nest success and implement appropriate nest-protection on important nesting beaches.
- 9. Ensure that law-enforcement activities prevent the illegal exploitation and harassment of sea turtles and increase law-enforcement efforts to reduce illegal exploitation.
- 10. Determine nesting beach origins for juveniles and subadult populations.

C.7.2.2.2 Habitat and Distribution

The hawksbill is the most tropical of the world's sea turtles, rarely occurring above 35° N or below 30° south (Witzell, 1983). After hatching, hawksbill sea turtles may spend 1 to 3 years at sea where they may often be associated with floating vegetation. Upon reaching a size of about 15 in. in length (in the Indo-Pacific), they recruit to nearshore foraging areas for foraging areas. Approximately once every three years, reproductive adults migrate hundreds to thousands of miles between foraging grounds and nesting beaches, and within feeding ground, typically maintain small ranges and return to the same nesting locations at night (Spotila, 2004). Van Houtan et al. (2016) suggest that hatchlings within the HCTT Study Area may move to coastal habitats and nearshore foraging grounds more quickly. Within the Study Area, nesting occurs only in the Hawaiian Islands, with known nesting activities only at Hawaii, Maui, and Molokai Islands (Brunson et al., 2022).

Less is known about the hawksbill's oceanic stage, but it is thought that neonates live in the oceanic zone where water depths are greater than 200 m. Distribution in the oceanic zone may be influenced by surface gyres (Gaos, 2011; Leon & Bjorndal, 2002).

Juveniles and adults share the same foraging areas, including tropical nearshore waters associated with coral reefs, hard bottoms, or estuaries with mangroves (Musick & Limpus, 1997). In nearshore habitats, resting areas for late juvenile and adult hawksbills are typically in deeper waters, such as sandy bottoms at the base of a reef flat (Houghton et al., 2003). As they mature into adults, hawksbills move to deeper habitats and may forage to depths greater than 90 m. During this stage, hawksbills are seldom found in waters beyond the continental or insular shelf unless they are in transit between distant foraging and nesting grounds (Renaud et al., 1996). Ledges and caves of coral reefs provide shelter for resting hawksbills are also found around rocky outcrops and high-energy shoals, where sponges are abundant, and in mangrove-fringed bays and estuaries. Adults migrate hundreds to thousands of miles between foraging grounds and nesting beaches. Females may lay 3 to 5 clutches of eggs within a nesting season, laying one clutch every 13 to 16 days (Spotila, 2004).

Hawksbill sea turtles have a varying diet and feeding habitat preference throughout different lifestages. Post-hatchling hawksbills feed on algae in floating habitats (e.g., *Sargassum*) in the open ocean (Plotkin & Amos, 1998; Van Houtan et al., 2016). During the later juvenile stage, hawksbills are considered omnivorous, feeding on sponges, sea squirts, algae, molluscs, crustaceans, jellyfish, and other aquatic invertebrates (Bjorndal, 1997). Older juveniles and adults are more specialized, feeding primarily on sponges, which compose as much as 95 percent of their diet in some locations (Meylan, 1988; Witzell, 1983). As adults, Hawksbill sea turtles fill a unique ecological niche in marine and coastal ecosystems, supporting the natural functions of coral reefs by keeping sponge populations in check, which may otherwise compete for space with reef-building corals (Hill, 1998; Leon & Bjorndal, 2002).

C.7.2.2.3 Population Trends

Gaos et al. (2021) analyzed 30 years of nesting data within the Hawaiian Islands (between 1998 and 2018) and determined that nesting trends had historic decreases through 2006, with slight annual increases occurring for the remainder of the monitoring period. Van Houtan et al. (2016) also noted increases around the same time as observed by Gaos et al. (2021). Hawksbills in the eastern Pacific Ocean are probably the most endangered sea turtle population in the world (Gaos & Yañez, 2008). A lack of nesting beach surveys for hawksbill sea turtles in the Pacific Ocean and the poorly understood nature of this species' nesting have made it difficult for scientists to assess the population status of hawksbills in the Pacific (Gaos & Yañez, 2008; Seminoff et al., 2003b). The largest of these regional populations is in the South Pacific Ocean, where 6,000–8,000 hawksbills nest off the Great Barrier Reef (Limpus, 1992).

C.7.2.2.4 Population Threats

In addition to the general threats described in Section C.8.1.5 (General Threats), the greatest threat to hawksbills is harvest for commercial and subsistence use (Van Houtan et al., 2016). Direct harvest of eggs and nesting adult females from beaches, as well as direct hunting of turtles in foraging areas, continues in many countries. International trade of tortoise shells is thought to be the most important factor endangering the species worldwide. The second-most significant threat to hawksbill sea turtles is loss of nesting habitat caused by the expansion of human populations in coastal areas of the world, as well as the increased destruction or modification of coastal ecosystems to support tourism (National Oceanic and Atmospheric Administration, 2024a). Coastal pollution as a result of increased development degrades water quality, particularly coral reefs, which are primary foraging areas for hawksbills. Due to their preference for nearshore areas, hawksbills are particularly susceptible to nearshore fisheries gear such as drift nets, entanglement in gill nets, and capture on fish hooks of fishermen (Gaos, 2011; National Marine Fisheries Service & U.S. Fish and Wildlife Service, 1993). Hawksbills in the North Pacific may occupy a variety of ecosystems, including coastal pelagic waters and shallow reefs in remote atolls, and therefore be exposed to threats specific to these environments (Van Houtan et al., 2016).

C.7.2.3 Olive Ridley Sea Turtle (Lepidochelys olivacea)

C.7.2.3.1 Status and Management

Olive ridley sea turtles that nest along the Pacific coast of Mexico are listed as endangered under the ESA, while all other populations are listed under the ESA as threatened (43 FR 32800). Based on genetic data, the worldwide olive ridley population is composed of four main lineages: east India, Indo-Western Pacific, Atlantic, and eastern Pacific Ocean (National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2014; Shankar et al., 2004). Most olive ridley sea turtles found in Hawaiian waters are of the eastern Pacific Ocean lineage, with about a third from the Indo-Western Pacific lineage. Off of California,

olive ridleys are thought to be within the eastern Pacific Ocean lineage (National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2014). There is no critical habitat designated for this species in the Study Area.

Recovery Goals

There has not been a Recovery Plan prepared specifically for olive ridley sea turtles of the breeding populations of the Pacific coast of Mexico. The 1998 Recovery Plan was prepared for olive ridleys found in the U.S. Pacific. Olive ridley sea turtles found in the Pacific could originate from the Pacific coast of Mexico or from another nesting population. As such, the recovery goals in the 1998 Recovery Plan for the U.S. Pacific olive ridley sea turtle can apply to both listed populations. See the 1998 Recovery Plan for the U.S. Pacific olive ridley sea turtles for complete down listing/delisting criteria for their recovery goals. The following items were the recovery criteria identified to consider delisting:

- (1) All regional stocks that use U.S. waters have been identified to source beaches based on reasonable geographic parameters.
- (2) Foraging populations are statistically significantly increasing at several key foraging grounds within each stock region.
- (3) All females estimated to nest annually at source beaches are either stable or increasing for over ten years.
- (4) Management plan based on maintaining sustained populations for turtles is in effect.
- (5) International agreements in place to protect shared stocks.

C.7.2.3.2 Habitat and Distribution

The olive ridley has a circumtropical distribution, occurring in the Atlantic, Pacific, and Indian Oceans (National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2014). In the eastern Pacific, olive ridleys typically occur in tropical and subtropical waters, as far south as Peru and as far north as California, but occasionally have been documented as far north as Alaska. Key arribada beaches include La Flor in Nicaragua, Nancite and Ostinal in Costa Rica, La Marinera and Isla Cañas in Panama, Gahirmatha, Rushikulya, and Devi River in India, and Eilanti in Suriname. Arribada is the common term for large concentrations of nesting activity.

Olive ridley sea turtles are primarily carnivorous. They consume a variety of prey in the water column and on the seafloor, including snails, clams, tunicates, fish, fish eggs, crabs, oysters, sea urchins, shrimp, and jellyfish (Polovina et al., 2004), though olive ridleys may also consume algae (Spotila, 2004). Like other sea turtle species olive ridleys are subject to predation by sharks, fish and sharks on hatchlings, and various land predators on hatchlings (e.g., ants, crabs, birds, and mammals)(Ariano-Sánchez et al., 2020; National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2014; Valverde et al., 2012).

Studies from different populations of olive ridley sea turtles show a strong preference for neritic areas (shallow part of the sea near a coast and overlying the continental shelf) (Plot et al., 2015; Polovina et al., 2004; Rees et al., 2016); however, deep water foraging has been documented in the north Pacific, where prey items are scattered and less predictable and migrate widely from nesting locations (Polovina et al., 2004). Comparing olive ridley habitat use in different regions, Plot et al. (2015) suggest that the differing migration patterns observed (i.e., oceanic migrations versus neritic movements) may be attributed to specific environmental conditions of the areas in close proximity to nesting sites.

Olive ridley sea turtles can dive and feed at considerable depths from 80 to 300 m (Chambault et al., 2016; Montero et al., 2016), although only about 10 percent of their foraging time is spent at depths

greater than 100 m (Polovina et al., 2002). In the eastern tropical Pacific Ocean, at least 25 percent of their total dive time is spent between 20 and 100 m (Parker et al., 2003). While olive ridley sea turtles are known to forage to great depths, Polovina et al. (2002) found that most dives (approximately 70 percent) were no deeper than 15 m.

Rare instances of nesting occur in the Hawaiian Islands, with the first olive ridley nest documented in 1985 at Paia, Maui. A second nest was recorded in Hilo, Hawaii, in 2002, and a third olive ridley nest was recorded at Marine Corps Base Hawaii in Kaneohe Bay in 2009 (Marine Corps Base Hawaii, 2011).

C.7.2.3.3 Population Trends

The olive ridley is the most abundant sea turtle in the world, with the most recent at-sea estimates of density and abundance providing a population range of 1.15–1.62 million olive ridley sea turtles (National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2014). Although this is a dramatic decrease over the past 50 years, where the population from the five Mexican Pacific Ocean beaches was previously estimated at 10 million adults, short-term population trends appear to be increasing overall. The number of olive ridley sea turtles occurring in U.S. territorial waters is believed to be small (National Marine Fisheries Service & U.S. Fish and Wildlife Service, 1998, 2014). At-sea abundance surveys conducted along the Mexican and Central American coasts between 1992 and 2006 provided an estimate of 1.39 million turtles in the region, which was consistent with the increases seen on the eastern Pacific Ocean nesting beaches between 1997 and 2006.

(Ariano-Sánchez et al., 2020; National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2014; Valverde et al., 2012)

C.7.2.3.4 Population Threats

Besides the array of threats to sea turtles in general, most of the species-specific threats for olive ridleys in the east Pacific coast population are associated with nesting habitats along the eastern Pacific coast. Lutcavage et al. (1997) note that impacts on nesting habitats for olive ridley sea turtles include construction of buildings and pilings, beach armoring and nourishment, and sand extraction. These activities have increased in many parts of the olive ridley's range and pose threats to major nesting sites in Central America (National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2014).

C.7.2.4 Loggerhead Turtle (Caretta caretta)

C.7.2.4.1 Status and Management

In 2009, a status review conducted for the loggerhead (the first turtle species subjected to a complete stock analysis) identified nine DPS within the global population (Conant et al., 2009). In a September 2011 rulemaking, the NMFS and USFWS listed five of these DPS as endangered and kept four as threatened under the ESA, effective as of October 24, 2011 (76 FR 58868). The North Pacific Ocean, South Pacific Ocean, North Indian Ocean, Northeast Atlantic Ocean, and Mediterranean Sea DPSs of the loggerhead sea turtle are classified as endangered under the ESA, and the Southeast Indo-Pacific Ocean, Southwest Indian Ocean, Northwest Atlantic Ocean, and South Atlantic Ocean DPS are classified as threatened. Only the North Pacific Ocean DPS occurs within the Study Area; however, mixing is known to occur between other populations in the Pacific and Indian Oceans, enabling a limited amount of gene flow with other DPSs (Gaos, 2011). NMFS and USFWS completed the most recent status review for the North Pacific Ocean DPS in 2020 (National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2020a).

There is no critical habitat designated for loggerhead sea turtles within the Study Area.

C.7.2.4.2 Habitat and Distribution

Loggerhead sea turtles occur in U.S. waters in habitats ranging from coastal estuaries to waters far beyond the continental shelf (Dodd, 1988; Martin et al., 2020); however, loggerheads are not found in high numbers within the HCTT Study Area. Loggerheads typically nest on beaches close to reef formations and in close proximity to warm currents (Dodd, 1988), preferring beaches facing the ocean or along narrow bays (National Marine Fisheries Service & U. S. Fish and Wildlife Service, 1998; Rice et al., 1984). Most of the loggerheads observed in the eastern North Pacific Ocean are believed to come from beaches in Japan where the nesting season is late May to August. Aschettino et al. (2015) found that most loggerheads that use the Southern California Bight are more similar, using stable isotope analysis, to loggerheads in the Central North Pacific, as opposed to loggerheads that nest in Baja. Migratory routes can be coastal or can involve crossing deep ocean waters (Schroeder et al., 2003). The species can be found hundreds of km out to sea, as well as in inshore areas, such as bays, lagoons, salt marshes, creeks, ship channels, and the mouths of large rivers. Coral reefs, rocky areas, and shipwrecks are often used as feeding areas. The nearshore zone provides crucial foraging habitat, as well as habitat during nesting season and overwintering habitat.

Loggerhead sea turtles are primarily carnivorous in both open ocean and nearshore habitats, although they also consume some algae (Bjorndal, 1997). Diet varies by age class (Godley et al., 1998) and by specializing in specific prey groups dependent on location (Besseling et al., 2015; Biggs et al., 2000). For post hatchlings that tend to be grouped in masses of floating habitats, various diet analyses of gut contents show parts of marine algae, zooplankton, jellyfish, larval shrimp and crabs, and gastropods (Browlow et al., 2016; Burkholder et al., 2004; Carr & Meylan, 1980; Harrison et al., 2021; Morales-Zárate et al., 2021; Richardson & McGillivary, 1991). Both juveniles and adults forage in coastal habitats, where they feed primarily on the bottom, although they also capture prey throughout the water column (Bjorndal, 2003; DiMatteo et al., 2022; Harrison et al., 2021; Morales-Zárate et al., 2021). Adult loggerheads feed on a variety of bottom-dwelling animals, such as crabs, shrimp, sea urchins, sponges, and fish. They have powerful jaws that enable them to feed on hard-shelled prey, such as whelks and conch. During migration through the open sea, they eat jellyfish, molluscs, flying fish, and squid (Besseling et al., 2015; Harrison et al., 2021; Martin et al., 2020; Rice et al., 1984).

Pacific Ocean loggerheads appear to use the entire North Pacific Ocean during development. There is substantial evidence that the North Pacific Ocean stock makes two transoceanic crossings. The first crossing (west to east) is made immediately after they hatch from the nesting beach in Japan, while the second (east to west) is made when they reach either the late juvenile or adult life stage at the foraging grounds in Mexico. Offshore, juvenile loggerheads forage in or migrate through the North Pacific Subtropical Gyre as they move between North American developmental habitats and nesting beaches in Japan. The highest densities of loggerheads can be found just north of Hawaii in the North Pacific Transition Zone (Briscoe et al., 2021; Polovina et al., 2000).

The North Pacific Transition Zone is defined by convergence zones of high productivity that stretch across the entire northern Pacific Ocean from Japan to California (National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2020a). Within this gyre, the Kuroshio Extension Bifurcation Region is an important habitat for juvenile loggerheads (Polovina et al., 2006). These turtles, whose oceanic phase lasts a decade or more, have been tracked swimming against the prevailing current, apparently to remain in the areas of highest productivity. Juvenile loggerheads originating from nesting beaches in Japan migrate through the North Pacific Transition Zone en route to important foraging habitats in Baja California, and are likely to be found in the Transit Corridor of the Study Area (Bowen et al., 1995).

Seminoff et al. (2014) report that waters off of the southern Baja Peninsula support a high abundance of loggerheads that originate from the Japanese nesting grounds. Capistrán et al. (2023) reported the first record of loggerhead presence in Monterey Bay, California, near the edge of the Monterey Submarine Canyon, sighted by a local kayaker in 2017.

The loggerhead sea turtle is known to occur at sea in the California Study Area but does not nest on Southern California beaches. Loggerhead sea turtles primarily occupy areas where the sea surface temperature is between 59 °F and 77°F (15 °C and 25°C). In waters off of the U.S. West Coast, most records of loggerhead sightings, stranding events, and incidental bycatch have been of juveniles documented from the nearshore waters of southern California. In general, sea turtle sightings increase during the summer, peaking from July to September off southern California and southwestern Baja California.

During El Niño events, foraging loggerheads from Mexican waters may expand their range north into Southern California waters. For this reason, U.S. Pacific Ocean waters east of 120° W longitude are closed to the large mesh drift gillnet fishery targeting swordfish and thresher shark during June, July, and August during a forecast or occurring El Niño event. These waters are considered an area of occurrence during the warm-water period. Allen et al. (2013) conducted stable isotope analysis on loggerheads in both the Southern California Bight and North Pacific Ocean loggerheads and noted strong genetic kinship among these population segments. Loggerheads are generally not found in waters colder than 60.8°F (16°C), so the area north of the 60.8°F (16°C) isotherm is depicted as an area of rare occurrence.

The loggerhead embarks on transoceanic migrations and has been reported as far north as Alaska and as far south as Chile. Loggerheads foraging in and around Baja California originate from breeding areas in Japan (Conant et al., 2009), while Australian stocks appear to migrate to foraging grounds off the coasts of Peru and Chile (Alfaro-Shigueto et al., 2004).

C.7.2.4.3 Population Trends

No loggerhead nesting occurs within the Study Area. The largest nesting aggregation in the Pacific Ocean occurs in southern Japan, where fewer than 1,000 females breed annually (Briscoe et al., 2021; Kamezaki et al., 2003; National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2020a). Despite historic long-term declines from Japan nesting beaches (50 to 90 percent), nesting populations in Japan have gradually increased since 2000 (National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2020a), based in part on modeling conducted by . (Morales-Zárate et al., 2021); Seminoff et al. (2014) carried out aerial surveys for loggerhead sea turtles along the Pacific Coast of the Baja California Southern California Bight resulted in 215 loggerhead sea turtle sightings over the course of one month in the fall of 2015 (Eguchi, 2015).

C.7.2.4.4 Population Threats

Loggerheads that occur within the Study Area primarily originate from nesting grounds in Japan and use the North Pacific as migration and foraging grounds. Therefore, species-specific threats are limited to this geographic area. A primary threat to North Pacific loggerheads is the high degree of juvenile and adult mortality off the Baja California Peninsula. As discussed previously, this location is considered a biological hotspot for loggerheads in a location where bycatch and human consumption present significant threats (Fisheries and Oceans Canada, 2011, 2016b; National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2020a). Mortality associated with shrimp trawls has been a substantial threat to juvenile loggerheads because these trawls operate in the nearshore habitats commonly used by this species. Although shrimping nets have been modified with turtle excluder devices to allow sea turtles to escape, the overall effectiveness of these devices has been difficult to assess (Bugoni et al., 2008; Ellis, 2016). Shrimp trawl fisheries account for the highest number of loggerhead sea turtle fishery mortalities; however, loggerheads are also captured and killed in other trawls, traps and pots, longlines, and dredges (Morales-Zárate et al., 2021; National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2020a).

C.7.2.5 Leatherback Sea Turtle (Dermochelys coriacea)

C.7.2.5.1 Status and Management

The leatherback sea turtle is listed as a single population and is classified as endangered under the ESA (35 FR 8491, January 26, 2012). Although USFWS and NMFS believe the current listing is valid, preliminary information indicates an analysis and review of the species should be conducted under the DPS policy (National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2013, 2020b). Recent information on population structure (through genetic studies) and distribution (through telemetry, tagging, and genetic studies) have led to an increased understanding and refinement of the global stock structure (Clark et al., 2010; National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2020b).

In 2012, NMFS designated critical habitat for the leatherback sea turtle off the western coast of the U.S. (77 FR 4170, January 26, 2012) This designation includes approximately 16,910 mi.² (43,798 km²) stretching along the California coast from Point Arena to Point Arguello east of the 3,000 m depth contour; and 25,004 mi.² (64,760 km²) stretching from Cape Flattery, Washington to Cape Blanco, Oregon east of the 2,000 m depth contour. The designated areas comprise approximately 41,914 mi.² (108,558 km²) of marine habitat and include waters from the ocean surface down to a maximum depth of 262 ft. (80 m) (National Marine Fisheries Service, 2012a). This critical habitat designation overlaps with the California portion of the Study Area. NMFS focused on the known and consistent coastal foraging areas that leatherbacks rely on after long migrations across the Pacific Ocean, which include neritic waters off the central California coast to encompass a prominent oceanographic front that occurs between cool, nearshore upwelling-modified waters and warmer offshore waters of the California Current. The front is located within 60 mi of the coast, providing a mechanism for aggregating leatherback prey, primarily brown sea nettles that have been advected from neritic central California waters and moon jellies (National Marine Fisheries Service, 2012a).

Recovery Goals

See the U.S. Pacific (NMFS and USFWS 1998a) and U.S. Caribbean, Gulf of Mexico and Atlantic Recovery Plans (NMFS and USFWS 1992) for leatherback sea turtles for complete down listing/delisting criteria for each of their respective recovery goals. The top five recovery actions identified in the Leatherback Five Year Action Plan were 1) Reduce fisheries interactions; 2) Improve nesting beach protection and increase reproductive output; 3) International cooperation; 4) Monitoring and research and 5) Public engagement.

C.7.2.5.2 Habitat and Distribution

The leatherback sea turtle is distributed worldwide in tropical and temperate waters of the Atlantic, Pacific, and Indian Oceans. Pacific leatherbacks are split into western and eastern Pacific subpopulations based on their distribution and biological and genetic characteristics. Eastern Pacific leatherbacks nest along the Pacific coast of the Americas, primarily in Mexico and Costa Rica, and forage throughout coastal and pelagic habitats of the eastern tropical Pacific, between the months of October and February (Burns et al., 2016; Eckert et al., 2015; Kuschke et al., 2023; Stewart et al., 2016b). Western Pacific leatherbacks nest in the Indo-Pacific, primarily in Indonesia, Papua New Guinea and the Solomon Islands. A proportion of this population migrates north through the waters of Indonesia, Malaysia, Philippines, and Japan, and across the Pacific past Hawaii to feeding areas off the Pacific coast of North America. Another segment of the western subpopulation migrates into the southern hemisphere through the Coral Sea, into waters of the western South Pacific Ocean (National Marine Fisheries Service, 2016u). The Western Pacific leatherback group is the primary stock that occurs within the Study Area.

Leatherback sea turtles are regularly sighted by fishermen in offshore waters surrounding the Hawaiian Islands, generally beyond the 3,800 ft. depth contour, and especially at the southeastern end of the island chain and off the northern coast of Oahu. Leatherbacks encountered in these waters, including those caught accidentally in fishing operations, may be migrating through waters surrounding Hawaii (National Marine Fisheries Service & U. S. Fish and Wildlife Service, 1998). Sightings and reported interactions with the Hawaii longline fishery commonly occur around seamount habitats above the Northwestern Hawaiian Islands (from 35°N to 45°N and 175°W to 180°W) (Skillman & Balazs, 1992; Skillman & Kleiber, 1998).

The leatherback sea turtle occurs in offshore areas surrounding the Hawaiian Islands beyond the 100 m isobath. Leatherbacks rarely occur inshore of this isobath. Incidental captures of leatherbacks have also occurred at several offshore locations around the main Hawaiian Islands (McCracken, 2000). Although leatherback bycatches are common off the island chain, leatherback-stranding events on Hawaiian beaches are uncommon. Since 1982, only five leatherbacks strandings have been reported in the Hawaiian Islands. Aerial and shipboard surveys in nearshore Hawaiian waters also suggest that nearshore occurrences are extremely rare (National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2013). Leatherbacks were not sighted during any of the NMFS shipboard surveys; their deep diving capabilities and long submergence times reduce the probability that observers could spot them during marine surveys. One leatherback sea turtle was observed along the Hawaiian shoreline during monitoring surveys in 2006 (Martin et al., 2020; National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2013, 2020b).

Leatherback sea turtles are regularly seen off the western coast of the U.S., with the greatest densities found in waters off of central California. Off central California, sea surface temperatures are highest during the summer and fall. These warmer temperatures and other oceanographic conditions create favorable habitat for leatherback sea turtle prey (jellyfish). There is some evidence that they follow the 61°F (16°C) isotherm into Monterey Bay, and the length of their stay apparently depends on prey availability. Satellite telemetry studies link leatherback sea turtles off the U.S. West Coast to one of the two largest remaining Pacific Ocean breeding populations in Jamursba Medi, Indonesia. Thus, nearshore waters off central California represent an important foraging region for the critically endangered Pacific Ocean leatherback sea turtle. There were 96 sightings of leatherbacks within 50 km of Monterey Bay from 1986 to 1991, mostly by recreational boaters (Benson, 2022; Benson et al., 2020; Eguchi et al., 2017; Starbird et al., 1993).

Leatherbacks lack the crushing chewing plates characteristic of hard-shelled sea turtles that feed on hard-bodied prey. Instead, they have pointed tooth-like cusps and sharp-edged jaws that are adapted for a diet of soft-bodied open-ocean prey such as jellyfish and salps. Leatherback sea turtles feed throughout the water column (Davenport, 1988; Eckert et al., 1989; Eisenberg & Frazier, 1983; Grant & Ferrell, 1993; James et al., 2005; Salmon et al., 2004). Leatherback prey is predominantly jellyfish (Aki et al., 1994; Bjorndal, 1997; James & Herman, 2001; Salmon et al., 2004). Engelhaupt et al. (2016)
conducted gastrointestinal analysis on two leatherbacks southeast of Hawaii and found 94 percent of stomach contents to be comprised of salps, the remaining portion were unidentifiable invertebrates.

C.7.2.5.3 Population Trends

Most stocks in the Pacific Ocean are faring poorly, where nesting populations have declined more than 80 percent since the 1980s, and because the threats to these subpopulations have not ceased, the International Union for Conservation of Nature has predicted a decline of 96 percent for the western Pacific subpopulation and a decline of nearly 100 percent for the eastern Pacific subpopulation by 2040 (Clark et al., 2010; National Marine Fisheries Service, 2016u; National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2020b; Sarti-Martinez et al., 1996; Stewart et al., 2016b). In contrast, western Atlantic and South African populations are generally stable or increasing. Causes for this decline include the intensive egg harvest in Pacific leatherback rookeries and high levels of mortality through the 1980s associated with bycatch in Pacific gill net fisheries (Fisheries and Oceans Canada, 2016a; Florida Fish and Wildlife Conservation Commission, 2015).

C.7.2.5.4 Population Threats

In addition to the general threats to sea turtles described previously, bycatch in commercial fisheries is a particular threat to leatherback sea turtles. Incidental capture in longline and coastal gillnet fisheries has caused a substantial number of leatherback sea turtle deaths, likely because leatherback sea turtles dive to depths targeted by longline fishermen and are less maneuverable than other sea turtle species. Natural factors, including the 2004 tsunami in the Indian Ocean and the tsunami that affected Japan in 2011, may have impacted leatherback nesting beach habitat through encroachment, erosion, or increased inundation with debris in leatherback foraging habitats and migratory routes (National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2013). Eckert and Sarti-Martinez (1997) attributed the decline in the Mexican population of leatherbacks to the growth of the longline and coastal gillnet fisheries in the Pacific. Leatherbacks from this population migrate to the north Pacific and southeastern Pacific where these fisheries operate. Robinson et al. (2013) suggest that climate change impacts are contributing to the Pacific leatherback population declines through a shifting of nesting dates, which increases stressor exposure. Lastly, climate change may impact leatherback distribution because leatherback distributions are closely associated with jellyfish aggregations (which are affected by changing ocean temperatures and dynamics) (Pike, 2014).

C.7.3 Species Not Listed under the Endangered Species Act

The only marine reptile species in the Study Area not listed under the ESA is the yellow-bellied sea snake. This species is described in more detail in the following subsections.

C.7.3.1 Yellow-bellied Sea Snake (Pelamis platura)

C.7.3.1.1 Status and Management

This species is not managed under any international or U.S. regulatory framework.

C.7.3.1.2 Habitat and Distribution

The species is the most pelagic of all sea snakes, occurring in the open ocean well away from coasts and reefs. However, a small number of sea snakes wash ashore, are observed in coastal waters, or occur in inter-tidal habitats (Murphy, 2012). In the open ocean, yellow-bellied sea snakes often occur in large numbers associated with long lines of debris. These aggregations are associated with sea caves, nesting sites, or near drift lines in the open ocean. In some areas, such as the Gulf of Panama in the eastern

Pacific Ocean, the aggregations can vary in width from 1 to 300 m and include up to 1,000 individuals (Brischoux et al., 2016; Cook et al., 2015).

The yellow-bellied sea snake is the most widely distributed species of marine sea snake, ranging from the Cape of Good Hope westward across the Indo-Pacific to the western coastline of Central America (Brischoux et al., 2016; Cook et al., 2015; Lillywhite et al., 2015). Because this sea snake species exhibits a passive drifting ecology, the yellow-bellied sea snake may be carried into regions where it does not maintain a resident breeding population (e.g., California, Hawaii, New Zealand, Tasmania, the Sea of Japan, and the Galapagos) (Lillywhite et al., 2015; Udyawer et al., 2013).

The strong El Niño conditions that developed throughout the Pacific in 2015 and 2016 likely caused changes in sea levels and living marine resources distributions (Milstein, 2015). Coupled with oceanic temperature warming trends, these factors are thought to facilitate sea snake occurrence in coastal waters of California.

Yellow-bellied sea snakes are believed to prey exclusively on fish, primarily in pelagic environments (Cook et al., 2015; Lillywhite et al., 2014). Yellow-bellied sea snakes likely make shallow dives (with average depths of approximately 11 m). Cook et al. (2015) implanted temperature-depth loggers on three other sea snake species in New Caledonia. Logging 1,850 dives, nearly all dives were less than 30 m deep. A maximum dive duration was approximately 124 minutes.

C.7.3.1.3 Population Trends

Lillywhite et al. (2015) suspected that the pan-oceanic population of yellow-bellied sea snakes is exceptionally large compared to other snakes because of this species' wide range and given that aggregations number in the thousands at various locations. Estimating population size for this species is difficult, as the range is very broad over several oceans. This species, however, is fairly common throughout its known range. In addition, the distribution pattern of the yellow-bellied sea snake is very clumped. Visual surveys from boats are probably the most suitable technique for estimating population size when they occur in large aggregations associated with marine debris or from opportunistic sightings on boats or when they wash ashore (Brischoux et al., 2016; Lillywhite et al., 2014).

C.7.3.1.4 Population Threats

Squid trawlers may be a source of bycatch, but is this is thought to be a minor threat because of this species' preference for open pelagic habitats (Brischoux et al., 2016). Marine debris may also be a minor threat to this species. Udyawer et al. (2013) reported the entrapment of a sea snake (*Hydrophis elegans*) with a ceramic washer encircling its body. The authors of this study report that a post-mortem examination determined that the snake was malnourished because of the constriction.

C.8 Birds

C.8.1 General Background

Seabirds – birds that forage primarily on the open ocean - are of particular interest as the group of birds with the broadest distribution and exposure to Navy activities in the Study Area. Seabirds are a diverse group that are adapted to living in aquatic environments (Enticott & Tipling, 1997; North American Bird Conservation Initiative, 2022) and, in the Study Area use coastal (nearshore) waters, offshore waters (continental shelf), or open ocean areas (Harrison, 1983). There are many biological, physical, and behavioral adaptations that are different for seabirds than for terrestrial birds. Seabirds typically live longer, breed later in life, and produce fewer young than other bird species (Onley & Scofield, 2007). The feeding habits of seabirds are related to their individual physical characteristics, such as body mass,

bill shape, and wing area (Hertel & Ballance, 1999). Some seabirds look for food (forage) on the sea surface, whereas others dive to variable depths to obtain prey (Burger, 2001). Many seabirds spend most of their lives at sea and come to land only to breed, nest, and occasionally rest (Schreiber & Chovan, 1986). Most species nest in groups (colonies) on the ground of coastal areas or oceanic islands, where breeding colonies number from a few individuals to thousands. However, many species are distributed nesters, and some seabirds are cavity nesters. Typical bird behavior to be encountered within the Study Area would include breeding, foraging, roosting, and migration. Beaches and wetlands within or bordering the Study Area may also be used as molting grounds by some species.

Additional information on the biology, life history, and conservation of bird species, including species-specific descriptions, is available from the websites of these sources:

- USFWS Migratory Bird Program and Endangered Species Program
- Birdlife International
- International Union for Conservation of Nature and Natural Resources Red List of Threatened Species
- National Audubon Society
- The Waterbird Society
- Department of Defense's Partners in Flight

The following sections contain additional information on group size, habitat use, dive behavior, hearing and vocalization, and general threats.

C.8.1.1 Group Size

Avian radar studies at sea shows some bird groups moving across open oceans in large numbers (Desholm et al., 2006; Gauthreaux & Belser, 2003). During the winter months, large groups of ducks (rafts) could be encountered. During the nesting and breeding season, pelagic seabirds could be encountered in large groups following the currents and upwellings in pursuit of prey (Sibley, 2014). In the nearshore environments, terns, gulls, shorebirds, and plovers may occur in large groups while in their breeding and feeding areas.

Most seabird species nest in groups (colonies) on the ground of coastal areas or oceanic islands, where breeding colonies number from a few individuals to thousands. This breeding strategy is believed to have evolved in response to the limited availability of relatively predator-free nesting habitats and distance to foraging sites from breeding grounds (Siegel-Causey & Kharitonov, 1990). Outside of the breeding season, most seabirds within the Order Procellariiformes, such as the black-vented shearwater (Puffinus opisthomelas), are solitary, though they may join mixed-species flocks while foraging and can be associated with whales and dolphins (Onley & Scofield, 2007) or areas where prey density is high (U.S. Fish and Wildlife Service, 2005b). During the breeding season, these seabirds usually form large nesting colonies. Pelecaniform (birds within the Order Pelecaniformes) breeding, whether on the ground or in trees, is typically colonial and the most common species in the Study Area. Foraging seabirds of the order Charadriiformes (e.g., Heermann's gull [Larus heermanni]) can range from singles or pairs (International Union for Conservation of Nature and Natural Resources, 2010a; U.S. Fish and Wildlife Service, 2005a) and can extend upward into larger groups where juveniles accompany adults to postbreeding foraging areas, where the water is calm and the food supply is good. There are post-season dispersal sites, where adults and fledglings congregate (U.S. Fish and Wildlife Service, 2006). Large groups are occasionally observed foraging at great distances from colonies, including at inland water sources (Atwood & Minsky, 1983).

C.8.1.2 Habitat Use

The entire world populations of Hawaiian petrels (*Pterodroma sandwichensis*) and Newell's shearwaters (*Puffinus auricularis newelli*) and more than 95 percent of the world's Laysan and black-footed albatrosses (*Phoebastria immutabilis* and *Phoebastria nigripes*, respectively) nest in the northwest Hawaiian Islands. Most of the world's ashy storm-petrels (*Oceanodroma homochroa*), western gulls (*Larus occidentalis*), and Brandt's cormorants (*Phalacrocorax penicillatus*) nest along the west coast of the U.S. (U.S. Fish and Wildlife Service, 2005a). In addition to breeding seabirds, millions of seabirds from more than 100 different species migrate to or through the Study Area. For example, an estimated 5.5 to 6 million seabirds representing more than 100 species are thought to occur off California based on at-sea surveys (U.S. Fish and Wildlife Service, 2005a). Surveys around the Hawaiian Islands found 40 different species of seabirds, half of which were local breeders and the remainder were migrant species (U.S. Fish and Wildlife Service, 2005a).

The Southern California Bight, within the California Current Large Marine Ecosystem, is important for both breeding and migratory bird species. More than 195 species of birds use coastal or offshore aquatic habitats in the Southern California Bight—the area of the Pacific Ocean lying between Point Conception on the Santa Barbara County coast to a point south of the U.S.-Mexico border (Anderson et al., 2007; Baird, 1993; Bearzi et al., 2009a; Hunt & Butler, 1980).

More than 300 bird species have been documented in and around San Diego Bay. The majority of these bay birds, representing 30 families, are migratory and may only stop to rest and feed, while others spend the winter or breed. Surveys in 2016 and 2017 identified 161 bird species and a total of 564,752 individual observations (Tierra Data Inc., 2018). Several are terrestrial birds of special concern or influence that are found about the Bay but may not directly depend upon it. Resident birds live and breed in the area year-round. Migrants that would not usually be in the area, disoriented in their travel, on the edges of their range, or simply looking for suitable habitat are regarded as vagrants. Although vagrants are not considered ordinarily dependent on the bay, a considerable number of them pass through and visit each year (U.S. Department of the Navy, 2013d).

C.8.1.3 Dive Behavior

Many of the seabird species found in the Study Area will dive, skim, or grasp prey at the water's surface or within the upper portion (1 to 2 m) of the water column (Cook et al., 2011; Jiménez et al., 2012; Sibley, 2014). However, numerous seabirds, including various species of diving ducks, cormorants, and alcids (the family that includes murres, murrelets, auks, auklets, shearwaters, and puffins), including the threatened Newell's shearwater are known to feed at depths greater than 100 ft. (Ehrlich et al., 1988). Some seabirds are aerial plunge divers in which they dive from above the surface and make generally shallow dives into the water column after prey (e.g., terns, gannets). Others are considered surface divers where they plunge directly from the surface underwater after prey (e.g., puffins, loons). Most diving species tend to catch the majority of their prey near the surface of the water column or on the bottom in shallow water (e.g., clams, mussels, and other invertebrates) (Cook et al., 2011), although some pursue prey to considerable depths as noted previously. Dive durations are correlated with depth and range from a few seconds in shallow divers to several minutes in alcids (Ponganis, 2015). Petrels forage both night and day; they capture prey by resting on the water surface and dipping their bill and by aerial pursuit of flying fish (International Union for Conservation of Nature and Natural Resources, 2010b). Hawaiian petrels eat mostly squid (50 to 75 percent of their diet), fish, and crustaceans (International Union for Conservation of Nature and Natural Resources, 2010b).

C.8.1.4 Hearing and Vocalization

Although hearing range and sensitivity has been measured for many land birds, fewer studies have focused on seabird hearing; most published literature on bird hearing focuses on terrestrial birds and their ability to hear in air. A review of 32 terrestrial and marine species indicates that birds generally have the greatest hearing sensitivity between 1 and 4 kHz (Beason, 2004; Dooling, 2002). Very few can hear below 20 Hz, most have an upper frequency hearing limit of 10 kHz, and none exhibit hearing at frequencies higher than 15 kHz (Dooling, 2002; Dooling & Popper, 2000). Hearing capabilities have been studied for several seabirds (Beason, 2004; Beuter et al., 1986; Crowell et al., 2015; Johansen et al., 2016; Thiessen, 1958; Wever et al., 1969); these studies show that seabird hearing ranges and sensitivity in air are consistent with what is known about bird hearing in general. More recent studies of long-tailed duck, common eider, and surf scoter (McGrew et al., 2022); and Atlantic puffin and common murre (Mooney et al., 2019) support previous conclusions that birds generally have greatest hearing sensitivity between 1 and 4 kHz. Two field studies (Mooney et al., 2020; Mooney et al., 2019) of wild captured Atlantic puffin produced auditory curves between 0.5 and 6 kHz, similar to measurements for other seabirds. Smith et al. (2023) measured the same range in marbled murrelet. Hansen et al. (2017) studied great cormorants and found maximum sensitivity at 2 kHz, and Larsen et al. (2020) found that great cormorants have underwater hearing sensitivity that is at least as good as their aerial sensitivity along with anatomical adaptations to underwater hearing (thickened eardrum).

Crowell et al. (2015) also compared the vocalizations of the same ten diving bird species to the region of highest sensitivity of in-air hearing. Of the birds studied, vocalizations of only eight species were obtained due to the relatively silent nature of two of the species. The peak frequency of the vocalizations of seven of the eight species fell within the range of highest sensitivity of in-air hearing. Crowell et al. (2015) suggested that the colonial nesters tested had relatively reduced hearing sensitivity because they relied on individually distinctive vocalizations over short ranges. Additionally, Crowell et al. (2015) observed that the species with more sensitive hearing were those associated with freshwater habitats, which are quieter compared to marine habitats with wind and wave noise.

Although important to seabirds in air, it is unknown if seabirds use hearing or vocalizations underwater for foraging, communication, predator avoidance or navigation (Crowell, 2016; Dooling & Therrien, 2012).

Diving birds may not hear as well underwater, compared to other (non-avian) species, based on adaptations to protect their ears from pressure changes (Dooling & Therrien, 2012). Because reproduction and communication with conspecifics occurs in air, adaptations for diving may have evolved to protect in-air hearing ability and may contribute to reduced sensitivity underwater (Hetherington, 2008). Hansen et al. (2020) observed that common murres (*Uria aalge*) consistently reacted to sounds produced by underwater sound bursts and mid-frequency sonar signals. There are many anatomical adaptations in diving birds that may reduce sensitivity both in air and underwater. Anatomical ear adaptations include cavernous tissue in the meatus and middle ear that may fill with blood during dives to compensate for increased pressure on the tympanum, active muscular control of the meatus to prevent water entering the ear, and interlocking feathers to create a waterproof outer covering (Crowell et al., 2015; Rijke, 1970; Sade et al., 2008). Zeyl et al. (2022) used nano-CT scanning of the ears of 127 bird species to measure the morphological adaptations to aerial and underwater hearing. Pursuit and deep diving species have heavily modified middle ears, including smaller tympanic membranes and columella footplate of the middle ear, shorter extrastapedius, and reduced cranial air

volume and connectivity. These likely facilitate hearing underwater and provide baroprotection, while potentially constraining the sensitivity of aerial hearing.

C.8.1.5 General Threats

Beach-nesting birds are vulnerable to disturbance from people, pets, and off road vehicles that may inadvertently destroy or disturb nests (North American Bird Conservation Initiative U.S. Committee, 2009). Feral species (primarily cats [*Felis catus*] and rats [*Rattus* spp.], occasionally pigs [*Sus scrofa*], and cattle [*Bos taurus*]) may destroy nesting colonies. Seabirds are especially vulnerable to feral species on islands where nests and populations have been devastated through predation or habitat destruction. Invasive plants can also eliminate nesting habitat on beaches (Clavero et al., 2009; North American Bird Conservation Initiative U.S. Committee, 2009).

Lighting on boats and on offshore oil and gas platforms has also contributed to bird fatalities in openocean environments when birds are attracted to these lights, usually in inclement weather conditions (Merkel & Johansen, 2011). Recent studies have looked at different lighting systems and how they may impact migrating songbirds (Poot et al., 2008). Land-based lighting has been linked to episodes of "fallout" (grounding) involving seabirds, especially petrels, and ship-based lighting could have similar effects (Rodríguez et al., 2017).

Large-scale wind energy development offshore Southern California and Hawaii is currently under consideration (Bureau of Ocean Energy Management, 2018) and has the potential to affect bird populations through (1) displacement from favored foraging habitats, especially to species that forage in deeper, offshore waters; and (2) mortality to species that tend to fly within the rotor-swept zones of large wind turbines (approximately 20 m and 200 m from the surface) (Biodiversity Research Institute, 2015).

Natural causes of seabird and shorebird population declines include disease, storms, and harmful algal blooms, although human activities are also associated with harmful algal blooms (Jessup et al., 2009; North American Bird Conservation Initiative U.S. Committee, 2009; Onley & Scofield, 2007). In addition, seabird distribution, abundance, breeding, and other behaviors are affected by cyclical environmental events, such as the El Niño Southern Oscillation and Pacific Decadal Oscillation in the Pacific Ocean (Congdon et al., 2007; Vandenbosch, 2000).

C.8.1.5.1 Water Quality

Spills of oil and other petroleum products pose a risk to seabirds and shorebirds through direct contamination and destruction of nesting, roosting, and foraging habitats. Estimates of bird mortality from the BP *Deepwater Horizon* oil spill in the Gulf of Mexico during 2010 are that approximately 200,000 birds were killed in the offshore area and approximately 700,000 killed along the coastline during the 103-day duration of the spill (Haney et al., 2014a, 2014b). Additional mortality occurred subsequently but has not been estimated.

Within the Study Area, the main risk of oil or other petroleum product spills is from ships, whether carrying petroleum to and from ports, or in fuel tanks, and from pipelines and onshore facilities that transport and store oil and gas. One of the largest spills in the Study Area occurred in 1989 when the tanker *Exxon Houston* broke away from its moorings and ran aground at Barber's Point on Oahu, spilling approximately 117,000 gallons of fuel and crude oil (U.S. Coast Guard, 2015).

C.8.1.5.2 Commercial Industries

Commercial fisheries are considered the most serious threat to the world's seabirds, while invasive species are the most pervasive – affecting the largest number of species; other threats include pollution, hunting, trapping, energy production, and mining (BirdLife International, 2012). A recent review of reported bycatch estimates suggests that at least 400,000 birds die in gillnets each year (Zydelis et al., 2013). Seabird bycatch in longline fisheries worldwide has been estimated as 160,000 to more than 320,000 annually (Anderson et al., 2011).

Large-scale offshore wind development may occur in highly productive areas offshore Southern California and Oahu, and impact bird populations by (1) displacing some species from their preferred foraging habitats and migration routes, and (2) increasing the mortality of species that fly within the rotor-swept zones of large turbines (Biodiversity Research Institute, 2015).

C.8.1.5.3 Disease and Parasites

Avian diseases can cause chronic population declines, dramatic die-offs or reductions in the reproductive success and survival of individual birds. They can even cause extinctions. Certain avian diseases appear to be spreading to populations previously unaffected, including to species already threatened by other factors. Examples include avian botulism, cholera, *Erysipelothrix rhusiopathiae*, West Nile virus, Mycoplasmal conjunctivitis, and highly pathogenic avian influenza (H5N1). A brief description of each follows from (BirdLife International, 2008).

Avian botulism is a bacterial disease that is arguably the most important disease of migratory birds worldwide, affecting millions of birds. Avian cholera and Erysipelothrix rhusiopathiae are two bacterial diseases that caused considerable declines of Indian yellow-nosed albatross (Thalassarche carteri) on Amsterdam Island (French Southern Territories). These two diseases may have spread to nearby colonies of sooty albatross (Phoebetria fusca) and Amsterdam albatross (Diomedea amsterdamensis) with a world population of approximately 130 birds. Avian cholera has also devastated the population of Cape cormorant (Phalacrocorax capensis) in Western Cape Province, South Africa, killing approximately 13,000 individuals between May and October 2002. The West Nile Virus, a largely mosquito-borne viral disease (causing both bird and human mortalities), has established itself over much of eastern U.S. since 1999, spreading to Latin America and the Caribbean. American crow (Corvus brachyrhynchos) and other corvid species have shown very high levels of mortality from this disease but remains relatively stable across its range. Mycoplasmal conjunctivitis, as the disease is commonly called, is caused by a unique strain of Mycoplasmal gallisepticum, a parasitic bacterium previously known to infect only poultry. This infectious disease has recently caused a significant decline in the introduced population of house finch (Carpodacus mexicanus) in eastern North America, and has started to spread to the native population of this species in western North America (BirdLife International, 2008).

Before humans arrived on the Hawaiian Islands, there were no mosquitoes or any other biting or blood sucking insects. By the mid-1800's however, mosquitoes were firmly established throughout the archipelago, introduced inadvertently through human activities. Of these, the southern house mosquito, (*Culex quinquefasciatus*) is the greatest challenge to Hawaiian bird conservation. Introduced in 1926, it is the primary vector of avian malaria and avian pox, and is implicated in the devastation and extinction of many of the native forest bird populations. The first was avian pox virus, first documented in forest birds in 1902. The second, first detected in the 1940s, was avian malaria. It is unclear when or how these diseases first appeared on the islands, it is thought they were first introduced with the importation of non-native bird species but it may also be that they have always been present on the islands at a low

level with migratory seabirds, shorebirds and waterfowl. That all changed with the relatively recent introduction of mosquitoes (Maui Forest Bird Recovery Project, 2017).

Recent research suggests that avian malaria has not only contributed to population declines and extinctions, but is affecting the elevational distributions of many native birds on the Island of Hawai'i. Native bird species experience lower rates of transmission/infection in high-altitude forests where conditions are relatively inhospitable for the mosquito vector. Bird species endemic to low- and midaltitude forests are at greater risk from this disease (Samuel et al., 2015).

Highly Pathogenic Avian Influenza viruses (H5N1) have infected domestic poultry and migratory birds since August 2020. The viruses have been linked to illness and deaths in birds throughout North America (U.S. Fish & Wildlife Service, 2024b). As of September 2024, approximately 10,036 wild U.S. birds have been detected with H5NI (Center for Disease Control and Prevention, 2024)

C.8.1.5.4 Invasive Animals

Significant threats to seabirds occur on islands, which is where seabirds breed, including predation and habitat disturbance from invasive alien species such as rats, cats and pigs. Ground nesting seabirds are particularly vulnerable to these threats, and invasive predators on islands have been the primary cause of global seabird declines, extirpations, and local extinctions (Spatz et al., 2014). Although effective island conservation can mitigate these threats, successful eradication or control of invasive species is extremely difficult in vast and sometime remote seabird habitat.

C.8.1.5.5 Climate Change

In the long term, global climate change could be the greatest threat to seabirds (North American Bird Conservation Initiative U.S. Committee, 2009). Species of seabirds that breed on low-lying Pacific islands are particularly vulnerable. For example, great frigatebird (*Fregata minor*) breeding colonies in the Pacific are largely restricted to islands with a maximum elevation of 8 m, making them vulnerable to sea level rise. Additionally, a sea level rise of 2 m would flood 39 to 91 percent of black-footed albatross nests on Midway Atoll, Hawaii (BirdLife International & National Audubon Society, 2015). Climate change impacts include changes in air and sea temperatures, precipitation, the frequency and intensity of storms, pH level of sea water, and sea level. These changes could impact the timing of migration and overall marine productivity, which could in turn have an impact on the food resources, distribution, and reproductive success of seabirds at critical times in their life cycles (Aebischer et al., 1990; Congdon et al., 2007; Davoren et al., 2012; Melillo et al., 2014).

Open-ocean seabird species are particularly vulnerable to climate change due to their low reproductive rates, their use of islands for nesting, and their reliance on a highly variable marine system (North American Bird Conservation Initiative & U.S. Committee, 2010). Coastal birds are vulnerable to climate change due to rising sea levels, which are expected to impact foraging and nesting habitat quality and quantity by flooding or fragmenting habitats such as barrier islands, beaches, and mudflats (North American Bird Conservation Initiative U.S. Committee, 2009).

C.8.1.5.6 Marine Debris

Marine debris is any persistent solid material that is manufactured or processed and directly or indirectly, intentionally or unintentionally, disposed of or abandoned into the marine environment or the Great Lakes (National Oceanic and Atmospheric Administration, 2016b). Marine debris is a growing environmental concern. With the rapid increase in global plastics production and the resulting large volume of litter that enters the marine environment, determining the consequences of this debris on

marine fauna, including seabirds and ocean health has now become a critical environmental priority, particularly for threatened and endangered species (Wilcox et al., 2016).

Plastic debris is abundant and pervasive in the world oceans and, because of its durability, is continuing to increase. The ingestion of plastics by seabirds such as albatrosses and shearwaters occurs with high frequency and is of particular concern because of impacts on body condition and the transmission of toxic chemicals, both of which affect mortality and reproduction. The rates of plastic ingestion by seabirds are closely related to the concentrations of plastics in different areas of the ocean due to waste discharges and ocean currents, and are increasing (Kain et al., 2016; Wilcox et al., 2015).

The impacts from entanglement of marine species in marine debris are clearly profound, and in many cases, entanglements appear to be increasing despite efforts over four decades to reduce the threat. Many coastal states have undertaken certain efforts to reduce entanglement rates through marine debris clean-up measures and installed fishing line recycle centers at boat landings in part due to entanglement of seabirds and other marine species. One such program is the California Lost Fishing Gear Recycling Project administered by the University of California–Davis Wildlife Health Center that began in 2005 (National Oceanic and Atmospheric Administration Marine Debris Program, 2014).

Fishing related gear, balloons and plastic bags were estimated to pose the greatest entanglement risk to marine fauna. In contrast, experts identified a broader suite of items of concern for ingestion, with plastic bags and plastic utensils ranked as the greatest threats. Entanglement and ingestion affected a similar range of taxa, although entanglement was rated as slightly worse because it is more likely to be lethal. Contamination was scored the lowest in terms of impact, affecting a smaller portion of the taxa and being rated as having solely non-lethal impacts (Wilcox et al., 2016).

There are likely other species from other regions of the U.S. that suffer injury or death from being entangled in marine debris, but are not widely recognized or reported. Most of the literature describes entanglement of marine species from Alaska, California, Puget Sound, and Florida. However, the Mid-Atlantic and Gulf of Mexico regions of the U.S. are lacking in reports of marine debris entanglement. Similarly, reports of marine debris entanglement on seabirds are limited to a few papers (National Oceanic and Atmospheric Administration Marine Debris Program, 2014). This review reported entanglement in marine debris in the U.S. of 44 species of seabirds. The majority of cases revolve around entanglement in fishing gear and abandoned, lost or otherwise discarded fishing gear and to a lesser degree other plastic debris.

Variable impacts of common debris items on the health of marine wildlife were identified, with entanglement by fishing related gear, balloons and plastic bags emerging as the greatest threat to seabirds. However, a wide variety of other items posed at least some threat to these organisms through either ingestion, contamination or both, suggesting that a comprehensive approach to preventing plastics from entering the ocean is vitally needed (Wilcox et al., 2016).

The amount, composition, and trends of marine debris on the U.S. Pacific Coast and Hawaii were assessed using data from 1998 to 2007 collected by the National Debris Monitoring Program (Ribic et al., 2012). Data from five sites on the southern California coast indicated the majority of marine debris was land-based (60 percent), followed by general source debris (31 percent) and ocean-based (8 percent) recreational and commercial sources. In contrast, data from five sites on Hawaii (Oahu) indicated most debris was from ocean-based sources (38 percent), followed by general source debris (33 percent) and land-based sources (29 percent). No items of military origin were differentiated. Land-based debris was associated with the concentration of people; general source debris consisted primarily of plastic bottles,

which may have been discarded either on land or at sea, and ocean-based debris from fishing and other maritime activities. The deposition of marine debris on beaches of the Study Area was found to be correlated with weather and to have declined in more recent years (Ribic et al., 2012).

For updated and detailed information on marine debris refer to Sections C.1.3.1.3 (Marine Debris in Nearshore and Offshore Areas off the Hawaiian Islands) and C.1.3.1.4 (Marine Debris in the Nearshore and Offshore Areas of the California Study Area).

C.8.2 Endangered Species Act-Listed Species

The following sections provide detailed species descriptions, including status and management, habitat and geographic range, population trends, predator and prey interactions, and species-specific threats for birds listed under the ESA.

C.8.2.1 California Least Tern (Sternula antillarum browni)

The California least tern is a federal and state endangered species that has been listed since 1970. California least terns are coastal and nearshore foragers and surface-feeding fish eaters. They are opportunistic in their search for prey, eating fish that are small enough to catch including anchovies (*Engraulidae* sp.) and smelt (*Atherinops* sp.). California least terns have black-capped heads and long, black-tipped narrow pale gray wings that contrast with their white bodies, and a broad, forked tail. When full grown, this species is less than 25 cm long and has a 75 cm wingspan (U.S. Fish and Wildlife Service, 2010b).

C.8.2.1.1 Status and Management

On October 13, 1970, the California least tern was listed as endangered under the ESA (35 FR 16047). No critical habitat has been designated for the California least tern. Conservation for the California least tern is addressed in multiple memoranda of understanding and INRMP for military lands and adjacent waters in the Study Area, including Naval Base Coronado (U.S. Department of the Navy, 2013c), San Diego Bay (U.S. Department of the Navy, 2013d), and Marine Corps Base Camp Pendleton (Marine Corps Base Camp Pendleton, 2012).

C.8.2.1.2 Habitat and Geographic Range

Preferred nesting habitat for the California least tern consists of beaches, dunes, and sand bars on the ocean shore (U.S. Fish and Wildlife Service, 1985). The California least tern nests in areas generally free of vegetation above the high tide mark. Colony sites are often near estuaries, lagoons, rivers, or the seacoast (U.S. Fish and Wildlife Service, 1985). Atwood and Minsky (1983) noted that before the decline of the species, at least 82 percent of known nesting sites in California were within 1 mi. of a river mouth or estuarine habitat.

California least terns spend the breeding season (April through August) in coastal waters along the central and southern California coast, as well as along the west and southwestern coast of Mexico. Their distribution is from San Francisco to Baja California on the Pacific Coast of North America (U.S. Fish and Wildlife Service, 2010b). The California least tern historically nested on coastal beaches of Monterey, California, to Cabo San Lucas, Baja California (Atwood & Minsky, 1983). The two largest nesting colonies in the state are on Marine Corps Base Camp Pendleton and Naval Base Coronado (Frost, 2016).

Foraging habitats include nearshore ocean waters, bays, river mouths, salt marshes, marinas, river channels, lakes, and ponds (Thompson et al., 1997). California least terns feed within 2 mi. of the shoreline in ocean waters less than 60 ft. deep, with most foraging within 1 mi. of shore (Atwood &

Minsky, 1983). Atwood and Minsky (1983) also observed a tendency for foraging birds to be concentrated in coastal waters near major river mouths. Foraging habitat use varies within and between years, depending on the stage of breeding and prey availability (Atwood & Minsky, 1983; BirdLife International, 2009). Atwood and Minsky (1983) noted in their coastal colony study that, before terns disperse after breeding, they typically forage within 2 mi. of nesting sites, although large groups were occasionally observed foraging at greater distances from colonies, including inland water sources. The presence of eelgrass is important because it is habitat for several prey species of the least tern such as topsmelt (U.S. Department of the Navy, 2013d).

California least terns occur in coastal waters throughout the California portion of the HCTT Study Area during the breeding, nonbreeding, and migration seasons. The current nesting range is from San Francisco Bay and south along the California coast to San Diego County which includes the California Study Area in the California Current Large Marine Ecosystem and parts north of the Study Area (Massey & Fancher, 1989). During migration, California least terns remain near the coast, although they have been observed foraging in multispecies feeding flocks 1 to 20 mi. off the western coast of Baja California in late April and early May (U.S. Fish and Wildlife Service, 2005a). The California least tern can be found in more offshore waters during the breeding season (courtship and incubation stages) when they forage farther from the nest site over open and deep water. Adults tend to travel farther when food availability is low, foraging in open ocean waters (BirdLife International, 2009).

California least terns forage by plunge-diving to catch prey in upper surface waters, usually within the first 1–2 m of water depth (U.S. Department of the Navy, 2013d). No information exists on specific dive depths for California least terns. Prey species include anchovies, topsmelt, opaleye, and gobies (BirdLife International, 2009). Prey species composition varies throughout the year, depending on availability. Length of foraging and peak foraging behavior typically occur from the end of May through mid-July after chicks hatch.

C.8.2.1.3 Population Trends

The California least tern population in California averaged about 4,300 pairs between 2000 and 2002, making up about 10 percent of the North American population (U.S. Fish and Wildlife Service, 2005a). The California population increased almost 12-fold from a low of 600 pairs in the early 1970s to roughly 7,100 pairs in 2005 (U.S. Fish and Wildlife Service, 2001, 2005a), but declined in recent years to an estimated 4,202–5,295 pairs as of 2015 (Frost, 2016). Monitoring in the 2018 and 2019 California least tern breeding season estimated 60 nesting sites and 3,741 to 4,502 breeding pairs (Sin et al., 2024).

C.8.2.1.4 Population Threats

Threats to breeding least terns include changing food resources, habitat modification due to encroaching vegetation, the alteration of river habitat, flooding and development of coastal areas, disruptive recreation, an increase in aggressive gulls that compete for nesting sites, predation by native and feral species, such as rats, great horned owls (*Bubo virginianus*), American peregrine falcons (*Falco peregrinus anatum*), burrowing owls (*Athene cunicularia*), gull-billed terns (*Gelochelidon nilotica*), black-crowned night herons (*Nycticorax nycticorax*), dogs, and cats, and disease (e.g., West Nile Virus and avian influenza) (Sidle et al., 1992; U.S. Fish and Wildlife Service, 1990, 2020b).

Anthropogenic related threats to California least terns include environmental contamination (e.g., DDT, selenium oil, and mercury), the degradation of habitat and rising sea levels associated with climate change, recreational beach use, disturbance during nesting season, intentional release of feral cats, and ultralight aircraft and drone use (U.S. Fish and Wildlife Service, 2010a, 2020b).

C.8.2.2 Hawaiian Petrel (Pterodroma Sandwichensis)

The Hawaiian petrel was recently split from the Galapagos petrel (*Pterodroma phaeopygia*) based on genetic and morphological evidence; before the split they were collectively known as the dark-rumped petrel (U.S. Fish and Wildlife Service, 2005a). The Hawaiian Petrel has a dark gray head, wings, and tail, and a white forehead and belly. It has a stout grayish-black bill that is hooked at the tip, and pink and black feet. This bird measures 16 in. in length and has a wing span of three ft. It has a distinctive call during breeding season that sounds like "oo ah oo." They also have calls that sound like the yapping of a small dog (U.S. Fish and Wildlife Service, 2012b).

C.8.2.2.1 Status and Management

The Hawaiian petrel is found only in Hawaii and is listed as endangered throughout its range under the ESA (U.S. Fish and Wildlife Service, 2005a); there is no designated critical habitat. It is known from five locations in the main Hawaiian Islands, at least two of which (Mauna Loa on Hawaii Island and West Maui) are threatened by development. Its limited distribution and declines primarily result from predation by introduced mammals and urbanization (International Union for Conservation of Nature, 2017). In some cases, predation has caused more than 70 percent nesting failure (U.S. Fish and Wildlife Service, 2005a). Numerous knowledge gaps remain for the Hawaiian Petrel such as foraging and other at-sea behavior; annual and age-specific survival, especially for non-breeders; and the scope and severity of threats at sea (U.S. Fish and Wildlife Service, 2011a). On Maui, there is a long-term monitoring program in the Haleakala National Park and efforts are made to control introduced mammals. In 1976, a perimeter fence was put up around the main colony to exclude feral goats and pigs from the habitat. The predator enclosures placed around the national park may have facilitated an increase in the number of birds in eastern Maui (International Union for Conservation of Nature, 2017). On Kauai, auditory surveys to detect colonies are ongoing, and have included documenting the first known nesting sites on Kauai in the Upper Limahuli Preserve. Also on Kauai, street lighting is shielded in critical areas and lighting on some buildings has been modified to reduce collisions. A ruling by the USFWS under the ESA has resulted in a campaign running since 2005, in which nonessential lights on Kauai are turned off or shielded between 15 September and 15 December when young birds leave their nests. The island's electricity company is helping by darkening all of its 3,000 street lights, and shielding or turning some of them off. The company has also fitted large balls to power lines in an effort to reduce the number of birds that collide with the cables. Significant improvements have been made in reducing light attraction and collision, although there is still a considerable amount of new and existing infrastructure that requires modification (International Union for Conservation of Nature, 2017).

C.8.2.2.2 Habitat and Geographic Range

Hawaiian Petrel ranges in the central Pacific and breeds only in the main Hawaiian Islands, though there are specimen records from Japan, Philippines, and Moluccas at the western edge of the distribution. On Maui, Mauna Kea and Mauna Loa, nesting takes place mainly between 2,000 and 3,000 m, in lava cavities with little vegetation nearby. Elsewhere, for example West Maui and Kauai, it nests at lower elevations, amongst dense shrubs and ferns, or in native grasslands with bracken. On Haleakala, Maui, birds nest in rock crevices and tunnels that are over 0.5 m deep, often exceeding 2 m. Generally, the nest chamber can be from 1 to 9 m deep. Pairs nest in cavities in the volcanic terrain, in burrows beneath rocks or at the base of clay cliffs. At lower elevations, they excavate burrows or nest in cavities often at the base of trees, although many burrows on Lanai are not at the base of trees. On Lanai, birds breed in dense uluhe fern habitat (*Dicranopteris linearis* and *Diplopterygium pinnatum*) and start

breeding in March, whereas on Haleakala, Maui, birds begin breeding in early February (International Union for Conservation of Nature, 2017).

The Hawaiian petrel typically feeds well offshore but tends to feed closer to shore (0 to 45 mi.) during spring than in the fall (most abundant at 170 to 230 mi.) (Spear et al., 1995). The Hawaiian petrel favors open ocean water conditions, with an average sea surface temperature of 80°F, sea surface salinity of 34 parts per thousand, wind speed of 19 mi. per hour (mph), and a wave height of 5 ft. It also prefers an average depth from the warmer surface water to the point where cold water begins (the thermocline) of 35 ft. (Spear et al., 1995).

The Hawaiian petrel is an open ocean species of the central tropical Pacific (U.S. Fish and Wildlife Service, 2005a). They occur in open ocean waters throughout most of the Hawaii portion of the Study Area and the western portion of the Transit Corridor in the Insular Pacific-Hawaiian Large Marine Ecosystem. The Hawaiian petrel occurs largely in equatorial waters of the eastern tropical Pacific, generally from 10 °S to 20 °N. Because of the difficulty in identification, the precise southeastern extent of the Hawaiian petrel and the northwestern extent of the similar Galapagos petrel remains uncertain (Spear et al., 1995).

Hawaiian petrels have important resting sites in coastal waters throughout the Hawaii Study Area in portions of the Insular Pacific-Hawaiian Large Marine Ecosystem. An area of the north shore of Kauai is widely known as a resting location for Hawaiian petrels (Birding Hawaii, 2004). Based on known or suspected colony sites, gathering areas likely occur near shore on Lehua Rock, Kauai, Molokai, Lanai, Maui, and Hawaii (Day & Cooper, 1995; Day et al., 2003; U.S. Fish and Wildlife Service, 2005a) and perhaps around Kahoolawe (U.S. Fish and Wildlife Service, 2005a). These areas provide resting habitat before the birds fly to inland nesting colonies. Hawaiian petrels move to and from nesting colonies during dusk and dawn (International Union for Conservation of Nature, 2017).

It has been found that at least some Hawaiian petrels nesting on Lanai feed in waters around the Aleutian Islands, as shown through the use of tracking devices on several breeding individuals. The species usually forages in mixed species flocks, typically over schools of predatory fish species. Hawaiian petrels eat mostly squid (50 to 75 percent of their diet), fish, and crustaceans. They forage both night and day; they capture prey by resting on the water surface and dipping their bill and by aerial pursuit of flying fish (International Union for Conservation of Nature, 2017). Although the range of Hawaiian petrels is unknown, birds have been recorded as far as 600 mi. north and 1,000 mi. south of Hawaii (U.S. Fish and Wildlife Service, 2022).

C.8.2.2.3 Population Trends

A population estimate supported by pelagic surveys put the total population at 19,000 (range 10,600– 34,400), including a best estimate of 4,500–5,000 breeding pairs. However, the discovery of previously unknown colonies in 2006–2007 may bring the total population closer to the upper estimate of 6,500–8,300 pairs (International Union for Conservation of Nature, 2017). The current status of the Hawaiian petrel is uncertain due to the difficulty surveying this species. Recent at-sea surveys are currently being analyzed for Hawaiian petrel and Newell's shearwater (U.S. Fish and Wildlife Service, 2011a). The total population of Hawaiian petrels was estimated at 20,000, with a breeding population of 4,500–5,000 pairs (Spear et al., 1995; U.S. Fish and Wildlife Service, 2005a) overall population trends on the Hawaiian Islands are not known (U.S. Fish and Wildlife Service, 2005a, 2022). Numbers of breeding Hawaiian petrels on Maui appear stable and have increased in areas of the Haleakala National Park, where predators are being managed (U.S. Fish and Wildlife Service, 2005a). On Hawaii, numbers may be declining because of predation by introduced species (U.S. Fish and Wildlife Service, 2005a).

C.8.2.2.4 Population Threats

Threats to the Hawaiian petrel include predation by introduced mammals, development, light attraction and collision, ocean pollution, and disturbance of its breeding grounds. The petrel does not have any natural defenses against predators such as rats, feral cats, and mongooses, and its burrows are very vulnerable (U.S. Fish and Wildlife Service, 2012b). Although predator control now occurs at several Hawaiian petrel breeding sites, the threat posed by introduced predators remains significant throughout the species' range (U.S. Fish and Wildlife Service, 2011a). Recently, Young et al. (2023) successfully translocated 110 Hawaiian petrels (along with 86 Newell's shearwaters) to a predator free enclosure on Kauai, establishing the first predator-free colony for Hawaiian petrels.

Collisions with artificial lights, utility poles, and fences kill Hawaiian petrels on some islands (International Union for Conservation of Nature, 2017). Little progress has been made toward addressing the chief threats to or meeting the recovery criteria for Hawaiian petrels. Remnant breeding colonies thought to occur on west Maui, Hawaii Island, Kauai, Lanai, and possibly Molokai are not mapped or managed. These colonies are certainly subject to predation by alien mammals, possibly are subject to the threat of light attraction and collision, and most are thought to be dwindling as well (U.S. Fish and Wildlife Service, 2011a).

The species may be adversely affected by declines in the populations of large predatory fish that drive prey species to the surface. In addition, a significantly lower percentage of birds come ashore to nest during El Niño years (ca.40 percent compared to ca.65 percent normally), suggesting that the species is sensitive to such disturbances in environmental conditions (International Union for Conservation of Nature, 2017). In addition, the species is currently threatened with habitat disturbance by goats, pigs and cattle. On Lanai, habitat degradation caused by the invasive tree, strawberry guava *Psidium cattleianum*, may be the biggest threat to the long term survival of the colony. On occasion, fledglings become grounded after colliding with lights, and mortality sometimes results from collisions with fences and powerlines. Once on the ground, fledglings are unable to fly and are killed by cars or cats and dogs, or die from starvation or dehydration (International Union for Conservation of Nature, 2017).

C.8.2.3 Short-tailed Albatross (Phoebastria albatrus)

The short-tailed albatross was formerly in the genus *Diomedea* and known as Steller's albatross. The largest of the north Pacific albatrosses, the adult short-tailed albatross has a prominent pink bill, white body, and a yellow wash on the head. Immature birds are dark but can be distinguished from black-footed albatross by their pink bill and flesh-colored feet. Adults can reach wingspans of 7 ft. (U.S. Fish and Wildlife Service, 2012d).

C.8.2.3.1 Status and Management

On July 31, 2000, the short-tailed albatross was listed as endangered throughout its range under the ESA throughout its range (65 FR 46643). Their decline at the beginning of the 20th century was attributed, in part, to albatross being killed for their feathers and various other body parts, including their down feathers being used for quilts and pillows, and wing and tail feathers being used for writing quills; their bodies were processed into fertilizer, and their eggs were collected for food (65 FR 46643). In 2020, USFWS indicated that short-tailed albatross are making good progress toward meeting some delisting recovery criteria, however a change in status was not recommended in their review. Critical habitat has not been designated or proposed for the short-tailed albatross. In the 2000 final rule (65 FR 46643), the

USFWS determined that designation of critical habitat was not prudent due to the lack of habitat-related threats to the species, the lack of specific areas in U.S. jurisdiction that could be identified as meeting the definition of critical habitat (U.S. Fish and Wildlife Service, 2008c).

C.8.2.3.2 Habitat and Geographic Range

The range of the short-tailed albatross extends from Siberia south to the China coast, into the Bering Sea and Gulf of Alaska south to Baja California, Mexico, and throughout the North Pacific. Breeding is primarily restricted to islands in Japan and Taiwan, principally Torishima Island and the Senkaku Islands of Japan (U.S. Fish and Wildlife Service, 2008c, 2020a). Short-tailed albatrosses are typically found in the open ocean and tend to concentrate along the edge of the continental shelf (NatureServe, 2004). Upwelling zones are not only nutrient rich, but they also bring prey (for example, squid and fish) typically found only in deeper water to the surface, where they become available to albatrosses. Upwelling occurs when the wind moves warm, nutrient poor water away from the area, which allows colder, nutrient rich water to rise to the surface of the ocean. Short-tailed albatross nest on isolated, windswept, offshore islands with restricted human access (U.S. Fish and Wildlife Service, 2000). Current and historical nesting habitat can be described as flat to steep slopes that are sparsely or fully vegetated. Short-tailed albatrosses disperse throughout the temperate and subarctic North Pacific approximately from May to October when they are not breeding, from Japan through California (U.S. Fish and Wildlife Service, 2005a, 2008a). Non-breeders and failed breeders disperse from the colony months sooner. While many non-breeders return to the colonies each year, the presence of immature birds far from the colony (such as the U.S. Pacific coast) during the breeding season suggests that some immature birds may spend years at sea before they return to the colony (U.S. Fish and Wildlife Service, 2005b).

The diet includes squid (especially the Japanese common squid [*Todarodes pacificus*]), shrimp, fish (including bonitos [*Sarda* sp.], flying fishes [*Exocoetidae*] and sardines [*Clupeidae*]), flying fish eggs, and other crustaceans. Short-tailed albatross forages diurnally and possibly nocturnally, either singly or in groups (occasionally in the 100s). The species is a surface feeder and scavenger, and predominately takes prey by surface-seizing, not diving (U.S. Fish and Wildlife Service, 2008b).

Open Ocean

The short-tailed albatross is an open ocean species that occurs throughout the Hawaii Study Area, Transit Corridor, and California Study Area. The range of the short-tailed albatross extends from Siberia south to the China coast, into the Bering Sea and Gulf of Alaska south to Baja California, Mexico, and throughout the North Pacific, including the Northwestern Hawaiian Islands (Committee on the Status of Endangered Wildlife in Canada, 2003; Harrison, 1983; Roberson, 2000). Their at-sea distribution includes the entire North Pacific Ocean north of about 20 latitude °N I. Short-tailed albatrosses move seasonally around the North Pacific Ocean, with high densities observed during the breeding season (December through May) in Japan and throughout Alaska and along the west coast of North America during the post-breeding season (April through September) (International Union for Conservation of Nature, 2017). Nonbreeding subadults can be found in all areas throughout the year. They are seen regularly in the North Pacific Subtropical Gyre (U.S. Fish and Wildlife Service, 2005b).

California Current Large Marine Ecosystem

Short-tailed albatrosses occasionally occur in California Study Area portion of the California Current Large Marine Ecosystem, which is part of the Study Area. As the population began a gradual recovery after 1950, sporadic sightings have been recorded off California (International Union for Conservation of Nature and Natural Resources, 2010c). Based on the number of sightings in the California Study Area, the short-tailed albatross is considered rare in that portion of the Study Area, as well as off the entire California coast. Breeding does not occur in the Southern California Bight, but because of the unique circulation and upwelling characteristics of this area, potential foraging habitat exists. Two documented sightings of the short-tailed albatross have occurred in southern California. Roberson (2000) reported a sighting in 1977 of an all-dark immature bird approximately 90 mi. west of the San Diego area. McCaskie and Garrett (2002) reported a sighting in the vicinity of Santa Barbara Island in late February of 2002.

Insular Pacific-Hawaiian Large Marine Ecosystem

Short-tailed albatrosses occur in coastal waters throughout the Hawaii portion of the Study Area in the Insular Pacific-Hawaiian Large Marine Ecosystem. The short-tailed albatross regularly occurs on Midway Atoll and has been observed at other Northwestern Hawaiian Islands. Since the 1930s, short-tailed albatrosses have been occasionally reported during the breeding season at Midway Atoll. Some of these short-tailed albatrosses were recorded for several successive years. The first confirmed nest site that produced an egg did not occur until 1993 (International Union for Conservation of Nature and Natural Resources, 2010c). A chick was fledged by a breeding pair on Midway Atoll in 2011, 2012, and 2014 (U.S. Fish and Wildlife Service, 2014). Nesting elsewhere on the Northwestern Hawaiian Islands has been attempted, but successful nesting has not been confirmed (U.S. Fish and Wildlife Service, 2005b). In the Hawaiian Islands, there was an unconfirmed sighting at Barking Sands on Kauai during March 2000 (Birding Hawaii, 2004). Other known occurrences in Hawaii are of single birds (in 1976 and 1981) at French Frigate Shoals in the Northwestern Hawaiian Islands (U.S. Fish and Wildlife Service, 2008b).

Short-tailed albatrosses are surface feeders and scavengers, feeding more inshore than other North Pacific albatrosses. In Japan, their diet consists of shrimp, squid, and fish (including bonita, flying fish, and sardines); diet information is not available for birds in the Study Area (U.S. Fish and Wildlife Service, 2005b). Unlike other North Pacific albatrosses, short-tailed albatrosses frequently feed in sight of land.

C.8.2.3.3 Population Trends

The total population estimate for breeding age short-tailed albatrosses as of the 2013–2014 nesting season is 1,928 individuals, including approximately 1,624 at Torishima (Japan), 293 on the Senkaku (or Diaoyutai) Islands (in disputed ownership among China, Taiwan, and Japan), 4 in the Northwestern Hawaiian Islands, and a few birds on other Japanese islands (U.S. Fish and Wildlife Service, 2014). Per the 2018–2019 breeding season, the number of breeding pairs was 1,011 and the total population of short-tailed albatross was estimated at 7,365 (U.S. Fish and Wildlife Service, 2020a).

The Torishima population is growing rapidly, averaging 8.9 percent annually (U.S. Fish and Wildlife Service, 2020a). Overall, the high population growth rates continue, and some substantial threats are being addressed in much of the species' range. However, to ensure the continuing recovery of the species, it is important to consider sources of uncertainty and work toward reducing those threats that adversely affect short-tailed albatrosses. The population does not yet meet the recovery goals for downlisting or delisting, and therefore, the short-tailed albatross remains endangered throughout its range (U.S. Fish and Wildlife Service, 2020a).

C.8.2.3.4 Population Threats

Short-tailed albatrosses have survived multiple threats to their existence. During the late 1800s and early 1900s, feather hunters clubbed to death an estimated five million of them, stopping only when the species was nearly extinct. In the 1930s, nesting habitat on the only active nesting island in Japan was

damaged by volcanic eruptions, leaving fewer than 50 birds by the 1940s. Loss of nesting habitat to volcanic eruptions, severe storms, and competition with black-footed albatrosses for nesting habitat continue to be natural threats to short-tailed albatrosses today. In addition, predation of short-tailed albatross by white-tailed eagles (*Haliaeetus albicilla*) and Steller's sea eagles (*H. pelagicus*) are known to occur.

Current threats to this species include ingestion of plastics mistaken for food items, volcanic eruption (at Torishima, Japan), typhoons, sunken longline fishing in Alaska and Russia, jig/troll fishery in Japan, invasive species at colonies (cats, rats, and plants), and researcher disturbance (U.S. Fish and Wildlife Service, 2005b). The prevalence and extent of plastic impacts needs further investigation to determine its acute and long-term effects on the short-tailed albatross (U.S. Fish and Wildlife Service, 2014). Additional human-induced threats include contamination from oil spills, and potential predation by introduced mammals on breeding islands. Furthermore, incidental interactions from commercial longline gear, though McCracken (2014) asserts in an internal report, there has not been an observed incidental interaction with a short-tailed albatross during the history of the NMFS observer program with respect to the Hawaii deep-set longline fishery. Shipping conflicts and potential oil spills appear to be growing threats but the likelihood and magnitude is uncertain. Global climate change may be causing changes in the distribution of the short-tailed albatross in the North Pacific, but the overall impact of that change is also unknown (U.S. Fish & Wildlife Service, 2024a). The lack of information about the magnitude or impact of these threats on the short-tailed albatross results in uncertainty about the future recovery of the population (U.S. Fish and Wildlife Service, 2014).

C.8.2.4 Marbled Murrelet (Brachyramphus marmoratus)

The marbled murrelet is a small, chubby seabird that has a very short neck. During the breeding season it has dark brown to blackish upperparts and a white belly and throat that are greatly mottled. During the winter the upperparts become grey, dark marks form on the sides of the breast and a white ring develops around the eye. Males and females are similar in appearance and size (U.S. Fish & Wildlife Service, 2024a).

C.8.2.4.1 Status and Management

On October 1, 1992, the marbled murrelet (*Brachyramphus marmoratus*) was listed as a threatened species in California, Oregon, and Washington under the ESA (57 FR 45328). This species is also considered endangered by the state of California (California Department of Fish and Wildlife, 2016). Marbled murrelet populations have suffered significant declines in the Pacific Northwest, caused primarily by the removal of essential nesting habitat by logging and coastal development . The most recent 5-year review was completed in 2024 (U.S. Fish & Wildlife Service, 2024a). Based on the evaluation of murrelet populations, habitats, and threats, USFWS (2024a) determined that the murrelet should remain listed as threatened. To stem these declines, critical habitat was designated in 1996 (61 FR 26256) and revised in 2011 (81 FR 51348) to protect mature and old-growth forest nesting habitat determined to have been occupied by the species at the time of listing. The entire area of designated critical habitat occurs outside of the Study Area.

C.8.2.4.2 Habitat and Geographic Range

Murrelets spend most of their lives in the marine environment where they forage in nearshore areas and consume a diversity of prey species, including small fish and invertebrates. In their terrestrial environment, the presence of platforms (large branches or deformities) used for nesting is the most important characteristic of their nesting habitat. Murrelet habitat use during the breeding season is positively associated with the presence and abundance of mature and old-growth forests, large core areas of old-growth, low amounts of edge habitat, reduced habitat fragmentation, proximity to the marine environment, and forests that are increasing in stand age and height (U.S. Fish and Wildlife Service, 2009). Marbled murrelets do not build a nest but use natural features, such as moss, clumps of mistletoe, or piles of needles as a nest site on tree limbs (International Union for Conservation of Nature, 2017; Wilk et al., 2016). Nests are in large conifers, such as coast redwood and western hemlock, in old-growth stands typically within 35 mi. of marine waters. Important features in nesting habitat are stands of 500 acres or larger, multistoried canopy layers, and less than average canopy closures (Grenier & Nelson, 1995; Hamer & Nelson, 1995; Miller & Ralph, 1995). In addition, habitat along major drainages (e.g., rivers and streams) is a key component, as murrelets tend to use these drainages as flight corridors to and from inland nest sites (Mclver et al., 2021).

Marbled murrelets generally remain near breeding sites year-round in most areas (U.S. Fish and Wildlife Service, 2005a). Birds occur closer to shore in exposed coastal areas and farther offshore in protected coastal areas (McIver et al., 2021). The highest concentrations are found in protected inshore waters (U.S. Fish and Wildlife Service, 2005a). Physical and biological oceanographic processes that concentrate prey (such as upwelling and rip currents) have an important influence on the foraging distribution of marbled murrelets (Day & Nigro, 2000; Jodice & Collopy, 1999; Strachan et al., 1995; Whitworth et al., 2000). They are more commonly found inland during the summer breeding season but make daily trips to the ocean to gather food and have been detected in forests throughout the year. When not nesting, the birds live at sea, spending their days feeding close to shore and then moving several miles offshore at night.

Marbled murrelets only occur in coastal waters of the California Current Large Marine Ecosystem within the northeast corner of the California Study Area. Eight reported sightings of marbled murrelets have been documented within the Study Area off the California coast. Sightings have been reported at Marina del Rey, off Santa Barbara Island, at Mugu Lagoon in Ventura County, along the coast in San Diego County, and at the northern end of the Study Area near San Simeon Point (McCaskie & Garrett, 2001). All of these documented sightings were recorded between November and March.

Foraging habitat in the Southern California Bight occurs usually within 3 mi. of the coast in waters less than 195 ft. deep (Day & Nigro, 2000; Felis et al., 2022; Henkel et al., 2004; Strong, 2020); however, because upwelling areas represent important foraging habitat for the marbled murrelet, the potential exists for individuals to be observed farther offshore in the Southern California Bight.

Winter distributions of marbled murrelets are poorly documented. In California, most birds appear to be year-round residents near breeding areas (Naslund, 1993), although dispersal in the winter as far south as Southern California and northern Mexico has been documented (Erickson et al., 1995). A single sighting has occurred at Ensenada Harbor (Erickson et al., 1995). The species is a rare fall/winter vagrant (occurring outside of its normal range) to Southern California, and is "accidental" from the U.S.-Mexico border south along the Mexico coastline (Strong, 2020).

Marbled murrelets feed opportunistically on small fish, including sand lance, anchovy, herring, capelin, and smelt, and also on invertebrates (U.S. Fish and Wildlife Service, 1996, 2005b). Feeding takes place in the nearshore marine environment, primarily in protected waters where both Pacific sand lance and surf smelt occur (Burger, 2002; Whitworth et al., 2005). Individuals forage by diving, using their wings for underwater propulsion. The murrelet forages by pursuit diving in relatively shallow waters, usually between 20 and 80 m in depth. Most birds are found as pairs or as singles in a band about 300–2,000 m

from shore. Foraging dive times averaged about 16 seconds. Murrelets generally forage during the day and are most active in the morning and late afternoon hours. Some foraging occurs at night (Ralph & Miller, 1995).

C.8.2.4.3 Population Trends

The total estimated marbled murrelet population is 358,200–417,500 individuals, rounded here to 350,000–420,000 individuals, based on 271,000 individuals in Alaska, 72,600–125,600 in British Columbia, and 14,631–20,952 individuals in Washington, Oregon and California (U.S. Fish & Wildlife Service, 2024a). The population was estimated to have declined by approximately 15 percent in 2000 to 2007 in Washington, Oregon, and California, with a 50 percent decrease in Alaska in 1972 to 1992 and a 29 percent decrease in 2001 to 2010, and a 40 percent decrease in some parts of British Columbia in 1982–1992. At-sea surveys over the past 25 years in British Columbia suggest declines of approximately 1 percent per year although radar surveys suggest the population may have been relatively stable since 1999. Availability of nesting habitat in British Columbia, which is strongly correlated with local breeding populations, has declined by 22 percent between 1978 and 2008 and is continuing. Declines are suspected to be very rapid and ongoing due to very low measured productivity rates (U.S. Fish & Wildlife Service, 2024a). Marbled murrelet 2020 population monitoring in southern Oregon and northern California estimated 6,821 individuals in the region. This estimate is consistent with past population estimates (Strong, 2020).

Within Conservation Zones 1 and 2, recent trends in abundance showed declines of -4.6 percent and -3.5 percent, respectively (U.S. Fish & Wildlife Service, 2024a). Within Zones 3 and 4, recent trends in abundance indicated slight increases of 1.6 percent and 2.8 percent, respectively. Within Zones 5 and 6, trends were slightly positive, but statistically flat at 1.5 percent and 0.01 percent, respectively. Productivity was low in all zones. Population resiliency ranges from moderate to very low. It is highest in the central portion of the range, in Conservation Zones 3 and 4, and lower in in the northern and southern portions of the range, in Conservation Zones 1, 2, 5, and 6. USFWS (2024a) described the 2018–2023 Zone-specific abundance range for marbled murrelets as Zone 1: 3,143–3,843 individuals, Zone 2: 1,018–1,657 individuals, Zone 3: 8,249–8,414 individuals, Zone 4: 5,132–6,822 individuals, Zone 5: 42 individuals, and Zone 6: 5,132–6,822 individuals.

C.8.2.4.4 Population Threats

The decline of marbled murrelets has been largely caused by extensive removal of late-successional and old growth coastal forest which serve as nesting habitat for murrelets. Additional factors in its decline include high nest-site predation rates and human-induced mortality in the marine environment from disturbance, gillnets, and oil spills. In addition, murrelet reproductive success is strongly correlated with the abundance of mid-trophic level prey. Effects to the marine environment that impact the availability of prey can occur through overfishing or oceanographic variation from weather or climate events. Affects to adults in the marine environment from disturbance events like underwater detonations or pile driving can also impact their ability to forage and successfully provide for their young (U.S. Fish and Wildlife Service, 2009). An estimated 3,500 murrelets are killed annually in Alaska by gill-net fisheries (Carter et al., 2005; Piatt & Naslund, 1995). In addition, more than 1,000 oiled marbled murrelet carcasses were collected after the Exxon Valdez oil spill in Alaska (Carter & Kuletz, 1995). Nest failure is caused by predation by raptors, ravens, and jays (Nelson, 1997; Pastran & Lank, 2024).

C.8.2.5 Newell's Shearwater (Puffinus auricularis newelli)

The Newell's shearwater or 'a'o as native peoples refer to it, is a medium-sized shearwater measuring 12 to 14 in. with a wing span of 30–35 in. It has a glossy black top, a white bottom, and a black bill that is sharply hooked at the tip. Its claws are well adapted for burrow excavation and climbing (U.S. Fish and Wildlife Service, 2012c).

As of May 2016, Newell's shearwater is considered a subspecies of Townsend's shearwater (*P. auricularis*) by the USFWS (*FR* 81 (91), 29165–29166, May 11, 2016). It is regarded by some authorities as a distinct species, *P. newelli* (American Ornithological Society, 2018; International Union for Conservation of Nature, 2017), and at least one author (Harrison, 1983) considered Newell's shearwater a subspecies of Manx shearwater (*P. puffinus newelli*), but since 1982, most authorities have considered it a subspecies of Townsend's shearwater (American Ornithologists' Union, 1998). Newell's shearwater is also known as Newell's dark-rumped shearwater. The Newell's shearwater is a bird of the open tropical seas and offshore waters near breeding grounds. During their nine-month breeding season from April through November, they nest in burrows under ferns on forested mountain slopes. These burrows are used year after year and usually by the same pair of birds. Although Newell's shearwater is capable of climbing shrubs and trees before taking flight, it needs an open downhill flight path through which it can become airborne (U.S. Fish and Wildlife Service, 2012c).

C.8.2.5.1 Status and Management

The Newell's shearwater was listed as a threatened species by the USFWS in 1975 (U.S. Fish and Wildlife Service, 2012c), and under evaluation to be upgraded to endangered (U.S. Fish and Wildlife Service, 2011b). This species is also listed as threatened by the state of Hawaii (U.S. Fish and Wildlife Service, 2005a). Newell's shearwater appears to have declined very rapidly on its main breeding island, possibly associated with the impacts of Hurricane Iniki in 1992, and continues to decline, with two known colonies in the early 1980s, and possibly a third, now abandoned. Combined with longer term declines owing to a number of other threats, it qualifies as Endangered (U.S. Fish and Wildlife Service, 2017a). A federal recovery plan was finalized in 1983 (U.S. Fish and Wildlife Service, 1983). The Newell's shearwater was once abundant on all main Hawaiian Islands. Today, the majority of these birds nest primarily in mountainous terrain between 500 and 2,300 ft. on Kauai. This seabird was reported to be in danger of extinction by the 1930s. The introduction of the mongoose, cat, black rat, and Norway rat may have played a primary role in the reduction of ground nesting seabirds (U.S. Fish and Wildlife Service, 2012c).

Newell's shearwater faces a high level of threat, the population is declining sharply, the threats are difficult and costly to mitigate, the threats are largely unmitigated, and the listed entity is currently recognized as a subspecies. This species' sharp decline and the level of threat warrant reclassification of Newell's shearwater from threatened to endangered as it is no longer "likely to become an endangered species" but is now "in danger of extinction throughout all of its range." (U.S. Fish and Wildlife Service, 2011b). Within the Hawaiian Islands Bird Conservation Region, Newell's shearwater is evaluated as highly imperiled, the most serious category, because of restricted breeding distribution and threats to breeding populations (U.S. Fish and Wildlife Service, 2003). There is no critical habitat designation for the Newell's shearwater.

Newell's shearwater was thought to be extinct by 1908 as a consequence of subsistence hunting by Polynesians and predation by introduced rats, pigs, and dogs. However, they were rediscovered offshore in 1947. One was collected on Oahu in 1954 (Day et al., 2003) and Newell's shearwaters were confirmed

as still breeding on Kauai in 1967 (U.S. Fish and Wildlife Service, 2005a). The two most important factors limiting population growth are low breeding probability (birds do not mature until 6 years of age and a high proportion are nonbreeding adults), and high rates of predation on adults and subadults (U.S. Fish and Wildlife Service, 2011b). Predator control in key habitat areas, the establishment of Bird Salvage-Aid Stations, translocation, and light attraction studies have been initiated to help save the Newell's shearwater. Outreach to Kauai's local community has resulted in people picking up injured birds and bringing them to aid stations for care and release, giving the seabirds a chance to live (U.S. Fish and Wildlife Service, 2012c).

C.8.2.5.2 Habitat and Geographic Range

Newell's shearwater occurs in open ocean waters in the southern portion of the Hawaii portion of the Study Area and into the western portion of the Transit Corridor Study Area. They spend most of their time in the open ocean year-round (U.S. Fish and Wildlife Service, 2005a) and come ashore only to nest. They avoid inshore waters except when gathering before they fly inland to breeding colonies at night (International Union for Conservation of Nature, 2017).

Newell's shearwaters forage only over open ocean waters of depths reportedly much greater than 6,560 ft. (Spear et al., 1995). Even when nesting, they feed over deep waters and are typically not within 15 mi. of island shores (International Union for Conservation of Nature, 2017). In particular, they find abundant food along oceanic fronts, such as the Equatorial Countercurrent (Spear et al., 1995). Preferred average ocean conditions are 80°F sea surface temperature, 34.5 parts per thousand sea surface salinity, and 250 ft. depth to cold water (Spear et al., 1995). The meteorological conditions favored by Newell's shearwaters are frequent clouds and rain squalls typical of intertropical convergence zones (Spear et al., 1995).

Although the diet of the Newell's shearwater is not well known, evidence suggests that squid are a major dietary item. It often forages hundreds of km offshore, often in large, mixed species flocks associated with schools of large, predatory fish that drive prey species to the ocean surface. Newell's shearwaters capture food by pursuit-plunging (diving into water and swimming after prey, typically 10 to 30 m deep), usually in company with multispecies feeding flocks associated with tuna (International Union for Conservation of Nature, 2017). This species is not attracted to discarded fish byproducts and does not follow ships (Onley & Scofield, 2007).

Insular Pacific-Hawaiian Large Marine Ecosystem

Newell's shearwater occurs in coastal waters throughout the Hawaii portion of the Study Area during the breeding season. Newell's shearwater nesting is entirely confined to the main Hawaiian Islands, from Lehua Rock east to Hawaii. Nesting is known on Lehua Rock, Kauai, Molokai, and Hawaii. No population estimates exist for the small nesting colonies that exist on Lehua Rock and Molokai (Day & Cooper, 1995; International Union for Conservation of Nature, 2017; U.S. Fish and Wildlife Service, 2005a). About 20 breeding colonies of Newell's shearwaters are known in the main Hawaiian Islands, but others probably exist (International Union for Conservation of Nature, 2017). In 1992, 11 colonies were known on Kauai. There is evidence but no confirmation of nesting on Oahu, Maui, and Lanai (U.S. Fish and Wildlife Service, 2005a).

Newell's shearwaters nest on Kauai at high elevations (525–3,935 ft.) on steep, densely vegetated mountain slopes and in burrows or deep rock crevices, although a substantial number also nest on dry sparsely vegetated cliffs on the Na Pali coast of Kauai and on Lehua Island (Reynolds & Ritchotte, 1997; U.S. Fish and Wildlife Service, 2005a). The use of steep slopes (mostly greater than 65 degrees) for

nesting is probably a consequence of predation pressure from introduced pigs, mongooses, and cats; they select sites where there is either an open canopy of trees and ground cover of uluhe ferns or a dense ground cover of tussock grasses (International Union for Conservation of Nature, 2017).

On the Island of Hawaii, Newell's shearwaters fly over the entire island except the southwestern coast. Shearwaters are most numerous flying to and from the Kohala Mountains on the north coast (Day et al., 2003). During adult presence in the breeding season (April to September), Newell's shearwaters gather on the water close to shore before they fly inland around sunset (International Union for Conservation of Nature, 2017). Based on known or suspected colony locations, Newell's shearwaters are expected to be found gathering in early evening at Niihau (north end around Lehua Rock), Kauai, Oahu, Maui, Molokai, Lanai, and Hawaii from April to September.

Open Ocean

During the breeding season, some Newell's shearwaters forage west and north of the Hawaiian Islands so that the central part of their marine range moves northward in the Transit Corridor portion of the Study Area (International Union for Conservation of Nature, 2017; U.S. Fish and Wildlife Service, 2005a).

C.8.2.5.3 Population Trends

Results from 1980 and 1994 surveys estimated Newell's shearwater pelagic populations at 84,000 individuals (with a 95 percent confidence interval of 57,000 to 115,000) and from this the breeding population is estimated at 16,700 to 19,300 pairs. Radar data from 1993 and 1999–2001 across 13 sites indicates a 60 to 62 percent decline in numbers visiting Kauai, while recoveries of stranded young birds showed a 72 percent decline over the same time period (Day & Cooper, 1995; Day et al., 2003). From 1998 to 2011 surveys, the at-sea populations are estimated at 27,011 (with a 95 percent confidence interval of 18,254 to 37,125) (U.S. Fish & Wildlife Service, 2016).

Population models incorporating best estimates of breeding effort and success yielded a population decline of 3.2 percent annually. When variables estimating the anthropogenic mortality suffered by the species (predation, light attraction, and collision) were included, these models predicted a population decline of 30 to 60 percent over 10 years. Combining this with longer term declines owing to habitat loss, introduced predators, disorientation owing to urban lighting and collision with powerlines, the species is estimated to be declining at rates exceeding 50 percent over 47 years, three generations (International Union for Conservation of Nature, 2017). Population in the 1980s and early 1990s was estimated at about 84,000, but numbers in 2000 may have been only 21 percent of what they were in 1987 (U.S. Fish and Wildlife Service, 2005a). The largest known population, found on Kauai, was devastated by two hurricanes in 1982 and 1992. Since that last storm, the species has been in steady decline on Kauai. The remaining adults and fledglings are suffering significant deaths from utility pole and line strikes (International Union for Conservation of Nature, 2017). Between 1978 and 2007, more than 30,000 Newell's shearwaters were picked up by island residents from Kauai's highways, athletic fields, and hotel grounds (U.S. Fish and Wildlife Service, 2012c). Continuing forest habitat destruction and predation from introduced mammals are also taking a toll on this species (International Union for Conservation of Nature, 2017).

C.8.2.5.4 Population Threats

Historical threats to Newell's shearwater included subsistence hunting by Polynesians and predation by introduced species (a continuing threat) including rats, dogs, pigs, barn owls, feral cats, and the small Indian mongoose (*Herpestes auropunctatus*) (Hawaii Department of Land and Natural Resources, 2005).

Recently, Young et al. (2023) successfully translocated 86 Newell's shearwaters (along with 110 Hawaiian petrels) to a predator free enclosure on Kauai, establishing the first predator-free colony for Newell's shearwaters.

Current threats include hooking and drowning on commercial longline gear (McCracken, 2014), artificial lights (e.g., street and resort lights) along the coast that blind and disorient fledglings. Once on the ground, these fledglings are unable to fly and thousands are killed each year by cars, cats, and dogs. In addition, adults can collide with power facilities and associated utility wires and associated lines are in the direct path of known Newell's flight corridors. Additional threats are the loss and degradation of forested habitat caused by introduced plants and herbivores.

On Kauai, hurricanes Iwa and Iniki devastated the forests in 1982 and 1992 (Ainley et al., 1997) and, since the latter, the species' population has been declining. Given that a large proportion of the population breeds on Kauai, catastrophic events, like hurricanes, are a serious threat (International Union for Conservation of Nature, 2017).

C.8.2.6 Band-rumped Storm-petrel (Oceanodroma [Hydrobates] castro), Hawaii Distinct Population Segment

The Hawaii DPS of band-rumped storm-petrel is also known as the Hawaiian storm-petrel (American Ornithologists' Union, 1998; Harrison, 1983). It is intermediate in many respects between the Wilson's and Leach's storm-petrels. Plumage is blackish-brown overall with pale wing bars and a clear, curved white band across rump; white on rump is more extensive than on Leach's but less than on Wilson's (where white extends fully onto undertail coverts). The band-rumped storm-petrel is difficult to identify reliably at sea (U.S. Fish and Wildlife Service, 2017b).

C.8.2.6.1 Status and Management

Storm-petrels are the smallest of all the oceanic seabirds (Onley & Scofield, 2007). The Hawaiian population had been a candidate for listing under the ESA since 1989 (U.S. Fish and Wildlife Service, 2004), and was listed as an endangered DPS in 2016 (81 FR 67786). The global population is not a conservation concern due to large populations in Japan and the Galapagos Islands (International Union for the Conservation of Nature and Natural Resources, 2010; U.S. Fish and Wildlife Service, 2005a). In the Hawaiian Islands, band-rumped storm-petrels are the rarest breeding seabirds (International Union for the Conservation of Nature and Natural Resources, 2010; U.S. Fish and Wildlife Service, 2005a). The State of Hawaii categorizes the local population as endangered (U.S. Fish and Wildlife Service, 2005a) and regards it as highly imperiled within the Hawaiian Islands Bird Conservation Region, based on population size, breeding distribution, and threats to breeding distribution (U.S. Fish and Wildlife Service, 2003).

C.8.2.6.2 Habitat and Geographic Range

Hawaiian Band-rumped storm-petrels prefer warm deep water of 1,000 m to more than 2,000 m deep. This species occurs close to land where deep water is near an island; otherwise, they occur offshore or in upwelling regions (International Union for the Conservation of Nature and Natural Resources, 2010). Preferred waters range from 80 to 84 °F (International Union for the Conservation of Nature and Natural Resources, 2010). Nesting habitat in the main Hawaiian Islands consists of steep cliffs and barren lava flows at high elevations. Nests are in burrows or crevices in rock or lava (International Union for the Conservation of Nature and Natural Resources, 2010; U.S. Fish and Wildlife Service, 2004, 2005a). Once widespread along the Hawaiian island chain, as evidenced by midden sites across the main Hawaiian Islands, its range is now isolated to pockets of high elevation nesting habitat (Price & Antaky, 2020). Band-rumped storm-petrels have been documented using artificial nest boxes (Beard et al., 2022; Price & Antaky, 2020; Raine et al., 2017). These sites may well be the last resort of predator avoidance for a species that formerly most likely nested closer to the coast (International Union for the Conservation of Nature and Natural Resources, 2010).

Band-rumped storm-petrels most likely feed on small fish, squid, and crustaceans, based on records from the Galapagos Islands; diet information is not available for Hawaiian birds (U.S. Fish and Wildlife Service, 2005a). Foraging is confirmed diurnally and suspected nocturnally. Food is captured while sitting on the water or off the surface by bill snatching as the bird gently flaps just above the surface of the water (International Union for the Conservation of Nature and Natural Resources, 2010). Foraging occurs mostly in deep water in all seasons. They are attracted to discarded fish by-product from fishing boats (Onley & Scofield, 2007). Band-rumped storm-petrels are vulnerable to predation by introduced rats, mice, cats, mongooses, pigs, and barn owls (U.S. Fish and Wildlife Service, 2005a).

Insular Pacific-Hawaiian Large Marine Ecosystem

Band-rumped storm-petrels occur in coastal waters of the Hawaii portion of the Study Area and into the western portion of the Transit Corridor portion of the Study Area. Colonies in the main Hawaiian Islands are known or suspected on Lehua Island, Kauai, Maui, Kahoolawe, and Hawaii. Other colonies are likely in Waimea Canyon and Hanapepe Valley on the western side of Kauai. On Hawaii, one small population is known to nest on the upper west slope of Mauna Loa. Nesting on remote cliffs on Lehua Island is also confirmed (81 FR 67786). Vocalizations have been heard, indicating occurrence on Kahoolawe, Lanai, Lehua Rock, and Maui (Haleakala Crater) (International Union for the Conservation of Nature and Natural Resources, 2010; Raine et al., 2017; U.S. Fish and Wildlife Service, 2004). There is no known nesting in the Northwestern Hawaiian Islands (U.S. Fish and Wildlife Service, 2004).

During the nesting season, deep water (more than 1,000 m) close to shore can be used for foraging. Fishermen report them mostly at about 3 mi. off the Na Pali coast of Kauai (International Union for the Conservation of Nature and Natural Resources, 2010; Price & Antaky, 2020). Band-rumped storm-petrels are known to gather in nearshore waters before they fly inland to nesting colonies in the early evening.

Open Ocean

Band-rumped storm-petrels occur in the Hawaii portion of the Study Area and the western portion of the Transit Corridor Study Area. They are distributed in the Pacific from Japan east to Central America and northern South America (Harrison, 1983). Pacific populations are divided into distinct Japanese, Hawaiian, and Galapagos breeding populations (U.S. Fish and Wildlife Service, 2004). The Hawaiian population at sea is thought to remain in the central Pacific, ranging south to the Equatorial Countercurrent. Some individuals spend most of their time in open ocean, occurring far offshore from nesting islands; others seem to remain close to nesting colonies year-round (U.S. Fish and Wildlife Service, 2005a).

C.8.2.6.3 Population Trends

The global population of band-rumped storm-petrels is estimated to be 20,000 to 200,000 individuals. Due to the difficulty in studying this species, the number of birds breeding in Hawaii is currently unknown but is thought to be in the low hundreds (Kauai Endangered Seabird Recovery Project, 2017; U.S. Fish and Wildlife Service, 2021c). The Hawaiian population appears to be significantly reduced in numbers following human occupation of the Hawaiian Islands (81 FR 67786) and is likely a tiny remnant of historical numbers (National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2005). In 2004, the population of band-rumped storm-petrels at sea was estimated at about 5,500 (U.S. Fish and Wildlife Service, 2004). In 2002, the population on Kauai was estimated at 171 to 221 breeding pairs, mostly occurring along the Na Pali coast (Pohakuao Valley, Kalalau Valley, Awaawapuhi Valley, Nuololo Aina, and Nuololo Kay) on the west side of the island.

C.8.2.6.4 Population Threats

The small population size and limited distribution of the band-rumped storm-petrel in Hawaii threaten this endangered population by increasing the potential population consequences of other threats, including natural catastrophes such as hurricanes and landslides (81 FR 67786). The band-rumped storm-petrel is highly vulnerable to predation by introduced rats, mice, cats, mongooses, pigs, and barn owls, as well as being vulnerable to striking power lines and street lights at night (U.S. Fish and Wildlife Service, 2005a). Street and resort lights disorient fledglings, causing them to collide with structures or fall to the ground, where they are at risk from predators and cars. Additional threats are commercial fishing and ocean pollution, and the loss and degradation of forested habitat caused by introduced plants and herbivores.

C.8.3 Species Not Listed under the Endangered Species Act

At least 195 species of birds are found within the Study Area that are not listed under the ESA. The major groups of birds are described in Section C.8.2 (Endangered Species Act-Listed Species) and Section C.8.3 (Species Not Listed under the Endangered Species Act), and Section C.8.3.9 (Migratory Birds) describes species that are protected and of conservation concern under the Migratory Bird Treaty Act (MBTA) and Bald and Golden Eagle Protection Act.

C.8.3.1 Geese, Swans, Dabbling and Diving Ducks (Order Anseriformes)

There are 50 species of swans, geese, and dabbling and diving ducks in the family Anatidae in North America. No birds from this group are considered Birds of Conservation Concern (BCC) (U.S. Fish and Wildlife Service, 2008a). Birds from this group range from dabbling ducks found in coastal bays, estuaries, and lagoons to more open water ducks found in deeper water environments. Several of these species are diving ducks that inhabit nearshore or offshore waters of the Study Area, and San Diego Bay in particular (Sibley, 2014). Scaups (*Aythya spp.*) and surf scoters (*Melanitta perspicillata*) are abundant during winter throughout San Diego Bay, diving and foraging on the bottom from shallow (intertidal) to relatively deep (> 20 ft.) waters (U.S. Department of the Navy, 2013d).

Representative species that can be found in the Study Area include geese (e.g., Canada goose [*Branta canadensis*], brant [*Branta bernicla*]); dabbling ducks (e.g., mallard [*Anas platyrhynchos*], American wigeon [*Anas americana*], northern shoveler [*Anas clypeata*]); diving ducks (e.g., bufflehead [*Bucephala albeola*], greater scaup [*Aythya marila*], lesser scaup [*Aythya affinis*], and red-breasted merganser [*Mergus serrator*]); and scoters (e.g., surf scoter [*Melanitta perspicillata*], black scoter [*Melanitta americana*]) (American Ornithologists' Union, 1998).

C.8.3.2 Loons (Order Gaviiformes)

There are five species of loons in the family Gaviidae in North America (American Ornithologists' Union, 1998), three of which occur in the Study Area. The common loon (*Gavia immer*) and the red-throated loon (*G. stellata*) are BCC (U.S. Fish and Wildlife Service, 2008a). Loons are medium to large fish-eating birds that capture prey by diving underwater (Sibley, 2014). Loons can dive down to 250 ft. with an average dive time of 40 seconds (Sibley, 2014). Loons move ashore only to breed, and all loon species nest on banks of inland ponds or lakes, requiring specific habitat features such as undeveloped shoreline and nest sites that have steep drop offs so they can approach their nest from underwater (Cornell Lab of

Ornithology, 2009). For example, common loons spend their time in both freshwater and saltwater environments but prefer to nest on islands where the shoreline is not developed. Most loons need about 100 ft. of room to take off, so size is another habitat feature that is important for nesting areas. During migration, loons fly high above land or water in loose groups or singly. They winter in coastal, nearshore, or open water marine habitats (Sibley, 2014). For example, the Pacific loon (*G. pacifica*) prefers deep water and is found on the open ocean and in bays. The red-throated loon, a representative species within the Study Area, has a circumpolar distribution, breeds in high latitudes on remote ponds, and winters along the Atlantic and Pacific coasts (American Ornithologists' Union, 1998).

C.8.3.3 Albatrosses, Fulmars, Petrels, Shearwaters, and Storm-Petrels (Order Procellariiformes)

The Procellariiformes is a large order of open ocean seabirds that are divided into four families: Diomedeidae (albatrosses), Procellariidae (petrels and shearwaters), Hydrobatidae (storm-petrels), and Pelecanoididae (diving-petrels) (Enticott & Tipling, 1997; Onley & Scofield, 2007). These seabirds are generally long-lived, breed once a year, and lay only one egg, thus, they have a low reproductive output. They have extremely broad distributions and include all marine birds that spend most of their lives at sea and exclusively feed in the open ocean, primarily on fish, crustaceans, and crabs. They can be found in high numbers resting on the water in flocks where prey is concentrated (Enticott & Tipling, 1997). Some species feed around fishing boats or become injured from longline gear (Enticott & Tipling, 1997) (Onley & Scofield, 2007). They nest in colonies on remote islands uninhabited by people. Some are ground nesters; others nest in cavities or burrows (Ramos et al., 1997). They return to their birth colonies. Most species of this order are monogamous and mate for life. Both parents participate in egg incubation and chick rearing (Elphick et al., 2001). Representative species that occur in the Study Area include Laysan albatross (*Phoebastria immutabilis*), Northern fulmar (*Fulmaris glacialis*), mottled petrel (*Pterodroma inexpectata*), pink-footed shearwater (*Puffinus creatopus*), and Wilson's storm-petrel (*Oceanites oceanicus*).

C.8.3.4 Boobies, Gannets, Cormorants, and Frigatebirds (Order Suliformes)

The Suliformes order is a diverse group of large seabirds including anhingas, gannets, boobies, cormorants, and frigatebirds. This order is composed of 16 species in 4 families – 12 species representing 2 families that occur within the Study Area. Three of these species are considered BCC (U.S. Fish and Wildlife Service, 2008a). Species of concern within the Study Area include the brown booby (*Sula leucogaster*), great cormorant (*Phalacrocorax carbo*), and magnificent frigatebird (*Fregata magnificens*) (American Ornithologists' Union, 1998).

Suliformes are less pelagic than the Procellariiformes, although some of these species such as frigatebirds are pelagic. Most species are colonial, feed on fish, and use a variety of breeding habitats including trees and bushes (but not burrows). Breeding strategies vary among species, with some being long-lived and having low breeding success, while others have higher annual breeding success, but higher annual adult death (Enticott & Tipling, 1997; Onley & Scofield, 2007).

Cormorants are voracious predators on inshore fishes and have been implicated as a major threat to the recovery efforts of Atlantic salmon in the Gulf of Maine where they feed on juvenile salmon (smolts) leaving the estuaries (Fay et al., 2006; National Marine Fisheries Service & U.S. Fish and Wildlife Service, 2005). Their offshore foraging range is limited by their need for undisturbed, dry nocturnal roosting sites (Shields et al., 2002).

Boobies and gannets are large seabirds that plunge from the air to capture their prey. Filling similar niches, boobies inhabit warmer areas and gannets colder regions. Boobies and gannets often nest on

islands in colonies, with gannets nesting on cliffs (BirdLife International, 2012) and boobies generally on the ground if predators allow (Pratt et al., 1987). They forage offshore, often in large flocks, feeding on fish but also foraging at night, often feeding on squid (Pratt et al., 1987).

Like tropicbirds and pelicans, members of this group all have webbed feet and eight toes, and all have a throat sac, called a gular sac (Brown & Harshman, 2008). This sac is highly developed and visible in pelicans and frigatebirds but is also readily apparent in boobies and cormorants. Pelicans use the sac to trap fish, frigatebirds use it as a mating display and to feed on fish, squid, and similar marine life (Dearborn et al., 2001), and cormorants and boobies use the sac for heat regulation. These birds nest in colonies, but individual birds are monogamous (Brown & Harshman, 2008).

C.8.3.5 Tropicbirds (Order Phaethontiformes)

Tropicbirds are medium-sized seabirds, predominately white with black patterning on the back, wings, and face. They have thick, pointed bills that are red or orange in color that are slightly decurved. Their most notable feature is the extremely long and narrow central tail feathers, which can be 11 to 22 in. long. Their wingspans average around 3 ft. Superficially, tropicbirds resemble terns. Tropicbirds are plunge divers that feed on fish and are highly pelagic foragers in tropical and subtropical oceans, coming to land mainly to breed (Sibley, 2014). Red-billed tropicbirds (*Phaethon aethereus*) are rare visitors to the Study Area in both southern California and Hawaiian waters, whereas white-tailed and red-tailed tropicbirds (*P. lepturus* and *P. rubricauda*, respectively) nest in the Hawaiian Islands occur in the surrounding waters (Sibley, 2014).

C.8.3.6 Pelicans, Herons, Egrets, Ibis, and Spoonbills (Order Pelecaniformes)

Pelecaniformes is a large group composed of long-legged, large billed species that includes pelicans, herons, egrets, ibis, and spoonbills. However, with the exception of two species of pelicans (described below), they are inhabitants of freshwater marshes and are unlikely to occur in the Study Area.

The brown pelican (*Pelecanus occidentalis*) primarily occurs in shallow (less than 150 ft.) warm coastal marine and estuarine environments, as well as offshore where they forage primarily on fish by head first plunge-diving. Most plunge-diving is limited to 1–2 m within the water column. Foraging occurs within 20 km of nesting islands during the breeding season, and up to 75 km offshore during the nonbreeding season (Shields et al., 2002). American white pelicans (*Pelecanus erythrorhynchos*) are found in shallow coastal bays, inlets, and estuaries that support forage fish (Knopf & Evans, 2004). Flocks forage cooperatively, swimming and encircling fish as a coordinated group or driving them into shallows, where they are caught with synchronized bill dipping (Enticott & Tipling, 1997; Onley & Scofield, 2007).

C.8.3.7 Osprey, Bald Eagles, Kites and Falcons (Orders Accipitriformes and Falconiformes)

Accipitriformes is a large group consisting of 60 species in three families (American Ornithologists' Union, 1998). This order generally has broad wings well suited for soaring. Falconiformes include 9 North American species that, with the exception of the caracara (*Caracara cheriway*), are fast-flying predators with pointed wings and a streamline body shape (Sibley, 2014). Members of both orders hunt by day and feed on a variety of prey, including fish, small mammals, reptiles, and carrion. Species that are likely to occur within the Study Area include the osprey (*Pandion haliaetus*) bald eagle (*Haliaeetus leucocephalus*), peregrine falcon (*Falco peregrinus*), and swallow-tailed kite (*Elanoides forficatus*). The bald eagle, peregrine falcon, and swallow-tailed kite are BCC.

Ospreys live near slow-moving waters of coastal, nearshore, and freshwater environments in many parts of the Study Area. They are plunge feeders but also have the ability to capture prey with their feet while

keeping their head above water. Fish make up a large portion of their diet, and therefore, their vision is well adapted to detecting underwater objects from 10 to 40 m above water (Poole et al., 2002). Ospreys nest around the shores of San Diego Bay and forage in the waters of the bay (U.S. Department of the Navy, 2013d).

C.8.3.8 Shorebirds, Phalaropes, Gulls, Noddies, Terns, Skimmers, Skuas, Jaegers, and Alcids (Order Charadriiformes)

Shorebirds are small, generally long-legged coastal birds, many of which forage below the high tide in the surf zone by picking and probing for small aquatic prey (Sibley, 2014). Shorebirds undergo some of the longest distance migrations known for birds, for example, the red knot annually migrates more than 15,000 km. Though most of their life cycle is spent in coastal areas, shorebird migration over open ocean does occur (Elphick, 2007). Although taxonomically grouped among some shorebirds, two species of phalaropes in the family Scolopacidae that occur within the Study Area are functionally seabirds, spending the nonbreeding months out on the open ocean. These include the red-necked phalarope (*Phalaropus lobatus*) and red phalarope (*Phalaropus fulicarius*), both of which breed in high arctic habitats but spend migrate and winter at sea, gathering in small flocks at upwellings and convergence zones, foraging on zooplankton and other small aquatic animals that rise to the surface (Rubega et al., 2000).

Gulls, noddies, and terns in the family Laridae are a diverse group of small to medium sized seabirds that inhabit coastal, nearshore, and open sea waters. Skuas and jaegers in the family Stercorariidae are stocky powerful birds with long pointed wings, long tails, strong hooked bills, and sharp talons known for robbing the food of smaller seabirds, teasing and harassing them until they drop their prey. Murres, murrelets, and auklets in the family Alcidae are good swimmers and divers and have short wings, which require them to flap their wings rapidly to fly.

Species in the order Charadriiformes occupy diverse habitats. Some species in this order spend most of their time at sea (e.g., jaegers, skuas, alcids), whereas others are more coastal or near shore (e.g., gulls). Many charadriiforms inhabit marine and freshwater wetlands; others spend most of their lives in or near the ocean. Many species breed in colonies, and some species lay more than one egg (Ericson et al., 2003; Fain & Houde, 2007; Harrison, 1983; Onley & Scofield, 2007). Representative species within the Study Area include semipalmated plover (*Charadrius semipalmatus*), Bonaparte's gull (*Larus philadelphia*), black-legged kittiwake (*Rissa tridactyla*), Forster's tern (*Sterna forsteri*), parasitic jaeger (*Stercorarius parasiticus*), common murre (*Uria aalge*), sooty shearwater (*Puffinus tenuirostris*), and rhinoceros auklet (*Cerorhinca monocerata*).

C.8.3.9 Migratory Birds

Most of the bird species that would be encountered in the Study Area are listed under the MBTA (U.S. Fish and Wildlife Service, 2015). The MBTA established federal responsibilities for protecting nearly all migratory species of birds as defined in the Act, their eggs, and nests. Under the MBTA, migratory bird means any bird, whatever its origin and whether or not raised in captivity, which belongs to a species listed in Section 10.13 of the MBTA, or which is a mutation or a hybrid of any such species, including any part, nest, or egg of any such bird, or any product, whether or not manufactured, which consists, or is composed in whole or part, of any such bird or any part, nest, or egg thereof. Under the MBTA regulations applicable to military readiness activities (50 CFR part 21), the USFWS has promulgated a rule that authorizes the incidental take of migratory birds provided they do not result in a significant impact on the population of a migratory bird species. Of the 1,027 species protected under the MBTA

(U.S. Fish and Wildlife Service, 2013), over 100 species occur in the Study Area. These species are not analyzed individually, but rather are grouped based on taxonomic or behavioral similarities based on the stressor that is being analyzed.

BCC are species, subspecies, and populations of migratory and non-migratory birds that the USFWS has determined to be the highest priority for conservation actions (U.S. Fish and Wildlife Service, 2021a).

The purpose of the BCC list is to prevent or remove the need for additional ESA bird listings by implementing proactive management and conservation actions needed to conserve these species. Of the species that occur within the Study Area, 15 are considered BCC (Table C-7). These species are not analyzed individually, but rather are grouped by taxonomic or behavioral similarities based on the stressor that is being analyzed.

Order/Family	Common Name	Scientific Name
Order Procellariiformes		
Family Diomedeidae		
	Laysan albatross	Phoebastria immutabilis
	Black-footed albatross	Phoebastria nigripes
Family Procellariidae		
	Pink-footed shearwater	Puffinus creatopus
	Christmas shearwater	Puffinus nativitatis
	Black-vented shearwater	Puffinus opisthomelas
Family Hydrobatidae		
	Ashy storm-petrel	Oceanodroma homochroa
	Band-rumped storm-petrel	Oceanodroma [Hydrobates] castro
	Tristram's storm-petrel	Oceanodroma tristrami
Order Falconiformes		
Family Falconidae		
	Peregrine falcon	Falco peregrinus
Order Charadriiformes		
Family Lardiae		
Subfamily Sterninae	Blue noddy	Procelsterna cerulean
	Gull-billed tern	Sterna nilotica
Subfamily Rynchopinae	Black skimmer	Rynchops niger
Family Ardeidae		
	Guadalupe murrelet	Synthliboramphus hypoleucus
	Scripps's murrelet	Synthliboramphus scrippsi
	Cassin's auklet	Ptychoramphus aleuticus

Table C-7: Birds of Conservation Concern that Occur within the Study Area

C.8.3.9.1 Grebes (Order Podicipediformes)

There are seven species of grebes in the family Podicipedidae in North America, all of which occur in the Study Area (American Ornithologists' Union, 1998). Two of these species, the pied-billed grebe (*Podilymbus podiceps*) and horned grebe (*Podiceps auritus*) are BCC (U.S. Fish and Wildlife Service, 2008a). Grebes can be found in a variety of aquatic habitats ranging from seasonally flooded scrubland and roadside ditches to deep lakes and coastal bays. Most grebe species winter in open waters while preferring marshy, vegetated habitats during the summer months (Sibley, 2014). Grebes forage by diving for small aquatic animals such as insects, fish, and crustaceans in the water column. For example, horned grebes can dive for up to 3 minutes and travel 500 ft. underwater, where they are sometimes

preyed upon by sharks and orcas (Ehrlich et al., 1988). Grebes tend to escape predators by diving or sinking, leaving only the head exposed, rather than taking flight. All grebe species build floating nests in marshes and winter on the ocean and nearshore coastal areas (Sibley, 2014).

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